# Attacking ECDSA with Nonce Leakage by Lattice Sieving: Bridging the Gap with Fourier Analysis-based Attacks* 

Yiming Gao ${ }^{1, \star \star}$, Jinghui Wang ${ }^{1, \star \star}$, Honggang $\mathrm{Hu}^{1,2}$, and Binang $\mathrm{He}^{1}$<br>${ }^{1}$ School of Cyber Science and Technology<br>University of Science and Technology of China, Hefei 230027, China<br>\{qw1234567,liqing21, hebinang\}@mail.ustc.edu.cn<br>${ }^{2}$ Hefei National Laboratory, Hefei 230088, China<br>hghu2005@ustc.edu.cn


#### Abstract

The Hidden Number Problem (HNP) has found extensive applications in side-channel attacks against cryptographic schemes, such as ECDSA and Diffie-Hellman. There are two primary algorithmic approaches to solving the HNP: lattice-based attacks and Fourier analysisbased attacks. Lattice-based attacks exhibit better efficiency and require fewer samples when sufficiently long substrings of the nonces are known. However, they face significant challenges when only a small fraction of the nonce is leaked, such as 1-bit leakage, and their performance degrades in the presence of errors.

In this paper, we address an open question by introducing an algorithmic tradeoff that significantly bridges the gap between these two approaches. By introducing a parameter $x$ to modify Albrecht and Heninger's lattice, the lattice dimension is reduced by approximately $\left(\log _{2} x\right) / l$, where $l$ represents the number of leaked bits. We present a series of new methods, including the interval reduction algorithm, several predicates, and the pre-screening technique. Furthermore, we extend our algorithms to solve the HNP with erroneous input. Our attack outperforms existing state-of-the-art lattice-based attacks against ECDSA. We break several records including 1-bit and less than 1-bit leakage on a 160-bit curve, while the best previous lattice-based attack for 1-bit leakage was conducted only on a 112-bit curve.


Keywords: ECDSA • Hidden Number Problem • Lattice Sieving • Latticebased Attacks

## 1 Introduction

The Hidden Number Problem (HNP) was originally proposed by Boneh and Venkatesan as a number theoretic problem to investigate the bit security of the

[^0]Diffie-Hellman key exchange scheme [11]. Their work was subsequently extended by Nguyen and Shparlinski to analyze the security of ECDSA with partial known nonce leakage [28].

In the scenario that an attacker can obtain some information about the nonce used in each signature generation of ECDSA, it is possible to recover the secret key by solving the corresponding HNP instance. Currently, there are two types of attacks for solving the HNP: Fourier analysis-based attacks and lattice-based attacks.

The foundational principles of Fourier analysis-based attacks were initially introduced by Bleichenbacher [10], providing the basis for subsequent research $[13,5,34,6]$. These attacks have been considered to be more tractable to break HNP instances with limited known bits and even with errors. However, they demand a substantial number of samples and exhibit a high computational overhead. The latest advance is obtained by Aranha et al., who successfully broke 192-bit ECDSA with less than 1-bit leakage [6].

In lattice-based attacks, the HNP is transformed into the Bounded Distance Decoding (BDD) Problem, which is a variant of the Closest Vector Problem (CVP). Using Kannan's embedding [22], it can be further transformed into the Unique Shortest Vector Problem (uSVP). The success of lattice-based attacks highly depends on whether the target vector corresponding to the secret is sufficiently short in the lattice. It is believed that the lattice-based attacks would become ineffective when only a small fraction of the nonce is revealed, particularly in the case of 1-bit leakage. Aranha et al. emphasized that exploiting a 1-bit nonce leakage to attack ECDSA is infeasible due to the underlying structure of the HNP lattices [5]. Additionally, lattice-based attacks have been considered to behave very poorly with noisy data, which poses constraints on practical side-channel attacks.

At EUROCRYPT 2021, Albrecht and Heninger [3] extended the applicability of lattice-based attacks with their Sieving with Predicate (Sieve-Pred) algorithm and the state-of-the-art lattice sieving library G6K [2]. The Sieve-Pred algorithm no longer treats sieving algorithms as black boxes for SVP. Instead, it uses a predicate to check all the vectors in the database output by sieving algorithms. The predicate they used involves scalar multiplication on the elliptic curve, which is a nonlinear operation and results in significant overhead. The nonlinear predicate was improved to a linear predicate by Xu et al. [37].

Lattice-based attacks and Fourier analysis-based attacks have their unique characteristics. Current lattice-based attacks are known for their minimal sample requirements and efficient processing. However, they are considered to be infeasible when dealing with challenging HNP instances. In contrast, Fourier analysis-based attacks can handle more difficult instances such as 1-bit leakage on a 192-bit curve [6], but demand a significantly larger sample size and computational time. This leads to an open question [19]: Can lattice-based attacks be enhanced by utilizing more samples? Is there a smooth tradeoff that can be characterized between these two types of algorithms?

### 1.1 Contributions

In this work, we present a solution to this open question. The lattice-based attacks are enhanced by utilizing more samples, significantly bridging the gap between lattice-based attacks and Fourier analysis-based attacks. We successfully address the case of 1-bit leakage on a 160-bit curve, surpassing the best previous lattice-based attack for 1-bit leakage, which was only conducted on a 112-bit curve [37]. Moreover, despite the belief that lattice-based attacks are ineffective for erroneous input [6], we demonstrate the effectiveness of our new attack in handling erroneous input, and successfully break the 160-bit ECDSA with less than 1-bit leakage. Our main contributions are as follows.

Improved Algorithms for Solving the HNP. Firstly, we propose a new lattice construction that introduces a parameter $x$ to trade off the lattice dimension. Our modification is based on Albrecht and Heninger's lattice, where the hidden number $\alpha$ is transformed into $k_{0}^{\prime}$ using the elimination method and the recentering technique. In our construction, $k_{0}^{\prime}$ is decomposed as $x \cdot \alpha_{0}+\alpha_{1}$, where $\left|\alpha_{1}\right| \leq x / 2$. The target lattice vector contains the information of $\alpha_{0}$, which is expected to be included in the database output by sieving algorithms. Our construction can reduce the lattice dimension by approximately $\left(\log _{2} x\right) / l$, where $l$ represents the number of leaked bits. The reduction of lattice dimension leads to a significant efficiency advantage, given that sieving algorithms have exponential complexity. As a tradeoff, our algorithm needs more samples to construct the new lattice. Moreover, we prove the existence of a constant $c>0$ that serves as a lower bound for the success probability of our algorithm, which is a new theoretical finding not reported in the literature.

Secondly, to determine the unique hidden number, we present an improved linear predicate that utilizes the linear constraints of $2 \log _{2} q$ HNP samples. Its efficiency outperforms the non-linear predicate proposed by Albrecht and Heninger, which involves time-consuming scalar multiplication over the elliptic curves [3]. Our predicate also outperforms the linear predicate used by Xu et al. [37]. Their predicate needs the knowledge of all elements of the candidate vector. On the other hand, our predicate requires the knowledge of the last two elements of the candidate vector.

Thirdly, a predicate for the decomposition technique is proposed. We design an interval reduction algorithm with expected time complexity $O\left(\log ^{2} x\right)$ to recover the remaining part $\alpha_{1}$, instead of an exhaustive search over the range $[-x / 2, x / 2]$. Moreover, we also present a pre-screening technique to pre-select candidates. This technique can effectively eliminate most incorrect candidates before checking the predicate.

Modified Algorithms for Handling Errors. We define HNP with erroneous input to handle practical scenarios in side-channel attacks where errors may exist in the leaked nonce. We demonstrate the effectiveness of our lattice construction for solving this problem, and provide the estimation for the lattice dimension. Furthermore, our new algorithms and techniques for solving the HNP are extended to address the case of erroneous input.

New Records of Lattice-based Attacks against ECDSA. We carry out experiments on lattice-based attacks against ECDSA with nonce leakage. Our attack demonstrates a significant efficiency advantage over previous works [3,37]. The most notable achievement is the successful key recovery for the ECDSA instance with 1-bit leakage on a 160-bit curve, which is considered to be extremely difficult by previous lattice-based approaches. Moreover, we also successfully conduct attacks for the case of less than 1-bit leakage on various elliptic curves, including a 160-bit curve.

Source Code. The source code of our attack will be publicly available via GitHub upon the publication of this paper.

### 1.2 Comparison with Related Work

In Table 1, our work is compared with previous records of lattice-based attacks. Several new records are listed, including 1-bit and less than 1-bit leakage on a 160-bit curve. To the best of our knowledge, we carry out the first lattice-based attack against ECDSA with less than 1-bit leakage. For the case of 4-bit leakage, we also make significant progress. While the previous record for 4-bit leakage was achieved on a 384-bit curve, we successfully extend this attack to a 512-bit curve [3].

Table 1: Lattice-based attacks against ECDSA with nonce leakage

|  | Nonce leakage |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Modulus | 4-bit | 3 -bit | 2 -bit | 1-bit | $<1$-bit |
| 112-bit | - | - | - | [37], ours (faster) | Ours |
| 128-bit | - | - | - | Ours | Ours |
| 160-bit | - | $[28]$ | $[3,33]$ | Ours | Ours |
| 256 -bit | $[3]$ | $[3,33]$ | $[37]$, ours (faster) | - | - |
| 384 -bit | $[3,33]$ | $[37]$, ours (faster) | - | - | - |
| 512 -bit | Ours | - | - | - | - |

Among lattice-based attacks, the currently best one is the Sieve-Pred algorithm in [3]. The efficiency of the predicate is crucial, as it is used to check the vectors in the database generated by sieving algorithms. Our linear predicate outperforms both predicates proposed in [3] and [37]. Our attack demonstrates superior efficiency when targeting various ECDSA instances. For example, we break the 112-bit ECDSA with 1-bit leakage in 10 minutes which is approximately 26 times faster than the currently fastest attack in [37].

Our work can also be viewed as a comprehensive extension of the work conducted by Sun et al. [33], who recognized the connection between Fourier-based attacks and lattice-based attacks, and proposed a general framework to enhance lattice attacks with more samples. However, they did not consider reducing the dimension of their lattice, nor did they utilize sieving algorithms to handle more challenging cases, such as 256-bit ECDSA with 2-bit leakage or 1-bit leakage case. Compared with their work, our algorithm requires significantly
fewer samples and achieves higher success rates. For instance, when targeting 160 -bit ECDSA with 2 -bit leakage, their algorithm required approximately $2^{27}$ samples and achieved a success rate of $15 \%$, while our algorithm only needs 411 samples with a success rate of approximately $100 \%$. Moreover, according to their estimation, the time complexity of their algorithm is $2^{110}$ BKZ- 30 operations for 160-bit ECDSA with 1-bit leakage, which is impractical. However, we break this instance using only 14.3 hours.

Our work shares some similarities with Fourier analysis-based attacks. However, except for very difficult cases, our attack works more efficiently with far fewer samples. Another advantage of our approach is the capability to recover the entire secret key all at once, while Fourier analysis-based attacks can only recover a few bits of the secret key in a single execution.

