BOIL: Proof-Carrying Data from Accumulation of Correlated Holographic IOPs

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Abstract. In this paper, we present a batching technique for oracles corresponding to codewords of a Reed–Solomon code. This protocol is inspired by the round function of the STIR protocol (CRYPTO 2024). Using this oracle batching protocol, we propose a construction of a practically efficient accumulation scheme, which we call BOIL. Our accumulation scheme can be initiated with an arbitrary correlated holographic IOP, leading to a new class of PCD constructions. The results of this paper were originally given as a presentation at zkSummit12.

1 Introduction

Proof-carrying data (PCD) [Chi10] is a cryptographic primitive that enables the dynamic compilation of a distributed computation, where each message is augmented by a short proof verifying that some local condition is met. An ideal PCD construction achieves this goal with minimal additional computation or communication overhead. A specific instance of PCD is incrementally verifiable computation (IVC) [Val08], a cryptographic primitive that allows one to produce a proof of the correctness of an iterative computation in an incremental fashion.

PCD via Recursive Composition. Early constructions of IVC and PCD relied on recursive composition, where each prover attaches a proof to each outgoing message, attesting that all previous local conditions have been met [BCCT12,BCTV14,COS20]. To achieve this, the constructions included a circuit representation of the verifier algorithm within a recursive statement. As a result, PCD was primarily limited to SNARKs – proof systems where the verifier's description is asymptotically smaller than the overall size of the statement being verified.

PCD via Accumulation. Later works [BGH19,BDFG21,BCMS20,BCL⁺21] showed that it is often possible to avoid the complete recursive proof verification at each iteration. Instead, the most expensive part of the verification can be accumulated outside the recursive statement, and checked only once at the very end of the distributed computation. Verifying the proof of the correctness of the accumulation is usually much simpler than a full proof verification. The folding approach can be considered an extreme version of accumulation schemes for

constructing IVC [KST22,BC23,EG23]. While a very small recursive overhead distinguishes constructions using folding, the accumulation approach allows using a broader class of NARKs as a basic block of the PCD scheme.

However, accumulation and folding schemes usually require the use of additively homomorphic commitment schemes. Therefore, this entire series of results is not compatible with (S)NARKs relying on code-based polynomial commitments, which are not homomorphic. However, even when using a full in-circuit verifier for recursion [COS20], such SNARKs perform excellently and are widely used in practice [Sta21,Teaa,Teab,KPV22]. The work of [BMNW24a] was the first attempt in trying to close this gap, showing how to build an accumulation scheme by postponing the code proximity test of such non-homomorphic constructions to the end. However, their work has significant shortcomings, discussed below in more detail, which our new construction addresses.

1.1 Our contributions

Oracle Batching Protocol. In this paper, we consider SNARKs that are built using a compilation of a Polynomial-IOP and a proximity proof for a linear code. This approach is widely adopted in the industry. Among the reasons, we can highlight the following.

- No need for a trusted ceremony and trapdoors to generate parameters.
- Such systems do not require public key assumptions.
- The system parameters can be adjusted to alter the efficiency trade-off between the prover and the verifier.
- Protocols for code proximity tests, for example, FRI, keep all arithmetic in the same field for prover and verifier, so no field switching is necessary. This means, in particular, that the recursive composition of proofs does not require the use of cycles of elliptic curves.

However, the polynomial commitment schemes derived from proximity proofs are not an additive like KZG [KZG10] or Pedersen [Ped92], which prevents a direct application of standard accumulation results.

Informally, the primary goal of FRI [BBHR18] (or any other proximity test) is to distinguish, by querying a function $f: D \to \mathbb{F}$ at a few locations, whether f coincides with the evaluation of some polynomial of degree less than d < |D| on the domain D, or whether it is far in relative Hamming distance from the evaluation of any low-degree polynomial. The batched version of the protocol [BCI⁺20,Hab22] allows one to perform a proximity test for several functions f_1, \ldots, f_n at once. However, to build more efficient IVC/PCD schemes, we need a reduction for multiple functions that does not require a full-fledged proximity test. Informally, this allows the incremental aggregation of new functions in batches, during the long-running computation. The problem of finding such a reduction was partially solved in [BMNW24a], but with a limitation on the number of recursive steps allowed. The question of finding a more general solution remained open.

Our first contribution is a batching oracle protocol heavily inspired by the recent STIR protocol [ACFY24a]. Suppose that we have n functions $f_1, \ldots, f_n : D \to \mathbb{F}$, for some $D \subset \mathbb{F}$. The verifier has oracle access to them, and the prover claims that f_i is δ -close to a low-degree polynomial, for all $i = 1, \ldots, n$. The protocol will produce a function $f_{\mathsf{new}} : D' \to \mathbb{F}$, for some other $D' \subset \mathbb{F}$, and reduce the n claims above to the single claim that f_{new} is δ -close to a low-degree polynomial.

This protocol does not require a proximity test, so it is much more efficient than batched FRI. We think it can be a base block for various designs such as a split accumulator or a linear combination scheme for PCS [BDFG21]. We consider the first construction in detail. The second follows implicitly, but the formalization is out of the scope of this paper.

Split Accumulation for IOPP. The new oracle batching protocol opens the doors for more efficient aggregation and recursive composition of proofs. Informally speaking, instead of performing a low-degree proximity test on each iteration of recursion, we can use the oracle batching protocol, thereby deferring this expensive test to the very end of the computation.

In the context of IVC/PCD constructions, an important performance metric is the recursive overhead. In the case of SNARKs based on the low-degree proximity test for Reed–Solomon codes, the recursive statement usually includes many hash invocations. The paper [COS20] formally shows how such SNARKs can be used to construct IVC/PCD. The described approach requires representing the verifier as a circuit, in which the lion's share is occupied by hash operations, even when using SNARK-friendly hash functions such as Poseidon [GKR⁺21]. The proximity test makes the largest contribution to this size:

 $O(\lambda \cdot c_{\delta} \log^2 d)$ hash invocations,

where λ is a security parameter, d is the corresponding polynomial degree and c_{δ} depends on the proximity parameter δ .

The paper [BMNW24a] proposes an alternative construction of the IVC/PCD based on a linearity test and exclusively symmetric assumptions. Their linearity test has a better asymptotic estimate of $O(\lambda \cdot c_{\delta} \log d)$ hash invocations. However, its use entails the problem of distance decay: with each iteration, the provable distance increases, so a much smaller proximity parameter δ/T must be used, where T is the number of iterations. For practically significant parameters, this negates the advantage since $O(\lambda \cdot c_{\delta/T} \log d)$ can be comparable to or even larger than $O(\lambda \cdot c_{\delta} \log^2 d)$.

Our technique, which we call BOIL (Batching Oracles for IOPP from Linearity), allows us to get the best of both worlds – logarithmic complexity and the absence of the distance decay problem. It is a theoretical and practical improvement over previous results.

We aim to show that BOIL can be used with various proof systems. Therefore, for formalization, we use the abstraction of correlated Holographic IOPs [CBBZ23]. Roughly speaking, a δ -correlated Holographic IOP (HIOP) [BGK⁺23] is a holographic proof system in which the verifier has access to an oracle that checks whether the requested polynomial is close to the Reed–Solomon code. This model captures many protocols (PLONK [GWC19a], Plonky2 [Teaa], RISC Zero [Teab], Redshift [KPV22]) and gives us the flexibility we need. We show that we can build a split accumulation scheme, given a round-by-round (RBR) knowledge sound δ -correlated HIOP, the Oracle batching protocol, and a RBR sound proximity test. The result of [BCL⁺21] directly yields the IVC/PCD construction.

1.2 Our techniques

To build our split accumulation scheme, we follow the overall strategy of [BMNW24a]: we start from a NARK and build a split accumulation scheme for its verifier relation.

As discussed above, running a proximity test for the Reed–Solomon code $\mathsf{RS}[\mathbb{F}, D, d]$ within a circuit is expensive, due to the large amount of hashes. Thus, we want to defer as much to the end of the recursive computation as we can, to minimize the size of the in-circuit verifier in the final IVC/PCD construction.

To achieve this, we want to recursively aggregate all these proximity checks for Reed–Solomon into a single one, which will be performed only once at the end, hence our interest in an oracle batching technique. This was achieved in [BMNW24a], using a simpler oracle batching technique. However, it imposed some limitations on their parameter choices which hindered the practicality of the scheme.

Oracle batching The construction in [BMNW24a] achieves the goal above by a technique that can be thought of as a single round of the FRI proximity test [BBHR18]: given functions $f_1, \ldots, f_n : D \to \mathbb{F}$, these are combined into a single function $f_{new} : D \to \mathbb{F}$ by means of a random linear combination, with randomness supplied by the verifier. Informally, if an honestly computed f_{new} is δ -close to RS[F, D, d], then with high probability so are f_1, \ldots, f_n . The prover sends an oracle for the purported f_{new} . The verifier ensures consistency between f_1, \ldots, f_n and f_{new} by means of spot checks at random points in D. This process can be iterated upon, and at the end the verifier simply checks proximity of the final aggregated function to RS[F, D, d]. This can be performed directly or by means of a fully fledged proximity test, like FRI or STIR.

This works, but has two significant limitations. One is that this approach requires to work within the unique decoding radius $(1-\rho)/2$ of the Reed–Solomon code, where ρ is the code rate, to prevent ambiguous decoding which thwarts the security proof of the accumulator. This leads to parameters that are inefficient in practice: the smaller the decoding radius, the more queries are necessary to guarantee the same level of soundness in the spot checks phase. The other issue is that the distance guarantee degrades with subsequent iterations of this procedure. Informally, what happens is that we can guarantee that

- f_{new} is δ -close to $\mathsf{RS}[\mathbb{F}, D, d]$, due to the final proximity test.

- the honest folding of f_1, \ldots, f_n is δ -close to f_{new} , due to the spot checks.

Hence, overall we can just guarantee that f_1, \ldots, f_n are 2δ -close to the code. More generally, over k recursion steps, we can only guarantee $k\delta$ -closeness to the code. From a theoretical point of view, this means that we can only build bounded-depth accumulation from this technique (although [BMNW24a] shows that this is enough to build PCD). From a practical point of view, this makes us into even more expensive choices of the code's proximity parameter, namely $(1 - \delta)/2k$.

These two problems are solved if we try to use a round from STIR [ACFY24a] instead of a round from FRI as our batching technique. It starts exactly as the previous approach, but includes additional steps at the end. Namely, it adds an out-of domain check and quotienting to disambiguate the decoding of f_{new} .

This is very reminiscent of the technique often used to turn FRI into a polynomial commitment scheme [KPV22]. Informally, this ensures that, with high probability, there is only one valid choice of codeword, even if we are in the list decoding regime. Moreover, it also gets rid of the distance decay issue: we can directly prove that if a (possibly dishonest) f_{new} is δ -close to the code, then f_1, \ldots, f_n are δ -close to the code. This allows us to work with the much better proximity parameter $1 - \sqrt{\rho}$ (or $1 - \rho$, under the usual Reed–Solomon decoding conjectures).

Split accumulation Our starting point is the framework of δ -correlated IOPs from [BGK⁺23]. These are IOPs equipped with an oracle that checks for δ -correlated agreement. Informally, n functions $f_1, \ldots, f_n : D \to \mathbb{F}$ are in δ -correlated agreement if each of them agrees with some codeword in RS[\mathbb{F}, D, d] in at least a (1 - d) fraction of the points in d, and the agreement subset of D is the same for all f_i .

This captures the notion of an IOP that relies on polynomial check and a proximity/correlated agreement as part of its final verification. Indeed, they show that a δ -correlated IOP for a relation \mathcal{R} can be combined with a (regular) IOP for correlated agreement to produce a (regular) IOP for \mathcal{R} , with soundness being preserved through the transformation.

