SoK: Polynomial Multiplications for Lattice-Based Cryptosystems

Vincent Hwang

Max Planck Institute for Security and Privacy, Bochum, Germany

Abstract. We survey various mathematical tools used in software works multiplying polynomials in 
\[ \frac{\mathbb{Z}_q[x]}{(x^n - ax - \beta)}. \]
In particular, we survey implementation works targeting polynomial multiplications in lattice-based cryptosystems Dilithium, Kyber, NTRU, NTRU Prime, and Saber with instruction set architectures/extensions Armv7-M, Armv7E-M, Armv8-A, and AVX2.

There are three emphases in this paper: (i) modular arithmetic, (ii) homomorphisms, and (iii) vectorization. For modular arithmetic, we survey Montgomery, Barrett, and Plantard multiplications. For homomorphisms, we survey (a) various homomorphisms such as Cooley–Tukey FFT, Good–Thomas FFT, Bruun’s FFT, Rader’s FFT, Karatsuba, and Toom–Cook; (b) various algebraic techniques for adjoining nice properties to the coefficient rings, including localization, Schönhage’s FFT, Nussbaumer’s FFT, and coefficient ring switching; and (c) various algebraic techniques related to the polynomial moduli, including twisting, composed multiplication, evaluation at \( \infty \), truncation, incomplete transformation, striding, and Toeplitz matrix-vector product. For vectorization, we survey the relations between homomorphisms and the support of vector arithmetic.

We then go through several case studies: We compare the implementations of modular multiplications used in Dilithium and Kyber, explain how the matrix-to-vector structure was exploited in Saber, and review the design choices of transformations for NTRU and NTRU Prime with vectorization. Finally, we outline several interesting implementation projects.

Keywords: Lattice-based cryptography · Polynomial multiplication · Modular arithmetic · Homomorphism · Vectorization

E-mail: vincentvbh7@gmail.com (Vincent Hwang)
Contents

1 Introduction
1.1 Why This Paper ................................................. 4
1.2 Emphases ....................................................... 4
1.3 Artifact ......................................................... 7
1.4 Related Works .................................................. 7
1.5 Assumed Knowledge ............................................. 7

2 Modular Arithmetic ............................................. 7
2.1 Integer Approximations ....................................... 7
2.2 Montgomery Arithmetic ....................................... 8
2.3 Barrett Arithmetic ............................................ 9
2.4 Plantard Arithmetic .......................................... 10
2.5 Comparisons ................................................... 11

3 Basic Homomorphisms .......................................... 11
3.1 Notations ....................................................... 12
3.2 Discrete Fourier Transform .................................. 12
3.3 Cooley–Tukey Fast Fourier Transform ...................... 13
3.4 Good–Thomas FFT ............................................ 14
3.5 Brunn-Like Fast Fourier Transforms ......................... 14
3.6 Rader’s Fast Fourier Transform .............................. 15
3.7 Karatsuba and Toom–Cook .................................... 16
3.8 Comparisons ................................................... 16

4 Coefficient Ring Injections .................................... 16
4.1 Localization ..................................................... 17
4.2 Schönhage’s and Nussbaumer’s Fast Fourier Transforms .. 18
4.3 Coefficient Ring Switching .................................... 21
4.4 Comparisons ................................................... 21

5 Polynomial Moduli .............................................. 22
5.1 Embedding (Polynomial Modulus) and Evaluation at ∞ .... 22
5.2 Twisting and Composed Multiplication ....................... 22
5.3 Truncation ....................................................... 23
5.4 Incomplete Transformation and Striding ..................... 25
5.5 Toeplitz Matrix-Vector Product ............................... 25

6 Vectorization .................................................... 28
6.1 Vector Instruction Sets/Extensions ............................ 28
6.2 Vectorization Friendliness .................................... 28
6.3 Permutation Friendliness ..................................... 29
6.4 Guide of Vectorization ....................................... 30

7 Case Studies .................................................... 31
7.1 Dilithium : Barrett vs Montgomery Modular Arithmetic .... 31
7.2 Kyber : Montgomery vs Plantard Modular Arithmetic .... 34
7.3 Homomorphism Caching ....................................... 36
7.4 Saber : Homomorphism Caching .............................. 36
7.5 NTRU : Toeplitz matrix-vector product ....................... 37
7.6 NTRU Prime : Vectorized FFTs ............................... 37
8 Overview of Advances

8.1 Modular Arithmetic ........................................ 39
8.2 Algebraic Techniques .......................................... 41

9 Directions for Future Works .................................. 42

A Modular Arithmetic for Principal Ideal Domains .......... 42
B Roots Defining Discrete Fourier Transforms ................ 44
C Algebraic View of Good–Thomas FFT ......................... 44
D Vector-Radix Transform ......................................... 45
E Generalization of Rader’s FFT .................................. 46
F A Formal Treatment of Localization ............................ 46
G Generalizations of Schönhage and Nussbaumer ............... 46
H Applications of Truncation ....................................... 47
  H.1 $R[x]/(x^r + 1)$ from $R[x]/(x^{2^r} - 1)$ for $r \perp 2$ .......... 47
  H.2 Nussbaumer from Schönhage .................................. 47
I Interpreting Multiplications in $R[x]/(x^n - \alpha x - \beta)$ as TMVPs 48
J A Formal Treatment of Bilinear Systems .................... 48
K Implementing Transposition Matrices ......................... 49
L Constructing the Column Representation of a Toeplitz Matrix 50

References .......................................................... 51
1 Introduction

Lattice-based cryptosystems have gained more popularity due to their balancing performance and the Post-Quantum Cryptography Standardization by the National Institute of Standards and Technology [NIS]. Among the commonly used building blocks of lattice-based cryptosystems, polynomial multiplication is one of the operations dominating the performance cycles. In this paper, we survey various implementation aspects of polynomial multiplications in the ring $\mathbb{Z}_q[x]/(x^n - \alpha x - \beta)$. In particular, we survey polynomial multiplications in Dilithium, Kyber, NTRU, NTRU Prime, and Saber. All of the polynomial multiplications fall into the case $\mathbb{Z}_q[x]/(x^n - \alpha x - \beta)$:

We have $\mathbb{Z}_{8380417}[x]/(x^{256} + 1)$ in Dilithium, $\mathbb{Z}_{3329}[x]/(x^{256} + 1)$ in Kyber, $\mathbb{Z}_{2^k}[x]/(x^n - 1)$ with prime $n$ in NTRU, $\mathbb{Z}_q[x]/(x^p - x - 1) \cong \mathbb{F}_{q^p}$ in NTRU Prime, and $\mathbb{Z}_{2^{13}}[x]/(x^{256} + 1)$ in Saber. We refer to [ABD+20a, ABD+20b, CDH+20, BBC+20, DKRV20] for the specifications.

1.1 Why This Paper

Many works in the literature argue the complexity of integer and polynomial multiplications. However, practitioners implemented specific approaches and justified the merit of the ideas with numerical evidence. There are no systematic and definite ways to evaluate the practical implications of the ideas since hardware gradually evolves, resulting in floating combinations of implementation considerations. People usually implement the ideas at the assembly-optimized level to determine the best approaches on target hardware. The objective of this paper is to formulate and abstract the justifications/implications of the numerical evidence in recent implementation works so when practitioners encounter similar implementational considerations on new platforms in the future, this paper can serve as a collection of practical techniques and guide them toward a convergence of highly optimized implementations on their desired platforms.

1.2 Emphases

This paper is written with three emphases: (i) modular arithmetic, (ii) homomorphisms of algebraic structures, and (iii) vectorization.

1.2.1 Modular Arithmetic

We survey various modular arithmetic computing representatives of elements in $\mathbb{Z}_q$. Let $\mathbb{R}$ be a power of two with exponent a power of two and $q \leq \mathbb{R}$. We call $\log_2 \mathbb{R}$ the width or precision of arithmetic. We only need the cases $\mathbb{R} = 2^{16}, 2^{32}$ in this paper. If $q$ is a power of two, then reduction modulo $q$ can be implemented as reduction modulo $\mathbb{R}$ and logical.

If $q$ is not a power of two, then there are two cases: $q$ is an even number with an odd factor, or $q$ is an odd number. We leave the discussion of even $q$ with an odd factor to future work since it is not used in the interested implementations of this paper.

Let’s assume $q$ is odd. For $a, b \in \mathbb{Z}_q$, there are many ways to compute $c \in \mathbb{Z}_q$ with $c \equiv ab \pmod{q}$. The requirement $c \in \mathbb{Z}_q$ is to ensure that everything we have at the end can be passed to successive computations with the same width of arithmetic. In practice, we prefer $c \in \mathbb{Z}_q$ with $q \leq B \leq \mathbb{R}$ for $B$ reasonably close to $q$. Montgomery multiplication [Mon85] achieves $B = 2q$ and Plantard multiplication [Pla21] achieves $B = q + 1$. Both modular multiplications come with multiplicative forms by design. Barrett reduction [Bar86] effectively achieves $B = 2q$ with $b = 1$, and $B = q$ while replacing $\mathbb{R}$ with
sufficiently large $2^k$. [BHK+22b] introduced Barrett multiplication – a multiplicative form of Barrett reduction – and showed that its range is the same as Montgomery multiplication. They introduced the notion “integer approximation” $\lceil a \rceil$ mapping a real number to an integer with a difference bounded by 1, and defined \( \text{mod} \lceil a \rceil \) as

$$\forall a \in \mathbb{Z}, q \left\lceil \frac{a}{q} \right\rceil = a - a \text{ mod } q.$$ 

[BHK+22b] established a correspondence between Montgomery and Barrett multiplications. While Montgomery multiplication is considered exact, Barrett multiplication encompasses various multiplication instructions by interpreting them as high-products (multiplication instructions returning the high parts) with integer approximations. Recently, [HKS23] showed that relaxing the condition on $\lceil a \rceil$ enables efficient Barrett multiplication on micro-controllers with limited multiplication instructions. Our survey of modular multiplication is built around the generalization of integer approximations by [HKS23]. We survey Montgomery multiplication in Section 2.2, Barrett multiplication in Section 2.3, and Plantard multiplication in Section 2.4.

<table>
<thead>
<tr>
<th>Topic</th>
<th>Content</th>
</tr>
</thead>
<tbody>
<tr>
<td>Montgomery multiplication</td>
<td>Modular multiplication with long/high exact multiplications.</td>
</tr>
<tr>
<td>Barrett multiplication</td>
<td>Modular multiplication with approximated high multiplication.</td>
</tr>
<tr>
<td>Plantard multiplication</td>
<td>Modular multiplication with long multiplication and middle product.</td>
</tr>
</tbody>
</table>

1.2.2 Homomorphisms of Algebraic Structures

This paper involves several notions of algebraic structures and their homomorphisms. An algebraic structure is a set $A$ of elements equipped with finitely many operations on $A$. In this paper, there are always identity elements for the operations. Homomorphisms are structure-preserving maps between two algebraic structures – a homomorphism $\eta : A \to B$ must satisfy that

$$\forall a, b \in A, \eta(a \cdot_A b) = \eta(a) \cdot_B \eta(b)$$

for $\cdot_A$ and $\cdot_B$ same type of operations. We call $\eta$ a monomorphism if it is injective. Common algebraic structures are rings, modules, and associative algebras. Associative algebras are algebraic structures that are modules and rings at the same time. For simplicity, we call associative algebra an algebra.

Let $R$ be a unital commutative ring. This paper surveys various algebra homomorphisms implementing the polynomial ring multiplication of $R[x]/(x^n - \alpha x - \beta)$ as an algebra. Since algebra homomorphisms are ring and module homomorphisms by definition, we can view them in both ways. In this paper, we always view algebra homomorphisms as module homomorphisms. Suppose we find a way to decompose an algebra homomorphism $\eta$ into a composition of module homomorphisms:

$$\cdots \circ \eta_{j+2} \circ \eta_{j+1} \circ \eta \circ \cdots \circ \eta_{j+2} \circ \eta_{j+1} \circ \eta_j \circ \cdots .$$

We identify the series of module homomorphisms resulting in ring homomorphisms. Such series enable us to multiply the homomorphic images of multiplicands. In practice, this is an interactive process with the target platform – we first write an algebra homomorphism as a composition of module homomorphisms, implement a series of module homomorphisms
giving a ring homomorphism, and decide if we want to implement the remaining module homomorphisms, or halt and multiply the images. Therefore, thoroughly exploring the efficiency of module homomorphisms in practice is crucial.

We survey various “basic homomorphisms”, including Cooley–Tukey FFT, Good–Thomas FFT, Bruun’s FFT, Rader’s FFT, and Toom–Cook, and their definability in Section 3. In practice, the target polynomial ring does not always exhibit nice properties defining the “basic homomorphisms”. We survey various coefficient ring injections adjoining the defining structures in Section 4, including localization, Schönhage’s FFT, Nussbaumer FFT, and coefficient ring switching. In Section 5, we also survey generic optimizations that are closely related to the shape of polynomial modulus, including embedding, twisting, composed multiplication, truncation, incomplete transformation, striding, and Toeplitz matrix-vector product.

<table>
<thead>
<tr>
<th>Topic</th>
<th>Content</th>
</tr>
</thead>
<tbody>
<tr>
<td>Cooley–Tukey</td>
<td>Factorizing into small dimensional binomial polynomials.</td>
</tr>
<tr>
<td>Good–Thomas</td>
<td>Factorizing into small dimensional polynomials with coprime dimensions.</td>
</tr>
<tr>
<td>Bruun</td>
<td>Factorizing into small dimensional trinomial polynomials.</td>
</tr>
<tr>
<td>Rader</td>
<td>Prime-size factorization.</td>
</tr>
<tr>
<td>Toom–Cook</td>
<td>Evaluation at integers.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Topic</th>
<th>Content</th>
</tr>
</thead>
<tbody>
<tr>
<td>Localization</td>
<td>Adjoin inverses.</td>
</tr>
<tr>
<td>Schönhage/Nussbaumer</td>
<td>Adjoin roots of unity.</td>
</tr>
<tr>
<td>Coefficient ring switching</td>
<td>Adjoin inverses and roots of unity.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Topic</th>
<th>Content</th>
</tr>
</thead>
<tbody>
<tr>
<td>Embedding and evaluation at ∞</td>
<td>Decrement the degree of polynomial modulus by one when ∞ is not involved.</td>
</tr>
<tr>
<td>Twisting/Composed multiplication</td>
<td>Convert $\mathbb{R}[x]/\langle g(x) \rangle$ into $\mathbb{R}[y]/\langle x - \zeta y, g(\zeta y) \rangle$.</td>
</tr>
<tr>
<td>Truncation</td>
<td>Convert a transformation over a polynomial modulus into a transformation over its factor.</td>
</tr>
<tr>
<td>Incomplete transformation/striding</td>
<td>Transformation over a substructure.</td>
</tr>
<tr>
<td>Toeplitz matrix-vector product</td>
<td>Convert a transformation multiplying size-$n$ polynomials into a polynomial multiplication for $\mathbb{R}[x]/\langle x^n - \alpha x - \beta \rangle$ resulting in small-dimensional Toeplitz matrix-vector products.</td>
</tr>
</tbody>
</table>

### 1.2.3 Vectorization

Vectorization is another important topic for highly-optimized assembly implementations. Common vector instruction sets are Neon on Arm Cortex-A processors and SSE/AVX/AVX2/AVX512 on Intel processors. Usually, vector instructions perform a wide variety of permutations and vector-by-vector arithmetic, including additions, subtractions, multiplications, shift operations, and variants. Section 6.2 formalizes vectorization-
friendliness capturing the uses of vector-by-vector arithmetic, and Section 6.3 formalizes permutation-friendliness capturing the interactions between permutations and vector-by-vector arithmetic. In Section 6.4, we give a short guide on designing transformations admitting efficient vectorization based on the existence of vector-by-vector and vector-by-scalar arithmetic.

<table>
<thead>
<tr>
<th>Topic</th>
<th>Content</th>
</tr>
</thead>
<tbody>
<tr>
<td>Vectorization-friendliness</td>
<td>Determine mapping to vector-by-vector arithmetic.</td>
</tr>
<tr>
<td>Permutation-friendliness</td>
<td>Determine mapping to vector-by-vector arithmetic and permutations.</td>
</tr>
</tbody>
</table>

1.3 Artifact

We are preparing C implementations for each of the ideas reviewed in this paper and will make them publicly available soon for referential purposes (we believe the material shown in the paper is self-contained but additional examples with actual programs will be helpful).

1.4 Related Works

There are many survey works targeting polynomial multiplications. We recommend [Win80, Nus82, DV90, Ber01, Ber08] for the underlying mathematical ideas, and [LZ22] for applications to lattice-based cryptography.

1.5 Assumed Knowledge

This paper assumes that readers have some basic understandings of commutative algebra. We list the following key words and corresponding references: rings from [Jac12a, Section 2] and [Bou89, Section 8, Chapter I], modules from [Jac12a, Section 3] and [Bou89, Section 1, Chapter II], dual modules from [Jac12b, Example 11, Section 1.3] and [Bou89, Section 2, Chapter II], tensor products of modules from [Jac12b, Section 3.7] and [Bou89, Section 3, Chapter II], associative algebras from [Jac12a, Section 7], [Jac12b, Section 3.9], and [Bou89, Sections 1 and 2, Chapter III], and tensor products of algebras from [Jac12b, Section 3.9] and [Bou89, Section 4].

2 Modular Arithmetic

We first survey various modular arithmetic. Section 2.1 generalizes integer approximations for unifying the modular arithmetic used in relevant works. Section 2.2 reviews Montgomery multiplication, Section 2.3 reviews Barrett multiplication, and Section 2.4 reviews Plantard multiplication.

