A Note on Efficient Computation of the Multilinear Extension

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July 6, 2024

Abstract

The multilinear extension of an *m*-variate function $f : \{0,1\}^m \to \mathbb{F}$, relative to a finite field \mathbb{F} , is the unique multilinear polynomial $\hat{f} : \mathbb{F}^m \to \mathbb{F}$ that agrees with f on inputs in $\{0,1\}^m$.

In this note we show how, given oracle access to $f : \{0,1\}^m \to \mathbb{F}$ and a point $z \in \mathbb{F}^m$, to compute $\hat{f}(z)$ using $O(2^m)$ field operations and only O(m) space. This improves on a previous algorithm due to Vu *et al.* (SP, 2013), which similarly uses $O(2^m)$ field operations but requires $O(2^m)$ space. Furthermore, the number of field additions in our algorithm is about half of that in Vu *et al.*'s algorithm, whereas the number of multiplications is the same up to small additive terms.

1 Introduction

The multilinear extension is a method for encoding the truth table of a function in a redundant form that is extremely useful in many applications. In particular, multilinear extensions have proven to be extremely useful in the development of efficient proof-systems. We refer the reader to the recent book by Thaler [Tha22], for further details on the key role that multilinear extensions play in these applications.

The Multilinear Extension. Let \mathbb{F} be a finite field and $m \in \mathbb{N}$ be an integer. For every function $f : \{0,1\}^m \to \mathbb{F}$ there exists a unique multilinear polynomial $\hat{f} : \mathbb{F}^m \to \mathbb{F}$ that agrees with f on $\{0,1\}^m$. We refer to \hat{f} as the multilinear extension of f.

The multilinear extension f can be expressed explicitly as:

$$\hat{f}(z) = \sum_{b \in \{0,1\}^m} eq(z,b) \cdot f(b),$$
(1)

where $eq(z, b) = \prod_{i \in [m]} eq_1(z_i, b_i)$ and $eq_1(z_i, b_i) = z_i \cdot b_i + (1 - z_i) \cdot (1 - b_i)$.

Efficient Evaluation of the Multilinear Extension. Consider the following basic computational task: given as input $z \in \mathbb{F}^m$ and the truth table of $f : \{0,1\}^m \to \mathbb{F}$, output $\hat{f}(z)$. Prior to the current note, there were two main methods for performing this computation:

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- 1. A direct method, described in [CTY11] (see also [Tha22, Lemma 3.7]) iterates over all indices $b \in \{0,1\}^m$ and for each index computes the contribution to the sum in Eq. (1). This involves computing the sequence of values $(eq(z,b))_{b\in\{0,1\}^m}$. Each value in this sequence can be generated using O(m) arithmetic operations, which leads to an overall cost of $O(m \cdot 2^m)$ field operations.
- 2. An alternate method, due to [VSBW13] (see also [Tha22, Lemma 3.8]), observes that the values eq(z, b)'s in the foregoing sequence are in fact related, and uses a memoization approach to generate them. Using their approach to compute $\hat{f}(z)$ requires 2^{m+1} multiplications and 2^{m+1} additions.¹ This memoization technique however also requires $O(2^m)$ space, in contrast to the "direct" approach that uses O(m) space. Their approach is also incompatible with some applications, such as in the context of streaming algorithms [CTY11, CMT12].

Our Result. We describe a new approach for computing the multilinear extension, which improves on both aforementioned results – it requires only 2^{m+1} multiplications, 2^m additions (and an additional O(m) field operations, including inversions) and uses only O(m) space. Thus, the amount of space used is exponentially smaller than the [VSBW13] approach and the number of additions is about half. In a nutshell, our approach follows the direct approach but utilizes the relations between the sequence of values eq(z, b), to generate it more efficiently on-the-fly and while leveraging a particularly convenient order of the b's.

We remark that our algorithm can be used in a streaming setting (i.e., when the values of f are given as a stream of data), as long as the stream is given in a specific order which we describe below.

1.1 Applications and Related Works

We note that, typically, proof-systems have a high space usage regardless of the computation of the multilinear extensions. In such cases, the *asymptotic* improvement in space that we achieve is lost. Still, we believe that even in these contexts, our approach may be concretely beneficial both due to the concrete space saving and, in contexts in which it is a bottleneck, also the saving in the number of additions.