Once we have a regular IOP, we can use the BCS transformation [BCS16] to obtain a NARK in the random oracle model. Finally, we build a split accumulator for the verifier relation of this NARK, using our new oracle batching technique as a key building block. This results in a construction with an accumulator verifier that does not need to run a full proximity test on each accumulation step. Thus, we avoid the issue of running a full proximity test inside of a circuit. Moreover, because of the STIR-based oracle batching technique, our construction does not inherit the same parameter limitations as the one in [BMNW24a].

1.3 Related works

Comparison with Folding-based constructions. Nova-like folding schemes [KST22,KS22,KS24] allow efficient IVC constructions but are based on the use of

R1CS or CCS arithmetization. Our construction allows the use of the Plonkish arithmetization [GW20b,GW20a], which is very expressive and widely used in practice.

Another important difference is that the EC-based IVC/PCD designs use cycles of curves [KST22,BC23,EG23]. This makes formalization somewhat more complicated [KS23,NBS23]. Moreover it requires the use of non-native arithmetic, which significantly increases the recursive overhead. By avoiding cycles of curves, we get a conceptually more straightforward construction.

Finally, IVC constructions are usually neither succinct nor zero knowledge: the size of the state that the prover must maintain is proportional to the size of the circuit. This significantly complicates the parallelization of proof generation for a distributed computation. In our design, this state size can be significantly reduced using the Oracle batching protocol. In particular, for a circuit represented by a matrix of $N \times M$ elements, the state size will be proportional to one column, i.e. N elements. In this aspect, we obtain some properties of end-to-end IVC schemes [Sou23].

PCD from solely symmetric-key assumptions. The authors of [BMNW24a] built a bounded depth accumulator without using a proximity test as in [COS20] and without public key assumptions. Our work improves this result and shows that building a full-fledged split accumulator in this setting is possible.

1.4 A note on concurrent work

Our results were first presented at zkSummit12 [KNS24]. Between this event and the publication of this text, two independent papers [BMNW24b] and [Sze24] were published, which also use the idea of a STIR-based oracle batching protocol, and provide a rigorous formalization.

Our work uses different building blocks, and our final design has some explicit practical optimizations of independent interest. However, during the process of writing this document, our ongoing work in formalizing split accumulation seemed to have much in common with the analysis in [BMNW24b]. Thus, we decided to publish the current semi-formal version of this paper. We believe that the approach used and some details of the constructions are different enough between these works. But, at the same time, we see little contribution in duplicating the analysis of [BMNW24b]. This explains the current state of Section 4, in which part of the proofs are not fully formalized.

2 Preliminaries

2.1 Reed–Solomon codes

Let \mathbb{F} be a finite field, and $D \subset \mathbb{F}$. Given a function $f: D \to \mathbb{F}$, we denote by \hat{f} the lowest-degree polynomial in $\mathbb{F}[X]$ that extends f.

Let $\mathsf{RS}[D,d]$ be the *Reed-Solomon code* over $D \subset \mathbb{F}$ with degree bound $d \mid \#D$, that is,

$$\mathsf{RS}[D,d] = \{ f : D \to \mathbb{F} \mid \deg \hat{f} < d \}.$$

We might write $\mathsf{RS}[\mathbb{F}, D, d]$ if we want to make the field explicit, but most of the time we ignore it for simplicity. The *code rate* is defined as $\rho = d/\#D$.

Given $f, g: D \to \mathbb{F}$, we denote by $\Delta(f, g)$ the relative Hamming distance between them, i.e.

$$\Delta(f,g) = \frac{\#\{x \in D \mid f(x) \neq g(x)\}}{\#D}.$$

Similarly, for a set $S \subset \mathbb{F}^D$, we denote

$$\Delta(f,S) = \min_{g \in S} \{\Delta(f,g)\}.$$

W define the *list decoding* of a function $f: D \to \mathbb{F}$ as

$$\mathsf{List}(f, d, \delta) = \{g \in \mathsf{RS}[D, d] \mid \Delta(f, g) \le \delta\}.$$

We say that $\mathsf{RS}[D, d]$ is (δ, ℓ) -list decodable if

$$\operatorname{List}(f, d, \delta) \leq \ell \quad \forall f : D \to \mathbb{F}.$$

Folding preserves correlated agreement For $\delta \geq 0$, we say that $f_1, \ldots, f_n : D \to \mathbb{F}$ have δ -corellated agreement in $\mathsf{RS}[D, d]$ if there exist

- a set $S \subset D$, with size $\#S/\#D \ge (1 - \delta)$, and - codewords $g_1, \ldots, g_n \in \mathsf{RS}[D, d]$,

such that

$$f_{i|S} = g_{i|S}, \quad \forall i = 1, \dots, n.$$

In particular, this implies that

$$\Delta(f_i, \mathsf{RS}[D, d]) < \delta, \quad \forall i = 1, \dots, n.$$

Let $f_1, \ldots, f_n : D \to \mathbb{F}$ and $\alpha \in \mathbb{F}$. We define:

$$\operatorname{Fold}_{\alpha}(f_1,\ldots,f_n) = \sum_{i=1}^n f_i \alpha^i.$$

Note that it is defined over the same domain as each individual function.

Lemma 1 ([BCI⁺20], Theorems 4.1 and 5.1 and [ACFY24a], Theorem 4.1). Let $f_1, \ldots, f_n : D \to \mathbb{F}, d \in \mathbb{N}, \rho = d/\#D, \delta \in (0, 1 - \sqrt{\rho})$. Define the error term

$$\varepsilon_{\mathsf{fold}} = \varepsilon_{\mathsf{fold}}(d, \rho, \delta, n) = \begin{cases} \frac{(n-1)\cdot d}{\rho \cdot \#\mathbb{F}} & \text{if } 0 < \delta \leq \frac{1-\rho}{2}.\\ \frac{(n-1)\cdot d^2}{\#\mathbb{F}\cdot \left(2\cdot\min\{1-\sqrt{\rho}-\delta,\frac{\rho}{20}\}\right)^7} & \text{if } \frac{1-\rho}{2} < \delta < 1-\rho. \end{cases}$$

Suppose that f_1, \ldots, f_n do not have δ -corellated agreement in $\mathsf{RS}[D,d]$. Then

$$\Pr\left[\alpha \leftarrow \mathbb{F} : \Delta(\mathsf{Fold}_{\alpha}(f_1, \dots, f_n), \mathsf{RS}[D, d]) \le \delta\right] \le \varepsilon_{\mathsf{fold}},$$

Out-of-domain sampling

Lemma 2 ([ACFY24a], Lemma 4.5). Let $f : D \to \mathbb{F}, d, s \in \mathbb{N}, \delta \in [0, 1]$. Define the error term

$$\varepsilon_{\text{out}} = \binom{\ell}{2} \cdot \left(\frac{d-1}{\#\mathbb{F} - \#D}\right)^s \le \frac{d^s \cdot \ell^2}{2 \cdot (\#\mathbb{F} - \#D)^s}.$$

If $\mathsf{RS}[D,d]$ is (δ,ℓ) -list decodable, then

$$\Pr\left[\begin{array}{cc} \exists u, u' \in \mathsf{List}(f, d, \delta) \ s. \ t.\\ x_1, \dots, x_s \leftarrow \mathbb{F} \setminus D: \ u \neq u' \land u(x_i) = u'(x_i)\\ \forall i = 1, \dots, s\end{array}\right] \leq \varepsilon_{\mathsf{out}}.$$

Quotienting Let $f : D \to \mathbb{F}$ and $\mathbf{x}, \mathbf{y} \in \mathbb{F}^q$, with $D \cap \mathbf{x} = \emptyset$. We define Quotient $(f, \mathbf{x}, \mathbf{y}) : D \to \mathbb{F}$ as follows. Let $\hat{p} \in \mathbb{F}[X]$ such that deg p < q and $p(x_j) = y_j$ for $j = 1, \ldots, q$. Then

Quotient
$$(f, \mathbf{x}, \mathbf{y})(x) = \frac{f(x) - \hat{p}(x)}{\prod_{j=1}^{q} (x - x_j)}$$
.

Lemma 3 ([ACFY24a], Lemma 4.4). Let $f : D \to \mathbb{F}, d \in \mathbb{N}, \delta \in (0, 1), \mathbf{x}, \mathbf{y} \in \mathbb{F}^q$ with $D \cap \mathbf{x} = \emptyset$ and q < d. Suppose that for every $u \in \text{List}(f, d, \delta)$, there exists $j \in \{1, \ldots, q\}$ such that $\hat{u}(x_j) \neq y_j$. Then

$$\Delta(\mathsf{Quotient}(f, \mathbf{x}, \mathbf{y}), \mathsf{RS}[D, d - (t+1)]) > \delta.$$

Degree correction Let $f: D \to \mathbb{F}$ and $d, d^* \in \mathbb{N}, r \in \mathbb{F}$ with $0 \le d \le d^*$. We define $\mathsf{DegCor}: D \to \mathbb{F}$ as follows:

$$\mathsf{DegCor}(d^*,r,f,d)(x) = f(x) \cdot \left(\sum_{\ell=0}^{d^*-d} (rx)^\ell\right).$$

Lemma 4 ([ACFY24a], Lemma 4.13). Let $f: D \to \mathbb{F}, d, d^* \in \mathbb{N}, r \in \mathbb{F}$ with $0 \le d \le d^*$. Let $\rho = d^*/\#D, \delta \in (0, \min\{1 - \sqrt{\rho}, 1 - \rho - 1/\#D\})$. Suppose that $\Delta(f, \mathsf{RS}[D, d]) > \delta$. Then

$$\Pr\left[r \leftarrow \mathbb{F} : \Delta(\mathsf{DegCor}(d^*, r, f, d), \mathsf{RS}[D, d^*]) \le \delta\right] \le \varepsilon_{\mathsf{corr}},$$

where $\varepsilon_{corr} = \varepsilon_{fold}(d^*, \rho, \delta, n(d^* + 1) - d)$ is the error term defined in Lemma 1.

2.2 Merkle commitments

We recall Merkle tree based vector commitment schemes, following the syntax of [CY24]. Let $k \in \mathbb{N}$, and $\mathcal{H} : \{0,1\}^* \to \{0,1\}^k$. Let Σ be an alphabet, and let $l \in \mathbb{N}$ be the length of the vector to commit. The Merkle tree vector commitment scheme $\mathsf{MT}[k, \Sigma, l]$ is composed by the following algorithms:

- MT.Commit: receives as input a message vector $\mathbf{m} \in \Sigma^l$, and computes a Merkle commitment $\mathsf{rt} \in \{0,1\}^k$ and corresponding opening trapdoor $\mathsf{td} \in \{0,1\}^{O(k \cdot l)}$.
- MT.Open: receives as input opening trapdoor td and a subset $I \subseteq [l]$, and computes an opening proof ap that authenticates the values at the locations in I.
- MT.Check: receives as input a Merkle commitment rt, subset $I \subseteq [l]$, claimed values $\mathbf{a} \in \Sigma^{I}$, and opening proof ap, and computes a bit indicating whether the opening proof ap authenticates \mathbf{a} as values for the locations in I with respect to rt.

Merkle tree vector commitments are used in the BCS transformation, described below, to swap oracles to functions by short descriptions of those functions, allowing to obtain an IP from an IOP.

2.3 Interactive oracle proofs

We denote oracle access to a function f by f. The result of a query at a point x is denoted by f(x).

We follow the definitions of Holographic IOPs from [COS20]. We consider indexed relations $\mathcal{R} = \{(i, x, w)\}$. In the context of verifiable computation, i is an index that defines the computation, x is the statement that contains the public inputs, and w is the witness that contains the secret inputs. In many modern general-purpose proof systems, these take polynomial form. We define the indexed language $\mathcal{L}_i = \{x \mid \exists w \text{ s. t. } (i, x, w) \in \mathcal{R}\}$.

The work of $[BGK^+23]$ considers *oracle relations*, that is, relations in which w may contain some functions, and x contains oracles to those functions. This is convenient to frame proximity proofs as IOPs, so we follow this approach. Thus, all definitions below apply to both regular relations and oracle relations, unless it is specified otherwise.