## 2 Preliminaries

Let $\mathbb{N}^{+}$be the set $\{1,2,3, \cdots\}$. The logarithm with base two is denoted as $\log (\cdot)$, and the Euclidean norm is denoted as $\|\cdot\|$. For any integer $z$, the unique integer $x$ satisfying $0 \leq x<q$ and $x \equiv z \bmod q$ is denoted by $|z|_{q}$. A function $f(k)$ is called negl $(k)$ if for every positive polynomial function $\mathrm{P}(k)$, there exists an integer $N_{\mathrm{P}}>0$ such that for all $k>N_{\mathrm{P}},|f(k)|<1 / \mathrm{P}(k)$.

### 2.1 Lattices and Hard Problems

Given a matrix $\boldsymbol{B}=\left(\boldsymbol{b}_{0}, \ldots, \boldsymbol{b}_{d-1}\right)^{T} \subset \mathbb{R}^{d \times d}$ with linearly independent rows, the lattice generated by the basis $\boldsymbol{B}$ is defined as $\mathcal{L}(\boldsymbol{B}):=\left\{\sum_{i}^{d} x_{i} \boldsymbol{b}_{i}: x_{i} \in \mathbb{Z}\right\}$. We define $\pi_{i}$ as the projections orthogonal to the span of $\boldsymbol{b}_{0}, \ldots, \boldsymbol{b}_{i-1}$, and the Gram-Schmidt orthogonalisation as $\boldsymbol{B}^{*}=\left(\boldsymbol{b}_{0}^{*}, \ldots, \boldsymbol{b}_{d-1}^{*}\right)$, where $\boldsymbol{b}_{i}^{*}:=\pi_{i}\left(\boldsymbol{b}_{i}\right)$. For any $0 \leq l<r \leq d$, the projected sublattice $\mathcal{L}_{[l: r]}$ is defined as the lattice with basis $\boldsymbol{B}_{[l: r]}:=\left(\pi_{l}\left(\boldsymbol{b}_{l}\right), \ldots, \pi_{l}\left(\boldsymbol{b}_{r-1}\right)\right)$.

Let $\lambda_{i}(\mathcal{L})$ be the radius of the smallest ball centred at the origin containing at least $i$ linearly independent lattice vectors. Then $\lambda_{1}(\mathcal{L})$ is the Euclidean norm of the shortest non-zero vector in lattice $\mathcal{L}$.

The Gaussian heuristic predicts the number of lattice points inside a measurable body $\mathcal{B} \subset \mathbb{R}^{n}$, and it tells us that the number $|\mathcal{L} \cap \mathcal{B}|$ of lattice points inside $\mathcal{B}$ is approximately equal to $\operatorname{Vol}(\mathcal{B}) / \operatorname{Vol}(\mathcal{L})$. Applying it to the Euclidean $d$-ball, the prediction of $\lambda_{1}(\mathcal{L})$ can be obtained.

Definition 1 (Gaussian Heuristic (GH)). We denote by $\mathrm{GH}(\mathcal{L})$ the expected first minimum of a lattice $\mathcal{L}$. For a full rank lattice $\mathcal{L} \subset \mathbb{R}^{d}$, it is given by

$$
\operatorname{GH}(\mathcal{L})=\frac{\Gamma\left(1+\frac{d}{2}\right)^{1 / d}}{\sqrt{\pi}} \cdot \operatorname{Vol}(\mathcal{L})^{1 / d} \approx \sqrt{\frac{d}{2 \pi e}} \cdot \operatorname{Vol}(\mathcal{L})^{1 / d}
$$

The final step above is obtained from Stirling's formula, and we utilize this asymptotic estimation in our theoretical analysis. In practical attacks and calculations, we directly compute the value of the Gamma function.

A critical problem on lattices is to find the shortest vector.

Definition 2 (Shortest Vector Problem (SVP)). Given a lattice basis B, find a shortest non-zero vector $\boldsymbol{v} \in \mathcal{L}(\boldsymbol{B})$.

Albrecht and Heninger formalized two lattice problems augmented with a predicate [3], which are defined as follows:

Definition 3 ( $\alpha$-Bounded Distance Decoding with Predicate $\left(\mathrm{BDD}_{\alpha, \mathrm{f}(\cdot)}\right)$ ). Given a lattice basis B, a vector $\boldsymbol{t}$ and a parameter $\alpha>0$ such that the Euclidean distance $\operatorname{dist}(\boldsymbol{t}, \boldsymbol{B})<\alpha \cdot \lambda_{1}(\mathcal{L}(\boldsymbol{B}))$, find the lattice vector $v \in \mathcal{L}(\boldsymbol{B})$ satisfying $f(\boldsymbol{v}-\boldsymbol{t})=1$ that is closest to $\boldsymbol{t}$.

Definition 4 (unique Shortest Vector Problem with Predicate ( $\left.\mathrm{uSVP}_{\mathrm{f}(\cdot)}\right)$ ). Given a lattice basis $\boldsymbol{B}$ and a predicate $f(\cdot)$, find the shortest non-zero vector $\boldsymbol{v} \in \mathcal{L}(\boldsymbol{B})$ that satisfies $f(\boldsymbol{v})=1$.
$\mathrm{BDD}_{\alpha, \mathrm{f}(\cdot)}$ can be solved using a $\mathrm{uSVP}_{\mathrm{f}(\cdot)}$ oracle due to Kannan embedding technique, by constructing the lattice

$$
\mathbf{C}=\left[\begin{array}{cc}
\mathbf{B} & 0 \\
\mathbf{t} & \tau
\end{array}\right]
$$

where $\tau$ is the embedding factor. If $\boldsymbol{v}$ is the closest vector to $\mathbf{t}$, then the short vector $(\mathbf{t}-\boldsymbol{v}, \tau)$ is contained in the lattice $\mathcal{L}(\mathbf{C})$.

### 2.2 Lattice Algorithms

BKZ. The Block Korkine-Zolotarey (BKZ) algorithm, which can be regarded as an extended version of the LLL algorithm [25], was first introduced by Schnorr and Euchner [32]. It uses an oracle that solves the SVP in the lattice with a block-size of $\beta$, spanned by $\boldsymbol{B}_{[0, \beta-1)]}$. The short vector is then recursively inserted into the lattice basis. A BKZ tour is initiated by calling an SVP-solver on consecutive blocks $\boldsymbol{B}_{[i, \min (i+\beta, d-1)]}$ for $i=0, \ldots, d-2$. The algorithm will proceed with these tours until there are no further changes observed within a single tour. The algorithm takes a lattice of dimension $d$ as input and outputs a short vector of length $\approx\left(\beta^{1 / 2 \beta}\right)^{d} \cdot \operatorname{det}(\mathcal{L})^{1 / d}$ in time $\beta^{\beta /(2 e)}$.

The root-Hermite factor $\delta$, which is used to analyze the quality of the basis independent of dimension $d$, is defined as $\delta=\left(\left\|b_{1}\right\| / \operatorname{vol}\left((\mathcal{L})^{1 / d}\right)\right)^{1 / d}$.

In order to achieve a better quality basis, it is desirable to minimize the Hermite factor $\delta$ as much as possible. Therefore, the first vector of some reduced basis has norm $\|v\|=\delta^{d} \cdot \operatorname{vol}(\mathcal{L})^{1 / d}$. In LLL algorithm, $\delta$ is approximately equal to 1.0219 , while in $\mathrm{BKZ}-\beta, \delta$ is equal to $\left((\beta / 2 \pi e)(\pi \beta)^{1 / \beta}\right)^{1 /(2(\beta-1)}$.

Based on Schnorr's Geometric Series Assumption (GSA) [31], we can analyze the performance of BKZ algorithm and predict the quality of the reduced basis. According to GSA, the norms of the Gram-Schmidt vectors satisfy $\left\|\boldsymbol{b}_{i}^{*}\right\|=\alpha^{i-1}\left\|\boldsymbol{b}_{1}^{*}\right\|$, where $i=1,2, \ldots, d$, and $\frac{3}{4} \leq \alpha^{2}<1$.

Lattice Sieving. Sieving algorithms are not only asymptotically superior to enumeration techniques $[22,16,32,18]$, but also showing better performance in
practice, due to the recent progress in both theory $[23,9,8,20]$ and practice [17,14,24,2,15].

The first sieving algorithm was proposed by Ajtai et al. [1] in 2001. It starts with a list of lattice vectors $L \subset \mathcal{L}$ and searches for shorter sums and differences of these vectors. The shorter combinations then replace the original longer vectors in the database. This process iterates until the database contains a significant number of short vectors, with the expectation of eventually finding the shortest vector.

Lattice sieving algorithms can be categorized into provably sieving algorithms and heuristic sieving algorithms. Heuristic sieving algorithms fall in the practical regime because of lower time and memory complexities. They are analyzed under the heuristic that the points in $L$ are independently and uniformly distributed in a thin spherical shell. Nguyen and Vidick [29] proposed the first practical sieving algorithm, utilizing a database of $(4 / 3)^{d / 2+o(d)}=2^{0.2075 d+o(d)}$ vectors and running in time $2^{0.415 d+o(d)}$. The time complexity was subsequently improved to $2^{0.292 d+o(d)}$ through nearest neighbor search techniques [8]. Various sieving algorithms have been efficiently implemented in G6K [2] and its GPU-accelerated version, G6K-GPU [15].

### 2.3 Hidden Number Problem

In the Hidden Number Problem (HNP) [11], we have an $n$-bit sized public modulus $q$, and there is a secret integer $\alpha \in \mathbb{Z}_{q}$, referred to as the hidden number. For $i=0,1, \ldots, m-1, t_{i}$ are uniformly random integers in $\mathbb{Z}_{q}$, and we are provided with the corresponding value $a_{i}$ such that $\left|t_{i} \cdot \alpha-a_{i}\right|_{q}=k_{i}<q / 2^{l}$. The problem is to recover the hidden number $\alpha$ when $m$ samples $\left(t_{i}, a_{i}\right)$ are given. For convenience, we denote the above problem as $\operatorname{HNP}(n, l)$.

### 2.4 Breaking ECDSA with Nonce Leakage

ECDSA. The global parameters for an ECDSA signature include an elliptic curve $E\left(\mathbb{F}_{p}\right)$ and a generator point $G$ on $E\left(\mathbb{F}_{p}\right)$ of a prime order $q$. The secret signing key is an integer $0 \leq s k<q$, and the public verifying key is a point $[s k] G$. To sign a message hash $h$, the signer first generates a random integer nonce $0 \leq k<q$, then computes the signature $(r, s)=\left(([k] G)_{x},\left|k^{-1} \cdot(h+s k \cdot r)\right|_{q}\right)$, where $x$ subscript represents the $x$ coordinate of the point.