In particular, proof-systems based on multilinear techniques, usually use an efficient implementations of the sumcheck protocol [Tha13, XZZ⁺19]. This implementation uses 2^m space regardless of the computation of the multilinear extension. Recent works by Setty *et al.* [STW23, Appendix G] and Chiesa *et al.* [CFFZ24] show a time-space tradeoff for the sumcheck protocol ([STW23] actually focus on the harder case of sparse polynomials). Still, even combining their techniques with our approach it is not unclear how to construct a sumcheck prover that runs simultaneously in linear-time and logarithmic space. Recent works show other optimizations to the sumcheck prover [Che23, Gru24, BDT24, DT24], focusing on use cases that arise in practice. Their techniques could potentially be combined with our approach.

A recent line of work, [BTVW14, BHR⁺20, BHR⁺21, BCHO22, FPP24, NDC⁺24] has studied proof-systems in which the prover is space-efficient. In this context we believe that our algorithm may be a helpful also as a step towards achieving new asymptotic results.

¹Actually, the description in [VSBW13] uses $3 \cdot 2^m$ multiplications and 2^m additions, but a known optimization (described, for example, in [DT24, Algorithm 1]) converts 2^m of the multiplications to be additions.

Setty *et al.* [STW23, Page 13] propose a way to obtain time-space tradeoff for computing the multilinear extension, that is geared towards sparse multilinear polynomials. In the general case though, it requires either a polynomial amount of space or super-linear time.

Lastly, we note that an unpublished observation due to Victor Vu from 2013 [Tha24], gives a similar space savings to our approach but requires double the number of multiplications. Loosely speaking, his approach is similar to the one based on the lexicographic order described in the first item of Section 2.1. We describe Vu's approach in Appendix A.

2 Computing the Multilinear Extension Efficiently in Small Space

Proposition 1. Given as input $z \in \mathbb{F}^m$, the sequence of values $(eq(z, b))_{b \in \{0,1\}^m}$ can be generated in time $O(2^m)$ and space O(m). In more detail, the algorithm performs exactly 2^m field multiplications and an additional O(m) additions, multiplications and inversions.

Proof. Assume first that all of the entries of z are not in $\{0, 1\}$ (later we shall show how to handle the general case).

We generate the sequence according to the *Gray code* ordering of the integers between 0 to $2^m - 1$. Recall that the Gray code has the property that the binary representation of each integer in the ordering only differs by a single bit from the previous one – i.e., it can be produced by XORing the current index with a unit vector. For any $b \in \{0,1\}^m$ and $i \in [m]$, using e_i to denote the *i*-th unit vector we have that:

$$eq(z, b \oplus e_i) = eq_1(z_i, b_i \oplus 1) \cdot \prod_{j \neq i} eq_1(z_j, b_j) = \frac{eq_1(z_i, b_i \oplus 1)}{eq_1(z_i, b_i)} \cdot eq(z, b),$$
(2)

where we use our assumption that $z_i \notin \{0,1\}$ so as not to divide by $0.^2$ By precomputing the 2m values $\left(\frac{eq_1(z_i,\sigma\oplus 1)}{eq_1(z_i,\sigma)}\right)_{i\in[m],\sigma\in\{0,1\}}$ before the enumeration starts, using Eq. (2) we can therefore compute $eq(z,b\oplus e_i)$ from eq(z,b) using a single multiplication.

Thus, we can generate the sequence of values $(eq(z, b))_{b \in \{0,1\}^m}$, by enumerating over $b \in \{0,1\}^m$, according to the Gray code order, and in each step store only the previous eq(z, b) and update it using a single multiplication. Overall, following the precomputation phase, the process requires $2^m - 1$ multiplications.

To handle general vectors $z \in \mathbb{F}^m$, we partition z according to coordinates $S \subseteq [m]$ that are Boolean valued vs. those that are not (i.e., coordinates in \overline{S} are in $\mathbb{F}\setminus\{0,1\}$). Recall that for every $b \in \{0,1\}^m$ it holds that $eq(z,b) = eq(z_S,b_S) \cdot eq(z_{\overline{S}},b_{\overline{S}})$. Observe that $eq(z_S,b_S) = 0$ whenever $b_S \neq z_S$ and otherwise (i.e., $z_S = b_S$)) it holds that $eq(z_S, b_S) = 1$. Thus, in our enumeration we can skip over all vectors b for which $b_S \neq z_S$ and for the remaining vectors, perform the enumeration only over the coordinates in \overline{S} .