A Holographic Interactive Oracle Proof (HIOP) for an indexed relation \mathcal{R} is a tuple $\Pi = (\mathcal{I}, \mathcal{P}, \mathcal{V})$, where \mathcal{I} is a PT algorithm, and \mathcal{P}, \mathcal{V} are stateful PPT algorithms. The prover and verifier engage interactively. The record of communications between them is called a *transcript*, and we denote it by $\pi \leftarrow \langle \mathcal{P}(i, x, w), \mathcal{V}^{\mathcal{I}(i)}(x) \rangle$. At the end, the verifier examines the transcript and outputs a bit. We denote this by $0/1 \leftarrow \mathcal{V}^{\mathcal{I}(i)}(x, \pi)$.

A HIOP $\Pi = (\mathcal{I}, \mathcal{P}, \mathcal{V})$ has *perfect completeness* if, for all $(i, x, w) \in \mathcal{R}$,

$$\Pr\left[\pi \leftarrow \langle \mathcal{P}(i, \mathbf{x}, \mathbf{w}), \mathcal{V}^{\mathcal{I}(i)}(\mathbf{x}) \rangle : 1 \leftarrow \mathcal{V}^{\mathcal{I}(i)}(\mathbf{x}, \pi)\right] = 1.$$

Flavors of soundness We first introduce the regular notions of soundness, as presented in [COS20, Section 4].¹

¹ The error terms in the following definitions are allowed to depend on i, x, but we often omit this for simplicity. We will make the dependency explicit when there is some ambiguity.

Definition 1. A HIOP $\Pi = (\mathcal{I}, \mathcal{P}, \mathcal{V})$ for a relation \mathcal{R} has soundness error ε if, for any PPT adversary $\tilde{\mathcal{P}}$, all i and all $x \notin \mathcal{L}_i$, we have that

$$\Pr\left[\pi \leftarrow \langle \tilde{\mathcal{P}}(\mathfrak{i}, \mathfrak{x}), \mathcal{V}^{\mathcal{I}(\mathfrak{i})}(\mathfrak{x}) \rangle : 1 \leftarrow \mathcal{V}(\mathfrak{i}, \mathfrak{x}, \pi)\right] < \varepsilon,$$

over the coin tosses of \mathcal{V} .

Definition 2. A HIOP $\Pi = (\mathcal{I}, \mathcal{P}, \mathcal{V})$ for a relation \mathcal{R} has knowledge error κ if there exists a PPT extractor Ext such that, for any PPT adversary $\tilde{\mathcal{P}}$ and all i, x, we have that

$$\Pr\left[\pi \leftarrow \langle \tilde{\mathcal{P}}(\mathfrak{i}, \mathfrak{x}), \mathcal{V}^{\mathcal{I}(\mathfrak{i})}(\mathfrak{x}) \rangle : 1 \leftarrow \mathcal{V}(\mathfrak{i}, \mathfrak{x}, \pi) \right] \\ - \Pr\left[\mathbb{w} \leftarrow \mathsf{Ext}^{\tilde{\mathcal{P}}}(\mathfrak{i}, \mathfrak{x}) : (\mathfrak{i}, \mathfrak{x}, \mathbb{w}) \in \mathcal{R}\right] < \kappa.$$

We now introduce round-by-round soundness and round-by-round knowledge soundness. These are interesting properties to us, because they are preserved through the transformations presented below.

We follow the formulation of $[BGK^+23]$, Definitions 3.12 and 3.13].

Definition 3. A public-coin HIOP Π for a relation \mathcal{R} has round-by-round soundness error ε_{rbr} if, for all indices i, there exists a set DoomedSet such that:

- 1. $x \notin \mathcal{L}_i \implies (x; \emptyset) \in \mathsf{DoomedSet}.$
- 2. $(\mathbf{x}; \tau) \in \mathsf{DoomedSet} \implies \mathcal{V}^{\mathcal{I}(\mathbf{i})}(\mathbf{x}; \tau) = 0$ for any complete transcript τ .
- 3. $(x; \tau) \in \text{DoomedSet} \implies \Pr_{c \leftarrow \$}[(x; \tau ||m||c) \notin \text{DoomedSet}] < \varepsilon_{rbr} \text{ for any partial transcript } \tau \text{ and any prover message } m.$

Definition 4. A public-coin HIOP Π for a relation \mathcal{R} has round-by-round knowledge error κ_{rbr} if there exists a PT extractor Ext such that, for all indices i, there exists a set DoomedSet such that:

- 1. $(\mathbf{x}; \emptyset) \in \mathsf{DoomedSet} \ for \ all \ \mathbf{x}.$
- 2. $(\mathbf{x}; \tau) \in \mathsf{DoomedSet} \implies \mathcal{V}^{\mathcal{I}(\mathbf{i})}(\mathbf{x}; \tau) = 0$ for any complete transcript τ .
- 3. $(\mathfrak{x}; \tau) \in \mathsf{DoomedSet} \land \Pr_{c \leftarrow \$}[(\mathfrak{x}; \tau ||m||c) \notin \mathsf{DoomedSet}] > \kappa_{\mathsf{rbr}} \Longrightarrow$ $(\mathfrak{i}, \mathfrak{x}, \mathfrak{w}) \in \mathcal{R}, \text{ where } \mathfrak{w} \leftarrow \mathsf{Ext}(\mathfrak{i}, \mathfrak{x}, \tau, m), \text{ for any partial transcript } \tau \text{ and } any prover message } m.$

From IOPs to non-interactive arguments in the ROM An IOP can be seen as a generalization of both IPs and PCPs, both of which can be transformed into non-interactive arguments, via the Fiat–Shamir transformation [FS87,PS96] and the CS proofs construction [Mic00,Val08], respectively. Thus, it is natural that a combination of this techniques yields a generic transformation from IOPs to non-interactive arguments. This was formalized as the BCS transformation [BCS16]. We summarize its properties in the following result. **Theorem 1.** Let $\mathcal{H} : \{0,1\}^* \to \{0,1\}^k$ be a random oracle, and let $Q \in \mathbb{N}$ be a bound on the number of queries to \mathcal{H} . Let $(\mathcal{I}, \mathcal{P}, \mathcal{V})$ be a HIOP for a regular (non-oracle) relation $\mathcal{R} = \{(\mathfrak{i}, \mathfrak{x}, \mathfrak{w})\}$, with the following properties:²

- $-\ell$: proof length.
- -q: number of queries to oracles provided by the prover (and oracles in x, in the case of oracle relations).
- $-\varepsilon_{rbr}$: round-by-round soundness error.
- $-\kappa_{rbr}$: round-by-round knowledge error.

Then, there exists a PT transformation BCS such that $(I_{BCS}, P_{BCS}, V_{BCS}) := BCS^{\mathcal{H}}(\mathcal{I}, \mathcal{P}, \mathcal{V})$ is a non-interactive holographic proof system for \mathcal{R} in the ROM, with the following properties:

- adaptive soundness error and knowledge error against Q-query adversaries:

$$\begin{split} \varepsilon_{\rm fs}(Q,k) &= Q\varepsilon_{\rm rbr} + 3(Q^2+1)/2^k, \\ \kappa_{\rm fs}(Q,k) &= Q\kappa_{\rm rbr} + 3(Q^2+1)/2^k. \end{split}$$

- adaptive soundness error and knowledge error against $Q - O(q \log(\ell))$ -query quantum adversaries:

$$\begin{split} \varepsilon_{\mathsf{qfs}}(Q,k) &= \Theta(Q \cdot \varepsilon_{\mathsf{fs}}), \\ \kappa_{\mathsf{qfs}}(Q,k) &= \Theta(Q \cdot \kappa_{\mathsf{fs}}). \end{split}$$

2.4 δ -correlated IOPs

A common strategy to build SNARKs is to combine a polynomial IOP with a proximity test for a Reed–Solomon code, and the BCS transformation. We recall the notion of δ -correlated HIOPs, introduced in [BGK+23], which provides a framework for some such polynomial IOPs, e.g. Plonk [GWC19b].

We start by considering a certain type of oracle relations relative to a fixed Reed–Solomon code.

Definition 5. An oracle relation \mathcal{R} is a (\mathbb{F}, D, d) -polynomial oracle relation if the oracles in statements in \mathcal{R} correspond to codewords in $\mathsf{RS}[\mathbb{F}, D, d]$.

In particular, we consider the following strict (\mathbb{F}, D, d) -polynomial oracle relation.

$$\mathsf{CoAgg} = \left\{ \begin{pmatrix} i \\ m \\ w \end{pmatrix} = \begin{pmatrix} \mathbb{F}, D, d, \delta, n \\ \overbrace{f_1, \dots, f_n}^{(f_1, \dots, f_n)} \end{pmatrix} \mid \begin{array}{c} \delta, n > 0, f_i : D \to \mathbb{F}, \\ \Delta(f_i, \mathsf{RS}[\mathbb{F}, D, d]) \le \delta \quad \forall i = 1, \dots, n \\ \text{(with δ-correlated agreement)} \end{array} \right\}.$$

Additionally, let $OCoAgg(\delta)$ be a function that works as follows. It receives as input (i, x), with δ being the proximity parameter in i. Then, it outputs 1 if and only if $(i, x, w) \in CoAgg$.

² As with the error terms, ℓ, q also depend on i, x.

Given a statement \mathbf{x} and a (potentially partial) transcript τ , let $(\mathbf{F}(\mathbf{x},\tau))$ denote the set of oracles that have appeared so far in either of them. We denote the set of functions behind these oracles by $\mathbf{F}(\mathbf{x},\tau)$.

Definition 6. Let $\delta \geq 0$. A HIOP $\Pi = (\mathcal{I}, \mathcal{P}, \mathcal{V})$ for a (\mathbb{F}, D, d) -polynomial oracle relation \mathcal{R} is δ -correlated if the following hold:

- \mathcal{V} has oracle access to $\mathsf{OCoAgg}(\delta)$.
- Let τ denote the transcript up to the last round of interaction. For the last round:
 - \mathcal{V} sends $\zeta \leftarrow S \subset \mathbb{F}$ (or an extension of \mathbb{F}).
 - \mathcal{P} sends evaluations of functions in $F(x, \tau)$.
- \mathcal{V} 's final check consists of the following:
 - Assert whether the evaluations sent by the prover in the final round are roots of a certain multivariate polynomial, determined from i, x, τ.
 - Check that a set of maps

$$\left[\mathsf{Quotient}(f_i, x_{i,\zeta}, f_i(x_{i,\zeta})) \mid f_i \in \mathsf{F}(\mathbb{x}, \tau)\right]_{i=1}^r$$

has δ -correlated agreement in $\mathsf{RS}[D, d-1]$, using OCoAgg on their oracles.

From δ -correlated IOPs to regular IOPs One of the main results from [BGK⁺23] is that one can turn a 0-correlated HIOP Π for \mathcal{R} into a δ -correlated IOP for \mathcal{R} , and then combine it with a HIOP for the CoAgg relation to produce a standard HIOP for \mathcal{R} . We summarize the properties of the transformation here.

Theorem 2 ([BGK⁺23], **Theorem 4.6**). Consider the following HIOPs:

- Π_{CA} is a HIOP for CoAgg, with round-by-round soundness error ε_{rbr}^{CA} .
- $\Pi^{\mathsf{OCoAgg}(0)} = (\mathcal{I}, \mathcal{P}, \mathcal{V})$ is a 0-correlated HIOP for a (\mathbb{F}, D, d) -polynomial oracle relation \mathcal{R} , with:
 - round-by-round soundness error ε_{rbr} .
 - round-by-round knowledge error κ_{rbr}

Let ρ be the code rate of $\mathsf{RS}[D,d]$, and let $\delta < 1 - \sqrt{\rho}$ and $\eta = 1 - \sqrt{\rho} - \delta > 0$.