ECDSA as a HNP. In a side-channel attack against ECDSA, the adversary may know $l$ least significant bits of the nonce $k$. If we write $k=k_{m s b} \cdot 2^{l}+k_{l s b}$, where $0 \leq k_{m s b}<q / 2^{l}$ and $0 \leq k_{l s b}<2^{l}$, then we can obtain the following equation based on $s=\left|k^{-1} \cdot(h+r \cdot s k)\right|_{q}$ :

$$
2^{-l}\left(k_{l s b}-s^{-1} \cdot h\right)+k_{m s b}=2^{-l} \cdot s^{-1} \cdot r \cdot s k \bmod q .
$$

This can be regarded as a HNP instance with $\left(t_{i}, a_{i}\right)=\left(\left|2^{-l} \cdot s^{-1} \cdot r\right|_{q}, \mid 2^{-l}\right.$. $\left.\left.\left(k_{l s b}-s^{-1} \cdot h\right)\right|_{q}\right)$ and hidden number $\alpha=s k$. Below we abbreviate $\operatorname{ECDSA}(n, l)$ as an $n$-bit ECDSA instance with $l$-bit leakage.

### 2.5 Solving the HNP with Lattices

To solve the HNP, in 1996, Boneh and Venkatesan [11] constructed the $(m+1)$ dimensional lattice generated by the rows of the following matrix:

$$
\left[\begin{array}{ccccc}
q & 0 & \cdots & 0 & 0 \\
0 & q & \cdots & 0 & 0 \\
\vdots & \vdots & & \vdots & \vdots \\
0 & 0 & \cdots & q & 0 \\
t_{0} & t_{1} & \cdots & t_{m-1} & 1 / 2^{l}
\end{array}\right] .
$$

There exists a lattice vector $\boldsymbol{v}=\left(t_{0} \cdot \alpha \bmod q, \ldots, t_{m-1} \cdot \alpha \bmod q, \alpha / 2^{l}\right)$. This lattice vector is close to the target vector $\mathbf{t}=\left(a_{0}, \ldots, a_{m-1}, 0\right)$ since the distance $\|\boldsymbol{v}-\mathbf{t}\|$ can be bounded by $\sqrt{m+1} \cdot q / 2^{l}$. If the distance is sufficiently small compared with other lattice vectors, the lattice vector can be found by solving the BDD problem using the nearest plane algorithm [7], or Kannan's embedding [22]. With Kannan's embedding, we construct the $(m+2)$-dimensional lattice basis

$$
\left[\begin{array}{cccccc}
q & 0 & \cdots & 0 & 0 & 0 \\
0 & q & \cdots & 0 & 0 & 0 \\
\vdots & \vdots & & \vdots & \vdots & \vdots \\
0 & 0 & \cdots & q & 0 & 0 \\
t_{0} & t_{1} & \cdots & t_{m-1} & 1 / 2^{l} & 0 \\
a_{0} & a_{1} & \cdots & a_{m-1} & 0 & \tau
\end{array}\right]
$$

where $\tau$ is the embedding number which can be the upper bound of $k_{i}$, i.e., $\tau=q / 2^{l}$. The target lattice vector becomes $\boldsymbol{v}= \pm\left(k_{0}, \ldots, k_{m-1}, \alpha / 2^{l},-\tau\right)$ with a bounded norm of $\sqrt{m+2} \cdot q / 2^{l}$.

Recentering Technique. In the definition of HNP, $0 \leq k_{i}<q / 2^{l}$, for $i=$ $0,1, \ldots, m-1$. Since the lattice can work for any sign of $k_{i}$, we can make a variable substitution $k_{i}^{\prime}=k_{i}-w$ where $w=q / 2^{l+1}$. The target vector becomes $\left(k_{0}^{\prime}, k_{1}^{\prime}, \ldots, k_{m-1}^{\prime}, \alpha / 2^{l},-\tau\right)$ and has a much shorter length. This technique can bring a significant improvement in practice and is widely used in the lattice attacks on HNP [28,12, $27,3,37$ ].

Elimination Method. Given a set of HNP equations $a_{i}+k_{i}=t_{i} \alpha \bmod q$, where $i=0,1, \cdots, m-1$, we can eliminate the variable $\alpha$ by substituting $\alpha=\mid\left(a_{0}+\right.$ $\left.k_{0}\right)\left.t_{0}^{-1}\right|_{q}$. This yields a new set of HNP equations. Incorporating the recentering technique, we have

$$
a_{i}+w-\left(a_{0}+w\right) t_{0}^{-1} t_{i}+k_{i}^{\prime}=t_{0}^{-1} t_{i} k_{0}^{\prime} \bmod q,
$$

where $i=1, \ldots, m-1$. This produces a transformed HNP instance $\left(t_{i}^{\prime}, a_{i}^{\prime}\right)=$ $\left(t_{0}^{-1} t_{i}, a_{i}+w-\left(a_{0}+w\right) t_{0}^{-1} t_{i}\right)$ with the transformed hidden number $k_{0}^{\prime}$. Then
the new lattice is generated by:

$$
\left[\begin{array}{cccccc}
q & 0 & \cdots & 0 & 0 & 0 \\
0 & q & \cdots & 0 & 0 & 0 \\
\vdots & \vdots & & & & \\
\vdots & \vdots \\
0 & 0 & \cdots & q & 0 & 0 \\
t_{1}^{\prime} & t_{2}^{\prime} & \cdots & t_{m-1}^{\prime} & 1 & 0 \\
a_{1}^{\prime} & a_{2}^{\prime} & \cdots & a_{m-1}^{\prime} & 0 & \tau
\end{array}\right]
$$

referred to as the Albrecht and Heninger's lattice [3]. The lattice dimension, denoted as $d$, is reduced to $m+1$. The target lattice vector becomes $\boldsymbol{v}=$ $\pm\left(k_{1}^{\prime}, \ldots, k_{m-1}^{\prime}, k_{0}^{\prime},-\tau\right)$, with a bounded norm of $\sqrt{m w^{2}+\tau^{2}}$. To find the target vector using a black box SVP solver, we expect the target vector to be the shortest vector, i.e., $\|\boldsymbol{v}\| \leq \sqrt{m w^{2}+\tau^{2}} \leq \mathrm{GH}(\mathcal{L})$. Combining this with $d=m+1$, we can estimate the minimal lattice dimension. Moreover, instead of using the upper bound of $\|\boldsymbol{v}\|$, Albrecht and Heninger considered the expected squared norm [3], i.e., $\mathbb{E}\left[\|\boldsymbol{v}\|^{2}\right]=m w^{2} / 3+m / 6+w^{2}$. Then the minimal lattice dimension can be estimated as the minimal integer $d$ satisfying $\mathbb{E}\left[\|\boldsymbol{v}\|^{2}\right] \leq \mathrm{GH}^{2}(\mathcal{L})$.

Sieving with Predicate. The sieving with predicate (Sieve-Pred) algorithm checks over the database generated by sieving algorithms using the predicate [3]. It does not treat the sieving algorithm as a black box SVP solver. This idea is inspired by Micciancio et al. [26], which suggests that the sieving algorithm not only outputs the shortest vector, but also provides all vectors with norm less than $\sqrt{4 / 3} \mathrm{GH}(\mathcal{L})$, under specific heuristic assumptions. Algorithm 1 is expected to find the target vector under Assumption 1 stated below.

Assumption 1 ([14]) When a 2-sieve algorithm terminates, it outputs a database $L$ containing all vectors with norm $\leq \sqrt{4 / 3} \mathrm{GH}(\mathcal{L})$.

Theorem 1 ([3]). Let $\mathcal{L} \subset \mathbb{R}^{d}$ be a lattice containing a vector $v$ such that $\|\boldsymbol{v}\| \leq \sqrt{4 / 3} \mathrm{GH}(\mathcal{L})$. Under Assumption 1, Algorithm 1 is expected to find the minimal $\boldsymbol{v}$ satisfying $f(\boldsymbol{v})=1$ in $2^{0.292 d+o(d)}$ steps and $(4 / 3)^{d / 2+o(d)}$ calls to the predicate $f(\cdot)$.

```
Algorithm 1: Sieving with Predicate
    Input: Lattice \(\mathcal{L}(\boldsymbol{B})\), predicate \(f(\cdot)\)
    Output: \(\boldsymbol{v}\) such that \(\|\boldsymbol{v}\| \leq \sqrt{4 / 3} \mathrm{GH}(\mathcal{L})\) and \(f(\boldsymbol{v})=1\) or \(\perp\)
    \(\boldsymbol{r} \leftarrow \perp\);
    Run the sieving algorithm on \(\mathcal{L}(\boldsymbol{B})\) and output list \(L\);
    for \(v \in L\) do
        if \(f(\boldsymbol{v})=1\) and \((r=\perp\) or \(\|\boldsymbol{v}\|<\|\boldsymbol{r}\|)\) then
            \(\boldsymbol{r} \leftarrow \boldsymbol{v} ;\)
    return \(r\);
```

Thus, using the Sieve-Pred algorithm, the minimal lattice dimension can be estimated as the minimal integer $d$ satisfying $\mathbb{E}\left[\|\boldsymbol{v}\|^{2}\right] \leq 4 \mathrm{GH}^{2}(\mathcal{L}) / 3$.

## 3 Improved Algorithms

In this section, we present several new algorithms for solving the HNP. We decompose the hidden number $k_{0}^{\prime}$ as $x \cdot \alpha_{0}+\alpha_{1}$, and introduce a new lattice construction that utilizes $x$ to trade off the lattice dimension. Through theoretical analysis, we demonstrate that the lattice dimension can be reduced by approximately $(\log x) / l$. While the target vector contains information about $\alpha_{0}$, the lack of information about $\alpha_{1}$ makes it impossible to directly compute the hidden number $\alpha$. This makes previous predicates ineffective [3,37]. Due to the idea of the Sieve-Pred algorithm, we need to search within the exponentially large database output by the sieving algorithms. Therefore, an efficient process that excludes the incorrect candidate is crucial. To address this problem, we propose a prescreening technique, an interval reduction algorithm, and the corresponding linear predicate. Moreover, we show that under Assumption 1, there exists a constant $c>0$ such that the success probability of our algorithm is at least $c$.

### 3.1 New Lattice Construction Based on Decomposition Technique

Lattice Construction. Following Albrecht and Heninger's lattice [3], we construct the lattice generated by

$$
\left[\begin{array}{cccccc}
q & 0 & \cdots & 0 & 0 & 0 \\
0 & q & \cdots & 0 & 0 & 0 \\
\vdots & \vdots & & \vdots & \vdots & \vdots \\
0 & 0 & \cdots & q & 0 & 0 \\
x \cdot t_{1}^{\prime} & x \cdot t_{2}^{\prime} & \cdots & x \cdot t_{m-1}^{\prime} & y & 0 \\
a_{1}^{\prime} & a_{2}^{\prime} & \cdots & a_{m-1}^{\prime} & 0 & \tau
\end{array}\right]
$$

where $x, y$, and $\tau$ are undetermined coefficients. This modification increases the lattice volume by a factor of $y$.