2.1 Integer Approximations

For a real number $\delta > 0$ and an integer-valued function $\lfloor \cdot \rfloor : \mathbb{R} \to \mathbb{Z}$, we call $\lfloor \cdot \rfloor$ a $\delta$-integer-approximation [BHK+22b, HKS23] if

$$\forall r \in \mathbb{R}, |\lfloor r \rfloor - r| \leq \delta.$$
To avoid clutter, we call \( \lfloor \rfloor \) an integer approximation as long as there is a \( \delta \) such that \( \lfloor \rfloor \) is a \( \delta \)-integer-approximation. Furthermore, for a positive integer \( q \in \mathbb{Z}_{>0} \), we define the corresponding modular reduction \( \mod\lfloor\rfloor q : \mathbb{Z} \rightarrow \mathbb{Z} \) as

\[
\forall z \in \mathbb{Z}, z \mod \lfloor\rfloor q = z - \left\lfloor \frac{z}{q} \right\rfloor q
\]

and \( |\mod\lfloor\rfloor q| = \max_{z \in \mathbb{Z}} |z \mod \lfloor\rfloor q| \). By definition, we have

\[
\forall z \in \mathbb{Z}, \begin{cases} \left\lfloor \frac{z}{q} \right\rfloor q = z - z \mod \lfloor\rfloor q, \\ z \equiv z \mod \lfloor\rfloor q \pmod{q}. \end{cases}
\]

We illustrate the idea with two examples: the floor function \( \lfloor \rfloor \) and the rounding function \( \lceil \rceil := r \mapsto \lfloor r + \frac{1}{2} \rfloor \).

The floor function \( \lfloor \rfloor \). The floor function \( \lfloor \rfloor \) maps a real number to the largest integer lower-bounding the real number. Therefore, for an \( r \in \mathbb{R} \), we have \( r - 1 < [r] \leq r \mapsto |[r] - r| \leq 1 \) and find \( \lfloor \rfloor \) a 1-integer-approximation. This function is commonly accompanied by unsigned arithmetic. We denote the corresponding modulo reduction as \( \mod\lfloor\rfloor = \mod^+ \) in this case.

The rounding function \( \lceil \rceil \). For the round function \( \lceil \rceil \) and an \( r \in \mathbb{R} \), since \( [r] = [r + \frac{1}{2}] \) and \( r - \frac{1}{2} < [r + \frac{1}{2}] \leq r + \frac{1}{2} \), we find \( |[r] - r| \leq \frac{1}{2} \) and \( \lceil \rceil \) a \( \frac{1}{2} \)-integer-approximation. If \( \lceil \rceil \) is used for signed arithmetic, we denote the corresponding modulo reduction as \( \mod\lceil\rceil = \mod^\pm \).

In this paper, we provide a unified view of Montgomery, Barrett, and Plantard multiplication using the pair \( (\lfloor \rfloor : \mod\lceil\rceil) \). Usually, two pairs of integer approximations \( (\lfloor\rfloor_0, \mod\lceil\rceil_0) \) and \( (\lfloor\rfloor_1, \mod\lceil\rceil_1 : \mathbb{R}) \) are involved where \( (\lfloor\rfloor_0, \mod\lceil\rceil_0) \) refers to the one we really want and \( (\lfloor\rfloor_1, \mod\lceil\rceil_1 : \mathbb{R}) \) refers to the practically efficient one.

2.2 Montgomery Arithmetic

Let \( a, b \) be integers. We wish to compute \( ab \mod \lfloor\rfloor q \) for a \( \mod\lfloor\rfloor_0 q \) with odd \( q \). Montgomery multiplication [Mon85, Sei18] computes a representative of \( ab \mod \lfloor\rfloor_1 q \) with possible scaling. Observe that \( ab + \left( ab (-q^{-1}) \mod \lceil\rceil : \mathbb{R} \right) q \) is equivalent to 0 modulo \( \mathbb{R} \) and \( ab \) modulo \( q^4 \), we have

\[
\frac{ab + (ab (-q^{-1}) \mod \lceil\rceil : \mathbb{R}) q}{\mathbb{R}} \equiv ab \mod^{-1} (\mod q).
\]

To see why this is a reduction, we bound the range as follows:

\[
|\frac{ab + (ab (-q^{-1}) \mod \lceil\rceil : \mathbb{R}) q}{\mathbb{R}}| \leq \frac{|ab| + |\mod\lceil\rceil : \mathbb{R}| q}{\mathbb{R}}.
\]

There are many ways to mitigate the scaling. A generic way is to perform an additional Montgomery multiplication with \( b = R^2 \mod \lfloor\rfloor q \) for some \( \mod\lfloor\rfloor_0 q \). If \( b \) is known in prior, we can precompute \( bR \mod \lfloor\rfloor q \) and compute

\[
\frac{a \left( bR \mod \lfloor\rfloor q \right) + (a \left( bR \mod \lfloor\rfloor q \right) (-q^{-1}) \mod \lceil\rceil : \mathbb{R}) q}{\mathbb{R}} \equiv ab \pmod{q}.
\]

\(^1\)Since \( R \cdot q \equiv 0 \pmod{\mathbb{R}} \) and \( c \equiv ab \pmod{q} \) solve to \( c = ab + \left( ab (-q^{-1}) \mod \lceil\rceil : \mathbb{R} \right) q \). This was pointed out by [Wan23].
Since $bR \mod \mathbb{P}_0 q$ is now bounded by $|\mod^\mathbb{P}_0 q|$, we have the following bound:

$$|a (bR \mod \mathbb{P}_0 q) + (a (bR \mod \mathbb{P}_0 q) (-q^{-1}) \mod \mathbb{P}_1 R) q| \leq \frac{(|a| \mod \mathbb{P}_0 q) + |\mod^{\mathbb{P}_1} R| q}{R}.$$  

For unsigned arithmetic with $\mod^{\mathbb{P}_1} R = \mod^+ R$ and $\mod^{\mathbb{P}_0} q = \mod^+ q$, the range is

$$\frac{|a| \mod^{\mathbb{P}_0} q + |\mod^{\mathbb{P}_1} R| q}{R} \leq q \left(1 + \frac{|a|}{R}\right).$$

For signed arithmetic with $\mod^{\mathbb{P}_1} R = \mod^\pm R$ and $\mod^{\mathbb{P}_0} q = \mod^\pm q$, the resulting range is

$$\frac{|a| \mod^{\mathbb{P}_0} q + |\mod^{\mathbb{P}_1} R| q}{R} \leq \frac{q}{2} \left(1 + \frac{|a|}{R}\right).$$

**Historical review.** [Mon85] proposed the unsigned Montgomery multiplication, and [Sei18] later proposed the signed variant along with the subtractive variant:

$$ab - (abq^{-1} \mod^\pm R) q.$$  

The benefit of the subtractive variant is that $(ab \mod^\pm R) - ((abq^{-1} \mod^\pm R) q \mod^\pm R) = 0$ whereas $(ab \mod^\pm R) - ((ab - q^{-1} \mod^\pm R) q \mod^\pm R) = 0$ or $R$ as integers. The former implies the following computation:

$$\left\lfloor \frac{ab}{R} \right\rfloor - \left(\frac{(abq^{-1} \mod^\pm R) q}{R}\right).$$

This replaces double-size products with high-products. See [KAK96, KA98] for the multi-limb versions.

### 2.3 Barrett Arithmetic

Let $\mathbb{P}_0, \mathbb{P}_1$ be integer approximations. Barrett multiplication computes

$$ab - \left\lfloor \frac{a}{R} \right\rfloor_0 \left\lfloor \frac{b}{q} \right\rfloor_0 \equiv ab \pmod{q}.$$  

Obviously, this is a representative of $ab \mod q$. The only question is if the resulting range falls into the data width. [BHK+22b] showed the following correspondence

$$ab - \left\lfloor \frac{a}{R} \right\rfloor_0 \left\lfloor \frac{b}{q} \right\rfloor_0 q = a \left(bR \mod \mathbb{P}_0 q\right) + \left(a \left(bR \mod \mathbb{P}_0 q\right) (-q^{-1}) \mod \mathbb{P}_1 R\right) q$$

and obtained the bound

$$\left|ab - \left\lfloor \frac{a}{R} \right\rfloor_0 \left\lfloor \frac{b}{q} \right\rfloor_0 q\right| \leq \frac{|a| \mod^{\mathbb{P}_0} q + |\mod^{\mathbb{P}_1} R| q}{R}.$$  

In Appendix A, we prove the correspondence for principal ideal domains. This captures the polynomial ring case with coefficient ring a finite field and is of independent interest.
Comparing Montgomery and Barrett multiplications. Since the absolute value of the result is smaller than \( \frac{1}{2} \) for signed arithmetic (\( R \) for unsigned arithmetic) in practice, we only need to compute \( ab \mod +R \) (\( ab \mod +R \) for unsigned arithmetic) instead of the full product. Same observation holds for \( \frac{a|\mod b|q}{R} \). Therefore, Barrett multiplication only requires one to compute a high-product implementing \( \frac{a|\mod b|q}{R} \) and two low-products multiplying in \( \mod +R \) or \( \mod +R \). On the other hand, one has to compute two full products (or high-products for the subtractive variant) and one low-product for Montgomery multiplication.\[\text{[BHK+22b]}\] saved one subtraction with Barrett multiplication since there is a subtractive variant for low-product and not high-product.

Historical review. For unsigned arithmetic, \[\text{[Bar86]}\] proposed the case \( b = 1 \), and \[\text{[Sho]}\] proposed Barrett multiplication for generic \( b \). The signed version and its correspondence to Montgomery multiplication was discovered by \[\text{[BHK+22b]}\]. Interestingly, \[\text{[Dho03]}\] proposed the finite field version. Appendix A proves the correspondence for principal ideal domains, and the impact for finite fields is left for future investigation. Recently, \[\text{[BHK+22a, Section 2.4]}\] improved the output range for \( b \neq 1 \) while replacing \( R \) for some \( 2^bR \), and \[\text{[HKS23]}\] furthered the approximation nature of \( \llbracket_1 \) and improved the modular multiplications on microcontrollers.

2.4 Plantard Arithmetic

Recently, \[\text{[Pla21]}\] proposed an unsigned modular multiplication essentially with precision \( 2 \log_2 R \). The signed versions were later proposed by \[\text{[HZZ+22, AMOT22]}\]. For multiplying an integer \( a \) by a constant \( b \) known in prior, Montgomery multiplication results in the bound \( \|a|\mod I\cdot q\|_R \). If we replace the precision \( \log_2 R \) with \( 2 \log_2 R \) and compute with

\[
\frac{a \left( bR^2 \mod I\cdot q \right) + \left( a \left( bR^2 \mod I\cdot q \right) \left( -q^{-1} \right) \mod I\cdot R^2 \right) q}{R^2},
\]

we have the bound

\[
\frac{|a| \mod I\cdot q \mod I\cdot R^2}{R^2}. \tag{1}
\]

For signed arithmetic with \( \|\mod I\cdot R^2\| \leq \frac{R^2}{2} \) and \( \|\mod I\cdot q\| \leq \frac{q}{2} \), the bound is \( \frac{q}{2} \left( 1 + \frac{|a|}{R^2} \right) \).

In practice, since \( |a| \leq R \) and \( q < R \), the result is strictly smaller than \( \frac{q}{4} \), and hence an integer in \( \{-\frac{q-1}{2}, \ldots, 0, \ldots, \frac{q-1}{2}\} \).

We borrow the integer-approximation view from \[\text{[HKS23]}\] and proceed with \[\text{[Pla21]}\]’s innovation for implementing the above observation. Suppose we find two integer approximations \( \llbracket_2 \) and \( \llbracket_3 \) implementing:

\[
\frac{c + \left( c \left( -q^{-1} \right) \mod I\cdot R^2 \right) q}{R^2} = \frac{\llbracket_2}{R^2} - \frac{\llbracket_2}{R^2} \]

for all \( c \in \mathbb{Z}_B \) with \( B \) sufficiently close to \( R^2 \), we claim the following:

\[
\frac{c + \left( c \left( -q^{-1} \right) \mod I\cdot R^2 \right) q}{R^2} = \frac{\llbracket_2}{R^2} - \frac{\llbracket_2}{R^2} \]
The proof is left as an exercise\(^2\). If \(c = ab\), we can instead precompute \(b \left( -q^{-1} \right) \mod \frac{1}{2} R^2\), and apply only two high-products. While \(z \mapsto \left[ \frac{zq}{R} \right]_3\) is the usual high-product multiplying numbers of precision \(\log_2 R\), the high-product \(z \mapsto \left[ \frac{zh(-q^{-1})}{R} \mod \frac{1}{2} R^2 \right]_2\) requires one to multiply \(a\) by a number with precision \(2 \log_2 R\). \([HZZ+22]\) identified the use case in Armv7E-M implementing the multiplication instructions \texttt{smulw}\((b, t)\)\(^3\), and \([AMOT22, Source code 1]\) implemented the idea when only multiplication instructions with precision \(2 \log_2 R\) are available.

### 2.5 Comparisons

We briefly review the required multiplication instructions with precision \(\log_2 R\). We categorize multiplication instructions into three groups:

- **Low multiplications**: \texttt{mullo} computes the lower \(\log_2 R\) bits of the product, \texttt{mlalo} computes the lower \(\log_2 R\) bits of the product and accumulate them to a register with \(\log_2 R\)-bit precision, and \texttt{mlslo} subtract the product from the register with \(\log_2 R\)-bit precision.

- **High multiplications**: \texttt{mulhi} computes the upper \(\log_2 R\) bits of the product within a reasonable approximation, \texttt{mlahi} is the accumulative variant, and \texttt{mlshi} is the subtractive variant.

- **Long multiplications**: \texttt{mull} computes the full-size product, \texttt{mlal} is the accumulative variant, and \texttt{mlsl} is the subtractive variant.

Table 6 is an overview.

**Montgomery multiplication.** For Montgomery multiplication, we need one \texttt{mull}, one \texttt{mullo}, and one \texttt{mlal} (in this order) as seen in Section 2.2. As for the subtractive variant, we need on \texttt{mulhi}, one \texttt{mullo}, and one \texttt{mlshi}.

**Barrett multiplication.** For Barrett multiplication, we need one \texttt{mullo}, one \texttt{mulhi}, and one \texttt{mlslo} since we only need the lower \(\log_2 R\)-bit of the difference of the lower products (cf. Section 2.3).

**Plantard multiplication.** For Plantard multiplication, we need a middle product computing the middle \(\log_2 R\)-bit of a product of a \(\log_2 R\)-bit number and a \(2 \log_2 R\)-bit number. Middle product can be implemented with one \texttt{mulhi} and one \texttt{mlalo}. As for the multiplication followed by \(\prod_{13}\), experiment shows that we have to add up the full-size product and certain constant with absolute value \(\leq \frac{R}{2}\) prior to applying \(\prod_{13}\), so we count the last multiplication as \texttt{mlal} (cf. Section 2.4).

### 3 Basic Homomorphisms

We survey several homomorphisms that are frequently used as key components. Section 3.2 reviews discrete Fourier transform, Section 3.3 reviews Cooley–Tukey FFT, Section 3.4 reviews Good–Thomas FFT, Section 3.5 reviews Brunn’s FFT, Section 3.6 reviews Rader’s FFT, Section 3.7 reviews Karatsuba and Toom–Cook, and Section 3.8 compares the domains, images, and defining conditions.

---

\(^2\)Hint: cancel out the terms \(\frac{R}{2}\), write the remaining as a multiple of \(\frac{R}{2}\), and rewrite the rest with \(\prod_{12}\).

\(^3\)w stands for a word and \((b, t)\) stands for the bottom or the top half-word.
Table 6: Overview of required multiplication instructions of Montgomery, Barrett, and Plantard multiplications where Montgomery (acc.) stands for the accumulative variant and Montgomery (sub.) stands for the subtractive variant.

<table>
<thead>
<tr>
<th></th>
<th>mullo</th>
<th>mlalo</th>
<th>mlalo</th>
<th>mulhi</th>
<th>mlshl</th>
<th>null</th>
<th>mlal</th>
</tr>
</thead>
<tbody>
<tr>
<td>Montgomery (acc.)</td>
<td>1</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>1</td>
<td>1</td>
</tr>
<tr>
<td>Montgomery (sub.)</td>
<td>1</td>
<td>0</td>
<td>0</td>
<td>1</td>
<td>1</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>Barrett</td>
<td>1</td>
<td>0</td>
<td>1</td>
<td>1</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>Plantard</td>
<td>0</td>
<td>1</td>
<td>0</td>
<td>1</td>
<td>0</td>
<td>0</td>
<td>1</td>
</tr>
</tbody>
</table>

3.1 Notations

For a ring $R$, we denote $R[x]$ the polynomial ring with indeterminate $x$ and coefficients in $R$. For a polynomial $g \in R[x]$, we denote $(g) := gR[x] \subset R[x]$ the ideal generated by $g$ and $R[x]/(g)$ the quotient ring. If $g = x^n$ for a positive integer $n$, we also denote the quotient ring $R[x]/(x^n)$ as $R[x]_{\leq n}$.

Maps. For two sets $S_0$ and $S_1$, we denote $S_0 \to S_1$ the signature of a map from $S_0$ to $S_1$. If the map is injective, we write $S_0 \hookrightarrow S_1$; and if the map is surjective, we write $S_0 \twoheadrightarrow S_1$. If the map is injective and surjective, we call it bijective and write $S_0 \cong S_1$.

Products. For a positive integer $n$, and rings $R_0, \ldots, R_{n-1}$, we denote $\prod_{0\leq i<n} R_i$ as the product ring of $R_0, \ldots, R_{n-1}$. Its elements are denoted as $n$-tuples. When the context is clear, we simply write $\prod_i$ where $i$ runs over all possible values in the context.