Then, there exists a HIOP Π for \mathcal{R} with the following properties:

- Round-by-round soundness error:

$$\varepsilon_{\rm rbr}'(i) = \max\left\{\frac{\varepsilon_{\rm rbr}(i)}{2\eta\sqrt{\rho}}, \varepsilon_{\rm rbr}^{\rm CA}(i_{\rm CA})\right\},\label{eq:critical_rbr}$$

where $i_{CA} = (\mathbb{F}, D, d, \delta, n)$, and n is the number of functions f_i involved in \mathcal{V} 's final check for δ -correlated agreement.

- Round-by-round knowledge error:

$$\kappa_{\mathsf{rbr}}'(\mathfrak{i}) = \max\left\{\frac{\kappa_{\mathsf{rbr}}(\mathfrak{i})}{2\eta\sqrt{\rho}}, \varepsilon_{\mathsf{rbr}}^{\mathsf{CA}}(\mathfrak{i}_{\mathsf{CA}})\right\},$$

where i_{CA} is the same as in the item above.

Given a 0-correlated HIOP Π , the transformation can be instantiated by using as Π_{CA} any correlated agreement protocol, like the batch variants of FRI [BBHR18], STIR [ACFY24a] or WHIR [ACFY24b].³ Moreover, one can just use the trivial check in which the verifier reads the whole function by querying the oracles at every position. Afterwards, the BCS transformation can be applied, yielding a non-interactive argument in the ROM.

2.5 Split accumulation in the ROM

We follow the split accumulation definitions from $[BCL^+21]$, adapted to our setting. Let $\mathcal{R} = \{(qi, qx, qw)\}$ be a relation. A *split accumulation scheme* for \mathcal{R} is a tuple of algorithms SA = (I, P, V, D) with the following syntax:

- $\ I(qi)$ outputs the index-specific prover key pk, verifier key vk, and decider key dk.
- $\mathsf{P}\left(\mathsf{pk}, (\mathsf{qx}_i, \mathsf{qw}_i)_{i=1}^n, (\mathsf{acc}_j)_{j=1}^m\right)$ outputs an accumulator $\mathsf{acc} = (\mathsf{acc.x}, \mathsf{acc.w})$, and a proof π_{acc} of correct accumulation. We consider $\mathsf{acc.x}$ and $\mathsf{acc.w}$ the short part and long part of the accumulator, respectively.
- V (vk, $(qx)_{i=1}^n$, $(acc_j.x)_{j=1}^m$, $acc.x, \pi_{acc}$) outputs 0/1. Note that it only accesses the short part of accumulators.
- D(dk, acc) outputs 0/1. Unlike V, the decider has access to a full accumulator.

A split accumulation scheme in the ROM is a split accumulation scheme in which P,V have access to the same random oracle \mathcal{H} .

Definition 7 (Completeness).

A split accumulation scheme in the ROM SA = (I, P, V, D) has perfect completeness if for any $(qi, (qx_i, qw_i)_{i=1}^n, (acc_j)_{j=1}^m)$ and any random oracle $\mathcal{H}: \{0, 1\}^* \to \{0, 1\}^k$, we have that

$$\Pr \begin{bmatrix} (\mathsf{q}i,\mathsf{q}\mathsf{x}_i,\mathsf{q}\mathsf{w}_i) \in \mathcal{R} \quad \forall i \in [n] \\ 1 \leftarrow \mathsf{D}(\mathsf{d}\mathsf{k},\mathsf{acc}_j) \quad \forall j \in [m] \\ (\mathsf{p}\mathsf{k},\mathsf{v}\mathsf{k},\mathsf{d}\mathsf{k}) \leftarrow \mathsf{I}(\mathsf{q}i), \\ (\mathsf{q}\mathsf{c}_i,\mathsf{q}\mathsf{w}_i)_{i=1}^n, \\ (\mathsf{acc},\pi_{\mathsf{acc}}) \leftarrow \mathsf{P}^{\mathcal{H}} \begin{pmatrix} \mathsf{p}\mathsf{k}, \\ (\mathsf{q}\mathsf{x}_i,\mathsf{q}\mathsf{w}_i)_{i=1}^n, \\ (\mathsf{acc}_j)_{j=1}^m \end{pmatrix} : \begin{array}{c} \Downarrow \\ \mathsf{v}\mathsf{k},(\mathsf{q}\mathsf{x}_i)_{i=1}^n, \\ \mathsf{d}\mathsf{cc}_j,\mathbb{X} \end{pmatrix}_{j=1}^m, \\ \mathsf{acc},\mathbb{X},\pi_{\mathsf{acc}} \end{pmatrix} \\ 1 \leftarrow \mathsf{D}(\mathsf{d}\mathsf{k},\mathsf{acc}) \end{bmatrix} = 1.$$

 3 In fact, one can see these protocols as HIOPs for $\mathsf{CoAgg},$ with n=1 in the non-batch case.

Definition 8 (Knowledge soundness). A split accumulation scheme in the ROM SA = (I, P, V, D) has knowledge error κ if there exists a PPT extractor Ext such that, for any PPT \tilde{P} , any auxiliary input ai, and any random oracle $\mathcal{H}: \{0,1\}^* \to \{0,1\}^k$, we have that

$$\Pr \begin{bmatrix} \begin{pmatrix} \mathsf{qi}, (\mathsf{qx}_i)_{i=1}^n, \\ (\mathsf{acc}, \mathbf{x})_{j=1}^m, \\ \mathsf{acc}, \pi_{\mathsf{acc}}, r \end{pmatrix} \leftarrow \tilde{\mathsf{P}}^{\mathcal{H}}(\mathsf{ai}) & 1 \leftarrow \mathsf{V}^{\mathcal{H}} \begin{pmatrix} \mathsf{vk}, (\mathsf{qx}_i)_{i=1}^n, \\ (\mathsf{acc}_j, \mathbf{x})_{j=1}^m, \\ \mathsf{acc}, \pi_{\mathsf{acc}}, r \end{pmatrix} \\ \leq 1 - \kappa, \\ \begin{pmatrix} (\mathsf{qw}_i)_{i=1}^n, \\ (\mathsf{acc}_j, \mathbf{w})_{j=1}^m \end{pmatrix} \leftarrow \mathsf{Ext}^{\mathcal{H}, \tilde{\mathsf{P}}}(\mathsf{ai}, r) & \Downarrow \\ (\mathsf{qi}, \mathsf{qx}_i, \mathsf{qw}_i) \in \mathcal{R} \quad \forall i \in [n] \\ 1 \leftarrow \mathsf{D}(\mathsf{dk}, \mathsf{acc}_j) \quad \forall j \in [m] \end{bmatrix} \geq 1 - \kappa, \end{cases}$$

where r is the randomness used by $\tilde{\mathsf{P}}$ above, and $\mathsf{acc}_j = (\mathsf{acc}_j.\mathtt{x}, \mathsf{acc}_j.\mathtt{w})$.

Split accumulators are particularly useful if we can build them for the verifier relation of a NARK for circuit satisfiability. More precisely, let $\mathcal{R} = \{(i, x, w)\}$ be the relation for circuit satisfability, and let $\mathsf{ARG} = (\mathcal{I}, \mathcal{P}, \mathcal{V})$ be a NARK for \mathcal{R} , and let us write

$$q\mathbf{i} = \mathbf{I},$$
$$q\mathbf{x} = (\mathbf{x}, \pi . \mathbf{x}),$$
$$q\mathbf{w} = \pi . \mathbf{w}.$$

Then, we define the relation $\mathcal{R}_{\mathcal{V}}$ such that

$$(qi, qx, qw) \in \mathcal{R}_{\mathcal{V}} \iff 1 \leftarrow \mathcal{V}(\mathsf{vk}_{\mathsf{NARK}}, \mathfrak{X}, (\pi.\mathfrak{X}, \pi.\mathfrak{W}))$$

where vk_{NARK} is the NARK verifier key obtained from $\mathcal{I}(i)$.

Suppose that there is a split accumulation scheme SA for $\mathcal{R}_{\mathcal{V}}$. Then, we can use ARG and SA to build PCD schemes [BCL⁺21, Theorem 5.3].

3 Oracle batching

3.1 The core interactive protocol

Suppose that we have n functions $f_1, \ldots, f_n : D \to \mathbb{F}$. The verifier has oracle access to them, and the prover claims that f_i is δ -close to a low-degree polynomial, for all $i = 1, \ldots, n$. The following protocol will produce a function f_{new} , and reduce the n claims above to the single claim that f_{new} is δ -close to a low-degree polynomial. The function f_{new} is defined over some other domain D' such that $D \cap D' = \emptyset$. The domains D, D' can be chosen as the two cosets of degree 2^s of the group of roots of unity of degree 2^{s+1} .

In our description below, we start from $f_i \in \mathsf{RS}[D,d]$ (or close) for $i = 1, \ldots, n$, and end up with $f_{\mathsf{new}} \in \mathsf{RS}[D']$ (or close), where t is a parameter that determines the number of verifier queries. Because we want to iteratively apply

this protocol to aggregate incoming sets of functions of degree d, we will apply some degree correction to f_{new} , to bring it back to degree d.

We describe the interactive protocol in Figure 3.1, and denote by $f_{\text{new}} \leftarrow OB(f_1, \ldots, f_n)$ its execution with input oracles to f_1, \ldots, f_n and output an oracle to f_{new} .⁴



Fig. 1. The oracle batching (OB) interactive protocol.

Proposition 1. Let $f_1, \ldots, f_n : D \to \mathbb{F}$, and let $d \in \mathbb{N}$. Suppose that, for all $i = 1, \ldots, n$, we have that $f_i \in \mathsf{RS}[D, d]$. Then

$$\Pr\left[f_{\mathsf{new}} \leftarrow \mathsf{OB}(f_1, \dots, f_n) : f_{\mathsf{new}} \in \mathsf{RS}[D', d]\right] = 1.$$

⁴ Note that $\mathsf{Quotient}(f_{\mathsf{fold}}, \mathbf{x}, \mathbf{y})$ is well defined, since f_{fold} is defined over D', whereas $x_0 \in \mathbb{F} \setminus D', x_1, \ldots, x_n \in D$, and $D \cap D' = \emptyset$.

Proof. We need to show that deg $\hat{f}_{quot} < d - (t + 1)$. From this, it will follow that deg $\hat{f}_{new} < d$, since DegCor is simply multiplying \hat{f}_{quot} by a polynomial of degree t + 1.

To prove this, observe that, if deg $\hat{f}_i < d$, then clearly deg $\hat{f}_{\mathsf{fold}} < d$, as folding honestly does not increase the degree. Next, we show that the quotient behaves as expected. Indeed, it is easy to check by inspection that $\hat{f}_{\mathsf{fold}}(x_j) = y_j$, and thus $\prod_{j=0}^t (X - x_j) \mid \hat{f}_{\mathsf{fold}}(X) - \hat{p}(X)$, where \hat{p} is as defined in Section 2.1. Therefore, deg $\hat{f}_{\mathsf{quot}} = \deg \hat{f}_{\mathsf{fold}} - (t+1) < d - (t+1)$, concluding the proof.

3.2 A proximity proof from oracle batching

Given the oracle batching protocol above, $OB = (\mathcal{P}_{OB}, \mathcal{V}_{OB})$, it is trivial to turn it into an IOP $\Pi_{OB} = (\mathcal{I}, \mathcal{P}, \mathcal{V})$ for the CoAgg relation, i.e. a batched proximity check:

- \mathcal{I} chooses the parameters of a Reed–Solomon code $\mathsf{RS}[\mathbb{F}, D, d]$, the proximity parameter δ , and the number n of functions in correlated agreement.
- $-\mathcal{P}$ is the same as prover \mathcal{P}_{OB} .
- \mathcal{V} runs \mathcal{V}_{OB} , and then checks directly whether $\Delta(f_{\text{new}}, \mathsf{RS}[D', d]) \leq \delta$, accepting if and only if this check passes.

By itself, this protocol is not very useful because of the expensive verifier, but can fit nicely into the accumulator construction, where the expensive part of checking f_{new} is relegated to the decider.