In [33], Sun et al. decomposed the hidden number $\alpha$ as $\alpha=2^{c} \cdot \alpha_{0}+\alpha_{1}$, where $0 \leq \alpha_{1}<2^{c}$. We propose a more generalized form of decomposition to the new hidden number: $k_{0}^{\prime}=x \cdot \alpha_{0}+\alpha_{1}$, where $\left|\alpha_{1}\right| \leq x / 2$. Here, $x$ is an arbitrary positive integer and $\left|\alpha_{1}\right|$ is 1 -bit smaller. Then, for $i=1, \ldots, m-1$, we have $x \cdot t_{i}^{\prime} \cdot \alpha_{0}-a_{i}^{\prime} \equiv k_{i}^{\prime}-\alpha_{1} \cdot t_{i}^{\prime} \bmod q$. The target vector becomes

$$
\boldsymbol{v}= \pm\left(k_{1}^{\prime}-\alpha_{1} \cdot t_{1}^{\prime}, \ldots, k_{m-1}^{\prime}-\alpha_{1} \cdot t_{m-1}^{\prime}, y \cdot \alpha_{0},-\tau\right)
$$

If an integer random variable $k$ is uniformly distributed over $[-w, w)$, then we have $\mathbb{E}\left[k^{2}\right]=k^{2} / 3+1 / 6$. In order to control the norm of the new target vector, we need these samples $\left(t_{i}^{\prime}, a_{i}^{\prime}\right)$ to satisfy $\left|t_{i}^{\prime}\right|<q /\left(2^{l+4} x\right)$. This requirement leads to more samples, i.e., $2^{l+3} \cdot x$ times of the original sample size. Therefore, we
have

$$
\begin{aligned}
\mathbb{E}\left[\left(k_{i}^{\prime}-\alpha_{1} t_{i}^{\prime}\right)^{2}\right] & =\mathbb{E}\left[\left(k_{i}^{\prime}\right)^{2}\right]-2 \mathbb{E}\left[\alpha_{1}\right] \mathbb{E}\left[k_{i}^{\prime} t_{i}^{\prime}\right]+\mathbb{E}\left[\alpha_{1}^{2}\right] \mathbb{E}\left[\left(t_{i}^{\prime}\right)^{2}\right] \\
& =\frac{w^{2}}{3}+\frac{1}{6}+\left(\frac{x^{2}}{12}+\frac{1}{6}\right)\left(\frac{q^{2}}{3 \cdot 2^{2 l+8} \cdot x^{2}}+\frac{1}{6}\right) \\
& \approx \frac{w^{2}}{3}\left(1+\frac{1}{768}\right) \approx \frac{w^{2}}{3}
\end{aligned}
$$

Given that $\left|k_{0}^{\prime}\right|$ is bounded by $w$, we know that $\left|\alpha_{0}\right| \leq w / x$. Then we have

$$
\mathbb{E}\left[\|\boldsymbol{v}\|^{2}\right]=(m-1) \frac{w^{2}}{3}+y^{2} \frac{w^{2}}{3 x^{2}}+\tau^{2}
$$

Our goal is to minimize the ratio $\mathbb{E}\left[\|\boldsymbol{v}\|^{2}\right] / \mathrm{GH}^{2}(\mathcal{L})$, where

$$
\mathrm{GH}^{2}(\mathcal{L})=\frac{(m+1)}{2 \pi e} \cdot q^{\frac{2(m-1)}{m+1}} \cdot y^{\frac{2}{m+1}} \cdot \tau^{\frac{2}{m+1}}
$$

Given $x$, according to the AM-GM inequality, we have

$$
\begin{aligned}
\mathbb{E}\left[\|\boldsymbol{v}\|^{2}\right] & =\underbrace{\frac{w^{2}}{3}+\cdots+\frac{w^{2}}{3}}_{m-1}+y^{2} \frac{w^{2}}{3 x^{2}}+\tau^{2} \\
& \geq(m+1)\left(\left(\frac{w^{2}}{3}\right)^{m-1} \cdot y^{2} \frac{w^{2}}{3 x^{2}} \cdot \tau^{2}\right)^{1 /(m+1)} \\
& =(m+1)\left(\frac{w^{2}}{3}\right)^{m /(m+1)} \cdot x^{-\frac{2}{m+1}} \cdot y^{\frac{2}{m+1}} \cdot \tau^{\frac{2}{m+1}}
\end{aligned}
$$

Thus, $\mathbb{E}\left[\|\boldsymbol{v}\|^{2}\right] / \mathrm{GH}^{2}(\mathcal{L})$ attains its minimum value when $y=x$ and $\tau=w / \sqrt{3}$.
Reduction of Lattice Dimension. The new lattice construction can lead to a reduction in the lattice dimension, which is described in Theorem 2. This significantly improves the efficiency of lattice-based attacks, as the time complexity of sieving algorithms increases exponentially with an increase in the lattice dimension $d$.
Theorem 2. For any $x \in \mathbb{N}^{+}$, the reduction in lattice dimension is given by

$$
\frac{2 \log x}{2 l+3-\log (\pi e)} \approx \frac{\log x}{l}
$$

Proof. According to Assumption 1, the lattice dimension is the minimal integer $d$ satisfying $\mathbb{E}\left[\|\boldsymbol{v}\|^{2}\right] \leq 4 / 3 \cdot \mathrm{GH}^{2}(\mathcal{L})$. In Albrecht and Heninger's lattice [3], let $\tau=w / \sqrt{3}$, then we have

$$
\begin{array}{r}
\mathbb{E}\left[\|\boldsymbol{v}\|^{2}\right]=m\left(\frac{w^{2}}{3}+\frac{1}{6}\right)+\tau^{2} \approx d \cdot \frac{w^{2}}{3} \\
\mathrm{GH}^{2}(\mathcal{L})=\frac{d}{2 \pi e} \cdot q^{\frac{2(d-2)}{d}} \cdot\left(\frac{w^{2}}{3}\right)^{\frac{1}{d}}
\end{array}
$$

Substituting $w=q / 2^{l+1}$, and taking the logarithm, we have

$$
d \geq \frac{2 l+2+2 \log q+\log 3}{2 l+3-\log (\pi e)}
$$

In our lattice, $\mathbb{E}\left[\|\boldsymbol{v}\|^{2}\right]$ remains approximately the same, but $\operatorname{GH}^{2}(\mathcal{L})$ increases by a factor of $x^{2 / d}$. Thus, the new lattice dimension $d^{\prime}$ needs to satisfy

$$
d^{\prime} \geq \frac{2 l+2+2 \log q+\log 3-2 \log x}{2 l+3-\log (\pi e)}
$$

The reduction in lattice dimension is given by

$$
\frac{2 \log x}{2 l+3-\log (\pi e)} \approx \frac{\log x}{l} .
$$

Figure 1 illustrates the reduction of lattice dimension as $x$ increases. Four lines are plotted in this figure, representing $\operatorname{HNP}(160,1), \operatorname{HNP}(192,1), \operatorname{HNP}(224,1)$, and $\operatorname{HNP}(384,2)$, respectively. Solving these instances is believed to be impractical by previous lattice-based approaches [5,6,3,33,37]. However, our experimental results in Section 5 demonstrate the feasibility of solving $\operatorname{HNP}(160,1)$ by using a large $x$. More computational resources and samples are required for solving more difficult instances such as $\operatorname{HNP}(192,1)$.


Fig. 1: Lattice dimension and $x$.
Success Probability. Under Assumption 1, the sieving algorithm outputs all vectors satisfying $\|\boldsymbol{v}\|^{2} \leq 4 \mathrm{GH}^{2}(\mathcal{L}) / 3$. Consequently, the probability that the sieving algorithm can output the target vector is represented as $\operatorname{Pr}\left(\|\boldsymbol{v}\|^{2} \leq\right.$ $\left.\mathbb{E}\left[\|\boldsymbol{v}\|^{2}\right]\right)$, which is the success probability of our algorithm.

Theorem 3. For all $d \geq 3$, there exists a constant $c>0$ such that $\operatorname{Pr}\left(\|\boldsymbol{v}\|^{2} \leq\right.$ $\left.\mathbb{E}\left[\|\boldsymbol{v}\|^{2}\right]\right) \geq c$.

Proof. Recall the vector representation

$$
\begin{aligned}
\boldsymbol{v} & =\left(k_{1}^{\prime}-\alpha_{1} t_{1}^{\prime}, \ldots, k_{m-1}^{\prime}-\alpha_{1} t_{m-1}^{\prime}, x \alpha_{0},-w / \sqrt{3}\right) \\
& =\left(v_{0}, \ldots v_{d-3}, v_{d-2}, v_{d-1}\right) .
\end{aligned}
$$

For $k_{i}^{\prime}, t_{i}^{\prime}, \alpha_{0}$, and $\alpha_{1}$, they are all uniformly distributed: $k_{i}^{\prime}$ is over $[-w, w), t_{i}^{\prime}$ is over $[-w /(8 x), w /(8 x)), \alpha_{0}$ is over $[-w / x, w / x)$, and $\alpha_{1}$ is over $[-x / 2, x / 2)$. It follows that $v_{0}, \ldots, v_{d-3}$ are independent and identically distributed.

Let $\mathbb{P}_{d}=\operatorname{Pr}\left(\frac{1}{d-2} \sum_{i=0}^{d-3} v_{i}^{2} \leq \mathbb{E}\left[v_{0}^{2}\right]\right)$. Then we have

$$
\begin{aligned}
\operatorname{Pr}\left(\|\boldsymbol{v}\|^{2} \leq \mathbb{E}\left[\|\boldsymbol{v}\|^{2}\right]\right) & =\operatorname{Pr}\left(\sum_{i=0}^{d-3} v_{i}^{2}+x^{2} \alpha_{0}^{2} \leq(d-2) \mathbb{E}\left[v_{0}^{2}\right]+\frac{w^{2}}{3}\right) \\
& \geq \operatorname{Pr}\left(\sum_{i=0}^{d-3} v_{i}^{2} \leq(d-2) \mathbb{E}\left[v_{0}^{2}\right]\right) \cdot \operatorname{Pr}\left(x^{2} \alpha_{0}^{2} \leq \frac{w^{2}}{3}\right) \\
& =\frac{\sqrt{3}}{3} \operatorname{Pr}\left(\frac{1}{d-2} \sum_{i=0}^{d-3} v_{i}^{2} \leq \mathbb{E}\left[v_{0}^{2}\right]\right)=\frac{\sqrt{3}}{3} \mathbb{P}_{d} .
\end{aligned}
$$

Since $\operatorname{Var}\left[v_{0}^{2}\right]<+\infty$, by the Central Limit Theorem, it holds that

$$
\lim _{d \rightarrow+\infty} \operatorname{Pr}\left(\frac{1}{d-2} \sum_{i=0}^{d-3} v_{i}^{2} \leq \mathbb{E}\left[v_{0}^{2}\right]\right)=\frac{1}{2} .
$$

Hence, there exists a positive constant $c_{1}>0$ such that $\mathbb{P}_{d} \geq c_{1}$ for any $d \geq 3$. Let $c=c_{1} / \sqrt{3}$. Finally, we get

$$
\operatorname{Pr}\left(\|\boldsymbol{v}\|^{2} \leq \mathbb{E}\left[\|\boldsymbol{v}\|^{2}\right]\right) \geq \frac{\sqrt{3}}{3} \mathbb{P}_{d} \geq c .
$$

### 3.2 Improved Linear Predicate

In Albrecht and Heninger's approach, they employ non-linear constraints as a predicate to determine the unique hidden number [3,4]. Their predicate initially checks whether the absolute value of the last element of the candidate vector is $\tau$. Subsequently, it determines the target vector by checking whether $r$ is equal to $([k] G)_{x}$, where $G$ is the generator point on the curve, $r$ is a specific signature, and $k$ is the corresponding nonce that can be computed from the candidate vector. The predicate involves time-consuming scalar multiplication on the curve.