3.2 Discrete Fourier Transform

Before jumping into various fast transformations, we first review discrete Fourier Transform (DFT). Essentially, DFT is a special case of the Chinese remainder theorem (CRT) for polynomial rings. For a ring $R$, a positive integer $n$, and an $n$-th root of unity $\omega_n \in R$. We call $\omega_n$ principal $n$-th root of unity if

$$\forall j = 1, \ldots, n-1, \sum_{0 \leq i < n} \omega_n^{ij} = 0.$$ 

The size-$n$ DFT refers to the following isomorphism:

$$\begin{align*}
\left\{ \begin{array}{c}
R[x]/(x^n-1) \\
R[x]/(x-\omega_n^n)
\end{array} \right\} & \leftrightarrow \prod_{0 \leq i < n} R[x]/(x-\omega_n^i) \\
(a(x)) & \mapsto (a(\omega_n^i))_{0 \leq i < n}
\end{align*}$$

with the inverse

$$\begin{align*}
\left\{ \begin{array}{c}
\prod_{0 \leq i < n} R[x]/(x-\omega_n^i) \\
R[x]/(x^n-1)
\end{array} \right\} & \leftrightarrow R[x]/(x-\omega_n^n) \\
(\hat{a}_i)_{0 \leq i < n} & \mapsto \sum_{0 \leq i < n} r_i \hat{a}_i
\end{align*}$$

where $r_i : = \frac{1}{n} \sum_{0 \leq j < n} \omega_n^{ij} x^j$. The correctness follows from the definition of principal $n$-th root of unity.
Vincent Hwang

For an invertible $\zeta \in R$, discrete weighted transform (DWT) generalizes DFT into an isomorphism between $R[x]/(x^n - \zeta^n)$ and $\prod_{0 \leq i < n} R[x]/\langle x - \zeta \omega^n \rangle$ where the $r_i := \frac{1}{n} \sum_{0 \leq j < n} \zeta^{-j} \omega_n^{-ij} x^j$ in the inversion map [CF94]. We call it cyclic when $\zeta^n = 1$ and negacyclic when $\zeta^n = -1$.

In summary, we need three conditions for defining an invertible DWT for $R[x]/(x^n - \zeta^n)$:

- The positive integer $n$ must be invertible in $R$. Notice that positive integers are encoded as repeat additions of the identity of $R$, and negative integers are encoded as repeat additions of the additive inverse of the identity of $R$.

- The element $\zeta$ must be invertible in $R$.

- There must exist a principal $n$-th root of unity. When $n$ is a power of two, the condition is equivalent to $\omega_n^2 = -1 \in R$ [Für09]. In Appendix B, we show that the condition $\Phi_n(\omega) = 0$ suffices where $\Phi_n$ is the $n$-th cyclotomic polynomial, the unique irreducible polynomial in $\mathbb{Z}[x]$ that is a divisor of $x^n - 1$ and not a divisor of $x^d - 1$ for all positive integer $d < n$.

### Historical review of the conditions.

For defining a DFT of size-$n$, [Pol71] showed that $n$ must be a divisor of $q - 1$ if $R = \mathbb{F}_q$ and $p - 1$ if $R = \mathbb{Z}_{p^k}$ for a prime $p$. The latter says that for $R = \mathbb{Z}_m$ with prime factorization $m = \prod_i p_i^{k_i}$, $n$ must divide $\gcd(p_i - 1)$ [Pol71, AB74]. [DV78b, Theorem 4] gave the condition when $R$ is a product of local rings$^4$, and [Für09, Section 2] showed that a principal $n$-th root of unity suffices. The cyclotomic condition was used in [SS71] and stated in [Für09] for a power-of-two $n$. The proof in [Für09] naturally generalizes to a prime-power $n$. For the general case, we can’t find such a statement in the literature and therefore, present it in Appendix B.

### 3.3 Cooley–Tukey Fast Fourier Transform

For the DFT implementing $R[x]/(x^n - \zeta^n) \cong \prod_{0 \leq i < n} R[x]/\langle x - \zeta \omega^n \rangle$, Cooley–Tukey FFT improves the computation when $n$ admits a factorization $\prod_{0 \leq j < k} n_j$. We define

$$g_{i_0, \ldots, i_{k-1}} := x - \zeta \omega_n^{\sum_{j=0}^{k-1} i_j n_j}$$

for all $0 \leq i_j < n_j$ and find $x^n - \zeta^n = \prod_{i_0, \ldots, i_{k-1}} g_{i_0, \ldots, i_{k-1}}$. Since all the $g_{i_0, \ldots, i_{k-1}}$’s are coprime, we have the following series of isomorphisms:

$$\frac{R[x]}{(x^n - \zeta^n)} \cong \prod_{i_0} \frac{R[x]}{g_{i_0, \ldots, i_{k-1}}} \cong \cdots \cong \prod_{i_0, \ldots, i_{k-1}} \frac{R[x]}{g_{i_0, \ldots, i_{k-1}}}.$$

### Real-world example(s).

In Dilithium, one is asked to implement the radix-2 FFT defined on $\mathbb{Z}_{8380417}[x]/\langle x^{256} + 1 \rangle$. Since $x^{256} + 1 = \Phi_{512}(x)$, the defining condition is the same for $\mathbb{Z}_{8380417}[x]/\langle x^{512} - 1 \rangle$. Observe that $8380417 = 2^{13} \cdot 3 \cdot 11 \cdot 31 + 1$, we can define a cyclic FFT with transformation size a divisor of $2^{13} \cdot 3 \cdot 11 \cdot 31$. This gives the isomorphism $\mathbb{Z}_{8380417}[x]/\langle x^{512} - 1 \rangle \cong \prod_i \mathbb{Z}_{8380417}[x]/\langle x - \omega_{512}^i \rangle$ and hence $\mathbb{Z}_{8380417}[x]/\langle x^{256} + 1 \rangle \cong \prod_i \mathbb{Z}_{8380417}[x]/\langle x - \omega_{512}^{2+i} \rangle$ by choosing $\zeta = \omega_{512}$ (any odd power of $\omega_{512}$ works) and $\omega_{256} = \omega_{512}^2$.

$^4$A ring with a unique maximal left/right-ideal.
3.4 Good–Thomas FFT

Good–Thomas FFT exploits the factorization of \( n = \prod_{0 \leq j < d} n_j \) when \( n_j \)'s are coprime to each other [Goo58]. For a cyclic size-\( n \) DFT implementing \( R[x]/(x^n - 1) \cong \prod_{0 \leq i < n} R[x] / (x - \omega_i^n) \), we define principal \( n_j \)-th root of unity \( \omega_{n_j} \) as \( \omega_i^n \) for all \( j \) where \( (e_j)_{0 \leq j < d} \) is the unique tuple of positive integers realizing \( 1 \equiv \sum_{0 \leq j < n} e_j \) (mod \( n \)) so

\[
\omega_n = \omega_n^\omega_{n_j} = \prod_{0 \leq j < d} \omega_{n_j}.
\]

If we rewrite the result of DFT as

\[
\sum_{0 \leq i < n} a_i \omega_n^i = \sum_{0 \leq j < d} a_i \prod_{0 \leq j < d} \omega_{n_j}^i = \sum_{0 \leq i < n} \sum_{i_k-1} a_i \prod_{0 \leq j < d} \omega_{n_j}^i
\]

where \( i_j = i \mod n_j \), we find that the right-hand side is a multi-dimensional cyclic DFT. In the language of polynomial rings, the cyclic size-\( n \) DFT is implemented as the following multi-dimensional cyclic DFT:

\[
\frac{R[x]}{(x^n - 1)} \cong \prod_{i_0, \ldots, i_{d-1}} \frac{R[x_{i_0}, \ldots, x_{d-1}]}{\left(x - \prod_{j} x_j - \left(\sum_{j \leq \frac{n}{d}} x_{i_0}^n \right) - \left(\sum_{j \leq \frac{n}{d}} x_{i_{d-1}}^n \right)\right)}
\]

The overall asymptotic run-time is the same as Cooley–Tukey, but we save linearly number of multiplications. We review the algebraic view of Good–Thomas FFT in Appendix C, and vector-radix FFT in Appendix D further improving the multi-dimensional transformation.

Real-world example(s). In [AHY22], they computed the products in \( R[x] / (x^{1536} - 1) \) via Good–Thomas. They first introduced \( x^4 \sim x_0 x_1, x_0^3 \sim 1 \), and \( x_1^{128} \sim 1 \) for vectorization-friendliness, and observed that vectorization-friendliness implies a flexible code-size optimization while permitting for Good–Thomas [AHY22, Sections 3.2 and 3.3]. We will formally review the notion of vectorization-friendliness in Section 6.2.

3.5 Bruun-Like Fast Fourier Transforms

After the introduction of Cooley–Tukey FFT over complex numbers, many works proposed several optimizations if the input coefficients are real. [Bru78] proposed Bruun’s FFT for the power-of-two case, [DH84] proposed split-radix FFT, [Bra84] proposed fast Hartley transform for the discrete Hartley transform (DHT) [Har42]. [Mey96] generalized Bruun’s FFT to arbitrary even sizes, and [JF07, Ber07, LVB07] improved the split-radix FFT.

This section reviews the works [Bru78, Mey96] over complex numbers for historical reasons. However, the actual use case relevant to us are the factorization of cyclotomic polynomials over finite fields [BC87, BGM93, Mey96]. See [TW13, BMGVdO15, WYF18, WY21] for recent progresses on this topic.

The complex case. Let \( n_j = [I_j] \), \( n = \prod_{j} n_j \), \( \xi, \zeta \in \mathbb{C} \) be invertible elements, and \( \omega_n \in \mathbb{C} \) a principal \( n \)-th root of unity. Bruun’s FFT [Bru78, Mey96] chooses \( g_{i_0, \ldots, i_{h-1}} \) as follows:

\[
g_{i_0, \ldots, i_{h-1}} = x^2 - \left(\xi \omega_n \sum_{i_j} \omega_{i_j}^{n_j} + \xi^{-1} \omega_n^{-\sum_{i_j} \omega_{i_j}^{n_j}}\right) \zeta x + \zeta^2.
\]

One can derive DFT and DHT from each other with linearly number of arithmetic during post-processing.
If $g_{i_0,\ldots,i_{n-1}}$’s are coprime (namely, $\xi \neq \xi^{-1}$ in the complex case), we have a fast transformation for the ring $R[x]/\langle x^{2^n} - (\xi^n + \xi^{-n}) \rangle$ since $\prod_{i_0,\ldots,i_{n-1}} g_{i_0,\ldots,i_{n-1}} = x^{2^n} - (\xi^n + \xi^{-n}) \in \mathbb{C}[x]/\langle x^{2^n} \rangle$. For $\zeta = 1$, $\xi = \omega_{4n} \in \mathbb{C}$, this implements the isomorphism $\mathbb{C}[x]/\langle x - \omega_{4n}^{1+2} \rangle$ if we further split into linear factors.

The finite field cases. In this paper, we are interested in the case $R = \mathbb{F}_q$ with $q \equiv 3 \pmod{4}$ which relies on the following theorem from [BGM93]:

**Theorem 1 ([BGM93]).** Let $q \equiv 3 \pmod{4}$ be a prime and $2^w$ be the highest power of $q + 1$. For $k < w$, $x^{2^k} + 1$ factors into irreducible trinomials $x^2 + \gamma x + 1 \in \mathbb{F}_q[x]$. For $k \geq w$, $x^{2^k} + 1$ factors into irreducible trinomials $x^{2^k-w+1} + \gamma x^{2^k-w} \not\in \mathbb{F}_q[x]$.

Real-world example(s). For the NTRU Prime parameter sets ntrulpr761/sntrup761, [HLY24] introduced a fast transformation (Good–Schönhage–Bruun) leading to computing in $\mathbb{Z}_{4591}[x]/\langle x^{1632} + 1 \rangle$. Since $4591 \equiv 3 \pmod{4}$ and $4591 + 1 = 287 \cdot 2^4$, we can split $\mathbb{Z}_{4591}[x]/\langle x^{32} + 1 \rangle$ into polynomial rings modulo trinomials of the form $x^4 + \gamma x^2 - 1$. [HLY24] split into rings of the form $\mathbb{Z}_{4591}[x]/\langle x^8 + ax^4 + 1 \rangle$ for efficiency reasons.

### 3.6 Rader’s Fast Fourier Transform

Let $n$ be a positive integer, $\mathcal{I} = \{0, \ldots, n-1\}$, and $\omega_n \in R$ be a principal $n$-th root of unity. If $n$ is an odd prime, Rader’s FFT computes the map $a \mapsto (a(\omega_n^i))_{i \in \mathcal{I}}$ via a size-$(n-1)$ cyclic convolution. See Appendix E for generalization.

We explain the idea for an odd prime $n$. Let $\mathcal{I}^* := \{1, \ldots, n-1\}$ be an index set, $(a_j)_{j \in \mathcal{I}} := a$, and $(\hat{a}_j)_{j \in \mathcal{I}} := (a(\omega_n^j))_{j \in \mathcal{I}}$. Since $n$ is prime, there is a $g \in \mathcal{I}$ with $\{g^k \in \mathcal{I}| k \in \mathbb{Z}_{n-1}\} = \mathcal{I}^*$ where the powers $g^k$ are reduced modulo $n$. We introduce the reindexing $j \in \mathcal{I}^* \mapsto -\log_g j \in \mathbb{Z}_{n-1}$ and $i \in \mathcal{I}^* \mapsto \log_g i \in \mathbb{Z}_{n-1}$ where $\log_g$ is the discrete logarithm, and split the computation $(a_j)_{j \in \mathcal{I}} \mapsto (\hat{a}_i)_{i \in \mathcal{I}}$ into $a_0 = \sum_{j \in \mathcal{I}} a_j$ and $\hat{a}_i = a_0 + \sum_{j \in \mathcal{I}} a_j \omega_n^{ij}$ for $i \in \mathcal{I}^*$. For the cases $i \in \mathcal{I}^*$, we move $a_0$ to the left-hand side, and rewrite it as

$$\hat{a}_g \omega_n^i - a_0 = \sum_{j \in \mathcal{I}^*} a_j \omega_n^{ij} = \sum_{-\log_g j \in \mathbb{Z}_{n-1}} a_j \omega_n^{\log_g j + \log_g i}.$$  

We can now compute $(\hat{a}_g - a_0)_{k \in \mathbb{Z}_{n-1}}$ as the size-$(n-1)$ cyclic convolution of $(a_g^{-1})_{k \in \mathbb{Z}_{n-1}}$ and $(\omega_n^{ik})_{k \in \mathbb{Z}_{n-1}}$. We give an example for $n = 5$ and $g = 2$:

$$\begin{align*}
(\hat{a}_g - a_0)_{k \in \mathbb{Z}_{5-1}} &= \left( a_1 \omega_n^2 + a_2 \omega_n^4 + a_3 \omega_n^0 + a_4 \omega_n^3 \right) \\
&= \left( a_2 \omega_n^2 + a_3 \omega_n^4 + a_2 \omega_n^0 + a_1 \omega_n^3 \right).
\end{align*}$$

Real-world example(s). The case $(n, g) = (17, 3)$ was used for multiplying over $\mathbb{Z}_{4591}$. [ACC+21] multiplied in $\mathbb{Z}_{4591}[x]/\langle x^{1530} + 1 \rangle$ on Cortex-M4, [HLY24] multiplied in $\mathbb{Z}_{4591}[x]/\langle x^{1632} - 1 \rangle$ with Armv8.0-A Neon, and [Hwa23] multiplied in $\mathbb{Z}_{4591}[x]/\langle \Phi_{17}(x^{96}) \rangle$ with Armv8.0-A Neon and Intel AVX2. Observe $1530 = 17 \cdot 90$ and $1632 = 17 \cdot 96$, their implementations relied on the size-17 cyclic FFT $\mathbb{Z}_{4591}[x]/\langle x^{17} - 1 \rangle \cong \prod_{i=0}^{16} \mathbb{Z}_{4591}[x]/\langle x - \omega_{17}^i \rangle$, and are implemented with Rader’s FFT. We will shortly review how [Hwa23] applied Rader’s FFT for $\mathbb{Z}_{4591}[x]/\langle \Phi_{17}(x^{96}) \rangle$ in Section 5.3.
3.7 Karatsuba and Toom–Cook

Let \( I = \{0, \ldots, 2n - 2\} \) and \( \{s_i\}_{i \in I} \subset \mathbb{Z} \) be a finite set. Karatsuba [KO62] and Toom–Cook [Too63] compute the size-(2n−1) product of two size-n polynomials with the maps \( R[x]_{2n} \hookrightarrow R[x]/\prod_{i \in I} (x - s_i) \). [KO62] proposed the case \( n = 2 \) with the point set \( \{0, 1, \infty\} \), [Too63] chose \( n \geq 2 \) and \( \{s_i\} \subset \mathbb{Z} \), and [Win80] extended the choice of \( \{s_i\} \) to \( \mathbb{Q} \cup \{\infty\} \). Let \( c \in \mathbb{Z} \). Evaluating \( x \) at \( c^{-1} \) means mapping a polynomial \( a(x) \) to \( c^{\deg(a)} a(c^{-1}) \) instead of \( a(c^{-1}) \). We will review the idea of evaluating at \( \infty \) in Section 5.1, and localization adjoining the inverses of integers in Section 4.1.

3.8 Comparisons

We briefly compare Cooley–Tukey, Good–Thomas, Bruun, Rader, and Toom–Cook. Table 7 summarizes the domains and images, and Table 8 summarizes the defining conditions.