Proposition 2. Let $\delta \in (0, \min\{1-\sqrt{\rho}, 1-\rho-1/\#D\})$. The IOP Π_{OB} described above has round-by-round soundness error

$$\varepsilon_{\mathsf{rbr}} = \max\{\varepsilon_{\mathsf{fold}}, \varepsilon_{\mathsf{out}}, \varepsilon_{\mathsf{corr}}, (1-\delta)^t\},\$$

where $\varepsilon_{\text{fold}}, \varepsilon_{\text{out}}, \varepsilon_{\text{corr}}$ are as defined in Lemmas 1, 2 and 4, respectively, t is the query parameter in the protocol, and δ is specified on i.

Proof. We start by fixing an index i, which fixes a certain Reed–Solomon code $\mathsf{RS}[D,d]$. Let \mathcal{L}_i be the language of statements for this particular i. We want to prove that there exists **DoomedSet** in the conditions of Definition 3. We construct **DoomedSet** to include the following four types of entries.

- (A) $(\mathbf{x}; \emptyset)$ such that $\mathbf{x} \notin \mathcal{L}_i$, i.e. f_1, \ldots, f_n do not have δ -correlated agreement.
- (B) $(\mathbf{x}; \alpha)$ such that:
 - \mathbf{x} is as in (A), and
 - $-\alpha$ does not lead to an *unlucky fold*. An unlucky fold is the event that $\Delta(\mathsf{Fold}_{\alpha}(f_1,\ldots,f_n),\mathsf{RS}[D,d]) \leq \delta.$
- (C) $(\mathbf{x}; \alpha || f_{\mathsf{fold}} || x_0)$ such that:
 - $-(\mathbf{x},\alpha)$ is as in (B), and
 - $-x_0$ does not lead to an *unlucky decoding*. An unlucky decoding is the event that $\exists u, u' \in \text{List}(f_{\text{fold}}, d, \delta)$ such that $u \neq u'$ and $u(x_0) = u'(x_0)$.

- (D) $(\mathbf{x}; \alpha || f_{\mathsf{fold}} || x_0 || y_0 || x_1, \dots, x_t)$ such that:
 - $(\mathbf{x}; \alpha || f_{\mathsf{fold}} || x_0)$ is as in (C), and
 - $-x_1, \ldots, x_t$ do not lead to an *unlucky spot check*. An unlucky spot check is the event that $\exists u \in \text{List}(f_{\text{fold}}, d, \delta)$ such that $\hat{u}(x_j) = y_j$ for all $j \in \{0, \ldots, t\}$.
- (E) $(\mathbf{x}; \alpha || f_{\mathsf{fold}} || x_0 || y_0 || x_1, \dots, x_t || r)$ such that:
 - $-(x; \alpha || f_{fold} || x_0 || y_0 || x_1, \dots, x_t)$ is as in (D), and
 - − r do not lead to an *unlucky degree correction*. An unlucky degree correction is the event that $\Delta(f_{\text{new}}, \text{RS}[D', d]) \leq \delta$.

Clearly, DoomedSet satisfies condition 1 from Definition 3, due to the inclusion of type-(A) entries.

We argue that full transcripts in **DoomedSet**, i.e. type-(E) entries, are always rejected. Indeed, because an unlucky degree correction does not happen,

$$\Delta(f_{\mathsf{new}}, \mathsf{RS}[D', d]) > \delta,$$

so the direct check on f_{new} will fail, and the verifier will reject. Therefore, condition 2 is also met. It just remains to argue that condition 3 is met, that is, doomed transcripts stay doomed with high probability.

- Type-(A) transcripts become type-(B) transcripts unless we have an unlucky fold, which happens with probability $\varepsilon_{\mathsf{fold}}$, due to Lemma 1.
- Type-(B) transcripts become type-(C) transcripts unless we have an unlucky out-of-domain check, which happen with probability ε_{out} , due to Lemma 2.
- Type-(C) transcripts become type-(D) transcripts unless we have an unlucky spot check, so we consider the probability of this event. Suppose that we have an unlucky spot check, i.e. $\exists u \in \text{List}(f_{\text{fold}}, d, \delta)$ such that $\hat{u}(x_j) = y_j$ for all $j \in \{0, \ldots, t\}$. At this point, observe that:

(i) An unlucky fold did not happen, so $\Delta(\mathsf{Fold}_{\alpha}(f_1,\ldots,f_n),\mathsf{RS}[D,d]) > \delta$.

(ii) An unlucky out-of-domain check did not happen, so *u* is unique.

Therefore, due to (ii), the probability of an unlucky spot check happening is bounded by

$$\Pr\left[\begin{array}{cc} \alpha \leftarrow \mathbb{F}, \\ x_0 \leftarrow \mathbb{F} \setminus D', \\ x_1, \dots, x_t \leftarrow D \end{array} : \hat{\mathsf{Fold}}_{\alpha}(f_1, \dots, f_n)(x_j) = \hat{u}(x_j) \quad \forall j = 1, \dots, t \right].$$

Moreover, (i) implies that $\operatorname{\mathsf{Fold}}_{\alpha}(f_1,\ldots,f_n)$ and $\hat{u}_{|D}$ only agree on a $(1-\delta)$ -fraction of the points in D at most, and therefore the probability of them agreeing on t random points $x_1,\ldots,x_t \leftarrow D$ is at most $(1-\delta)^t$.

- Type-(D) transcripts become type-(E) transcripts unless we have an unlucky degree correction. Because an unlucky spot check does not happen, for any $u \in \text{List}(f_{\text{fold}}, d, \delta)$, there exists $j \in \{1, \ldots, n\}$ such that $\hat{u}(x_i) \neq \text{Fold}_{\alpha}(f_1, \ldots, f_n)(x_i)$. Hence, by Lemma 3,

$$\Delta(f_{\mathsf{quot}}, \mathsf{RS}[D', d - (t+1)]) > \delta$$

Therefore, aplying Lemma 4 to $f_{\mathsf{new}} = \mathsf{DegCor}(d, r, f_{\mathsf{quot}}, d - (t+1))$, we have that

$$\Delta(f_{\mathsf{new}}, \mathsf{RS}[D', d]) > \delta$$

except with probability ε_{corr} . This completes the proof.

Remark 1. The out-of-domain check is necessary to reduce $\Pr[E_3]$ to the probability of $\operatorname{\mathsf{Fold}}_{\alpha}(f_1,\ldots,f_n)$ agreeing on t random points with a single codeword u. Without this requirement, we could have different $u \in \operatorname{List}(f_{\mathsf{fold}},d,\delta)$ that agree with $\operatorname{\mathsf{Fold}}_{\alpha}(f_1,\ldots,f_n)$ in different subsets of D.

4 NARKs from correlated HIOP

In this section, we often deal with non-interactive versions of protocols obtained using the BCS transform or its modifications. In this case, the prover computes the Merkle-tree root for every oracle message and uses it as a short commitment. For the sake of clarity, we will use \boxed{f} as shorthand for the part of the output of the non-interactive prover corresponding to a (possibly virtual) oracle \boxed{f} . In particular, \boxed{f} contains

- The Merkle-tree root $\mathsf{rt} = \mathsf{MT.Commit}(\mathsf{g}|_{\mathsf{D}})$ for some function $g: D \to \mathbb{F}$. If f is not virtual then g = f,

$$- (d^*, r, d) \text{ if } f = \mathsf{DegCor}(d^*, r, g, d), - (\mathbf{x}, \mathbf{y}) \text{ if } f = \mathsf{Quotient}(g, \mathbf{x}, \mathbf{y}).$$

We also denote by **Check** the verification that all value-position pairs of $[v_i, \mathsf{pos}_i]_{i=1}^t$ with the corresponding Merkle-tree paths $[\mathsf{ap}_i]_{i=1}^t$ are consistent with the description of the oracle.

Check($[v_i, \mathsf{pos}_i]_{i=1}^t, [\mathsf{ap}_i]_{i=1}^t, [f] \rightarrow 0/1$: 1. for $i = 1, \dots, t$: 2. Parse value $g_i = g(\mathsf{pos}_i)$ from ap_i . 3. Given g_i and [f], calculate $f(\mathsf{pos}_i)$. 4. $b_i = (f(\mathsf{pos}_i) = v_i) \land (\mathsf{MT.Check}([f], \mathsf{rt}, \mathsf{pos}_i, g_i, \mathsf{ap}_i) = 1)$. 5. return $\land_{i=1}^t b_i$.

To begin, we present a slight modification of transformation that allows us to compile a δ -correlated HIOP and IOPP into a classical HIOP (Theorem 2). The main difference is that we split the Verifier into two parts. The first one makes his final decision before the interactive part of the second one starts. This way, we can separate the part of the proof (in the non-interactive version) for independent verification. This transformation simplifies our construction of the split accumulator. Let $\delta \geq \delta_0$. **Definition 9.** The transformation $\mathsf{T}[\delta, \delta_0]$ takes as input a public coin δ -correlated HIOP $\Pi = (I, P, V)$ for indexed polynomial oracle relation $\mathcal{R} =$ $(i, x, w), HIOP \Pi_{CA} = (I_{CA}, P_{CA}, V_{CA})$ for polynomial oracle relation CoAgg and outputs a plain HIOP $(\mathcal{I}, \mathcal{P}, \mathcal{V})$ defined below.

- $-\mathcal{I}$ outputs encodings Π .I(i) and $i_{CA}(i)$, where the latter contains the parameters of a Reed-Solomon code $\mathsf{RS}[F, D, d]$, the proximity parameter δ_0 , and the number n of functions in correlated agreement.
- $-\mathcal{P}(i, x, w)$ is a pair of interactive algorithms $\mathcal{P}_1, \mathcal{P}_2$, where
 - \mathcal{P}_1 is the same as the prover Π .P,
 - \mathcal{P}_2 is the same as the prover Π_{CA} . P_{CA} .

First, the algorithm $\mathcal{P}_1(\mathbf{i}, \mathbf{x}, \mathbf{w})$ is executed. Let $\mathbf{f} = (f_1, \ldots, f_n)$ be the words on which the verifier would call the oracle $OCoAgg(\delta)$ during its final decision process. Then, the algorithm $\mathcal{P}_2(i_{\mathsf{CA}}, [\mathbf{f}], \mathbf{f})$ is executed.

- $-\mathcal{V}^{\mathcal{I}(i)}(\mathbf{x})$ is a pair of interactive algorithms $\mathcal{V}_1, \mathcal{V}_2$, where
 - \mathcal{V}_1 is the same as the verifier Π .V except that it does not call oracle OCoAgg. Instead, upon completion, it sends an additional "dummy" messaae.

• \mathcal{V}_2 is the same as the verifier $\Pi_{\mathsf{CA}}.\mathsf{V}_{\mathsf{CA}}.$ Verifier launches $\mathcal{V}_1^{\mathcal{I}(i)}(\mathbb{x})$, then $\mathcal{V}_2^{i_{\mathsf{CA}}}(\mathbf{f})$. \mathcal{V} accepts if and only if $\mathcal{V}_1 \wedge \mathcal{V}_2$.

If we applied the BCS transformation (Theorem 1) to the $T[\delta, \delta_0](\Pi, \Pi_{CA})$, the proof format would be as follows

$$\pi = \left((\mathsf{rt}_1, \dots, \mathsf{rt}_{\mathsf{k}_1}), (\mathsf{ap}_1, \dots, \mathsf{ap}_{\mathsf{q}_1}), \sigma_{k_1}, (\mathsf{rt}_1^{\mathsf{CA}}, \dots, \mathsf{rt}_{\mathsf{k}_2}^{\mathsf{CA}}), (\mathsf{ap}_1^{\mathsf{CA}}, \dots, \mathsf{ap}_{\mathsf{q}_2}^{\mathsf{CA}}), \sigma_{k_2}^{\mathsf{CA}}\right),$$

where k_1 and k_2 are the number of oracle messages sent by \mathcal{P}_1 and \mathcal{P}_2 , respectively, q_1 and q_2 are the number of requests to these oracles and the index made by \mathcal{V}_1 and \mathcal{V}_2 , respectively. Thanks to this transformation, the verifier has an intermediate Merkle-tree root σ_{k_1} , which allows after all k_1 rounds of Π to check the first part of the proof independently of the remaining part. We will reflect this in our modification of the BCS transformation (Definition 10).