In this section, we propose an improved linear predicate that utilizes linear constraints from $2 \log q$ HNP samples. Moreover, we present a modified version of the Sieve-Pred algorithm to integrate our predicate, and achieve higher efficiency.

Linear Predicate. Our linear predicate is described in Algorithm 2. It operates on a 2 -dimensional vector $\boldsymbol{v}=\left(v_{0}, v_{1}\right)$, representing the last two elements
of a candidate vector in the database. This predicate determines whether the candidate vector satisfies a set of linear conditions. If these conditions are met, the predicate reveals the hidden number; otherwise, it returns $\perp$. The algorithm follows these steps:
(1) Check if $0<\left|v_{0}\right| \leq w$ and whether $\left|v_{1}\right|$ equals $\pm \tau$. If this condition is met, proceed to the next step; otherwise, return $\perp$.
(2) Calculate the candidate $\alpha^{\prime}$ from $\boldsymbol{v}$ and the HNP sample $\left(t_{0}, a_{0}\right)$.
(3) For $N$ HNP samples $\left(t_{i}, a_{i}\right)$, check whether $\left|t_{i} \cdot \alpha^{\prime}-a_{i}\right|_{q}<q / 2^{l}$ for $i=$ $0, \ldots, N-1$. If this condition holds, return the candidate $\alpha^{\prime}$ as the correct hidden number; otherwise, return $\perp$.

According to the definition of HNP, the correct candidate $\alpha^{\prime}$ should satisfy all these constraints in the last step of the algorithm. However, for an incorrect candidate, there still exists a small chance of meeting all the constraints. The probability is computed as follows. Assume that $\left|t_{i} \cdot \alpha^{\prime}-a_{i}\right|_{q}$ is uniformly distributed in $[0, q-1]$. Then for $i=0,1, \ldots, N-1$, we have

$$
\operatorname{Pr}\left(\left|t_{i} \cdot \alpha^{\prime}-a_{i}\right|_{q}<q / 2^{l}\right)=2^{-l}
$$

Let $N=2 \log q$. Then an incorrect candidate $\alpha^{\prime}$ satisfies all the constraints with probability $2^{-2 l \log q}=q^{-2 l}$. Since there are $q-1$ incorrect candidate $\alpha^{\prime}$, the probability that the algorithm can find the candidate in the interval $[0, q-1]$ is given by

$$
\left(1-q^{-2 l}\right)^{q-1} \geq 1-(q-1) q^{-2 l} \geq 1-\frac{q-1}{q^{2}}=1-\operatorname{negl}(\log q)
$$

Thus, the predicate has an overwhelming success probability.

```
Algorithm 2: Improved Linear Predicate
    Input: A 2-dimensional vector \(\boldsymbol{v}=\left(v_{0}, v_{1}\right)\), modulus \(q\), number of nonce
            leakage \(l\), embedding number \(\tau, N=2 \log q\) HNP samples \(\left(t_{i}, a_{i}\right)\)
    Output: The hidden number \(\alpha\) or \(\perp\)
    if \(v_{0}=0\) or \(\left|v_{0}\right|>q / 2^{l+1}\) or \(\left|v_{1}\right| \neq \tau\) then
        return \(\perp\);
    \(k_{0} \leftarrow-\operatorname{sign}\left(v_{1}\right) \cdot v_{0}+q / 2^{l+1} ;\)
    \(\alpha^{\prime} \leftarrow t_{0}^{-1} \cdot\left(a_{0}+k_{0}\right) \bmod q ;\)
    for \(i=0\) to \(N-1\) do
        if \(\left|t_{i} \cdot \alpha^{\prime}-a_{i}\right|_{q} \geq q / 2^{l}\) then
            return \(\perp\);
    return \(\alpha^{\prime}\);
```

In [37], Xu et al. also introduced a linear predicate. However, the key difference is that their predicate requires the entire $d$-dimensional vector. In the
sieving implementation G6K [2], the vectors in the output database are represented as coordinates under the lattice basis. To obtain all positions of the candidate vector, one needs to perform $d$ vector inner products, i.e., multiply the $d$-dimensional coordinate vector by the $d \times d$ lattice basis matrix. While our predicate only involves two vector inner products, which provides a significant efficiency advantage in practice.

Another modification is that we utilize linear constraints from new HNP samples, instead of samples used in lattice construction. The reason is that the vector $\boldsymbol{v}$ in sieving database is inherently shorter. If we use the HNP samples $\left(t_{i}, a_{i}\right)$ that construct the lattice, the probability $\operatorname{Pr}\left(\left|t_{i} \cdot \alpha^{\prime}-a_{i}\right|<q / 2^{l+1}\right.$ ) (which is equal to $\left.\operatorname{Pr}\left(\left|v_{i}\right|<q / 2^{l+1}\right)\right)$ will be higher. So more linear constraints need to be verified to identify a false candidate. With new HNP samples, the expected number of verifying operations for each candidate can be calculated: if we assume that there are $M$ candidates, then the expected number of candidates meeting the first constraint is $M / 2^{l}$, the expected number of candidates meeting the second constraint is $M / 2^{2 l}$, and so on. Thus, the total expected number of verifying operations needed for $M$ candidates is

$$
M+\frac{M}{2^{l}}+\frac{M}{2^{2 l}}+\cdots=\frac{M}{1-2^{-l}} .
$$

Therefore, on average, only $1 /\left(1-2^{-l}\right)$ verifying operations are needed for each candidate, and the parameter $2 \log q$ does not affect the efficiency of our predicate.

As we have made modifications to both the input and output of the predicate, a modified version of the Sieve-Pred algorithm is proposed to ensure compatibility with the new predicate. The algorithm is outlined in Algorithm 3. It no longer takes the entire lattice vector as input but only the last two elements. Moreover, the algorithm immediately outputs the solution when our linear predicate returns true, instead of searching the entire database.

```
Algorithm 3: Modified Sieving with Predicate
    Input: Lattice \(\mathcal{L}(\boldsymbol{B})\) with dimension \(d\), predicate \(f(\cdot)\)
    Output: The hidden number \(\alpha\) or \(\perp\)
    Run the sieving algorithm on \(\mathcal{L}(\boldsymbol{B})\) and output list \(L\);
    for \(\boldsymbol{v} \in L\) do
        \(\alpha \leftarrow f\left(v_{d-2}, v_{d-1}\right) ;\)
        if \(\alpha \neq \perp\) then
            return \(\alpha\);
    return \(\perp\);
```


### 3.3 Predicate for Decomposition Technique

In Section 3.1, the transformed hidden number $k_{0}^{\prime}$ is decomposed as $\alpha_{0} x+$ $\alpha_{1}$ where $\left|\alpha_{1}\right| \leq x / 2$, and the target vector is $\boldsymbol{v}= \pm\left(k_{1}^{\prime}-\alpha_{1} t_{1}^{\prime}, \ldots, k_{m-1}^{\prime}-\right.$ $\left.\alpha_{1} t_{m-1}^{\prime}, x \alpha_{0},-\tau\right)$. This vector contains information about $\alpha_{0}$, which is a part
of $k_{0}^{\prime}$. However, due to the absence of information about $\alpha_{1}$, it is impossible to directly compute the entire $k_{0}^{\prime}$. Consequently, previous predicates are ineffective in this scenario [3,37].

The straightforward approach to recover $k_{0}^{\prime}$ is to perform an exhaustive search over all possible values of $\alpha_{1}$, which has time complexity $O(x)$. For each candidate value of $\alpha_{0}$, we need to check the predicate for $x$ candidate values of the hidden number. An exhaustive search will result in a substantial time overhead and becomes impractical when $x$ is large. To address this issue, we introduce an interval reduction algorithm that reduces the complexity from $O(x)$ to $O\left(\log ^{2} x\right)$. Based on this algorithm, a predicate for the decomposition technique is also proposed.

There are two necessary notations. Assume that $R$ is the union of a set of intervals. Let $|R|$ be the number of intervals in $R$, and $\|R\|$ be the number of integers within the intervals in $R$. For example, if $R=\{[1,4]\}$, then $|R|=1$ which means that there is one interval in $R$, and $\|R\|=4$ which means that there are four integers within the interval $[1,4]$.

Interval Reduction Algorithm. The interval reduction algorithm takes an interval of length $M$ and $\log M$ transformed HNP samples as input, and produces a set of smaller intervals as output. We denote the input interval as [low, high], where $M=$ high - low +1 . Let $R$ be the set of intervals output by this algorithm. The interval reduction algorithm guarantee that if the hidden number is in the input interval [low, high], then the hidden number must be in one interval of $R$. This algorithm is described in Algorithm 4, and it contains two steps as follows.

```
Algorithm 4: Interval Reduction Algorithm
    Input: interval [low, high] that may contain the hidden number \(k_{0}^{\prime}\),
            modulus \(q\), parameter \(l, N=\log M\) transformed samples \(\left(t_{i}^{\prime}, a_{i}^{\prime}\right)\)
            satisfying \(t_{i}^{\prime}=O(q / M)\)
    Output: set \(R\) of intervals that may contain \(k_{0}^{\prime}\)
    \(R \leftarrow\{[\) low, high \(]\} ;\)
    for \(i=0\) to \(N-1\) do
        Generate a new interval set \(R_{\text {new }}\) based on \(i\)-th sample \(\left(t_{i}^{\prime}, a_{i}^{\prime}\right)\);
        \(R \leftarrow\) IntervalSetIntersection \(\left(R, R_{\text {new }}\right)\);
    return R ;
```

Firstly, we generate the intervals based on $\log M$ transformed samples $\left(t_{i}^{\prime}, a_{i}^{\prime}\right)$. These intervals are computed using the HNP equations and the interval [low, high]. It holds that

$$
t_{i}^{\prime} \cdot \text { low } \leq t_{i}^{\prime} k_{0}^{\prime}=a_{i}^{\prime}+k_{i}^{\prime}+n q \leq t_{i}^{\prime} \cdot \text { high }
$$

for $i=1, \ldots, \log M$. Since $-w \leq k_{i}^{\prime} \leq w-1$, we get a set $\mathcal{S}$ that contains all possible values of $n$. For a specific $n_{1}$ in $\mathcal{S}$, we have

$$
t_{i}^{\prime} k_{0}^{\prime}=a_{i}^{\prime}+k_{i}^{\prime}+n_{1} q \in\left[a_{i}^{\prime}+n_{1} q-w, a_{i}^{\prime}+n_{1} q+w-1\right]
$$

Therefore,

$$
t_{i}^{\prime} k_{0}^{\prime} \in \bigcup_{n \in \mathcal{S}}\left[a_{i}^{\prime}+n q-w, a_{i}^{\prime}+n q+w-1\right]
$$

This process yields a set of intervals that are sorted in ascending order, and one of these intervals may contain $k_{0}^{\prime}$. To limit the number of intervals in this set, we require that $t_{i}^{\prime}=O(q / M)$. For the rationale of this requirement, the reader is referred to the proof of Theorem 4.