**Cooley–Tukey vs Good–Thomas.** Both Cooley–Tukey and Good–Thomas relies on a factorization of the dimension \( n \), the existence of a principal \( n \)-th root of unity, and the existence of \( n^{-1} \) in the coefficient ring. While Cooley–Tukey works for arbitrary factorization of \( n \), Good–Thomas relies on a coprime factorization. As for the shape of polynomial modulus, Cooley–Tukey is definable on \( R[x]/(x^n - \zeta^n) \), and Good–Thomas reviewed in Section 3.4 is definable only on \( R[x]/(x^n - 1) \). Generally speaking, if the order of \( \zeta \) is coprime to \( n \), we can also define Good–Thomas on \( R[x]/(x^n - \zeta^n) \) via truncation as illustrated in [HVDH22, Sections 3.5 and 3.6]. See Appendix C for more explanations. If both approaches are definable, Good–Thomas saves linearly number of multiplications.

**Cooley–Tukey vs Bruun.** While Cooley–Tukey factorizes into polynomial rings with binomial moduli, Bruun factorizes into polynomial rings with trinomial moduli. If the coefficient ring is a finite field or finite ring, Bruun works in some cases where Cooley–Tukey doesn’t since factorizing into binomials implies factorizing into trinomials but the converse doesn’t always hold. The downside of Bruun is the increased number of arithmetic during the transformation.

**Rader vs others.** Rader converts size-\( n \) cyclic transformation into a size-(\( n - 1 \)) cyclic convolution with linear pre- and post-processing when \( n \) is an odd prime. Other approaches rely on a factorization of \( n \), implying that \( n \) must be composite.

**Toom–Cook vs others.** Cooley–Tukey, Good–Thomas, Bruun, and Rader are isomorphisms where the dimensions are preserved during the transformation. On the hand, Toom–Cook is a monomorphism where the dimension is essentially doubled after the transformation. For the definability, Toom–Cook requires the existences of the inverses of some integers. This is generally more favorable than the FFTs in this section since one can always go for localization for constructing the inverses of integers 4.1 which, in practice, amounts to replacing the coefficient ring with a slightly larger one. FFTs require the existence of a principal \( n \)-th root of unity and the inverse \( n^{-1} \) where the former only exists in certain coefficient ring (cf. Section 3.2).

4 Coefficient Ring Injections

This section reviews existing techniques and benefits of a coefficient ring injection:

\[ R \hookrightarrow R'. \]
Table 7: Overview of the domains and images for Cooley–Tukey, Good–Thomas, Bruun, Rader, and Toom–Cook.

<table>
<thead>
<tr>
<th>Approach</th>
<th>Domain</th>
<th>Image</th>
</tr>
</thead>
<tbody>
<tr>
<td>Cooley–Tukey</td>
<td>$\mathbb{R}[x]/(x^n - \zeta \cdot \zeta^{-1})$</td>
<td>$\prod_i \mathbb{R}[x]/(x - \omega_i)$</td>
</tr>
<tr>
<td>Good–Thomas</td>
<td>$\mathbb{R}[x]/(x^n - 1)$</td>
<td>$\prod_i \mathbb{R}[x]/(x - \omega_i)$</td>
</tr>
<tr>
<td>Bruun</td>
<td>$\mathbb{R}[x]/(x^n - (\xi \cdot \zeta^{-1}) \cdot \zeta^n \cdot x^n + \zeta^n)$</td>
<td>$\prod_i (x^2 - (\xi \cdot \omega_i - (\xi \cdot \omega_i)^{-1}) \cdot \zeta \cdot \zeta^{-1})$</td>
</tr>
<tr>
<td>Rader</td>
<td>$\mathbb{R}[x]/(x^n - 1)$</td>
<td>$\prod_i \mathbb{R}[x]/(x - \omega_i)$</td>
</tr>
<tr>
<td>Toom–Cook</td>
<td>$\mathbb{R}[x]/n$</td>
<td>$\prod_{i=0,\ldots,2n-2} \mathbb{R}[x]/(x - \zeta^i)$</td>
</tr>
</tbody>
</table>

Table 8: Overview of the defining conditions of Cooley–Tukey, Good–Thomas, Bruun, Rader, and Toom–Cook.

<table>
<thead>
<tr>
<th>Approach</th>
<th>Requirements</th>
<th>Comment</th>
</tr>
</thead>
<tbody>
<tr>
<td>Cooley–Tukey</td>
<td>$\exists \omega_n, \zeta, \zeta^{-1}, n^{-1} \in \mathbb{R}$</td>
<td>Fairly flexible.</td>
</tr>
<tr>
<td>Good–Thomas</td>
<td>$\exists \omega_n, n^{-1} \in \mathbb{R}$</td>
<td>$\exists$ coprime factorization of $n$.</td>
</tr>
<tr>
<td>Bruun</td>
<td>$\exists \omega_n, (\omega_n^{-1}, \zeta, \zeta^{-1}, n^{-1} \in \mathbb{R}$</td>
<td>More flexible than Cooley–Tukey.</td>
</tr>
<tr>
<td>Rader</td>
<td>$\exists \omega_n, n^{-1} \in \mathbb{R}$</td>
<td>Odd prime $n$.</td>
</tr>
<tr>
<td>Toom–Cook</td>
<td>Inverses of integers.</td>
<td>Fairly flexible.</td>
</tr>
</tbody>
</table>

In this section, we focus on the structural implications. There are two points in this section.

- What if there are no inverses of some integers required for defining a correct algorithm?
- What if there are no principal roots of unity required for defining a correct algorithm?

Section 4.1 reviews localization at non-zero integers for adjoining inverses, Section 4.2 reviews Schönhage’s and Nussbaumer’s FFTs adjoining symbolic principal roots of unity, Section 4.3 reviews an alternative approach choosing $\mathbb{R}'$ with suitable inverses and principal roots of unity, and Section 4.4 compares the cost of coefficient ring injections. See Table 9 for an overview of the structural implications of the techniques.

Table 9: Overview of coefficient ring injection techniques.

<table>
<thead>
<tr>
<th>Technique</th>
<th>Inverse</th>
<th>Principal root of unity</th>
</tr>
</thead>
<tbody>
<tr>
<td>Localization</td>
<td>✓</td>
<td>-</td>
</tr>
<tr>
<td>Schönhage/Nussbaumer</td>
<td>-</td>
<td>✓</td>
</tr>
<tr>
<td>Coeff. ring switching</td>
<td>✓</td>
<td>✓</td>
</tr>
</tbody>
</table>

### 4.1 Localization

Let $n \in \mathbb{Z}$ be non-invertible in $\mathbb{R}$. Localization formulates “division by an integer $n^k$ in $\mathbb{R}$.” We quote the following from [Jac12b, Section 7.2] for the propose of localization:

Given a (commutative) ring $\mathbb{R}$ and a subset $S$ of $\mathbb{R}$, to construct a ring $\mathbb{R}_S$ and a homomorphism $\lambda_S$ of $\mathbb{R}$ into $\mathbb{R}_S$ such that every $\lambda_S(s)$, $s \in S$, is invertible in $\mathbb{R}_S$, and the pair $(\mathbb{R}_S, \lambda_S)$ is universal for such pairs in the sense that if $\eta$ is any homomorphism of $\mathbb{R}$ into a ring $\mathbb{R}'$ such that every $\eta(s)$ is invertible, then there exists a unique homomorphism $\hat{\eta} : \mathbb{R}_S \to \mathbb{R}'$ such that $\eta = \hat{\eta} \circ \lambda_S$.

---

6The last sentence actually ends with “such that the diagram [Figure] is commutative”. We replace the description with the desired composition.
The ring $R_5$ is also commonly denoted as $S^{-1}R$. We leave the formal treatment to Appendix F and explain with a small example.

Suppose we want to compute $c_0 + c_1 x = (a_0 + a_1 x)(b_0 + b_1 x)$ in $\mathbb{Z}_{2^{15}}[x]/\langle x^2 - 1 \rangle$ with “Cooley–Tukey FFT”. We compute $a_0 + a_1 x \mapsto (a_0 + a_1, a_0 - a_1)$ and $b_0 + b_1 x \mapsto (b_0 + b_1, b_0 - b_1)$, point-multiply them, and perform an add-sub pair. The result is $\((a_0 + a_1)(b_0 + b_1) \pm (a_0 - a_1)(b_0 - b_1)) = 2(a_0 b_0 + a_1 b_1, a_0 b_1 + a_1 b_0)$. It remains to “divide by two”. Localization means the following monomorphisms:

$$\mathbb{Z}_{2^{15}}[x] \longrightarrow \prod \mathbb{Z}_{2^{16}}[x] \longrightarrow \mathbb{Z}_{2^{16}}[x] \longrightarrow \mathbb{Z}_{2^{15}}[x]/\langle x^2 - 1 \rangle.$$ 

Since we know that the result is a 2-multiple of the desired one, we can extract the result by maintaining the set of 2-multiples as in $\mathbb{Z}_{2^{16}}$.

![Figure 1: Localization for $\mathbb{Z}_{2^{15}}$ in $\mathbb{Z}_{2^{16}}$. We store the 15-bit values $a_0, a_1, b_0, b_1$ as halfwords (little endian in the Figure). For the 15-bit values $c_0, c_1$, we compute the 16-bit values $2c_0$ and $2c_1$ and extract the $c_0$ and $c_1$ by shifting.](image)

Real-world example(s). Recall that for Toom-3 with the point set $\{0, \pm 1, 2, \infty\}$, we have to apply

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & -1 & 1 \\ 1 & 2 & 4 & 8 & 16 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix}^{-1} = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ -\frac{1}{2} & 1 & -\frac{1}{2} & -\frac{1}{2} & 2 \\ -1 & \frac{1}{2} & \frac{1}{2} & 0 & -1 \\ \frac{1}{2} & -\frac{1}{2} & -\frac{1}{2} & \frac{1}{2} & -2 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix}.$$

If we work over the ring $\mathbb{Z}_{2^{15}}[x]$ used in ntruhsps2048677, then we have to maintain the values in $\mathbb{Z}_{2^{15}}$ for adjoining $2^{-1}$. Another example is Toom-5. If we choose $\{0, \pm 1, \pm 2, \pm 3, \infty\}$ as the point set for evaluation, we must adjoin $16^{-1}$. [CCHY23] showed that one can instead switch to $\{0, \pm 1, \pm 2, \pm 3, \infty\}$ requiring only $8^{-1}$.

It should be noted that localization need not to adjoin the inverses uniformly in practice. For example, if we apply Toom-4 with the point set $\{s_i\} = \{0, \pm 1, \pm 2, 3, \infty\}$, then we only need to implement the following monomorphism:

$$\mathbb{Z}_{2^k}[x] \hookrightarrow \mathbb{Z}_{2^{k+2}}[x]/\langle x - 1 \rangle \times \mathbb{Z}_{2^{k+2}}[x]/\langle x + 1 \rangle \times \mathbb{Z}_{2^{k+3}}[x]/\langle x - 2 \rangle \times \mathbb{Z}_{2^{k+3}}[x]/\langle x + 2 \rangle \times \mathbb{Z}_{2^{k+3}}[x]/\langle x - 3 \rangle \times \mathbb{Z}_{2^{k+3}}[x]/\langle x - \infty \rangle.$$

This implies one can apply more aggressive transformations to some subproblems by working over $\mathbb{Z}_{2^{k+2}}$ and $\mathbb{Z}_{2^k}$ instead of $\mathbb{Z}_{2^{k+3}}$. The non-uniform property of localization with Toom–Cook does not seem to appear in the literature, but we believe there are practical benefits for implementations.

4.2 Schönhage’s and Nussbaumer’s Fast Fourier Transforms

Schönhage’s [Sch77] and Nussbaumer’s [Nus80] FFTs craft principal roots of unity defining FFTs. For simplicity, we explain the ideas for the cases $R[x]/\langle x^{2k} \pm 1 \rangle$. 


Cyclic Schönhage. For the Schönhage in the cyclic case \( R[x] / \langle x^{2^k} - 1 \rangle \) [Ber01, Section 9], we choose an \( l \geq \frac{k}{2} - 1 \), introduce the relation \( x^{2^l} \sim y \), and replace the relation with \( x^{2^k+1} \sim -1 \). Define \( \mathcal{R}' := R[x] / \langle x^{2^k+1} + 1 \rangle \), and rewrite the polynomial ring as a polynomial ring with indeterminate \( y \) and coefficient ring \( \mathcal{R}' \). Since \( x^{2^k+1} = -1 \in \mathcal{R}' \) and \( l + 2 \geq k - l \), \( x^{2^{k+1-2^l}} \) is a principal \( 2^{k-l} \)-th root of unity defining a size-\( (k-l) \) cyclic FFT. In summary, we have

\[
\frac{R[x]}{\langle x^{2^k} - 1 \rangle} \cong \frac{R[x, y]}{\langle x^{2^l} - y, y^{2^{k-l} - 1} \rangle} \hookrightarrow \frac{\mathcal{R}'[y]}{\langle y^{2^{k-l} - 1} \rangle} \cong \prod_i \frac{\mathcal{R}'[y]}{\langle y - \omega^{2^l}_{2^k-1} \rangle}
\]

where \( \omega^{2^l}_{2^k-1} := x^{2^{l+1-k}} \). The optimal choice is \( l = \left\lfloor \frac{k}{2} \right\rfloor - 1 \) leading to

\[
\frac{R[x]}{\langle x^{2^k} - 1 \rangle} \hookrightarrow \frac{\mathcal{R}'[y]}{\langle y^{2^{l+1}} + 1 \rangle} \cong \prod_i \frac{\mathcal{R}'[y]}{\langle y - \omega^{2^{l+1}}_{2^k-1} \rangle}
\]

with \( \mathcal{R}' = R[x] / \langle x^{2^{l+1}} + 1 \rangle \). Since multiplications by powers of \( x \) in \( \mathcal{R}' \) amounts to negacyclic shifts, we only need additions and subtractions for converting a polynomial multiplication in \( R[x] / \langle x^{2^k} - 1 \rangle \) into \( 2^{k-l} \) many polynomial multiplications in \( R[x] / \langle x^{2^k} + 1 \rangle \).

Negacyclic Schönhage. We can also apply Schönhage to \( R[x] / \langle x^{2^k} + 1 \rangle \): we choose \( l \geq \frac{k}{2} - 1 \) and proceed similarly as in the cyclic case. This leads to

\[
\frac{R[x]}{\langle x^{2^k} + 1 \rangle} \cong \frac{R[x, y]}{\langle x^{2^l} - y, y^{2^{k-l} - 1} + 1 \rangle} \hookrightarrow \frac{\mathcal{R}'[y]}{\langle y^{2^{k-l} + 1} \rangle} \cong \prod_i \frac{\mathcal{R}'[y]}{\langle y - \omega^{2^{l+1}}_{2^k-1} \rangle}
\]

where \( \mathcal{R}' := R[y] / \langle y^{2^{l+1}} + 1 \rangle \) and \( \omega^{2^{l+1}}_{2^k-1} := x^{2^{l+1-k}} \). For the optimal choice \( l = \left\lfloor \frac{k}{2} \right\rfloor \), we have

\[
\frac{R[x]}{\langle x^{2^k} + 1 \rangle} \hookrightarrow \frac{\mathcal{R}'[y]}{\langle y^{2^{l+1}} + 1 \rangle} \cong \prod_i \frac{\mathcal{R}'[y]}{\langle y - x^{2^{l+1}} \rangle}
\]

Nussbaumer. Nussbaumer is only applicable to the negacyclic case, but it sometimes results in smaller subproblems. Conceptually, we swap the roles of \( x \) and \( y \) while applying the FFT. We choose an \( l \leq \frac{k}{2} \), introduce the relation \( x^{2^l} \sim y \), and replace it with \( x^{2^{l+1}} \sim 1 \). Instead of regarding the polynomial ring as a polynomial ring with indeterminate \( y \) in Schönhage, we regard it as a polynomial ring with indeterminate \( x \). Define \( \mathcal{R}' := R[y] / \langle y^{2^{l+1}} + 1 \rangle \). Since \( y^{2^{l+1}} = -1 \in \mathcal{R}' \), \( y^{2^{l+1}} \) is a principal \( 2^{l+1} \)-th root of unity defining a size-\( 2^{l+1} \) cyclic FFT. Overall, we have

\[
\frac{R[x]}{\langle x^{2^k} + 1 \rangle} \cong \frac{R[x, y]}{\langle x^{2^l} - y, y^{2^{k-l}} + 1 \rangle} \hookrightarrow \frac{\mathcal{R}'[y]}{\langle x^{2^{l+1}} - 1 \rangle} \cong \prod_i \frac{\mathcal{R}'[y]}{\langle x - \omega^{2^{l+1}}_{2^k+1} \rangle}
\]

where \( \omega^{2^{l+1}}_{2^k+1} := y^{2^{k-l+1}} \). For the optimal choice \( l = \left\lfloor \frac{k}{2} \right\rfloor \), we have

\[
\frac{R[x]}{\langle x^{2^k} + 1 \rangle} \hookrightarrow \frac{\mathcal{R}'[x]}{\langle x^{2^{l+1}} - 1 \rangle} \cong \prod_i \frac{\mathcal{R}'[x]}{\langle x - \omega^{2^{l+1}}_{2^k+1} \rangle}
\]
Comparing of Schönhage and Nussbaumer. Table 10 summarizes the domains, images, and defining conditions of radix-2 Schönhage and Nussbaumer, and Table 11 summarizes the domains and images of radix-2 Schönhage and Nussbaumer with optimal parameters. As seen in Table 11, for the negacyclic case \( R[x]/\langle x^k + 1 \rangle \), Nussbaumer results in size-\( \left\lceil \frac{k}{2} \right\rceil \) negacyclic convolutions and Schönhage results in size-\( \left\lceil \frac{k + 1}{2} \right\rceil \) negacyclic convolutions. This implies Nussbaumer is more preferable in the negacyclic case if the number of operations in \( R \) is the sole optimizing target [Ber01, Section 9].

Table 10: Overview of radix-2 Schönhage and Nussbaumer.