Definition 10. The transformation BCST takes as input a public coin HIOP $\Pi' = T[\delta, \delta_0](\Pi, \Pi_{CA})$ and outputs the preprocessing non-interactive argument in the ROM $(\mathbf{I}, \mathbf{P}, \mathbf{V} = (\mathbf{V_1}, \mathbf{V_2}))$, defined below.

- $\mathbf{I}^{\mathcal{H}}(i) \rightarrow (\mathsf{pk}, \mathsf{vk}).$ The algorithm is the same as what we would get by applying the BCS transformation. For simplicity, we write the i_{CA} parameters directly into the verification vk and proving pk keys. We denote corresponding deterministic extraction algorithm as $Parse(vk/pk)) \rightarrow i_{CA}$.
- $-\mathbf{P}^{\mathcal{H}}(\mathsf{pk}, \mathbb{x}, \mathbb{w}) \rightarrow \pi = (\pi.\mathbb{x}, \pi.\mathbb{w}).$ We make the following changes compared to the prover obtained using the BCS transform.
 - If the prover sends several oracles in one round, a separate commitment is calculated for each in the non-interactive version.
 - The parameters for calculating the value of the virtual oracle at each point are written directly to the proof (degree, vectors for quotients, etc.)

Then the proof π has the form

$$\begin{split} \pi.\mathbb{x} &= \left((\mathsf{m}_1, \dots, \mathsf{m}_{\mathsf{k}_1}), (\mathsf{ap}_1, \dots, \mathsf{ap}_{\mathsf{q}_1}), \sigma_{k_1} \right), \\ \pi.\mathbb{w} &= \left((\mathsf{m}_1^{\mathsf{CA}}, \dots, \mathsf{m}_{\mathsf{k}_2}^{\mathsf{CA}}), (\mathsf{ap}_1^{\mathsf{CA}}, \dots, \mathsf{ap}_{\mathsf{q}_2}^{\mathsf{CA}}), \sigma_{k_2}^{\mathsf{CA}} \right), \end{split}$$

 k_1, k_2, q_1, q_2 are as described above, messages m_i, m_i^{CA} contain the roots of Merkle-trees and scalar values.

- $\mathbf{V}^{\mathcal{H}}(\mathsf{vk}, \mathbb{x}, \pi) = (\mathbf{V}_{1}^{\mathcal{H}}, \mathbf{V}_{2}^{\mathcal{H}})(\mathsf{vk}, \mathbb{x}, \pi) \rightarrow \{0, 1\}.$ We split the verifier that we obtained using the BCS transformation into two parts.
 - $\mathbf{V}_{1}^{\mathcal{H}}(\mathsf{vk}, \mathbb{x}, \pi.\mathbb{x})$ verifies the first part of the proof, makes a decision, and saves the state $aux = (f_1, \ldots, f_n, \sigma_{k_1})$. We denote the deterministic oracle extraction algorithm as $ParseDesc(vk, \pi.x)$.
 - $\mathbf{V}_{\mathbf{2}}^{\mathcal{H}}(\mathsf{aux},\mathsf{vk},\mathbb{x},\pi.\mathbb{w})$ uses the state to continue verifying the rest of the proof. The correctness of requests to functions f_i is checked using Check and the corresponding f_i .
- \mathbf{V} accepts if and only if
- $\begin{array}{l} 1. \ \mathbf{V}_{1}^{\mathcal{H}}(\mathsf{vk}, \mathbbm{x}, \pi. \mathbbm{x}) = 1 \\ 2. \ \mathbf{V}_{2}^{\mathcal{H}}(\mathsf{aux}, \mathsf{vk}, \mathbbm{x}, \pi. \mathbbm{y}) = 1, \ where \ \mathsf{aux} = (\texttt{ParseDesc}(\mathsf{vk}, \pi. \mathbbm{x}), \sigma_{k_{1}}) \end{array}$

Now, let us consider a trivial version of the proximity test. Although such a test is of no practical interest, it helps us conceptualize the split accumulation scheme. Let $\Pi_{TRV} = (I, P, V)$ is a HIOP for the polynomial oracle relation CoAgg (Section 2.4).

- I outputs $\mathrm{i}_{\mathsf{CA}},$ which contains the parameters of a Reed–Solomon code $\mathsf{RS}[F, D, d]$, the proximity parameter δ_0 , and the number n of functions in correlated agreement.
- V checks directly (by reading the oracle $[\mathbf{f}]$ entirely) whether $(i_{CA}, [\mathbf{f}], \mathbf{f}) \in$ $CoAgg(\delta_0)$, accepting if this check passes.

Suppose that we use the transformation T together with the HIOP Π_{TRV} for some δ_0 -correlated HIOP Π . Then, in the non-interactive version of the result

$$\mathsf{BCST}(\mathsf{T}[\delta, \delta_0](\mathsf{\Pi}, \mathsf{\Pi}_{\mathsf{TRV}})),$$

the second part of the proof π .w will contain only value-authentication path pairs $[v_i, \mathsf{ap}_i^{\mathsf{CA}}]_{i=1}^{n \cdot |D|}$. This is a consequence of the fact that the prover $\Pi_{\mathsf{TRV}}.\mathsf{P}$ does not send additional oracle messages and the verifier Π_{TRV} . V does not need additional randomness. The job of the verifier $\mathbf{V_2}$ is

- to check the authentication paths ap_i with respect to the f_1, \ldots, f_n contained in aux, and the oracle \mathcal{H} . We denote the deterministic values and authentication paths extraction algorithms as ParseEvaluations(vk, π .w) \rightarrow v_i and ParseAP(vk, π .w) \rightarrow ap_i, respectively. Then:

CheckAP(f, vk, π .w) $\rightarrow 0/1$: 1. $v_i \leftarrow ParseEvaluations(vk, \pi.w)$

- $\begin{array}{ll} 2. \ \mathsf{ap}_i \leftarrow \mathtt{ParseAP}(\mathsf{vk}, \pi.\texttt{w}) \\ 3. \ \mathbf{return} \ \mathtt{Check}([v_i, i], [\mathsf{ap}_i], f) \end{array}$
- to check that the resulting vector of values is δ_0 -close to the $\mathsf{RS}[\mathbb{F}, D, d]$, and make the final decision.

Therefore, **V**₂ only needs a simplified interface (without x and σ_{k_1}):

 $\mathbf{V}_{\mathbf{2}}^{\mathcal{H}}(\mathsf{aux}',\mathsf{vk},\pi.\mathbb{w}), \text{ where } \mathsf{aux}' = \mathsf{ParseDesc}(\mathsf{vk},\pi.\mathbb{x}).$

Since we only check for proximity to the code, some values may differ from the expected ones. Therefore, we will also allow some authentication paths to be missing. To reflect this, we will introduce another modification of the BCS transformation (Definition 11) for the special case of Π_{TRV} .

Definition 11. The transformation BCST^{\perp} takes as input a public coin HIOP $\Pi' = \mathsf{T}[\delta, \delta_0](\Pi, \Pi_{\mathsf{TRV}})$ and outputs the preprocessing non-interactive argument in the ROM $(\mathbf{I}, \mathbf{P}, \mathbf{V} = (\mathbf{V_1}, \mathbf{V_2}))$. The transformation BCST^{\perp} is identical to BCST except for the algorithm $\mathbf{V_2}$, which can now accept the symbol \perp instead of the authentication path ap_i . In this case, when checking the proximity to the $\mathsf{RS}[\mathbb{F}, D, d]$, it considers the corresponding value to be \perp .

Let

$$\Pi = \mathsf{BCST}[\delta, \delta_0](\mathsf{T}(\mathsf{\Pi}_0, \mathsf{\Pi}_{\mathsf{TRV}})),$$
$$\Pi^{\perp} = \mathsf{BCST}^{\perp}(\mathsf{T}[\delta, \delta_0](\mathsf{\Pi}_0, \mathsf{\Pi}_{\mathsf{TRV}}))$$

If Π is knowldge sound then Π^{\perp} is knowledge sound.

Finally, let us consider the last ingredient. We denote by $OCoAgg^{(k)}$ the oracle for the verification algorithm of the correlation agreement for a set of k functions. Then, we present a transformation from a δ -correlated HIOP, during which the verifier calls $OCoAgg^{(n)}$, to a δ -correlated HIOPk during which the verifier calls $OCoAgg^{(1)}$.

Definition 12. The transformation B takes as input a public coin δ -correlated HIOP $\Pi = (I, P, V^{OCoAgg^{(n)}})$ for indexed polynomial oracle relation $\mathcal{R} = (i, x, w)$ and outputs another δ -correlated HIOP $\Pi_B = (I_B, P_B, V_B^{OCoAgg^{(1)}})$ for the same relation \mathcal{R} . Let $OB = (\mathcal{P}_{OB}, \mathcal{V}_{OB})$ be as defined in Section 3.

- I_{B} is same as the indexer $\mathsf{I},$
- $\mathsf{P}_{\mathsf{B}}(\mathfrak{i}, \mathfrak{x}, \mathfrak{w})$ is a pair of interactive algorithms $\mathcal{P}_1, \mathcal{P}_2$, where
 - \mathcal{P}_1 is the same as the prover Π .P,
 - \mathcal{P}_2 is the same as the prover $OB.\mathcal{P}_{OB}$.

First, the algorithm $\mathcal{P}_1(\mathfrak{i}, \mathfrak{x}, \mathfrak{w})$ is executed. Let $\mathbf{f} = (f_1, \ldots, f_n)$ be the words on which the verifier would call the oracle $\mathsf{OCoAgg}^{(n)}(\delta)$ during its final decision process. Then, the algorithm $\mathcal{P}_2(\mathfrak{i}_{\mathsf{CA}}, [\mathbf{f}], \mathbf{f})$ is executed.

 $- V_{\mathsf{B}}^{\mathcal{I}(i),\mathsf{OCoAgg}^{(1)}}(\mathbb{x})$ is a pair of interactive algorithms $\mathcal{V}_1, \mathcal{V}_2$, where

- V₁ is the same as verifier Π.V except that it does not call oracle OCoAgg. Instead, upon completion, it sends an additional "dummy" message.
- \mathcal{V}_2 is the same as verifier OB. \mathcal{V}_{OB} , except that, upon completion, \mathcal{V}_2 queries OCoAgg⁽¹⁾(f_{new}).

The verifier launches $\mathcal{V}_1^{\mathcal{I}(\mathfrak{i})}(\mathbb{x})$, then $\mathcal{V}_2^{\mathfrak{i}_{\mathsf{CA}}}(\mathbf{f})$. \mathcal{V} accepts if and only if $\mathcal{V}_1 \wedge \mathcal{V}_2$.

Let Π be a RBR knowledge sound δ -correlated HIOP for an indexed polynomial oracle relation $\mathcal{R} = (i, x, w)$. Then $\mathsf{B}(\Pi)$ is a RBR knowledge sound δ -correlated HIOP for the relation \mathcal{R} .

5 Split accumulation and PCD

Let us recall our notations.

- $ParseDesc(vk/pk, \pi.x)$ parses the proof and outputs a description f for which the proximity test is performed.
- ParseEvaluation(pk, π .w) and ParseAP(pk, π .w) parse the proof and output a vector of evaluations v_i and corresponding auth paths ap_i , respectively.
- CheckAP([f], pk, π . w) parses the proof and verifies authentication paths with respect to [f].