Secondly, we intersect all the sets of intervals generated from the $\log M$ samples. For this operation, we present an interval set intersection algorithm in Algorithm 5. It takes two sets of intervals that are in ascending order as input and outputs their intersection. The time complexity of Algorithm 5 is $O(m+n)$, where $m$ and $n$ are the numbers of intervals in two sets respectively.
Predicate for decomposition technique. Our predicate for the decomposition technique is described in Algorithm 6. Firstly, this algorithm verifies whether $\left|v_{0}\right|<q / 2^{l+1}$ and whether $\left|v_{1}\right|$ equals $\pm \tau$. Secondly, it computes the interval [low, high] that may contain $k_{0}^{\prime}$. Thirdly, the interval reduction algorithm is employed to generate a set $R$. Finally, an exhaustive search is carried out to check the linear predicate for each integer in the intervals of $R$. The expected time complexity of this algorithm is $O\left(\log ^{2} x\right)$, as shown in Theorem 4.

```
Algorithm 5: Interval Set Intersection Algorithm
    Input: Two sets of intervals in ascending order: \(A, B\)
    Output: Intersection of \(A\) and \(B\)
    \(i, j \leftarrow 0\);
    \(R \leftarrow\} ;\)
    while \(i<|A|\) and \(j<|B|\) do
        Let \(\left[a_{0}, a_{1}\right]\) and \(\left[b_{0}, b_{1}\right]\) be the \(i\)-th and \(j\)-th intervals in A and B ,
        respectively;
        if \(a_{1}<b_{0}\) then
            \(i \leftarrow i+1 ;\)
            Continue;
        if \(b_{1}<a_{0}\) then
            \(j \leftarrow j+1 ;\)
            Continue;
        if \(a_{1} \geq b_{1}\) then
            \(j \leftarrow j+1 ;\)
            Add the interval \(\left[\max \left(a_{0}, b_{0}\right), b_{1}\right]\) to \(R\);
            Continue;
        \(i \leftarrow i+1 ;\)
        Add the interval \(\left[\max \left(a_{0}, b_{0}\right), a_{1}\right]\) to \(R\);
    return \(R\);
```

Theorem 4. The expected time complexity of Algorithm 6 is $O\left(\log ^{2} x\right)$.
Proof. There are two parts in Algorithm 6. The first part is the interval reduction algorithm, and the second part is an exhaustive search.

```
Algorithm 6: Predicate for Decomposition Technique
    Input: A 2-dimensional vector \(\boldsymbol{v}=\left(v_{0}, v_{1}\right)\), modulus \(q\), number of nonce
                leakage \(l\), embedding number \(\tau\), predicate \(f(\cdot)\)
    Output: hidden number \(\alpha\) or \(\perp\)
    if \(v_{0}=0\) or \(\left|v_{0}\right|>q / 2^{l+1}\) or \(\left|v_{1}\right| \neq \tau\) then
        return \(\perp\);
    low \(\leftarrow-\operatorname{sign}\left(v_{1}\right) \cdot v_{0}-x / 2, \operatorname{high} \leftarrow-\operatorname{sign}\left(v_{1}\right) \cdot v_{0}+x / 2\);
    \(R \leftarrow\) IntervalReduction([low, high]);
    for \([a, b] \in R\) do
        for \(h=a\) to \(b\) do
            \(\alpha \leftarrow f(h,-\tau) ;\)
            if \(\alpha \neq \perp\) then
                    return \(\alpha\);
    return \(\perp\);
```

(1) Let us study the time complexity of the first part. We need to bound $\left|R_{\text {new }}\right|$, where $R_{\text {new }}$ is given in Algorithm 4. For any transformed sample ( $t_{i}^{\prime}, a_{i}^{\prime}$ ), we have both $n q+a_{i}^{\prime}+w-1 \geq t_{i}^{\prime}$. low and $n q+a_{i}^{\prime}-w \leq t_{i}^{\prime} \cdot$ high. Hence, the number of possible values of $n$ is not bigger than

$$
\frac{t_{i}^{\prime} \cdot(\text { high }- \text { low })+2 w-1}{q}+1=\frac{t_{i}^{\prime} \cdot x-t_{i}^{\prime}+2 w-1}{q}+1 .
$$

Since $t_{i}^{\prime}=O(q / x)$, there exists a constant $C$ such that $\left|R_{\text {new }}\right| \leq C$.
For $i=0,1, \ldots, N-1$, let $R_{i}$ be the set returned by the interval set intersection algorithm in Algorithm 4 just after $i$-th sample. Then we have $\left|R_{i}\right| \leq$ $(i+1) C$. Thus, for any $0 \leq i \leq N-1$, the time complexity of $i$-th step in Algorithm 4 is at most $O((i+2) C)$. It follows that the time complexity of the first part is $O\left(N^{2}\right)=O\left(\log ^{2} x\right)$.
(2) For the time complexity of the second part, let $R_{-1}=[$ low, high $]$. Then $\left\|R_{-1}\right\|=x$. For an incorrect hidden number candidate, the probability that this candidate satisfies the constraint given by each HNP sample is only $1 / 2^{l}$. Thus, for $0 \leq i \leq N-1$, we have

$$
\frac{\mathbb{E}\left(\left\|R_{i}\right\|\right)}{\mathbb{E}\left(\left\|R_{i-1}\right\|\right)}=\frac{1}{2^{l}}
$$

Finally, we get

$$
\mathbb{E}\left(\left\|R_{N-1}\right\|\right)=\mathbb{E}\left(\left\|R_{-1}\right\|\right) \cdot\left(\frac{1}{2^{l}}\right)^{N} \leq \frac{x}{2^{N}}=1
$$

Therefore, the expected time complexity of the second step is $O(1)$.
By (1) and (2), the expected time complexity of Algorithm 6 is $O\left(\log ^{2} x\right)$.
Pre-screening Technique. Before the interval reduction algorithm in Algorithm 6, we could use a pre-screening technique to eliminate the majority of
incorrect candidates. This technique involves only some linear operations, and can enhance the efficiency of Algorithm 6 notably.

The pre-screening technique makes use of a small number of transformed HNP samples $\left(t_{i}^{\prime}, a_{i}^{\prime}\right)$, where $\left|t_{i}^{\prime}\right| \leq q /\left(2^{l+3} x\right)$. For an incorrect candidate $\alpha_{0}^{\prime}$, it will be rejected if the following condition is satisfied:

$$
\left|\left|x \cdot t_{i}^{\prime} \cdot \alpha_{0}^{\prime}-a_{i}^{\prime}+q / 2\right|_{q}-q / 2\right|>w+q / 2^{l+4}
$$

Let us explain the reason. For any correct candidate $\alpha_{0}$, we have $x \cdot t_{i}^{\prime} \alpha_{0}-a_{i}^{\prime} \equiv$ $k_{i}^{\prime}-\alpha_{1} t_{i}^{\prime} \bmod q$. Therefore, we get

$$
\left|k_{i}^{\prime}-\alpha_{1} t_{i}^{\prime}\right| \leq\left|k_{i}^{\prime}\right|+\left|\alpha_{1}\right| \cdot\left|t_{i}^{\prime}\right| \leq w+\frac{x}{2} \cdot \frac{q}{2^{l+3} x}=w+\frac{q}{2^{l+4}} .
$$

Note that this technique does not increase the sampling cost, as we can use the samples that satisfy $q /\left(2^{l+4} x\right) \leq\left|t_{i}^{\prime}\right| \leq q /\left(2^{l+3} x\right)$ for pre-screening. These samples are already available during the pre-selection of the samples used to construct the new lattice in Section 3.1.

To illustrate the efficiency improvements brought by the interval reduction algorithm and pre-screening technique, we conduct experiments on $\operatorname{HNP}(256,2)$ with $x=2^{15}$. The experimental data demonstrates that, compared with the exhaustive search, the interval reduction algorithm provides a 2590 -fold speedup. Furthermore, when combined with the pre-screening technique, we could get a 3895 -fold speedup.

## 4 Hidden Number Problem with Erroneous Input

In practical side-channel attacks, errors often appear in the data. This means that attackers may obtain incorrect nonces, resulting in erroneous HNP samples. Lattice-based attacks are believed to perform poorly when dealing with erroneous input [30,6]. A common strategy to tackle this issue is to run the HNP solver on subsets of the samples until a correct solution is found [21]. However, this method does not fundamentally improve the lattice's ability to handle errors. Consequently, some works assume that the input is error-free [21,33,37]. In [3], Albrecht and Heninger discussed the solution for handling errors, but did not provide a detailed analysis. With the increase of error rate, the dimension of their lattice would increase rapidly. The restricted efficiency of their nonlinear predicate would result in a high cost for searching the sieving database, thereby constraining the ability to handle erroreous HNP instances. On the other hand, Fourier analysis-based attacks demonstrated stronger robustness to errors [13,5,6], highlighting a gap between these two approaches.

In this section, we define HNP with erroneous input based on the ECDSA nonce leakage model. The effectiveness of our new lattice construction in solving this problem is demonstrated through theoretical analysis. An estimation for the minimum lattice dimension is also provided. Furthermore, we extend our algorithms in Section 3, and significantly enhance the lattice's ability to handle errors. This narrows the gap between lattice-based attacks and Fourier analysisbased attacks.

### 4.1 Theoretical Analysis

Definition 5 (Hidden Number Problem with Erroneous Input). Given a modulus $q$, an error rate $0<p<1 / 2$, and both the hidden number $\alpha$ and the coefficients $t_{i}$ being random numbers in $\mathbb{Z}_{q}$, the elements $a_{i}$ satisfy the condition that with probability $1-p,\left|t_{i} \alpha-a_{i}\right|_{q}<q / 2^{l}$, while with probability $p,\left|t_{i} \alpha-a_{i}\right|_{q}$ is a random number in $\mathbb{Z}_{q}$. The problem is to recover the hidden number $\alpha$ when $m$ samples $\left(t_{i}, a_{i}\right)$ are given.

Let us show the rationality of this definition in more details. In the ECDSA signature, let $k=2^{l} k_{m s b}+k_{l s b}$, where $0 \leq k_{m s b}<q / 2^{l}$, and $0 \leq k_{l s b}<2^{l}$. Then we have

$$
2^{-l}\left(k_{l s b}-s^{-1} \cdot h\right)+k_{m s b} \equiv 2^{-l} s^{-1} r \cdot s k \quad \bmod q .
$$

Assume that we have probability $1-p$ to obtain the correct value of $k_{l s b}$, and probability $p$ to obtain a random integer $k_{l s b}^{\prime}$ in $\left[0,2^{l}-1\right]$.