<table>
<thead>
<tr>
<th>Domain</th>
<th>Image</th>
<th>Condition</th>
</tr>
</thead>
<tbody>
<tr>
<td>Cyclic Schönhage</td>
<td>( R[x]/\langle x^{k - 1} \rangle \left( \frac{R[x]}{\langle x^{2^{k/2} + 1} \rangle} \right)^{2^{k/2}} )</td>
<td>( l \geq \frac{k}{2} - 1 )</td>
</tr>
<tr>
<td>Negacyclic Schönhage</td>
<td>( R[x]/\langle x^{k + 1} \rangle \left( \frac{R[x]}{\langle x^{2^{k/2} + 1} \rangle} \right)^{2^{k/2}} )</td>
<td>( l \geq \frac{k}{2} - 1 )</td>
</tr>
<tr>
<td>Nussbaumer</td>
<td>( R[x]/\langle x^{k + 1} \rangle \left( \frac{R[y]}{\langle y^{2^{k/2} + 1} \rangle} \right)^{2^{k/2}} )</td>
<td>( l \leq \frac{k}{2} )</td>
</tr>
</tbody>
</table>

Table 11: Overview of optimal radix-2 Schönhage and Nussbaumer.

<table>
<thead>
<tr>
<th>Domain</th>
<th>Image</th>
</tr>
</thead>
<tbody>
<tr>
<td>Cyclic Schönhage</td>
<td>( R[x]/\langle x^{k - 1} \rangle \left( \frac{R[x]}{\langle x^{2^{k/2} + 1} \rangle} \right)^{2^{k/2}} )</td>
</tr>
<tr>
<td>Negacyclic Schönhage</td>
<td>( R[x]/\langle x^{k + 1} \rangle \left( \frac{R[x]}{\langle x^{2^{k/2} + 1} \rangle} \right)^{2^{k/2}} )</td>
</tr>
<tr>
<td>Nussbaumer</td>
<td>( R[x]/\langle x^{k + 1} \rangle \left( \frac{R[y]}{\langle y^{2^{k/2} + 1} \rangle} \right)^{2^{k/2}} )</td>
</tr>
</tbody>
</table>

Generalizations. There are several directions generalizing Schönhage and Nussbaumer. For the polynomial modulus \( x^{2^k} \pm 1 \) in Schönhage, the idea applies to any factors of \( x^{2^k} \pm 1 \). In fact, the case \( x^{2^k} + 1 \) directly follows from \( x^{2^k + 1} - 1 \). As for the polynomial modulus in Nussbaumer, we demonstrate the roles of the polynomial factors in Appendix H.2. Another direction is to replace \( x \) by an odd power of \( x \). In both cases, we replace the indeterminate in the polynomial modulus of the inner ring by a power of two of an odd power. Finally, for the general \( n \), we refer to Appendix G.

Real-world example(s). [BBCT22] transformed \( \mathbb{Z}_{4591}[x]/\langle (x^{1024} + 1)(x^{512} - 1) \rangle \) as follows. They started with Schönhage for

\[
\frac{\mathbb{Z}_{4591}[x]}{\langle (x^{1024} + 1)(x^{512} - 1) \rangle} \cong \frac{\mathbb{Z}_{4591}[x, y]}{\langle x^{32} - y, (y^{32} + 1)(y^{16} - 1) \rangle} \leftrightarrow \frac{\mathbb{Z}_{4591}[x]}{\langle (y^{32} + 1)(y^{16} - 1) \rangle} \left[ y \right]
\]
and applied Nussbaumer to $\mathbb{Z}_{4591}[x]/\langle x^{64} + 1 \rangle$.

### 4.3 Coefficient Ring Switching

For multiplying polynomials in $\mathbb{Z}_q[x]/\langle g \rangle$ for $g = x^n \pm 1$, we can always multiply in $\mathbb{Z}[x]/\langle g \rangle$ and reduce to $\mathbb{Z}_q$ at the end. There are many ways to compute the result in $\mathbb{Z}$. For simplicity, let’s assume we want to multiply two polynomials. Since the result over $\mathbb{Z}$ has coefficients with absolute values bounded by $nq^2$ for signed arithmetic, we choose a $q'$ admitting a suitable FFT over $g$ with $\frac{q'}{2} > \frac{nq^2}{4}$ and compute in $\mathbb{Z}_{q'}[x]/\langle g \rangle$ with signed arithmetic. For unsigned arithmetic, the condition is replaced by $q' > nq^2$.

In many lattice-based cryptosystems, one of the operands has coefficients with absolute values bounded by a small constant, and $q'$ only needs to be larger than a small-multiple of $nq$. For example, one of the operands in NTRU [CDH+20] has coefficients drawn from $\{0, \pm 1\}$ and the small secret polynomials in Saber [DKRV20] has coefficients drawn from $\{-3, \ldots, 0, \ldots, 3\}, \{-4, \ldots, 0, \ldots, 4\}, \{-5, \ldots, 0, \ldots, 5\}$. Obviously, $\mathbb{Z}_q \hookrightarrow \mathbb{Z}_{q'}$ is an injection. If arithmetic defined over $q'$ is too large for efficient implementations, one can also choose coprime integers $q_i$’s as long as their product $q' := \prod_i q_i$ fulfills the same conditions. The tuple of coprime integers is called a residue number system (RNS). Multiplying over $\mathbb{Z}_{q'}$ and $\prod_i \mathbb{Z}_{q_i}$ is used in many contexts, including lattice-based cryptography [FSS20, BBC+20, ACC+21, CHK+21, ACC+22], and also before public key cryptography [Nic71, Pol71].

### 4.4 Comparisons

We briefly compare the cost of coefficient ring injections. See Table 12 for a summary.

**Coefficient ring switching vs localization.** Localization introduces inverses of integers, commonly $2^{-k}$. In practice, we replace the coefficient ring with the $k$-bit larger one. Very often, we choose a $k$ such that the new coefficient ring still amount to the same arithmetic precision, so there is usually no additional cost in practice. As for coefficient ring switching, since the bit-size is at least $2 \times$ larger, cares must be taken while choosing the new coefficient ring.

**Coefficient ring switching vs Schönhage/Nussbaumer.** Schönhage and Nussbaumer adjoin the principal roots of unity by extending the polynomial moduli, and result in $2 \times$ number of coefficients. Coefficient ring switching introduces the principal roots by replacing the coefficient rings with much larger ones, and the polynomial moduli remain the same. To figure out which technique is more beneficial, programmers have to first figure out the efficiency of the multiplication in the coefficient rings. In Schönhage and Nussbaumer, the coefficient ring remains the same but we have doubly many elements. On the other hand, if we switch to a new coefficient ring, the bit-size of the new coefficient ring is at least $2 \times$ larger than the original one. If the cost of multiplication in the original coefficient ring is very fast compared to the new large coefficient ring, then Schönhage and Nussbaumer might be more preferable.

| Table 12: Summary of the cost of coefficient ring injections. |
|-------------|----------------|----------------|----------------|
| Technique       | Adjoined structure | Coeff. ring (bit-size) | Poly. modulus |
| Localization    | $2^{-k}$          | $k$-bit larger.       | -             |
| Schönhage/Nussbaumer | $\omega_{2^k}$   | -                   | $2 \times \#\text{coeff.}$ |
| Coeff. ring switching | $2^{-k}, \omega_{2^k}$ | $2^t \times$ larger. | -             |
5 Polynomial Moduli

This section reviews several techniques related to the polynomial modulus \( g \) of \( R[x]/(g(x)) \). Section 5.2 reviews twisting and composed multiplication converting \( R[x]/(g(x)) \) into a polynomial ring of the form \( R[y]/(g(\zeta y)) \). Section 5.1 reviews embedding and evaluation at \( \infty \) for choosing a polynomial \( h \) admitting the monomorphism \( R[x]/(g(x)) \mapsto R[x]/(h(x)) \). Section 5.3 reviews truncation computing products in \( R[x]/\prod_{i \in \mathbb{Z}} g_i \) with an isomorphism derived from an isomorphism for \( R[x]/(\prod_{i \in \mathbb{Z}} g_i) \) with \( \mathbb{Z}' \subset \mathbb{Z} \). Section 5.4 reviews incomplete transformations and striding, and Section 5.5 reviews the Toeplitz matrix-vector product for \( R[x]/(x^n - ax - \beta) \) from the dual module view of algebra homomorphisms multiplying two size-\( n \) polynomials in \( R[x] \).

5.1 Embedding (Polynomial Modulus) and Evaluation at \( \infty \)

Let \( g \in R[x] \) be a polynomial with \( \deg(g) \leq n \). An obvious approach for multiplying polynomials in \( R[x]/(g) \) is multiplying in \( R[x] \) followed by reducing modulo \( g \). This is the embedding technique for ignoring the structure of \( g \). For \( R[x] \), one further applies an identity map from \( R[x] \) to \( R[x]/(h) \) where \( h \) is a polynomial with degree larger than the product in \( R[x] \). \( h \) is usually a polynomial with a very nice structure for fast transformations.

Evaluation at \( \infty \) is an optimization for choosing \( h \) [Win80]. Suppose \( r \) is the product in \( R[x] \), \( d \) the degree, and \( r_d \) the leading term of \( r \). Instead of computing \( r \), we compute \( r - r_d h \) by embedding into \( R[x]/(h) \) with \( \deg(h) = d \). The term \( r_d h \) is computed individually and added back. In the literature, the idea is commonly presented as allowing \( h \) to contain the polynomial \( x - \infty \). Historically, evaluation at \( \infty \) was first used by [KO62], [Too63] chose small integers for evaluation, and [Win80, Page 31] replaced a point with \( \infty \) for unifying Karatsuba and Toom–Cook. [Win80]'s idea was already as general as this section and applied to other choices of \( h \).

In [KO62], they computed \((a_0 + a_1 x)(b_0 + b_1 x)\) with \( (a_0 + a_1 x)(b_0 + b_1 x) = a_0 b_0 + ((a_0 + a_1)(b_0 + b_1) - a_0 b_0 - a_1 b_1)x + a_1 b_1 x^2 \). If we choose \( h = x^2 + x \), the polynomial \((a_0 + a_1 x)(b_0 + b_1 x) = a_0 b_0 + (a_0 b_1 + a_1 b_0 - a_1 b_1)x \) can be computed in \( R[x]/(x^2 + x) \). Applying \( R[x]/(x^2 + x) \cong R[x]/(x) \times R[x]/(x - 1) \) gives us \((a_0, a_0 + a_1)\) and \((b_0, b_0 + b_1)\). After point-multiplying and inverting, we have \( a_0 b_0 + (a_0 + a_1)(b_0 + b_1) - a_0 a_1 x \). Adding \( a_1 b_1 x^2 + x \) derives the desired result.

It doesn’t seem that people have ever chosen \( h \) with \( x - \infty \) for FFT in the literature. We believe the reason is that one usually splits \( h \) into a large number of small factors for FFT, and the benefit of replacing one of them with \( x - \infty \) is marginal. Nevertheless, we give the following example of multiplying \((a_0 + a_1 x)(b_0 + b_1 x)\) for referential purposes. We rewrite \((a_0 + a_1 x)(b_0 + b_1 x)\) as \((a_0 b_0 + a_1 b_1) + (a_0 b_1 + a_1 b_0)x + a_1 b_1 x^2 - 1,\) compute \((a_0 b_0 + a_1 b_1) + (a_0 b_1 + a_1 b_0)x\) with the isomorphism \( R[x]/(x^2 - 1) \cong \prod R[x]/(x^2 - 1) \), and finally add \( a_1 b_1 x^2 - 1\) to the result.

5.2 Twisting and Composed Multiplication

5.2.1 Twisting

Let \( \zeta \in R \) be an invertible element. Twisting is an isomorphism from \( R[x]/(g(x)) \) to \( R[y]/(g(\zeta y)) \) by introducing \( x \sim \zeta y \). We have the isomorphism \( R[x]/(g(x)) \cong R[x, y]/(x - \zeta y, g(\zeta y)) \) and treat \( R[x]/(x - \zeta y) \) as the coefficient ring. Let \( n = \deg(g) \). In order to change the basis from \((1, x, \ldots, x^{n-1})\) to \((1, y, \ldots, y^{n-1}) = (1, \zeta x, \ldots, \zeta^{n-1} x^{n-1})\), we have to multiply the coefficients with the powers \( \zeta, \ldots, \zeta^{n-1} \). This usually amounts to \( n - 1 \) multiplications in \( R \). However, if \( n \) is odd and \( \zeta = -1 \), we do not need any multiplication for the isomorphism \( R[x]/(x^{n + 1}) \cong R[x, y]/(x + y, y^n - 1) \). We will shortly see
how this insight can be systemized in Section 5.3.

Twisting was introduced in [GS66] for computing FFTs with \( R[x]/(x^{n_0} - 1) \cong \prod_i R[x]/(x^{n_i} - 1) \). See [DH84, Für09] for more insights on the choices of \( n_0 \) and \( n_i \).

### 5.2.2 Composed Multiplication

We go through a specialized approach when \( R = \mathbb{F}_q \). Given \( f_0, f_1 \in \mathbb{F}_q[x] \), we defined their composed multiplication [BC87] as

\[
f_0 \circ f_1 := \prod_{f_0(x) = 0} \prod_{f_1(y) = 0} (x - \alpha \beta)
\]

where \( \alpha, \beta \) are elements from an extension field of \( \mathbb{F}_q \). Composed multiplication generalizes twisting to the polynomial modulus of the form \( (x - \zeta) \circ f(x) \). In particular, we have \( \mathbb{F}_q[x]/\langle (x - \zeta) \circ f(x) \rangle \cong \mathbb{F}_q[y]/\langle x - \zeta, f(y) \rangle \).

Another benefit of composed multiplication is systematically deriving transformations based on (presumably much simpler) coprime factorizations. Let \( f_0 = \prod_{i_0} f_{0,i_0} \) and \( f_1 = \prod_{i_1} f_{1,i_1} \) be coprime factorizations in \( \mathbb{F}_q[x] \). We have \( f_0 \circ f_1 = \prod_{i_0} (f_{0,i_0} \circ f_1) = \prod_{i_0,i_1} (f_{0,i_0} \circ f_{1,i_1}) \). A practically important example is \( f_0 = x^{r} - 1 = \prod_{i_0} (x - \omega_{i_0}^r) \in \mathbb{F}_q[x] \) and \( f_1 = x^{2^k} - 1 \). Given a factorization \( x^{2^k} - 1 = \prod_{i_0} f_{1,i_0} \) in \( \mathbb{F}_q[x] \), we have

\[
x^{2^k r} - 1 = \prod_{i_0} (x^{2^k} - \omega_{r,i_0}^{2^k}) = \prod_{i_0,i_1} \omega_{r,i_1}^{\deg(f_{1,i_1})} f_{1,i_1}(\omega_{r,i_0}^{2^k}).
\]

**Real-world example(s).** For an odd number \( r \) with \( r | (4591 - 1) \), we have the size-\( r \) transformation \( R[x]/\langle x^r - 1 \rangle \cong \prod_{i_0} R[x]/\langle x - \omega_{i_0}^r \rangle \). We extend it to a size-\( 2^k r \) transformation for the ease of vectorization. [HLY24] implemented the isomorphism \( \mathbb{Z}_{4591}[x]/\langle x^{1632} - 1 \rangle \cong \prod_{i_0} \mathbb{Z}_{4591}[x]/\langle x^{16} \pm \omega_{i_0}^r \rangle \), and factor \( \mathbb{Z}_{4591}[x]/\langle x^{16} \pm \omega_{i_0}^r \rangle \) into polynomial rings modulo the composed multiplications of \( x - \omega_{i_0}^r \) and factors of \( x^{16} \pm 1 \).

### 5.3 Truncation

Truncation is a simple and powerful idea. Let \( I' \subset I \) be index sets and \( \{g_i\}_{i \in I} \) be coprime polynomials in \( R[x] \). Suppose we are given the following isomorphism

\[
\eta : \left\{ \frac{R[x]}{\langle \prod_{i \in I} g_i \rangle} \right\} \rightarrow \prod_{i \in I} \frac{R[x]}{\langle g_i \rangle}, \quad a \mapsto (a \mod g_i)_{i \in I}.
\]

We can naturally define an isomorphism \( \eta_{I'} \) as

\[
\eta_{I'} : \left\{ \frac{R[x]}{\langle \prod_{i \in I'} g_i \rangle} \right\} \rightarrow \prod_{i \in I'} \frac{R[x]}{\langle g_i \rangle}, \quad a \mapsto (a \mod g_i)_{i \in I'}.
\]

\( \eta_{I'} \) is called the truncation of \( \eta \) at \( R[x]/\langle \prod_{i \in I'} g_i \rangle \). Truncation was introduced by [CF94, Section 7]. [Ber08] (according to [vdH04], the work [Ber08] was already online prior to [vdH04]) described the benefit in terms of complexity, and [vdH04] named the technique “truncated Fourier transform” for the FFT case. We call it truncation since it is not restricted to FFTs. We demonstrate some of its applications in this section. See Appendix H for more applications to fast transformations.
5.3.1 Application I: $R[x]/\langle x^{2^k-1} + 1 \rangle$ from $R[x]/\langle x^{2^k} - 1 \rangle$

We derive FFT for $R[x]/\langle x^{2^k-1} + 1 \rangle$ from the one for $R[x]/\langle x^{2^k} - 1 \rangle$. For a principal $2^k$-th root of unity $\omega_{2^k}$ realizing $R[x]/\langle x^{2^k} - 1 \rangle \cong \prod_{i=0}^{2^k-1} R[x]/(x - \omega_{2^k}^i)$, we have $R[x]/\langle x^{2^k-1} + 1 \rangle \cong \prod_{i=0}^{2^k-1} R[x]/(x - \omega_{2^k}^{2^k+i})$. We can generalize the idea to arbitrary transformation size $n$. Below is a straightforward generalization of [CF94, Sections 4.12.3 and 4.12.4] outlined in [Hwa22, Section 10].