Let Π be a RBR knowledge sound δ -correlated HIOP for an indexed regular (non-oracle) relation $\mathcal{R} = (i, x, w)$ and

$$\mathsf{NARK} = \mathsf{BCST}^{\perp}(\mathsf{T}[\delta, 0](\mathsf{B}(\mathsf{\Pi}), \mathsf{\Pi}_{\mathsf{TRV}})) = (\mathsf{I}, \mathsf{P}, \mathsf{V} = (\mathsf{V}_1, \mathsf{V}_2)).$$

In this section, we build a split accumulation scheme SA for the non-interactive argument system NARK. We will use the relation $\mathcal{R}_{\mathcal{V}}$ defined below:

$$\mathcal{R}_{\mathcal{V}} = \left\{ \begin{pmatrix} \mathsf{qi} \\ \mathsf{qx} \\ \mathsf{qw} \end{pmatrix} = \begin{pmatrix} \mathsf{i} \\ (\mathbb{x}, \pi.\mathbb{x}) \\ \pi.\mathbb{w} \end{pmatrix} \mid \frac{(\mathsf{pk}_{\mathsf{NARK}}, \mathsf{vk}_{\mathsf{NARK}}) \leftarrow \mathsf{NARK}.\mathsf{I}^{\mathcal{H}}(\mathsf{i}),}{\mathsf{NARK}.\mathsf{V}^{\mathcal{H}}(\mathsf{vk}_{\mathsf{NARK}}, \mathbb{x}, (\pi.\mathbb{x}, \pi.\mathbb{w})) = 1} \right\}.$$

We will also define a non-interactive version of the oracle batching protocol, a key block in our design.

NOB = BCST^{$$\perp$$}(T[δ , 0](OB, Π_{TRV})).

The accumulator is represented by a short part acc.x, containing the description of the oracle f, and a witness part acc.w, including authentication paths to the vector of the evaluations of function f. In practice, all the authentication paths in witness part can be represented by a single hash code corresponding to the root of the Merkle-tree. The introduced notations make calls ParseDesc(acc.x) and ParseEvaluation(acc.w) legitimate.

Formally, the split accumulation scheme $\mathsf{S}\mathsf{A}$ is represented by the following algorithms.

- $\mathsf{SA}.\mathbf{I}^{\mathcal{H}}(\mathsf{qi}) \rightarrow (\mathsf{pk}_{\mathsf{SA}},\mathsf{vk}_{\mathsf{SA}},\mathsf{dk}_{\mathsf{SA}}).$
 - 1. $(\mathsf{pk}_{\mathsf{NARK}}, \mathsf{vk}_{\mathsf{NARK}}) \leftarrow \mathsf{NARK}.\mathsf{I}^{\mathcal{H}}(\mathsf{qi})$
 - 2. Set i_{NOB}
 - (a) $i_{NOB} \leftarrow Parse(vk_{NARK})$. Note that we change the number of functions for a correlated agreement check from 1 to n + m.
 - 3. $(\mathsf{pk}_{\mathsf{NOB}}, \mathsf{vk}_{\mathsf{NOB}}) \leftarrow \mathsf{NOB}.\mathsf{I}^{\mathcal{H}}(\mathfrak{i}_{\mathsf{NOB}})$
 - 4. $pk_{SA} = pk_{NARK} || pk_{NOB}$
 - 5. $vk_{SA} = vk_{NARK} ||vk_{NOB}|$
 - 6. $dk_{SA} = vk_{NOB}$

$$- \mathsf{SA}.\mathbf{P}^{\mathcal{H}}(\mathsf{pk}_{\mathsf{SA}}, (\mathsf{qx}_i, \mathsf{qw}_i)_{i=1}^n, (\mathsf{acc}_j)_{j=1}^m) \to (\mathsf{acc} = (\mathsf{acc}.\mathbb{X}, \mathsf{acc}.\mathbb{W}), \pi_{\mathsf{acc}})$$

- 1. $(\mathsf{pk}_{\mathsf{NARK}},\mathsf{pk}_{\mathsf{NOB}}) \leftarrow \mathtt{Parse}(\mathsf{pk}_{\mathsf{SA}})$
- 2. for $i \in [n]$
 - (a) $((\mathbf{x}_i, \pi_i.\mathbf{x}), \pi_i.\mathbf{w}) \leftarrow \mathsf{Parse}(\mathsf{qx}_i, \mathsf{qw}_i)$
 - (b) $f_i \leftarrow \texttt{ParseDesc}(\mathsf{pk}_{\mathsf{NARK}}, \pi_i.\mathbb{x})$
 - (c) $f_i \leftarrow \text{ParseEvaluation}(\mathsf{pk}_{\mathsf{NARK}}, \pi_i.\mathbb{W})$
- 3. for $j \in [m]$
 - (a) $f_{i+j} \leftarrow \texttt{ParseDesc}(\mathsf{pk}_{\mathsf{SA}}, \mathsf{acc}_j.\mathbb{X})$
 - (b) $\overbrace{f_{n+j}} \leftarrow \texttt{ParseEvaluation}(\mathsf{pk}_{\mathsf{SA}}, \mathsf{acc}_j. \mathbb{W})$
- 4. $\mathbf{x}' = f_1, \dots, f_{n+m}$
- 5. $w' = (f_1, \dots, f_{n+m})$
- 6. $(\pi_{NOB}.\mathfrak{X}, \pi_{NOB}.\mathfrak{W}) \leftarrow NOB.P^{\mathcal{H}}(\mathsf{pk}_{NOB}, \mathfrak{X}', \mathfrak{W}')$
- 7. acc.x $\leftarrow \texttt{ParseDesc}(\mathsf{pk}_{\mathsf{NOB}}, \pi_{\mathsf{NOB}}.\mathtt{x})$
- 8. acc. $\mathbb{W} \leftarrow \pi_{\mathsf{NOB}}.\mathbb{W}$
- 9. $\pi_{\text{acc}} = \pi_{\text{NOB}}.\mathbb{X}$
- SA. $\mathbf{V}^{\mathcal{H}}(\mathsf{vk}_{\mathsf{SA}}, (\mathsf{qx}_i)_{i=1}^n, (\mathsf{acc}_j.\mathbb{x})_{j=1}^m, \mathsf{acc.}\mathbb{x}, \pi_{\mathsf{acc}}) \to 0/1.$ 1. $(\mathsf{vk}_{\mathsf{NARK}}, \mathsf{vk}_{\mathsf{NOB}}) \leftarrow \mathsf{Parse}(\mathsf{vk}_{\mathsf{SA}})$ 2. for $i \in [n]$
 - 2. IOI $i \in [n]$
 - (a) $(\mathbf{x}_i, \pi_i.\mathbf{x}) \leftarrow \mathsf{Parse}(\mathsf{qx}_i)$
 - (b) $v_i \leftarrow \mathsf{NARK}.\mathsf{V}_1^{\mathcal{H}}(\mathsf{vk}_{\mathsf{NARK}}, \mathbb{x}_i, \pi_i.\mathbb{x})$
 - (c) $f_i \leftarrow \texttt{ParseDesc}(\mathsf{vk}_{\mathsf{NARK}}, \pi_i.\mathbb{X})$
 - 3. for $j \in [m]$
 - (a) $f_{n+j} \leftarrow \texttt{ParseDesc}(\mathsf{vk}_{\mathsf{SA}}, \mathsf{acc}_j.\mathbb{X})$
 - 4. $\mathbf{x}' = f_1, \dots, f_{n+m}$
 - 5. $v_{n+1} \leftarrow \text{NOB.V}_1^{\mathcal{H}}(\mathsf{vk}_{\mathsf{NOB}}, \mathbb{x}', \pi_{\mathsf{acc}})$
 - $6. \ v_{n+2} = (\texttt{ParseDesc}(\mathsf{vk}_{\mathsf{SA}}, \mathsf{acc}.\mathtt{x}) == \texttt{ParseDesc}(\mathsf{vk}_{\mathsf{NOB}}, \pi_{\mathsf{acc}}))$
 - 7. return $\bigwedge_{i=1}^{n+2} v_i$
- SA. $\mathbf{D}^{\mathcal{H}}(\mathsf{dk}_{\mathsf{SA}},\mathsf{acc}) \to 0/1.$
 - 1. $\mathsf{vk}_{\mathsf{NOB}} \leftarrow \mathsf{Parse}(\mathsf{dk}_{\mathsf{SA}})$
 - 2. $|f| \leftarrow \texttt{ParseDesc}(\texttt{acc}.\texttt{x})$
 - 3. $v \leftarrow \mathsf{NOB}.\mathsf{V}_2^{\mathcal{H}}([f], \mathsf{vk}_{\mathsf{NOB}}, \mathsf{acc}.\mathbb{w})$

4. return \boldsymbol{v}

Proposition 3. SA is complete.

Proof. We will that the probability

$$\Pr \begin{bmatrix} (\mathsf{qi},\mathsf{qx}_i,\mathsf{qw}_i) \in \mathcal{R}_{\mathcal{V}} \ \forall i \in [n] \\ 1 \leftarrow \mathsf{SA}.\mathbf{D}^{\mathcal{H}}(\mathsf{dk}_{\mathsf{SA}},\mathsf{acc}_j) \ \forall j \in [m] \\ \downarrow \\ \begin{pmatrix} \mathsf{qk}_{\mathsf{SA}},\mathsf{vk}_{\mathsf{SA}},\mathsf{dk}_{\mathsf{SA}} \end{pmatrix} \leftarrow \mathsf{SA}.\mathbf{I}^{\mathcal{H}}(\mathsf{qi}) \\ \begin{pmatrix} \mathsf{qk}_{\mathsf{SA}}, \\ (\mathsf{qx}_i,\mathsf{qw}_i)_{i=1}^n, \\ (\mathsf{acc}_j)_{j=1}^m \end{pmatrix} : \\ 1 \leftarrow \mathsf{SA}.\mathbf{V}^{\mathcal{H}} \begin{pmatrix} \mathsf{vk}_{\mathsf{SA}}, \\ (\mathsf{qx}_i)_{i=1}^n, \\ (\mathsf{acc}_j.\mathbb{X})_{j=1}^m, \\ \mathsf{acc}.\mathbb{X}, \pi_{\mathsf{acc}} \end{pmatrix} \\ 1 \leftarrow \mathsf{SA}.\mathbf{D}^{\mathcal{H}}(\mathsf{dk}_{\mathsf{SA}},\mathsf{acc}) \end{bmatrix}$$

is equal to 1. $\forall i \in [n], \forall j \in [m]$

$$\begin{cases} (\mathsf{qi},\mathsf{qx}_i,\mathsf{qw}_i) \in \mathcal{R}_{\mathcal{V}}, \\ \mathsf{SA}.\mathbf{D}^{\mathcal{H}}(\mathsf{dk}_{\mathsf{SA}},\mathsf{acc}_j) = 1 \end{cases} \Rightarrow \begin{cases} \mathsf{NARK}.\mathsf{V}_2^{\mathcal{H}}([f_i],\mathsf{vk}_{\mathsf{NARK}},\pi_i.\mathbb{w}) = 1, \\ \mathsf{NOB}.\mathsf{V}_2^{\mathcal{H}}([f_{n+j}],\mathsf{vk}_{\mathsf{NOB}},\mathsf{acc}_j.\mathbb{w}) = 1, \end{cases}$$

where

$$\begin{array}{l} - \ (\mathsf{vk}_{\mathsf{NARK}}, \mathsf{vk}_{\mathsf{NOB}}) \leftarrow \mathsf{Parse}(\mathsf{vk}_{\mathsf{SA}}) \\ - \ (\mathsf{pk}_{\mathsf{NARK}}, \mathsf{pk}_{\mathsf{NOB}}) \leftarrow \mathsf{Parse}(\mathsf{pk}_{\mathsf{SA}}) \\ - \ ((\mathbb{x}_i, \pi_i.\mathbb{x}), \pi_i.\mathbb{w}) \leftarrow \mathsf{Parse}(\mathsf{qx}_i, \mathsf{qw}_i) \ \forall i \in [n] \\ - \ f_i \leftarrow \mathsf{ParseDesc}(\mathsf{vk}_{\mathsf{NARK}}, \pi_i.\mathbb{w}) \ \forall i \in [n] \\ - \ f_i \leftarrow \mathsf{ParseEvaluation}(\mathsf{pk}_{\mathsf{NARK}}, \pi_i.\mathbb{w}) \ \forall i \in [n] \\ - \ f_{n+j} \leftarrow \mathsf{ParseDesc}(\mathsf{pk}_{\mathsf{SA}}, \mathsf{acc}_j.\mathbb{w}) \ \forall j \in [m] \\ - \ f_{n+j} \leftarrow \mathsf{ParseEvaluation}(\mathsf{pk}_{\mathsf{SA}}, \mathsf{acc}_j.\mathbb{w}) \ \forall j \in [m] \end{array}$$