Let $\alpha=s k, a_{i}=\left|2^{-l}\left(k_{l s b}-s^{-1} \cdot h(m)\right)\right|_{q}, k_{i}=k_{m s b}$, and $t_{i}=\left|2^{-l} s^{-1} r\right|_{q}$. If we obtain a random integer $k_{l s b}^{\prime}$, then $a_{i}=\left|2^{-l}\left(k_{l s b}^{\prime}-s^{-1} \cdot h\right)\right|_{q}$, and we have

$$
\left|t_{i} \alpha-a_{i}\right|_{q}=\left|k_{m s b}+2^{-l}\left(k_{l s b}-k_{l s b}^{\prime}\right)\right|_{q}=\left|2^{-l}\left(k-k_{l s b}^{\prime}\right)\right|_{q} .
$$

Since $k$ is randomly chosen from $\mathbb{Z}_{q}$ and $q$ is a prime number, $\left|2^{-l}\left(k-k_{l s b}^{\prime}\right)\right|_{q}$ is also a random number in $\mathbb{Z}_{q}$. Thus, we obtain a HNP instance with erroneous input.

New Minimum Lattice Dimension. In this section, the lattice constructed by us is the same as that in Section 3.1:

$$
\left[\begin{array}{cccccc}
q & 0 & \cdots & 0 & 0 & 0 \\
0 & q & \cdots & 0 & 0 & 0 \\
\vdots & \vdots & & \vdots & \vdots & \vdots \\
0 & 0 & \cdots & q & 0 & 0 \\
x \cdot t_{1}^{\prime} & x \cdot t_{2}^{\prime} & \cdots & x \cdot t_{m-1}^{\prime} & x & 0 \\
a_{1}^{\prime} & a_{2}^{\prime} & \cdots & a_{m-1}^{\prime} & 0 & \tau
\end{array}\right] .
$$

The target vector is $\boldsymbol{v}= \pm\left(k_{1}^{\prime}-\alpha_{1} t_{1}^{\prime}, \ldots, k_{m-1}^{\prime}-\alpha_{1} t_{m-1}^{\prime}, x \alpha_{0}, \tau\right)$. From the definition above, for $i=0, \ldots, m-1, k_{i}$ is randomly distributed in $[0, q)$ with probability $p$. Thus, $x \alpha_{0} \equiv k_{0}^{\prime}-\alpha_{1} \equiv k_{0}-w-\alpha_{1}$ and $k_{i}^{\prime}-\alpha_{1} t_{i}^{\prime} \equiv k_{i}-w-\alpha_{1} t_{i}^{\prime}$ also have probability $p$ of being randomly distributed in $[-q / 2, q / 2)$. So we have

$$
\begin{aligned}
\mathbb{E}\left[\|\boldsymbol{v}\|^{2}\right] & =(d-1)(1-p) \frac{w^{2}}{3}+(d-1) \frac{p q^{2}}{12}+\tau^{2} \\
& =(d-1) \frac{w^{2}}{3}\left(1+p\left(2^{2 l}-1\right)\right)+\tau^{2}
\end{aligned}
$$

Similar to the analysis in Section 3.1, when $\tau^{2}=w^{2}\left(1+p\left(2^{2 l}-1\right)\right) / 3$, the ratio $\mathbb{E}\left[\|\boldsymbol{v}\|^{2}\right] / \mathrm{GH}^{2}(\mathcal{L})$ obtains its minimum. Substituting this into $\mathbb{E}\left[\|\boldsymbol{v}\|^{2}\right] \leq$ $4 \mathrm{GH}^{2}(\mathcal{L}) / 3$, we get

$$
d \geq \frac{2 l+2+2 \log q+\log 3-2 \log x-\log \left(1+p \cdot\left(2^{2 l}-1\right)\right)}{2 l+3-\log (\pi e)-\log \left(1+p \cdot\left(2^{2 l}-1\right)\right)}
$$

The reduction of dimension is $2 \log x /\left(2 l+3-\log \pi e-\log \left(1+p \cdot\left(2^{2 l}-1\right)\right)\right)$, which is more than $\log x / l$. This discovery reveals that the new lattice construction can achieve a greater reduction (compared to Albrecht and Heninger's lattice) in lattice dimension in the presence of erroneous samples compared to error-free samples.

From a different perspective, the parameter $x$ can be viewed as a balance to the error rate $p$. Given the lattice dimension $d, p$ amplifies the target vector's squared magnitude by $1+p\left(2^{2 l}-1\right)$, while $x$ amplifies $\mathrm{GH}^{2}(\mathcal{L})$ by $x^{2 / d}$. To maintain this ratio, we can set $1+p\left(2^{2 l}-1\right)=x^{2 / d}$, which leads to $x=(1+$ $\left.p\left(2^{2 l}-1\right)\right)^{d / 2}$. Thus, for a higher error rate, we can increase $x$ to keep the lattice dimension unchanged.

### 4.2 Modified Algorithms

Linear Predicate for Erroneous Input. Using the linear predicate in Section 3.2 , we compute $\left|t_{i} \alpha^{\prime}-a_{i}\right|_{q}$ for each sample $\left(t_{i}, a_{i}\right)$. If this value is in $\left[0, q / 2^{l}\right)$, then $\alpha^{\prime}$ passes the test; otherwise, it fails.

For error-free samples, if a single test fails, the hidden number candidate is incorrect. However, if there are potential errors in the samples, this is not true. To address this problem, we test samples using the hidden number candidate $\alpha^{\prime}$, and count the number of samples that pass the test. Table 2 lists the passing probability for error-free and erroneous samples. We denote the probability of passing a single sample as $p_{1}$ when $\alpha^{\prime}=\alpha$, and as $p_{2}$ when $\alpha^{\prime} \neq \alpha$. Then $p_{1}=1-p+p \cdot 2^{-l}, p_{2}=2^{-l}$, and $p_{1}>p_{2}$.

Table 2: Passing probability for error-free and erroneous samples

|  | Error-free sample | Erroneous sample |
| :---: | :---: | :---: |
| $\alpha^{\prime}=\alpha$ | 1 | $2^{-l}$ |
| $\alpha^{\prime} \neq \alpha$ | $2^{-l}$ | $2^{-l}$ |

We collect $N=2 \log q$ samples, and calculate the number $M$ of samples that $\alpha^{\prime}$ passes. If $M>N\left(p_{1}+p_{2}\right) / 2, \alpha^{\prime}$ is believed to be the correct hidden number $\alpha$. Otherwise, we discard it. This procedure is detailed in Algorithm 7.

Theorem 5. Algorithm 7 has overwhelming success probability $1-\operatorname{negl}(\log q)$.
Proof. Let $P_{1}$ be the probability that Algorithm 7 rejects a correct hidden number, and $P_{2}$ be the probability that Algorithm 7 accepts an incorrect candidate. We prove both $P_{1}$ and $P_{2}$ are negligible. Define

$$
X_{i}= \begin{cases}1, & \text { if } \alpha^{\prime} \text { passes the } i \text {-th sample } \\ 0, & \text { if } \alpha^{\prime} \text { fails the } i \text {-th sample }\end{cases}
$$

```
Algorithm 7: Predicate for erroneous input
    Input: A 2-dimensional vector \(\boldsymbol{v}=\left(v_{0}, v_{1}\right)\), modulus \(q\), number of nonce
                leakage \(l\), embedding number \(\tau, N=2 \log q\) erroneous samples \(\left(t_{i}, a_{i}\right)\)
    Output: The hidden number \(\alpha\) or \(\perp\)
    if \(v_{0}=0\) or \(v_{0}>q / 2^{l+1}\) or \(\left|v_{1}\right| \neq \tau\) then
        return 0 ;
    \(k_{0} \leftarrow-\operatorname{sign}\left(v_{1}\right) v_{0}+q / 2^{l+1} ;\)
    \(\alpha^{\prime} \leftarrow t_{0}^{-1}\left(a_{0}+k_{0}\right) \bmod q ;\)
    \(M \leftarrow 0 ;\)
    for \(i=0\) to \(N-1\) do
        if \(\left|t_{i} \alpha^{\prime}-a_{i}\right|_{q}<q / 2^{l}\) then
            \(M \leftarrow M+1 ;\)
    if \(M>N\left(1-p+(1+p) 2^{-l}\right) / 2\) then
        return \(\alpha^{\prime}\);
    else
        return \(\perp\);
```

When $\alpha^{\prime}=\alpha, X_{i}$ follows the Bernoulli distribution with probability $p_{1}$, and when $\alpha^{\prime} \neq \alpha, X_{i}$ follows the Bernoulli distribution with probability $p_{2}$. Let $S_{N}=\sum_{i=1}^{N} X_{i}$.

For the case of $P_{1}$, let $\mu_{1}$ be the expected value of $S_{N}$. Then $\mu_{1}=p_{1} N$. Let $\delta_{1}=\left(p_{1}-p_{2}\right) /\left(2 p_{1}\right) \geq 1 /\left(8 p_{1}\right)$. By the Chernoff inequality, we have

$$
P_{1}=\operatorname{Pr}\left(S_{N} \leq \frac{N\left(p_{1}+p_{2}\right)}{2}\right)<e^{-\mu_{1} \frac{\delta_{1}^{2}}{2}} \leq e^{-\frac{p_{1} N}{128 p_{1}^{2}}} \leq e^{-\frac{\log q}{64}} .
$$

For the case of $P_{2}$, let $\mu_{2}$ be the expected value of $S_{N}$. Then $\mu_{2}=p_{2} N$. Let $\delta_{2}=\left(p_{1}-p_{2}\right) /\left(2 p_{2}\right)=(1-p)\left(2^{l}-1\right) / 2 \geq 2^{l-3}$. By the Chernoff inequality, we have

$$
P_{2}=\operatorname{Pr}\left(S_{N}>\frac{N\left(p_{1}+p_{2}\right)}{2}\right)<e^{-\mu_{2} \frac{\delta_{2}^{2}}{2}} \leq e^{-p_{2} N \frac{2^{2 l-6}}{2}} \leq e^{-2^{l-6} \log q} \leq e^{-\frac{\log q}{32}} .
$$

Pre-screening Technique for Erroneous Input. The idea above can also be applied to extend the pre-screening technique. To achieve efficient screening, we use $\log q$ samples that satisfy $\left|t_{i}^{\prime}\right|<q /\left(2^{l+3} x\right)$. For each sample $\left(t_{i}^{\prime}, a_{i}^{\prime}\right)$, we compute $\left|\left|x t_{i}^{\prime} \alpha_{0}-a_{i}^{\prime}+q / 2\right|_{q}-q / 2\right|$. A sample $\left(t_{i}, a_{i}\right)$ is called non-compliant if $\left|\left|x t_{i}^{\prime} \alpha_{0}-a_{i}^{\prime}+q / 2\right|_{q}-q / 2\right|>w+q / 2^{l+4}$.