Let $b = n$ and $\hat{b} = \sum_j b_j 2^j$ be the 2’s complement representation of $-n$ as a $\lceil \log_2 n \rceil$-bit integer. We have $b + \hat{b} = 2 \lceil \log_2 n \rceil$ by definition and define a transformation for

$$R[x]/\left\langle \frac{x^{2^{|\log_2 n|}} - 1}{\prod_j (x^{2^j} + 1)_{b_j}} \right\rangle.$$

This boils down to transformations for rings of the form $R[x]/\langle x^{2^k} \pm 1 \rangle$. An example is the Schönhage for $R[x]/\langle (x^{2048} + 1)(x^{512} - 1) \rangle$ derived from $R[x]/\langle x^{2048} - 1 \rangle$.

5.3.2 Application II: Rader’s FFT

Let $p$ be an odd prime, $I = \{0, \ldots, p-1\}$, $I^* = \{z \in I: z \perp p\}$, and $g$ be a generator of $I^*$. For a principal $p$-th root of unity, we show how Rader’s FFT converts the computing task of size-$p$ cyclic FFT into a size-$\lambda(p)$ cyclic convolution in Section 3.6. In this section, we show that the isomorphism $R[x]/\langle \prod_{i \in I^*} (x - \omega_p^i) \rangle \cong \prod_{i \in I^*} R[x]/(x - \omega_p^i)$ and its inverse can also be converted into size-$\lambda(p)$ cyclic convolutions. For generalization truncating a size-$n$ cyclic DFT to the roots with exponents coprime to $n$, see [Ber23, Sections 4.12.3 and 4.12.4].

**Forward transformation.** Given a polynomial $\sum_{j \in \mathbb{Z}_{\lambda(p)}} a_j x^j \in R[x]/\langle \prod_{i \in I^*} (x - \omega_p^i) \rangle$ and its image $(\hat{a}_{i-1})_{i \in I^*} = \sum_{j \in \mathbb{Z}_{\lambda(p)}} a_j x^j \mod (x - \omega_p^i)$, we have:

$$\hat{a}_{g^{\log_2 i} p}^{-1} = \hat{a}_{i-1} = \sum_{j \in \mathbb{Z}_{\lambda(p)}} a_j \omega_p^{ij} = \omega_p^{-1} \sum_{j \in \mathbb{Z}_{\lambda(p)}} a_j \omega_p^{(j+1)i} = \omega_p^{-1} \sum_{j \in I^*} a_{j-1} \omega_p^{ij}.$$

If we multiply both sides by $\omega_p^{g^{\log_2 i}}$, then we find that $\left(\omega_p^g a_{g^{\log_2 i}-1}\right)_{k \in \mathbb{Z}_{\lambda(p)}}$ is a size-$\lambda(p)$ cyclic convolution of $(a_{g^{k-1}})_{k \in \mathbb{Z}_{\lambda(p)}}$ and $(\omega_p^g)_{k \in \mathbb{Z}_{\lambda(p)}}$.

**Inverse transformation.** [Ber23, Section 4.8.2] showed that convolution by $(\omega_p^g)_{k \in \mathbb{Z}_{\lambda(p)}}$ can be inverted by convolution. By definition, convolution in the polynomial ring $R[x]/\langle x^{\lambda(p)} - 1 \rangle$ is the ring multiplication in the group algebra $R[\mathbb{Z}_{\lambda(p)}]$. Therefore, the inversion amounts to multiplying the multiplicative inverse of $\left(\omega_p^g\right)_{k \in \mathbb{Z}_{\lambda(p)}}$ in the group algebra $R[\mathbb{Z}_{\lambda(p)}]$. The inverse of $\left(\omega_p^g\right)_{k \in \mathbb{Z}_{\lambda(p)}}$ is $\frac{1}{p} \left(\omega_p^{-g^{-k}} - 1\right)_{k \in \mathbb{Z}_{\lambda(p)}}$. [Ber23] proved this by showing that the convolution of $(\omega_p^g)_{k \in \mathbb{Z}_{\lambda(p)}}$ and $\left(\omega_p^{-g^{-k}} - 1\right)_{k \in \mathbb{Z}_{\lambda(p)}}$ is
\((\delta_{0,k}p)_{k\in\mathbb{Z}_p}\): For all \(k\in\mathbb{Z}_p\), we find
\[
\sum_{i+j=k} \omega_n^{g^i} (\omega_n^{-g^{-j} - 1}) = \sum_{i+j=k} \omega_n^{g^i (1-g^{-i+j})} - \sum_{i+j=k} \omega_n^{g^i} = \delta_{0,k}p
\]
as desired.

5.4 Incomplete Transformation and Striding

5.4.1 Incomplete Transformation

For a monic polynomial \(g(x^n) \in \mathbb{R}[x]\), we call a homomorphism \(f : \mathbb{R}[x]/\langle g(x^n) \rangle \to \mathbb{A}\) “incomplete” if \(f\) starts with introducing \(x^n \sim y\) and proceed as a polynomial ring in \(y\) with the coefficient ring \(\mathbb{R}[x]/\langle x^n - y \rangle\). There are several benefits for an incomplete transformation: (i) the definability of fast transformation, (ii) the vectorization-friendliness of \(x^n \sim y\), and (iii) the code size for implementing \(f\). We give an example for (i) in this section. For the benefit of vectorization, see Section 6.2. As for (iii), we refer to [AHY22, Sections 3.2 and 3.3] for more details.

Real-world example(s). Let’s take the polynomial ring \(\mathbb{Z}_{3329}[x]/\langle x^{256} + 1 \rangle\) used in Kyber as an example. Since 3329 is a prime, we can only define a size-\(n\) cyclic FFT for \(n=3329\). This doesn’t permit splitting the polynomial ring into linear factors since \(x^{256} + 1 = \Phi_{512} \text{ and } 512 \not| 3328\). What we can do is introduce \(x^2 \sim y\) and split \((\mathbb{Z}_{3329}[x]/\langle x^2 - y \rangle) / \langle y^{128} + 1 \rangle\) into linear factors in \(y\).

5.4.2 Striding

A closely related idea is striding – we regard \(\mathbb{R}[y]/\langle g(y) \rangle\) as the coefficient ring. This is Nussbaumer (cf. Section 4.2) if we replace \(x^n - y\) with an \(h(x)\), and ask \(g(y)\Phi_{n'}(y)\) and \(h(x)|(x^{n'} - 1)\) with \(n' \geq 2v - 1\). We also have striding Toom–Cook [Ber01, BMK^+22] if \(h(x) = \prod_i (x - s_i)\) for \(\{s_i\} \subset \mathbb{Q} \cup \{\infty\}\).

5.5 Toeplitz Matrix-Vector Product

This section goes through a generic technique converting a fast computation for \(\mathbb{R}[x]\) into a fast computation for \(\mathbb{R}[x]/\langle x^n - \alpha x - \beta \rangle\). We present the mathematical background in this section and will review the architectural insights in Section 6.4.2.

5.5.1 Bilinear System

We review a generic technique for bilinear systems adapted from [Win80, Theorem 6].

**Theorem 1** ([Win80, Theorem 6] for \(R\) commutative). Let \(R\) be a ring, \(I, J, K\) be finite index sets, and \((a_i)_{i\in I}, (b_j)_{j\in J}, (c_k)_{k\in K}\) be tuples drawn from \(R\). For a bilinear system
\[
S_0 : \forall k \in K, \sum_{i\in I, j\in J} r_{i,j,k} a_i b_j
\]
with \(r_{i,j,k} \in R\), we construct the following bilinear systems:
\[
S_1 : \forall j \in J, \sum_{i\in I, k\in K} r_{i,j,k} a_i c_k,
\]
\[
S_2 : \forall i \in I, \sum_{j\in J, k\in K} r_{i,j,k} c_k b_j.
\]
Then any bilinear algorithm for one of \(S_0, S_1\) or \(S_2\) leads to algorithms for the other two.
One can prove Theorem 1 by defining a \( |\mathcal{K}| \times |\mathcal{I}| \) matrix \( B_{k,i} := \left( \sum_{j \in \mathcal{J}} r_{(i,j,k)} b_j \right) \), and write \( S_0 \) as \( 3a \) and \( S_2 \) as \( B^T c \) where \( a \) and \( c \) are the column representations of \( (a_i)_{i \in \mathcal{I}} \) and \( (c_k)_{k \in \mathcal{K}} \). See Appendix J for details. If we choose \( r_{(i,j,k)} := \|i + j = k\| \) where \( \| \) is the Iverson bracket\(^7\) and \( |\mathcal{K}| = |\mathcal{I}| + |\mathcal{J}| - 1 \), \( S_0 \) represents the coefficients of \( \left( \sum_{i \in \mathcal{I}} a_i x^i \right) \left( \sum_{j \in \mathcal{J}} b_j x^j \right) \) in an obvious way. Then, \( S_2 \) becomes

\[
S_2 : \forall i \in \mathcal{I}, \sum_{j \in \mathcal{J}, k \in \mathcal{K}} [k - j = i] c_k b_j.
\]

This is called a transposed multiplication [Sho99, Section 3] or a middle product [HQZ04]. [Fid73, Theorem 4 and 5] proved that transposing an algorithm results in same numbers of constant multiplications (\( r a \) for a constant \( r \) in \( R \)), non-constant multiplications (\( a_i b_j \)), and additions/subtractions with a linear difference. For the history of transposition principle, see [BCS13, Section 4].

We illustrate with the case \( |\mathcal{I}| = |\mathcal{J}| = n \). \( S_0 : \forall k \in \mathcal{K}, \sum_{i \in \mathcal{I}} \sum_{j \in \mathcal{J}} [i + j = k] a_i b_j = \sum_{i \in \mathcal{I}, i \leq k} a_i b_{k-i} \) can be written as:

\[
\begin{pmatrix}
a_0 & 0 & \cdots & 0 \\
\vdots & \ddots & \cdots & \vdots \\
0 & \cdots & \ddots & \vdots \\
0 & \cdots & \cdots & a_n-1
\end{pmatrix}
\begin{pmatrix}
b_0 \\
\vdots \\
b_{n-1}
\end{pmatrix}.
\]

And \( S_2 : \forall i \in \mathcal{I}, \sum_{j \in \mathcal{J}, k \in \mathcal{K}} [k - j = i] c_k b_j = \sum_{j \in \mathcal{J}} c_{i+j} b_j \) can be written as:

\[
\begin{pmatrix}
c_0 & \cdots & \cdots & \cdots \\
\vdots & \ddots & \cdots & \vdots \\
0 & \cdots & \cdots & c_{n-1}
\end{pmatrix}
\begin{pmatrix}
b_0 \\
\vdots \\
b_{n-1}
\end{pmatrix}.
\]

\( S_2 \) relates \( S_0 \) to polynomial multiplication modulo a polynomial.

5.5.2 Toeplitz Transform for \( R[x]/(x^n - \alpha x - \beta) \)

Let \( M \) be an \( n \times n \) matrix. We call \( M \) a Hankel matrix if \( M_{i,j} = M_{i+1,j-1} \) for all possible \( i,j \), and a Toeplitz matrix if \( M_{i,j} = M_{i+1,j+1} \) for all possible \( i,j \). Notice that a Hankel matrix can be converted into a Toeplitz matrix by multiplying an anti-diagonal matrix of ones and vice versa.

This section explains how to derive a fast computation for \( R[x]/(x^n - \alpha x - \beta) \) by looking at an already well-studied algebra homomorphism \( f \) multiplying two size-\( n \) polynomials in \( R[x] \). There are four steps: (i) interpreting multiplication in \( R[x]/(x^n - \alpha x - \beta) \) as a Toeplitz matrix-vector product; (ii) interpreting the Toeplitz matrix-vector product as a composition of applying an anti-diagonal matrix of ones and a Hankel matrix–vector product; (iii) rewriting the Hankel matrix–vector product as a bilinear system of the form \( S_2 \); and (iv) converting the computing task into a bilinear system of the form \( S_2 \). Once we go through all the steps (i) – (iv), we can now convert an \( f \) into an algorithm for

\(^7\)Iverson bracket is an indicator function for the truthfulness. The image of \( \| \) is \( \{0, 1\} \), which can be certainly embedded into a ring.
\( R[x]/(x^n - \alpha x - \beta) \) via the module–theoretic view. Notice that steps (ii) and (iii) are sometimes described as a single step. We describe them separately for clarity.

Steps (i) – (iii) are already shown in previous paragraphs. We now explain how to interpret the multiplication in \( R[x]/(x^n - \alpha x - \beta) \) as a Toeplitz matrix–vector product with potential post-processing. We define \( \text{Toeplitz}_n \) as the following function mapping a \((2n - 1)\)-tuple drawn from \( R \) to a Toeplitz matrix over \( R \):

\[
\text{Toeplitz}_n : (z_{2n-2}, \ldots, z_0) \mapsto \begin{pmatrix}
  z_{n-1} & \cdots & z_0 \\
  \vdots & \ddots & \vdots \\
  z_{2n-2} & \cdots & \cdots \\
\end{pmatrix}.
\]

Let \( a = \sum_i a_i x^i, b = \sum b_i x^i \) be size-\( n \) polynomials. We recall that computing \( \sum_i c_i x^i = ab \) in \( R[x] \) can be regarded as the following matrix–vector product:

\[
\begin{pmatrix}
  c_0 \\
  \vdots \\
  c_{2n-2}
\end{pmatrix} = \begin{pmatrix}
  b_0 & 0 & \cdots & 0 \\
  \vdots & \ddots & \ddots & \vdots \\
  0 & \cdots & \cdots & b_{n-1} \\
  0 & \cdots & \cdots & 0
\end{pmatrix} \begin{pmatrix}
  a_0 \\
  \vdots \\
  a_{n-1}
\end{pmatrix}.
\]

Since \( (c_0, \ldots, c_{n-1}) \) can be computed with a Toeplitz matrix–vector product, we only need to convert reduction modulo \( x^n - \alpha x - \beta \) into the manipulation of Toeplitz matrices. A standard approach for reducing modulo \( x^n - \alpha x - \beta \) multiplying \( (c_{n}, \ldots, c_{2n-2}) \) by \( \alpha \) and \( \beta \) and adding the results to \( (c_1, \ldots, c_{n-1}) \) and \( (c_0, \ldots, c_{n-2}) \). Based on this, \( ab \) \( \text{mod} \ (x^n - \alpha x - \beta) \) can be written as

\[
(M_0 + M_1 + M_2) a
\]

where

\[
\begin{cases}
  M_0 = \text{Toeplitz}_n(b_{n-1}, \ldots, b_0, 0, \ldots, 0), \\
  M_1 = \text{Toeplitz}_n(0, \ldots, 0, \beta b_{n-1}, \ldots, \beta b_1),
\end{cases}
\]

and

\[
M_2 = \alpha \begin{pmatrix}
  0 & 0 & \cdots & 0 \\
  0 & b_{n-1} & \cdots & b_0 \\
  \vdots & \ddots & \ddots & \vdots \\
  0 & \cdots & \cdots & 0
\end{pmatrix}.
\]

A specialized approach for \( \beta = 1 \). We review the case \( \beta = 1 \) implied by [FH07, Section 3.2]. See [HB95, FD05] for related works when \( R = F_2 \) and Appendix I for an approach handling generic \( \beta \) with some overhead. Since \( \beta = 1 \), \( M_0 + M_1 \) is the circulant matrix implementing \( ab \) \( \text{mod} \ (x^n - 1) \). Obviously, if we multiply a circulant matrix by a cyclic shift matrix (either left-multiplying or right-multiplying), we still have a circulant matrix. Let \( P \) be the matrix moving the 0-th row of a circulant matrix to the bottom. We find that both \( P(M_0 + M_1) \) and \( PM_2 \) are Toeplitz matrices. Therefore, \( P(M_0 + M_1 + M_2) \) is a Toeplitz matrix and we can implement \( (M_0 + M_1 + M_2) a \) as

\[
(M_0 + M_1 + M_2) a = P^{-1} (P(M_0 + M_1 + M_2) a).
\]

In Section 6.2, we will justify why cyclic shift matrices are practically efficient.
Padding. The last instrument is padding. Suppose we have an $n \times n$ Toeplitz matrix $T = \text{Toeplitz}(z_{2n-2}, \ldots, z_0)$. For an $n' \geq n$, we can always pad $T$ to an $n' \times n'$ Toeplitz matrix $T'$ as follows:

$$T' = \text{Toeplitz} \begin{pmatrix} 0, \ldots, 0, z_{2n-2}, \ldots, z_0, 0, \ldots, 0 \\ n'-n \end{pmatrix}.$$  

The point is that if a $n \times n$ Toeplitz matrix does not admit efficient implementations, we can pad them to slightly larger ones with efficient implementations [IKPC22, Section 3.1].

6 Vectorization

This section reviews the formalization of vectorization by [Hwa23].

6.1 Vector Instruction Sets/Extensions

Vector instruction sets and extensions are important ingredients for optimized implementations since high-dimensional polynomial rings in lattice-based cryptosystems admit high degree of parallelism. Common vector instructions sets and extensions are the Digital Signal Processing extension in Armv7-M [ARM21b, Section A1.3] (in this case, we also call it Armv7E-M), the Neon extension in Armv7-A [ARM12, Section A2.6], the Advanced SIMD extension Armv8-A [ARM21a, Section A1.5], the Helium extension in Armv8-M [ARM23, Sections B5 and C2.3.1], AVX2, and AVX-512 [Int23].

A vector contains power-of-two number of bits of data, for example, we have 32-bit registers in Armv7E-M, 128-bit vector registers in Armv7-A and Armv8-A, 256-bit vector registers in AVX2, and 512-bit vector registers in AVX-512. In a vector instruction set/extension, we have vector instructions with vector registers as arguments. For bit-field arithmetic, we have logical or/exclusive-or/and/not and logical/arithmetic shift. For arithmetic and permutations, we have additions, subtractions, multiplications, and permutation instructions operating on vector registers as packed 8-bit, 16-bit, 32-bit, 64-bit data. When the context is clear, we denote $v$ as the number of elements with a fixed bit-size in a vector register.