Combining Proposition 1 with Eq. (1) we immediately obtain the following corollary.

Corollary 2. There exists a time $O(2^m)$ and space O(m) algorithm that, given as input $z \in \mathbb{F}^m$ and oracle access to a function $f : \{0,1\}^m \to \mathbb{F}$, outputs $\hat{f}(z)$. In more detail, the algorithm performs exactly 2^{m+1} multiplications, 2^m additions and an additional O(m) field operations.

²Observe that $eq(z_i, b_i) = 0$ if and only if $z_i = NOT(b_i)$.

Note that in case the function f is Boolean-valued, the number of multiplications reduces to 2^m .

Remark 3. Our approach can be parallelized by partitioning the index set 2^m into k equal sized parts and handling each part separately. This will reduce the parallel time by a factor of k but requires an additional $k \cdot m$ bits of space, due to the k running indices.

2.1 Generating $eq(z, \cdot)$ in Lexicographic Order

In some applications it may be important to generate the stream of values $eq(z, \cdot)$ in lexicographic order rather than the Gray code order used in Proposition 1. For example, if the function f is given as a stream of values in lexicographic order.

We describe two ways to adapt our algorithm to this setting:

- 1. We can use a similar algorithm to the one in Proposition 1 while observing that (1) the number of multiplications needed per update is equal to the Hamming distance from the (binary representation of the) previous index, and (2) that the *amortized* Hamming distance between the binary representation of consecutive integers (in lexicographic order) is roughly 2. However, this approach doubles the number of multiplications as compared to the Gray code order. As noted above, an approach similar to this was made as an unpublished observation by Vu, see Appendix A.
- 2. If \mathbb{F} is a binary extension field (i.e., it has characteristic 2), we can handle the lexicographic order without doubling the number of multiplications, as follows.

Consider the function $G : \{0, 1\}^m \to \{0, 1\}^m$ that maps an index $i \in \{0, 1\}^m$ to its Gray code encoding (i.e., the *i*-th index in the Gray code order). This function is *linear* over $\mathbb{GF}(2)$ (see, e.g., [BCC⁺10, Section 2]). Observe that $eq(z, G(b)) = eq(G^{-1}(z), b)$ clearly holds for all $z \in \{0, 1\}^m$. But since G is linear, both sides of the equation are multilinear (in z), and therefore the equation must hold for all $z \in \mathbb{F}^m$.

Thus, when using a binary extension field, to stream the values of eq(z, b) in lexicographic order, we can simply use the algorithm described in the proof of Proposition 1 to stream the values of $eq(G^{-1}(z), b)$ in the Gray code order.

Acknowledgements

The author is grateful to Binyi Chen, Ben Fisch, Justin Thaler and Hadas Zeilberger for extremely useful discussions.

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A Vu's Approach

In this appendix we describe Vu's approach for a space efficient implementation of the [VSBW13] algorithm for computing the sequence of values $eq(z, \cdot)$.

For every vector $b \in \{0, 1\}^j$, where $j \in \{0, \ldots, m\}$, let $\chi_b = \prod_{i=1}^j eq_1(z_i, b_i)$. Consider a full binary tree with 2^m leaves, where each vertex is labeled by a string of length at most m in the following way: the root is labeled with the empty string, and the two children of a vertex labeled by b, are labeled by b0 and b1. We associate with every vertex b the value χ_b defined above.

Observe that for $b \in \{0, 1\}^j$ and $\sigma \in \{0, 1\}$, it holds that $\chi_{b\sigma} = \chi_b \cdot eq_1(z_{i+1}, \sigma)$. Thus, the value associated with each vertex can be computed from its parent using a single multiplication (or using

the optimization in [DT24, Algorithm 1], both children can be computed using one multiplication and one addition).

The idea underlying [VSBW13] is to generate the entire tree, and observe that the desired values are associated with the leaves. Vu's observation is that the values associated in the leaves can be generated by scanning the leaves via a depth-first search of the tree, which requires storing at most m field elements associated with the current position in the scan.