During the pre-screening, we cannot make any decision based only on a single non-compliant sample. Our strategy is to collect a set of samples, and make the decision when the number of non-compliant samples reaches a certain threshold. Different from Algorithm 7, the goal of pre-screening is to retain the correct hidden numbers, rather than to eliminate all incorrect candidates. The number of
erroneous samples is at most $3 p \log q$ with overwhelming probability. If more than $3 p \log q$ samples are non-compliant, the hidden number candidate is removed.

Sub-sampling Technique. In Section 3.3, we introduce an interval reduction algorithm for lattices constructed from the decomposition technique. This algorithm can efficiently perform an exhaustive search over an interval. However, it requires error-free samples. Otherwise, it may exclude correct hidden number. To overcome this limitation, we propose a sub-sampling technique. The specific steps are as follows.
(1) Select $3 \log x / 2$ samples to form a pool.
(2) Draw $\log x$ samples from this pool, and apply Algorithm 6 to the candidate $\alpha_{0}^{\prime}$, but replace the linear predicate in Algorithm 6 with the predicate for erroneous input in Algorithm 7. Return upon success.
(3) Repeat the second step for $\gamma$ times. If the hidden number is not found, the candidate is rejected.

Let $P_{1}$ be the probability that this algorithm rejects a correct hidden number candidate, and $P_{2}$ be the probability that this algorithm accepts an incorrect hidden number candidate. For any correct hidden number $\alpha$, it has probability $p_{1}=1-p+p \cdot 2^{-l}$ to pass a single sample. Hence, the second step has probability $p_{1}^{\log x}$ to return $\alpha$. Therefore, $P_{1}=\left(1-p_{1}^{\log x}\right)^{\gamma}$. For any incorrect hidden number $\alpha$, if $\alpha$ is returned, $\alpha$ must be returned by Algorithm 7. By Theorem 5, we have $P_{2}=\operatorname{negl}(\log q)$.

In practice, for given $p, x$ and $l$, we can adjust $\gamma$ to minimize $P_{1}$. For example, for the case of $p=0.02, x=2^{25}, l=1$, let $\gamma=10$, then we get $P_{1}<3 \times 10^{-7}$.

## 5 Key Recovery of ECDSA with Nonce Leakage

In this section, experimental results are provided to demonstrate the performance of our algorithms. Assume that the least significant bits of the nonce used for each signature are leaked. Our goal is to recover the secret signing key by solving the corresponding HNP instance. The experimental machine is equipped with two Intel Xeon Gold 6154 CPUs, 2TB memory, and three GeForce RTX 2080Ti GPUs.

Before applying Algorithm 3 to the lattice basis constructed from HNP samples, we preprocess the basis with BKZ-20, which can randomize the lattice basis and increase the success rate. In [3], Albrecht et al. used BKZ-(d-20) in their preprocessing step. However, the experimental results show that our preprocessing step is much more efficient and achieves a success rate close to [3]. Moreover, the integration of the progressive sieving technique plays a pivotal role in enhancing the quality of the basis $[24,14]$.

To introduce the strategy of our attack on instances of varying difficulty, we categorize ECDSA instances into three classes. Specifically, this classification relies on the minimum lattice dimension $d$ estimated via Albrecht and Heninger's lattice. These three classes are denoted as Easy ( $d \leq 100$ ), Medium ( $100<d \leq$
$140)$, and Hard ( $d>140$ ). In practical applications, we may adjust the parameter $x$. This allows us to obtain an optimal balance between time consumption and the number of available samples.

### 5.1 Compared with Other Lattice-based Attacks

Solving Easy Instances. Table 3a lists our attack results for several easy instances. These experiments are conducted with a single thread and G6K library [2]. For each instance, the average CPU-seconds and the success rate ( $\mathrm{s} / \mathrm{r}$ ) are calculated from 100 experiments. Figure 2 illustrates the efficiency comparison between our algorithm and recent works [3,33,37]. It is evident that our algorithm exhibits a significant efficiency advantage. For example, when dealing with ECDSA(384, 4), Albrecht and Heninger [3] successfully conducted an attack in 49200 seconds, and Xu et al. [37] improved the time to 11153 seconds, whereas we only require 5583 seconds. When targeting $\operatorname{ECDSA}(192,2)$, our attack also demonstrates a speedup of 31 times compared with the work by Albrecht and Heninger [3]. When $x=1$, the key difference between our work and other works $[3,37]$ lies in the predicate used in the attack. We substitute our predicate with those in [3] and [37] separately, and record the time of searching the database on the same machine. We denote the time taken by our predicate as $t_{1}$, and the time taken by the predicates in [3] and [37] as $t_{2}$ and $t_{3}$, respectively. The speed-up ratio brought by our predicate is shown in Figure 3.


Fig. 2: Comparison of CPU-seconds with previous works.

Table 3: Performance of our lattice-based attacks

| Curve | Leakage | $d$ | $x$ | CPU-seconds | s/r | Previous records |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| secp160r1 | 2 | 82 | 1 | 206s | $52 \%$ | 259s in [37] |
|  |  | 77 | $2^{10}$ | 71s | 58\% |  |
| secp192r1 | 2 | 99 | 1 | 10360s | 60\% | 87500s in [3] |
|  |  | 94 | $2^{10}$ | 2829s | 69\% |  |
| secp256r1 | 4 | 66 | 1 | 7 s | 65\% | 15 s in [37] |
|  |  | 64 | $2^{10}$ | 5 s | 79\% |  |
|  | 3 | 87 | 1 | 634 s | 53\% | 924s in [37] |
|  |  | 84 | $2^{10}$ | 359s | 57\% |  |
| secp384r1 | 4 | 98 | 1 | 8154s | 62\% | 11153s in [37] |
|  |  | 96 | $2^{10}$ | 5583s | 56\% |  |

(a) Easy instances

| Curve | Leakage | $d$ | $x$ | Wall time | Mem GiB | Previous records |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| secp112r1 | 1 | 116 | 1 | 10 min | 35 | 260 min in $[37]$ |
| secp256r1 | 2 | 129 | 1 | 232 min | 219 | 466 min in $[37]$ |
|  |  | 3 | 125 | $2^{10}$ | $74 \min$ |  |

(b) Medium instances

The success rate of our attack can be further improved by increasing the lattice dimension. Taking $\operatorname{ECDSA}(160,2)$ as an example, Figure 4 illustrates how the success rate notably increases as the lattice dimension grows. We conduct experiments on 500 randomly generated instances. When the lattice dimension reaches 92 , the success rate approaches $100 \%$. This observation can be attributed to the fact that the majority of the $\|\boldsymbol{v}\| / \mathrm{GH}$ ratios are below $\sqrt{4 / 3}$, which enables us to find the target vectors through sieving algorithms with high success rates. The experimental results also indicate that our algorithm can still handle instances with $\|\boldsymbol{v}\| / \mathrm{GH}$ ratios greater than $\sqrt{4 / 3}$ with a lower success rate, rather than failing $100 \%$.

Solving Medium Instances. Our attack results for medium instances are presented in Table 3b. We employ G6K-GPU [15] to achieve high-performance sieving algorithms. The process of searching the database is parallelized. Our attacks demonstrate high efficiency. Taking $\operatorname{ECDSA}(256,2)$ as an example, when $x$ is set to 1 , we complete the attack in 232 minutes by constructing a 129dimensional lattice. The time can be further reduced to 74 minutes by setting


Fig. 3: Searching the sieving database using different predicates.

Table 4: New records of lattice-based attack against ECDSA

| Curve | Leakage | $d$ | $x$ | Wall time | Mem GiB |
| :---: | :---: | :---: | :---: | :---: | :---: |
| brainpoolp512r1 | 4 | 130 | 1 | 268 min | 254 |

(a) 4-bit leakage

| Curve | Leakage | $d$ | $x$ | Wall time | Mem GiB |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 131 | 1 | 178 min | 294 |
| secp128r1 | 1 | 118 | $2^{15}$ | 18 min | 53 |
| secp160r1 | 1 | 138 | $2^{25}$ | 855 min | 781 |

(b) 1-bit leakage

| Curve | Error rate | $d$ | $x$ | Wall time | Mem GiB |
| :--- | :---: | :---: | :---: | :---: | :---: |
| secp128r1 | 0.01 | 126 | $2^{10}$ | 60 min | 143 |
|  | 0.1 | 140 | $2^{20}$ | $983 \min$ | 927 |
| secp160r1 | 0.01 | 141 | $2^{25}$ | 1575 min | 1215 |

(c) Less than 1-bit leakage
$x=2^{10}$. On the other hand, the attack in [37] required 466 minutes with four GeForce RTX 3090 GPUs.


Fig. 4: Breaking $\operatorname{ECDSA}(160,2)$ via lattices with different dimensions.

### 5.2 New Records of Lattice-based Attack against ECDSA

4-bit Leakage. The previous record for 4-bit leakage is only achieved on a 384bit curve. As depicted in Table 4a, our algorithm is able to break $\operatorname{ECDSA}(512,4)$ by a 130 -dimensional lattice, which takes 268 minutes and consumes 254 GiB of memory.

1-bit Leakage. Breaking ECDSA with 1-bit leakage using lattice algorithms has been considered to be very difficult. In 2023, Xu et al. reported a successful key recovery for 1-bit leakage on a 112-bit curve [37]. However, breaking $\operatorname{ECDSA}(160,1)$ was regarded as exceptionally challenging by previous lattice approaches [5,6,3,33,37]. Xu et al. required a lattice dimension of approximately 165 , which would make the time and space complexities of sieving algorithms unacceptable [37]. Besides, Sun et al. estimated the time complexity of their guessing bits algorithm is $2^{110} \mathrm{BKZ}-30$ operations [33].

We present the first implementation of lattice attacks against ECDSA with 1-bit leakage on both 160 -bit and 128 -bit curves. The experimental results are presented in Table $4 b$. When targeting $\operatorname{ECDSA}(160,1)$, it is essential to reduce the lattice dimension to a manageable size for sieving algorithms. We set $x$ to $2^{25}$, and obtain a lattice dimension of 138 . Thus, from a probabilistic perspective, $2^{35}$
samples are required to obtain 137 transformed HNP samples ( $t_{i}^{\prime}, a_{i}^{\prime}$ ) satisfying $\left|t_{i}^{\prime}\right|<q / 2^{29}$. Then the attack succeeds in approximately 855 minutes, using 781 GiB of memory.

Less than 1-bit Leakage. Before this work, only Fourier analysis-based attacks [6] could break ECDSA with less than 1-bit nonce leakage. We provide the first lattice-based attack results in Table 4c. Our attacks successfully handle an ECDSA instance with an error rate of at most 0.1 on a 128 -bit curve and an ECDSA instance with an error rate of 0.01 on a 160 -bit curve.

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    ** Yiming Gao and Jinghui Wang are the co-first authors of this work.