Roughly speaking, there are two categories of vector instructions:

- Vector-by-vector instructions: the vector instruction takes two vector registers as inputs and returns a vector register as the output.
- Vector-by-scalar instructions: the vector instruction takes a vector registers and a scalar (a constant, a lane of a vector register [ARM21b, ARM12, ARM21a], or a non-vector register [ARM23])

6.2 Vectorization Friendliness

We first review the notion “vectorization-friendliness” formally relating homomorphisms to vector-by-vector instructions [Hwa23]. Conceptually, vectorization-friendliness qualifies if a homomorphisms can be mapped to a string of vector-by-vector instructions and cyclic/negacyclic shifts. Cyclic and negacyclic shifts are vectorization-friendly since we can implement them with extractions or memory operations:

- Extraction: For cyclic shift, we extract consecutive elements from a pair of vector registers and extract again with input swapped. The resulting pair of vector registers is now a cyclic shift of the original pair. For the negacyclic shift, we replace a vector register by its negative value in one of the extractions. This idea is applicable to Armv7/8-A since we have $\text{ext}$ implementing exactly the desired operation [HLY24].
• Memory operations: We can also implement cyclic/negacyclic shift with memory operations – we perform unaligned loads, shuffle the last vector register (and negate it in the negacyclic case), and store the vectors to memory [BBCT22].

The set \textit{BlockDiag}. We define \textit{BlockDiag} as a certain set of block diagonal matrices implementing cyclic/negacyclic shifts and twisting. Formally, \textit{BlockDiag} is defined as a set of all possible block diagonal matrices with each block a $v' \times v'$ matrix that is a diagonal matrix implementing twisting or a cyclic/nagecyclic shift matrix for all $v$-multiple $v'$.

Vectorization friendliness, formally [Hwa23]. Let $f$ be an algebra homomorphism and $M_f$ its matrix form. We call $f$ vectorization-friendly if
\[
M_f = \prod_i (M_{f_i} \otimes I_v) S_{f_i}
\]
for $S_{f_i} \in \text{BlockDiag}$ and some matrices $M'_{f_i}$'s. One we find such a decomposition for a vectorization-friendly $f$, we implement $M_{f_i} \otimes I_v$ with vector additions, subtractions, and multiplications, and $S_{f_i}$ with vector multiplications and cyclic/negacyclic shifts.

Dimension requirement of vectorization friendliness. From the definition, we know that $f$ is vectorization friendly only if its domain has dimension a multiple of $v$.

Additional properties of vectorization friendliness. Obviously, if an algebra homomorphism is vectorization-friendly, its inverse and module-theoretic dual are also vectorization-friendly.

6.3 Permutation Friendliness
Conceptually, permutation-friendliness stands for vectorization-friendliness up to a special type of permutation – interleaving.

The set \textit{Interleave} [Hwa23]. Again, let $v'$ be a multiple of $v$. We define the transposition matrix $T_{v^2}$ as the $v'^2 \times v'^2$ matrix permuting the elements as if transposing a $v' \times v'$ matrix. See Appendix K for examples. We call a matrix $M$ interleaving matrix with step $v'$ if it takes the form
\[
M = (\pi' \otimes I_{v'}) (I_m \otimes T_{v^2}) (\pi \otimes I_{v'})
\]
for a positive integer $m$ and permutation matrices $\pi, \pi'$ permuting $mv'$ elements. The set \textit{Interleave} consists of interleaving matrices of all possible steps. Obviously, we can implement an interleaving matrix as a transposition matrix with on-the-fly permutations.

Permutation friendliness, formally [Hwa23]. Let $g$ be an algebra homomorphism and $M_g$ its matrix form. We call $g$ permutation-friendly if
\[
M_g = \prod_i S_{g_i} M_{g_i}
\]
for $S_{g_i} \in \text{Interleave}$ and vectorization-friendly $M_{g_i}$'s. Once we find such a decomposition of a permutation friendly $g$, we implement the vectorization-friendly parts as described in previous section and the interleaving matrices with permutation instructions.
Dimension requirement of permutation friendliness. From the definition, permutation friendliness necessitates a stronger dimension condition than vectorization friendliness due to the existence of interleaving matrices. Interleaving matrices necessitates that a permutation-friendly homomorphism must have dimension a multiple of $v^2$.

6.4 Guide of Vectorization

6.4.1 Vectorization with Vector-By-Vector Multiplication Instructions
Generally, while computing with vector-by-vector instructions, we choose algebra homomorphisms $f$ and $g$ such that $f$ is vectorization-friendly and $g$ is permutation-friendly. Their composition $g \circ f$ then admits a suitable mapping to our target vector instruction set.

6.4.2 Vectorization Vector-By-Scalar Multiplication Instructions
For an $m \times n$ Toeplitz matrix $M = \text{Toeplitz}_{m \times n}(a_{m-1}, \ldots, a_0, a'_1, \ldots, a'_{n-1})$ over the ring $R$, [CCHY23] demonstrated the benefit of vector-by-scalar multiplication instructions when applying $M$ to a vector $b = (b_0, \ldots, b_{n-1})$. Since polynomial multiplications in $R[x]/(x^n - \alpha x - \beta)$ can be rephased as Toeplitz matrix-vector products (cf. Section 5.5.2 and Appendix I), we can multiply polynomials in $R[x]/(x^n - \alpha x - \beta)$ with vector-by-scalar multiplication instructions. Conceptually, the goal is to design transformations resulting in small-dimensional Toeplitz matrix-vector products and implement them with vector-by-scalar multiplication instructions. We outline the overall strategy as follows.

1. Choose a vectorization-friendly algebra homomorphism $f$ decomposing into small-dimensional polynomial multiplications.

2. If the resulting polynomial multiplications are small-dimensional Toeplitz matrix-vector products, then we are done.

3. If step 2 fails (for example, when some polynomial multiplications in the image are not Toeplitz matrix-vector products), we dualize the transformation as described in Section 5.5.2.

4. Eventually, we have small-dimensional Toeplitz matrix-vector products regardless if $f$ if results in small-dimensional Toeplitz matrix-vector products.

The remaining question is the relation between small-dimensional Toeplitz matrix-vector products and vector-by-scalar multiplication instructions.

Small-dimensional Toeplitz matrix-vector products [CCHY23]. For the small-dimensional case, [CCHY23] showed that one can implement the Toeplitz matrix-vector product efficiently with vector-by-scalar multiplication instructions. For simplicity, we demonstrate with the case $m = n = 4$ and $R = \mathbb{Z}_{2^{32}}$:

\[
\begin{pmatrix}
  c_0 \\
  c_1 \\
  c_2 \\
  c_3
\end{pmatrix} = \begin{pmatrix}
  a_0 & a'_1 & a'_2 & a'_3 \\
  a_1 & a_0 & a'_1 & a'_2 \\
  a_2 & a_1 & a_0 & a'_1 \\
  a_3 & a_2 & a_1 & a_0
\end{pmatrix} \begin{pmatrix}
  b_0 \\
  b_2 \\
  b_1 \\
  b_3
\end{pmatrix}.
\]

For deploying vector-by-scalar multiplications, the key is to identify the reuses of the scalar operands. Obviously, we find that each of $b_0, \ldots, b_3$ is involved in four multiplications in $R$: we compute $a_0b_0, a_1b_0, a_2b_0, a_3b_0$ for the operand $b_0$, etc. Therefore, an obvious choice is to map each columns to a vector and apply vector-by-scalar multiplications. There are two
ways for constructing the column vectors of **Toeplitz**($a_3, \ldots, a_0, a'_1, \ldots, a'_3$) from an array storing $a'_3, \ldots, a'_1, a_0, \ldots, a_3$: either loading from the addresses pointing to $a_0, a'_1, \ldots, a_3$, or loading the first column and first row and combining them with special instructions. See Appendix L for illustrations. After constructing the matrix column-wise, we now identify the column vector $c$ as the sum of columns scaled by the corresponding elements in $b$. In other words,

$$
\begin{pmatrix}
  c_0 \\
  c_1 \\
  c_2 \\
  c_3
\end{pmatrix} =
\begin{pmatrix}
  a_0 \\
  a_1 \\
  a_2 \\
  a_3
\end{pmatrix} + b_1
\begin{pmatrix}
  a'_1 \\
  a_0 \\
  a_1 \\
  a_2
\end{pmatrix} + b_2
\begin{pmatrix}
  a'_2 \\
  a'_1 \\
  a_0 \\
  a_1
\end{pmatrix} + b_3
\begin{pmatrix}
  a'_3 \\
  a'_2 \\
  a'_1 \\
  a_0
\end{pmatrix}.
$$

Algrotihm 1 is an illustration.

**Algorithm 1** Applying a $4 \times 4$ Toeplitz matrix with vector-by-scalar multiplication instructions [CCHY23].

**Inputs:** **Toeplitz**($a_3, a_2, a_1, a_0, a'_1, a'_2, a'_3$), ($b_0, b_1, b_2, b_3$).

**Outputs:** **Toeplitz**($a_3, a_2, a_1, a_0, a'_1, a'_2, a'_3$)($b_0, b_1, b_2, b_3$).

1: $t0 = a_3 || a_2 || a_1 || a_0$
2: $t1 = a_2 || a_1 || a_0 || a'_1$
3: $t2 = a_1 || a_0 || a'_1 || a'_2$
4: $t3 = a_0 || a'_1 || a'_2 || a'_3$
5: $c = \text{mul}(t0, b_0)$
6: $c = \text{mla}(c, t1, b_1)$
7: $c = \text{mla}(c, t2, b_2)$
8: $c = \text{mla}(c, t3, b_3)$

## 7 Case Studies

We go through several case studies in this section. Section 7.1 compares Barrett and Montgomery multiplications with Dilithium implementations for modular arithmetic, and Section 7.2 compares Montgomery and Plantard multiplications with Kyber implementations. We then go through several algebraic techniques and vectorization. Section 7.4 explains how to exploit the matrix-to-vector structure with Saber as an example, Section 7.5 reviews the benefit of Toeplitz matrix-vector multiplication with NTRU as an example, and Section 7.6 details the design choices for vectorization with NTRU Prime as an example.

### 7.1 Dilithium : Barrett vs Montgomery Modular Arithmetic

This section reviews the modular arithmetic used in Dilithium. In Dilithium, we want to multiply polynomials in $\mathbb{Z}_q[x]/(x^{256} + 1)$ for $q = 2^{23} - 2^{13} + 1$. Since $q$ is a prime supporting a size-$2^{13}$ cyclic FFT, we can split $x^{256} + 1$ into linear factors (recall that $x^{256} + 1 = \Phi_{512}(x^{512} - 1)$ and $512|2^{13}$). The choice of FFT is already determined by the specification – one of the operands is assumed to be transformed. The remaining question is to compute the modular arithmetic efficiently. For a 32-bit value $a$, modular reduction is fairly simple. Since $q$ is fairly close to $2^{23}$, $a - \left\lfloor \frac{a}{2^{23}} \right\rfloor q$ is a representative of $a \mod q$ within an acceptable range.

How about modular multiplications? In Section 2.5, we compare three classes of modular multiplications – Montgomery, Barrett, and Plantard, and review the required multiplication instructions. In practice, low multiplications are fairly common, while high

\[\text{The actual range for } -2^{31} \leq a < 2^{31} \text{ is } [-4186113, 4194303] \text{ by brute-force testing.}\]
multiplications and long multiplications usually lack accumulative or subtractive variants. See Table 13 for a summary for combinations of precisions and architectures. For the actual instructions, see [ARM21b, Section A4.4.3], [ARM21a, Sections C3.5.14, C3.5.16, and C3.5.18], and [Ora14, Section 3.7].

Table 13: Overview of the available forms of input-independent signed multiplication instructions in some popular instruction set architectures and extensions.

<table>
<thead>
<tr>
<th></th>
<th>Low multiplications</th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>mullo</td>
<td>mlalo</td>
<td>mlsllo</td>
</tr>
<tr>
<td>Avmv7-M</td>
<td>✓ (R = 2^{12})</td>
<td>✓ (R = 2^{12})</td>
<td>✓ (R = 2^{12})</td>
</tr>
<tr>
<td>Avmv7E-M</td>
<td>✓ (R = 2^{12})</td>
<td>✓ (R = 2^{12})</td>
<td>✓ (R = 2^{12})</td>
</tr>
<tr>
<td>Avmv8.0-A</td>
<td>✓ (R = 2^{8}, 2^{16}, 2^{24})</td>
<td>✓ (R = 2^{8}, 2^{16}, 2^{24})</td>
<td>✓ (R = 2^{8}, 2^{16}, 2^{24})</td>
</tr>
<tr>
<td>Avmv8.1-A</td>
<td>✓ (R = 2^{8}, 2^{16}, 2^{24})</td>
<td>✓ (R = 2^{8}, 2^{16}, 2^{24})</td>
<td>✓ (R = 2^{8}, 2^{16}, 2^{24})</td>
</tr>
<tr>
<td>AVX2</td>
<td>✓ (R = 2^{16}, 2^{24})</td>
<td>-</td>
<td>-</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th></th>
<th>High multiplications</th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>mulhi</td>
<td>mlahi</td>
<td>mlshi</td>
</tr>
<tr>
<td>Avmv7-M</td>
<td>-</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Avmv7E-M</td>
<td>✓ (R = 2^{12})</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Avmv8.0-A</td>
<td>✓ (R = 2^{16}, 2^{24})</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Avmv8.1-A</td>
<td>✓ (R = 2^{16}, 2^{24})</td>
<td>✓ (R = 2^{16}, 2^{24})</td>
<td>✓ (R = 2^{16}, 2^{24})</td>
</tr>
<tr>
<td>AVX2</td>
<td>✓ (R = 2^{16})</td>
<td>-</td>
<td>-</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th></th>
<th>Long multiplications</th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>mull</td>
<td>mlal</td>
<td>mlsl</td>
</tr>
<tr>
<td>Avmv7-M</td>
<td>-</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Avmv7E-M</td>
<td>✓ (R = 2^{16}, 2^{24})</td>
<td>✓ (R = 2^{16}, 2^{24})</td>
<td>-</td>
</tr>
<tr>
<td>Avmv8.0-A</td>
<td>✓ (R = 2^{8}, 2^{16}, 2^{24})</td>
<td>✓ (R = 2^{8}, 2^{16}, 2^{24})</td>
<td>✓ (R = 2^{8}, 2^{16}, 2^{24})</td>
</tr>
<tr>
<td>Avmv8.1-A</td>
<td>✓ (R = 2^{8}, 2^{16}, 2^{24})</td>
<td>✓ (R = 2^{8}, 2^{16}, 2^{24})</td>
<td>✓ (R = 2^{8}, 2^{16}, 2^{24})</td>
</tr>
<tr>
<td>AVX2</td>
<td>✓ (R = 2^{16})</td>
<td>-</td>
<td>-</td>
</tr>
</tbody>
</table>

7.1.1 Avmv8-A Neon Implementations

For vectorized implementations, [BHK+22b] implemented Barrett multiplication and the subtractive variant of Montgomery multiplication with Avmv8.0-A Neon. For Avmv8.0-A, there are multiplication instructions sq{, r}dmulh computing and doubling the high-products – For two values $a$ and $b$, sqdmulh computes $\lfloor \frac{2ab}{R} \rfloor$ with saturations, and sqrdmulh applies rounding $\lfloor \rfloor$ instead of flooring $\lfloor \rfloor$. For Montgomery multiplication, [BHK+22b] implemented

$$\frac{1}{2} \left( \left\lfloor \frac{2ab}{R} \right\rfloor - \left\lfloor \frac{2(abq^{-1} \mod \frac{\pm R}{\pm R})}{R} \right\rfloor \right)$$

as shown in Algorithm 2. One can show that $\frac{1}{2} \left( \left\lfloor \frac{2ab}{R} \right\rfloor - \left\lfloor \frac{2(abq^{-1} \mod \frac{\pm R}{\pm R})}{R} \right\rfloor \right) = \left\lfloor \frac{\pm q}{R} \right\rfloor - \left\lfloor \frac{abq^{-1} \mod \frac{\pm R}{\pm R} q}{R} \right\rfloor$. We leave the justification to readers. For Barrett multiplication,

9Apply McEliece’s observation that for a continuous, monotonically increasing function $f : R' \to R''$ with $R', R'' \subset R$ and $f(x) \in Z \rightarrow x \in Z$, we have $\lfloor f(x) \rfloor = \lfloor f([x]) \rfloor$ when $f(x), f([x]) \in R'$ and $\lfloor f([x]) \rfloor$ when $f(x), f([x]) \in R'$ [GKP94, Equation 3.10].
[BHK+22b] implemented

\[ ab - \left\lfloor \frac{a}{\frac{q}{R}} \right\rfloor_2 \\mod q \]

for \( \lfloor r \rfloor_2 = r \mapsto 2^\lfloor \frac{r}{2} \rfloor \) as shown in Algorithm 3. Since there is a subtractive form for low products only, Barrett multiplication saves one addition/subtraction compared to Montgomery multiplication. Additionally, [HLY24, Algorithms 3 and 4] proposed the accumulative and subtractive variants computing representatives of \( d \pm ab \mod q \) and [Yan22] found their benefits for computing radix-2 Cooley–Tukey butterflies on platforms implementing barrel shift (for example, Cortex-M4). We leave the exploration of the accumulative/subtractive Barrett multiplication to the readers.

Algorithm 2 Single-width Montgomery multiplication [BHK+22b, Algorithm 12].

Inputs: Values \( a, b \in [-\frac{R}{2}, \frac{R}{2}) \).