In particular, this means that

$$(i_{\mathsf{NOB}}, \mathbf{f_i}) \in \mathsf{CoAgg}(0),$$

where $i_{\mathsf{NOB}} \leftarrow \mathsf{Parse}(\mathsf{vk}_{\mathsf{NARK}})$. And with probability 1,

$$\mathsf{NOB.V}_2^{\mathcal{H}}([g], \mathsf{vk}_{\mathsf{NOB}}, \pi_{\mathsf{NOB}}. \mathbb{W}) = 1,$$

where

$$\begin{array}{l} - \mathbf{x}' = \overbrace{f_1, \ldots, f_{n+m}}, \\ - \mathbf{w}' = (f_1, \ldots, f_{n+m}), \\ - \operatorname{NOB.P}^{\mathcal{H}}(\mathsf{pk}_{\mathsf{NOB}}, \mathbf{x}', \mathbf{w}') \to (\pi_{\mathsf{NOB}}.\mathbf{x}, \pi_{\mathsf{NOB}}.\mathbf{w}), \\ - [g] \leftarrow \operatorname{ParseDesc}(\mathsf{pk}_{\mathsf{NOB}}, \pi_{\mathsf{NOB}}.\mathbf{x}) = \operatorname{ParseDesc}(\mathsf{acc.x}). \end{array}$$

In other words, $SA.D^{\mathcal{H}}(dk_{SA}, acc) = 1$. We have already shown that

$$\begin{cases} \forall i \in [n] \text{ NARK.V}_{1}^{\mathcal{H}}(\mathsf{vk}_{\mathsf{NARK}}, \mathbb{x}_{i}, \pi_{i}.\mathbb{x}) = 1, \\ \mathsf{NOB.V}_{1}^{\mathcal{H}}(\mathsf{vk}_{\mathsf{NOB}}, \mathbb{x}', \pi_{\mathsf{NOB}}.\mathbb{x}) = 1. \end{cases}$$

This means that

$$\mathsf{SA}.\mathbf{V}^{\mathcal{H}}\left(\mathsf{vk}_{\mathsf{SA}},(\mathsf{qx}_{i})_{i=1}^{n},(\mathsf{acc}_{j}.\mathtt{x})_{j=1}^{m},\mathsf{acc}.\mathtt{x},\pi_{\mathsf{acc}}\right)=1$$

with probability 1.

Following [BMNW24a], we also show the knowledge soundness with respect to $\delta_0 = \delta$. Namely, we consider the specified property relative to the following systems

$$\begin{split} \mathsf{NARK}^{\perp} &= \mathsf{BCST}^{\perp}(\mathsf{T}[\delta,\delta](\mathsf{B}(\mathsf{\Pi}),\mathsf{\Pi}_{\mathsf{TRV}})), \\ \mathsf{NOB}^{\perp} &= \mathsf{BCST}^{\perp}(\mathsf{T}[\delta,\delta](\mathsf{OB},\mathsf{\Pi}_{\mathsf{TRV}})). \end{split}$$

Theorem 3. SA is knowledge sound with respect to NARK^{\perp} and NOB^{\perp}.

Proof. We need to show that the following probability:

$$\Pr \begin{bmatrix} \mathsf{ai} \leftarrow \mathcal{D}(1^{\lambda}) & 1 \leftarrow \mathsf{SA}.\mathbf{V}^{\mathcal{H}} \begin{pmatrix} \mathsf{vk}_{\mathsf{SA}}, (\mathsf{qx}_{i})_{i=1}^{n}, \\ (\mathsf{acc}_{j}.\mathbb{x})_{j=1}^{m}, \\ \mathsf{acc}, \pi_{\mathsf{acc}} \end{pmatrix} \leftarrow \tilde{\mathcal{P}}^{\mathcal{H}}(\mathsf{ai}) & 1 \leftarrow \mathsf{SA}.\mathbf{V}^{\mathcal{H}} \begin{pmatrix} \mathsf{vk}_{\mathsf{SA}}, (\mathsf{qx}_{i})_{i=1}^{n}, \\ (\mathsf{acc}_{j}.\mathbb{x})_{j=1}^{m}, \\ \mathsf{acc}, \pi_{\mathsf{acc}} \end{pmatrix} \leftarrow \tilde{\mathcal{P}}^{\mathcal{H}}(\mathsf{ai}) & 1 \leftarrow \mathsf{SA}.\mathbf{D}^{\mathcal{H}}(\mathsf{dk}_{\mathsf{SA}}, \mathsf{acc}) \\ \begin{pmatrix} (\mathsf{qw}_{i})_{i=1}^{n}, \\ (\mathsf{acc}_{j}.\mathbb{w})_{j=1}^{m} \end{pmatrix} \leftarrow \mathsf{E}^{\tilde{\mathcal{P}}, \mathcal{H}}(\mathsf{ai}) & \\ (\mathsf{pk}_{\mathsf{SA}}, \mathsf{vk}_{\mathsf{SA}}, \mathsf{dk}_{\mathsf{SA}}) \leftarrow \mathsf{SA}.\mathbf{I}^{\mathcal{H}}(\mathsf{qi}) & 1 \leftarrow \mathsf{SA}.\mathbf{D}^{\mathcal{H}}(\mathsf{dk}, \mathsf{acc}_{j}) \; \forall j \in [m] \\ 1 \leftarrow \mathsf{SA}.\mathbf{D}^{\mathcal{H}}(\mathsf{dk}, \mathsf{acc}_{j}) \; \forall j \in [m] \end{bmatrix}$$

is negligibly close to 1. It is easy to see that

$$\mathsf{NOB}^{\perp}.\mathsf{V}^{\mathcal{H}}(\mathsf{vk}_{\mathsf{NOB}}, \mathbb{x}', (\pi_{\mathsf{acc}}, \mathsf{acc}.\mathbb{w})) = 1,$$

where

$$\begin{array}{l} - \ (\mathsf{vk}_{\mathsf{NARK}}, \mathsf{vk}_{\mathsf{NOB}}) \leftarrow \mathsf{Parse}(\mathsf{vk}_{\mathsf{SA}}), \\ - \ (\mathsf{pk}_{\mathsf{NARK}}, \mathsf{pk}_{\mathsf{NOB}}) \leftarrow \mathsf{Parse}(\mathsf{pk}_{\mathsf{SA}}), \\ - \ (\mathtt{x}_i, \pi_i. \mathtt{x}) \leftarrow \mathsf{Parse}(\mathsf{qx}_i) \forall i \in [n], \\ - \ f_i \leftarrow \mathsf{ParseDesc}(\mathsf{vk}_{\mathsf{NARK}}, \pi_i. \mathtt{x}) \forall i \in [n], \\ - \ f_{n+j} \leftarrow \mathsf{ParseDesc}(\mathsf{pk}_{\mathsf{SA}}, \mathsf{acc}_j. \mathtt{x}) \forall j \in [m], \\ - \ \mathtt{x}' = \ f_1, \dots, f_{n+m} \end{array}$$

Then, except with probability at most $\kappa^{\mathsf{NOB}^{\perp}},$ we have that

$$\mathsf{E}^{P,\mathcal{H}}_{\mathsf{NOB}^{\perp}} \to \hat{\pi}_1, \dots, \hat{\pi}_{n+m},$$

where $\mathsf{E}_{\mathsf{NOB}^{\perp}}$ is a knowledge extractor for NOB^{\perp} , and

$$extsf{CheckAP}(f_i], \mathsf{pk}_{\mathsf{NOB}}, \hat{\pi}_i) = \mathsf{true} \; \forall i \in [n+m].$$

This means that

$$\mathsf{SA}.\mathbf{D}^{\mathcal{H}}(\mathsf{dk}_{\mathsf{SA}}, (\mathsf{acc}_{j}.\mathbb{x}, \hat{\pi}_{j})) = 1 \text{ for } j = i + 1, \dots, n + m,$$
$$\mathsf{NARK}^{\perp}.\mathsf{V}^{\mathcal{H}}(\mathsf{vk}_{\mathsf{NARK}}, \mathbb{x}_{i}, (\pi_{i}.\mathbb{x}, \hat{\pi}_{i})) = 1, \forall i \in [n].$$

Thus, the knowledge soundness error is equal to $\kappa^{NOB^{\perp}}$.

Given NARK and the split accumulation scheme SA, we can use [BCL⁺21, Theorem 5.3] to build a PCD scheme. Recall that PCD allows us to show the correctness of a distributed computation. More precisely, given a compliance predicate ϕ , PCD enables untrusted provers to demonstrate that if a computational node uses local input data z_{loc} , received messages z_1, \ldots, z_t , and outputs z_{out} , then

$$\phi(z_{\mathsf{out}}, z_{\mathsf{loc}}, z_1, \dots, z_t) = 1.$$

Informally speaking, the PCD prover takes as input $z_{\text{loc}}, z_{\text{out}}$ and messages $(z_i)_{i=1}^t$ augmented with corresponding PCD proofs $(\pi_i^{\text{PCD}})_{i=1}^t$, where

$$\pi_i^{\mathsf{PCD}} = ((\pi_i.\mathbb{X}, \pi_i.\mathbb{W}), (\mathsf{acc}_i.\mathbb{X}, \mathsf{acc}_i.\mathbb{W})).$$

It accumulates $((z_i, \pi_i.\mathbf{x}), \pi_i.\mathbf{w}, (\mathsf{acc}_i.\mathbf{x}, \mathsf{acc}_i.\mathbf{w}))_{i=1}^t$ to obtain a new accumulator **acc** and accumulation proof π_{acc} . Finally, the prover uses NARK to generate a proof π_{NARK} for the following statement (presented as a circuit):

1. $\phi(z_{\mathsf{out}}, z_{\mathsf{loc}}, (z_i)_{i=1}^t) = 1$, 2. $\mathsf{SA.V}((z_i, \pi_i.\mathbb{X})_{i=1}^t, (\mathsf{acc}_i.\mathbb{X})_{i=1}^t, \mathsf{acc.}\mathbb{X}, \pi_{\mathsf{acc}}) = 1$. The PCD prover outputs the new proof $\pi^{\mathsf{PCD}} = (\pi_{\mathsf{NARK}}, \mathsf{acc})$.

Proof size The size of the PCD proof is largely determined by the value of $|\pi.w|+|acc.w|$ and, for many practical constructions, is comparable to the size of the recursive circuit. Generally, this requires provers to send significant amounts of data and complicates parallelization. Due to the fact that we use the OB protocol twice, in the accumulator scheme and in the NARK, we get a much smaller size of the PCD proof. In particular, for a Plonkish circuit represented by a matrix of $N \times M$ elements, the proof size will be proportional to one column, i.e., N elements. In practice, this results in a smaller proof by several orders of magnitude.

Decider efficiency The PCD verifier takes as input a message z, a proof π^{PCD} , and outputs a decision bit (using NARK's verifier and SA's decider algorithms). In practice, we can take an additional step to accumulate π_{NARK} and acc and get a new accumulator $\operatorname{acc}^{final}$ and accumulation proof $\pi_{\operatorname{acc}}^{final}$. In addition, we can use algorithms such as FRI or STIR to obtain succinct proof π_{PRX} of the $\operatorname{acc}^{final}$'s proximity to the RS.

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