Output: \( c = \frac{1}{2} \left( \left\lfloor \frac{2ab}{R} \right\rfloor - \frac{2(abq^{-1} \mod \pm R)}{R} \right) \).

1: sqdmulh \( c, a, b \) ▷ \( c = \left\lfloor \frac{2ab}{R} \right\rfloor \).
2: mul \( t, a, bq^{-1} \mod \pm R \) ▷ \( t = abq^{-1} \mod \pm R \).
3: sqdmulh \( t, t, q \) ▷ \( t = \left\lfloor \frac{2(abq^{-1} \mod \pm R)}{R} \right\rfloor \).
4: shsub \( c, c, t \) ▷ \( c = \frac{1}{2} \left( \left\lfloor \frac{2ab}{R} \right\rfloor - \frac{2(abq^{-1} \mod \pm R)}{R} \right) \).

Algorithm 3 Single-width Barrett multiplication [BHK+22b, Algorithm 10].

Inputs: Values \( a, b \in [-\frac{R}{2}, \frac{R}{2}) \).

Output: \( lo = ab - \left\lfloor \frac{a}{\frac{q}{R}} \right\rfloor_2 \\mod q \).

1: mul \( lo, a, b \) ▷ \( lo = ab \).
2: sqrdmulh \( hi, a, \left\lfloor \frac{a}{\frac{q}{R}} \right\rfloor_2 \) ▷ \( hi = \left\lfloor \frac{a}{\frac{q}{R}} \right\rfloor_2 \).
3: mls \( lo, hi, q \) ▷ \( lo = ab - \left\lfloor \frac{a}{\frac{q}{R}} \right\rfloor_2 \\mod q \).

7.1.2 Armv7-M Implementations

This section reviews [HKS23]’s observation of Barrett multiplication on Cortex-M3. Cortex-M3 implements the ISA Armv7-M where \( \{u, s\}\{mul, mla, mls\} \) are the only multiplication instructions. However, double-size products \( \{u, s\}\{mul, mla, mls\} \) take input-dependent time [ARM10] and can only be used for computing public data. For computing the 32-bit NTTs of secret data in Dilithium, [GKS21] implemented 32-bit Montgomery multiplication while emulating the double-size products with \( \{u, s\}\{mul, mla, mls\} \) as shown in Algorithm 4.

[HKS23] proposed using Barrett multiplication for 32-bit modular multiplications on Cortex-M3. They observed the following:

B1 While Montgomery multiplication requires two double-size/high products and one low product, Barrett multiplication requires one high product and two low products.

B2 In Barrett multiplication, the high product only needs to be approximately correct.
Algorithm 4 Constant-time 32-bit Montgomery multiplication [GKS21, Listing 7]

**Inputs:** al + ah \cdot R = a, bl + bh \cdot R = b.

**Output:** tmph = \frac{ab + (-abq^{-1} \mod \pm R)q}{R}.

1: **SBSMULL** tmpl, tmph, al, ah, bl, bh  
   \triangleright  tmpl + tmph \cdot R = ab.
2: mul ah, tmpl, \neg q^{-1} \mod \pm R  
   \triangleright  ah = abq^{-1} \mod \pm R.
3: ubfx al, ah, #0, #16
4: asr ah, ah, #16  
   \triangleright  al + ah \cdot R = -abq^{-1} \mod \pm R.
5: **SBSMLAL** tmpl, tmph, al, ah, ql, qh  
   \triangleright  tmph = \frac{ab + (-abq^{-1} \mod \pm R)q}{R}.

Observation B1 saves one emulation of the double-size/high product, and observation B2 enables a faster emulation with tolerable errors.

Let’s consider [] the following integer approximation:

\[ \forall r \in \mathbb{R}, [r] = a_{r,h} + \left\lfloor \frac{a_{r,l}b_h}{\sqrt{R}} \right\rfloor + \left\lfloor \frac{a_{r,h}b_l}{\sqrt{R}} \right\rfloor \]

for \( a_{r,l} + a_{r,h} \sqrt{R} = \frac{r}{\sqrt{R}} \) and \( b_l + b_h \sqrt{R} = \frac{[b]}{\sqrt{R}} \). For \( -\frac{2}{2} \leq b < \frac{2}{2} \) and \(-\frac{2}{2} \leq a_{r,l} + a_{r,h} \sqrt{R} < \frac{2}{2} \), [HKS23] showed that \( |r - [r]| \leq 3 \) and \( \| \mod [R] \| \leq \frac{25}{2} \), and computed

\[
ab - \left\lfloor \frac{a}{\frac{[b]}{\sqrt{R}}} \right\rfloor q
\]

as a representative of \( ab \mod \pm q \) with range bounded by

\[
\frac{|a| \mod \pm q}{R} + \| \mod [R] \| q \leq \frac{|a| \frac{q}{2} + \frac{25q}{2}}{R} = \frac{q}{2} \left( 7 + \frac{|a|}{R} \right).
\]

Algorithm 5 is an illustration.

Algorithm 5 Constant-time 32-bit Barrett multiplication with approximated high product [HKS23].

**Inputs:** a = a, b = b.

**Output:** t3 = ab - \left\lfloor \frac{a}{\frac{[b]}{R}} \right\rfloor q.

1: mul t3, a, b  
   \triangleright  t3 = ab \mod \pm R.
2: ubfx t0, a, #0, #16
3: asr a, a, #16  
   \triangleright  t0 + a \cdot R = a.
4: smmulr_approx t1, a, bhi, t0, blo, t2  
   \triangleright  t1 = \left\lfloor \frac{a}{\frac{[b]}{R}} \right\rfloor q.
5: mls t3, t1, q, t3  
   \triangleright  t3 = ab - \left\lfloor \frac{a}{\frac{[b]}{R}} \right\rfloor q.

7.2 Kyber: Montgomery vs Plantard Modular Arithmetic

In this section, we compare the applications of Montgomery and Plantard multiplications to Kyber, which requires modular multiplication for the coefficient ring \( \mathbb{Z}_{3329} \). We assume \( R = 2^{16} \) in this section. [HZZ’22] and [AMOT22] independently found the signed Plantard multiplications. [HZZ’22] identified the benefit of 16-bit modular arithmetic if there
are 16 × 32-bit multiplication instructions, and [AMOT22] identified the benefit of 32-bit modular arithmetic using only 64-bit multiplication instructions. [HZZ+] later implemented 16-bit Plantard multiplication following [AMOT22]’s insights when there are no 16 × 32-bit multiplication instructions.

7.2.1 Armv7-M Implementations

In Armv7-M, since all the registers contain 32-bit values, we can compute the 16-bit Montgomery multiplication with `mul` and `mla` in an obvious way (cf. Algorithm 6). [HZZ+] implemented 16-bit Plantard multiplication with [AMOT22]’s insights. For 16-bit values
\[ a \in \left[ -\frac{R}{2}, \frac{R}{2} \right) \] and
\[ b \in \left[ -\frac{q^2}{2}, \frac{q^2}{2} \right), \]
we compute
\[
\left\lfloor \frac{-abq^{-1} \mod \pm R^2}{R} \right\rfloor q + 2^a q
\]
as a representative of \(-abR^{-2} \mod \pm q\). See 7 for an illustration. If \(b\) is known in prior, we skip the computation for \(-bq^{-1} \mod \pm R^2\) and cancel out the scaling \(-R^2 \mod \pm R^2\) by precomputing \(-(-bR^2 \mod \pm q) q^{-1} \mod \pm R^2\).

Algorithm 6 16-bit Montgomery multiplication with Armv7-M [GKS21].

Inputs: Values \(a, b \in \left[ -\frac{R}{2}, \frac{R}{2} \right)\).
Output: \(t0 = ab + (-abq^{-1} \mod \pm R) q\).

1: mul \(t0, a, b\) \(\triangleright t0 = ab\).
2: mul \(t1, t0, -q^{-1} \mod \pm R\) \(\triangleright t1 = -abq^{-1} \mod \pm R\).
3: sxth \(t1, t1, #0, #16\)
4: mla \(t0, t1, q, t0\) \(\triangleright t0 = ab + (-abq^{-1} \mod \pm R) q\).
5: \(\triangleright\) The desired result is stored in the upper half.

Algorithm 7 16-bit Plantard multiplication with Armv7-M [HZZ+].

Inputs: Values \(a \in \left[ -\frac{R}{2}, \frac{R}{2} \right), -bq^{-1} \in \left[ -\frac{R^2}{2}, \frac{R^2}{2} \right)\).
Output: \(t = \left( \left\lfloor \frac{-abq^{-1} \mod \pm R^2}{R} \right\rfloor + 2^a \right) q\).

1: mul \(t, b, -q^{-1} \mod \pm R^2\) \(\triangleright t = -bq^{-1} \mod \pm R^2\).
2: mul \(t, t, a\) \(\triangleright t = -abq^{-1} \mod \pm R^2\).
3: add \(t, 2^a, t, asr \#16\) \(\triangleright t = \left( \left\lfloor \frac{-abq^{-1} \mod \pm R^2}{R} \right\rfloor + 2^a \right) q\).
4: mul \(t, t, q\) \(\triangleright t = \left( \left\lfloor \frac{-abq^{-1} \mod \pm R^2}{R} \right\rfloor + 2^a \right) q\).
5: \(\triangleright\) The desired result is stored in the upper half.

7.2.2 Armv7E-M Implementations

We briefly compare Montgomery and Plantard multiplications with the Digital Signal Processing extension in Armv7E-M where “E” stands for “extension”. [ABCG20] showed that 16-bit Montgomery multiplication can be implemented with three 16-bit multiplication instructions from the extension as shown in Algorithm 8. Recently, [HZZ+22] found that the multiplication instruction `smulwb` is a nice fit for 16-bit Plantard multiplication. Algorithm 9 is an illustration. If one of the multiplicands is known in prior, we can remove one multiplication and cancel out the scaling with precomputation as shown in previous section.
Algorithm 8 16-bit Montgomery multiplication with Armv7E-M [ABCG20]

Inputs: $l_0(a) = a_1, l_0(b) = b_1$.  
Outputs: $hi(t) = \frac{a_1b_1 + (-a_1b_1q^{-1} \mod \mathbb{R})q}{q}$.

1: $\text{smul} \ b \ t, a, b$ \hspace{1cm} \& \hspace{1cm} $hi = a_1b_1$.
2: $\text{smul} \ \ b \ t, -q^{-1} \mod \mathbb{R}$ \hspace{1cm} $l_0 = (a_1b_1 \mod \mathbb{R})(-q^{-1} \mod \mathbb{R})$.
3: $\text{smul} \ \ b \ t, q, th$ \hspace{1cm} $th = a_1b_1 + (-a_1b_1q^{-1} \mod \mathbb{R})q$.
4: $\text{mul} \ t, th$, \hspace{1cm} $\triangleright$ The desired result is stored in the upper half.

Algorithm 9 16-bit Plantard multiplication with Armv7E-M [HZZ22]

Inputs: $l_0(a) = a_1, b \in \left[\frac{-q}{2}, \frac{q}{2}\right]$.  
Outputs: $hi(t) = \frac{\left[-a_1bq^{-1} \mod \mathbb{R}^2\right]q + 2^\alpha q}{q}$.

1: $\text{mul} \ t, b, -q^{-1} \mod \mathbb{R}^2$ \hspace{1cm} $\triangleright t = -bq^{-1} \mod \mathbb{R}^2$.
2: $\text{smul} \ b \ t, a$ \hspace{1cm} $\triangleright t = \frac{a(-bq^{-1} \mod \mathbb{R}^2)}{\mathbb{R}}$.
3: $\text{smul} \ b \ t, q, 2^\alpha q$ \hspace{1cm} $\triangleright t = \frac{-a_1bq^{-1} \mod \mathbb{R}^2}{\mathbb{R}} q + 2^\alpha q$.
4: $\text{smul} \ b \ t, th$, \hspace{1cm} $\triangleright$ The desired result is stored in the upper half.

7.3 Homomorphism Caching

Let $f : A \to B$ be an algebra monomorphism, and $a_0, a_1, b \in A$. Suppose we want to implement $a_0b$ and $a_1b$. We can compute with $f^{-1}(f(a_0)f(b))$ and $f^{-1}(f(a_1)f(b))$ using only three applications of $f$ and two applications of $f^{-1}$. This is called homomorphism caching and FFT-caching if $f$ is an FFT. [Ber08, Section 2.9] said this was widely known in 1992. Section C will show historical evidence that caching was used implicitly in [Goo71] dating back to 1971.

7.4 Saber : Homomorphism Caching

In Saber, the most performance-critical polynomial operation is multiplying $l \times l$ matrix by an $l \times 1$ vector over the polynomial ring $\mathbb{Z}_{8192}[x]/\langle x^{256} + 1 \rangle$. We review the benefit of caching algebra and module homomorphisms.

**Algebra homomorphism caching.** Let $f : \mathbb{Z}_{8192}[x]/\langle x^{256} + 1 \rangle \to S$ be an algebra homomorphism, $\cdot S$ be the multiplication in $S$, and $+ S$ be the addition in $S$. We denote $C(-)$ as the cost function of a map. If we apply $f$ to all the polynomials, compute matrix–vector multiplication over $S$, and transform back to a vector over $\mathbb{Z}_{8192}[x]/\langle x^{256} + 1 \rangle$, the total cost is

$$(l^2 + l)C(f) + l^2C(\cdot S) + (l^2 - l)C(+S) + lC(f^{-1}).$$

Optimizations for the matrix–vector multiplication over $\mathbb{Z}_{8192}[x]/\langle x^{256} + 1 \rangle$ should base the comparisons on the dominating term $C(f) + C(\cdot S) + C(+S)$. [KRS19] chose $f$ as Toom–Cook but didn’t exploit the homomorphic property. [MKV20] exploited the homomorphic property for Toom–Cook, and [CHK+21] chose $f$ as an FFT. The FFT-type approaches for Saber remain the fastest [CHK+21, ACC+22, BHK+22b].

**Module homomorphism caching.** In the previous paragraph, we have seen the importance of caching algebra homomorphisms. [BHK+22b] introduced “asymmetric multiplication” which falls into module homomorphism caching. For a polynomial
$a \in \mathbb{Z}_{256}$ and an algebra homomorphism $f : \mathbb{Z}_{256} \to S$, we first regard $f(a)$ as a module homomorphism mapping $f(b)$ to $f(a)f(b)$ for $b \in \mathbb{Z}_{256}$. If $f(a)$ amounts to polynomial multiplications modulo $x^v - \zeta$, we can turn $f(a)$ into a special kind of module homomorphism — Toeplitz matrix-vector multiplication (cf. Section 5.5). In practice, the Toeplitz matrix conversion of $f(a)$ is cached. This is called asymmetric multiplication [BHK+22b, Section 4.2].

7.5 NTRU : Toeplitz matrix-vector product

Section 5.5 discusses how to turn arbitrary algebra homomorphisms multiplying size-$n$ polynomials in $R[x]$ into a Toeplitz matrix-vector product for multiplying in $R[x]/(x^n - \alpha x - \beta)$. In Section 6.4.2, we discuss the benefit of computing Toeplitz matrix-vector products with vector-by-scalar multiplications. We review the Toeplitz matrix-vector product approach for multiplying polynomials in $\mathbb{Z}_{2048}[x]/(x^{677} - 1)$ used by the NTRU parameter set ntruhps2048677.

7.5.1 Armv7E-M Implementation

[IKPC22] applied Toeplitz matrix-vector product with Karatsuba and Toom–Cook. They first considered the following sequence of Karatsuba and Toom–Cook multiplying two size-720 polynomials:

$$\text{TC-4} \rightarrow \text{K-3} \rightarrow \text{K-3} \rightarrow \text{K-2}$$

where K-2 is the usual Karatsuba in Section 3.7 and K-3 is the subtractive variant of 3-way Karatsuba\(^{10}\). They then took the dual of Toom–Cook, Karatsuba, and their inverses, and formed Toeplitz matrix-vector products as shown in Section 5.5. [IKPC22] identified that one no longer needs to reduce modulo a polynomial since it is merged with the polynomial multiplication itself (cf. Section 5.5.2).

7.5.2 Armv8-A Implementation

Shortly after, [CCHY23] explored the vectorization of Toeplitz matrix-vector products with Armv8-A. They started with the following sequence of Karatsuba and Toom–Cook multiplying two size-720 polynomials:

$$\text{TC-5} \rightarrow \text{TC-3} \rightarrow \text{TC-3} \rightarrow \text{K-2}$$

and took the dual of all the homomorphisms. They showed that small-dimensional power-of-two Toeplitz matrix-vector product can be implemented efficiently for the following reasons: (i) one can construct Toeplitz matrices efficiently from its first row and column (cf. Section 6.4.2) and (ii) the existence of vector-by-scalar multiplication instructions implement the outer-product-based matrix-vector multiplication while avoiding permutations and reducing register pressure significantly [CCHY23]. See [CCHY23, Section 5.1] for more details on memory optimizations while inverting Karatsuba and Toom–Cook.

7.6 NTRU Prime : Vectorized FFTs

In this section, we go through a detailed analysis of vectorized polynomial multipliers in NTRU Prime. Our central objective is to answer the following question:

How FFT-, vectorization-, and permutation-friendly the coefficient ring is?

\(^{10}\)In principle, we compute all possible $a_ib_i$ and $(a_i - a_j)(b_i - b_j)$ for $i \neq j$ so arbitrary $a_ib_j$ can be derived by only additions and subtractions, see [WP06, Section 3.2] for details.
We briefly review the friendliness measures found by [HLY24, Hwa23]. The state-of-the-art AVX2 implementation [Hwa23] computed the products in $\mathbb{Z}_{4591}^2$ with truncated Rader, Good–Thomas, and Bruun FFTs. We first discuss a generic approach using Schönhage and Nussbaumer for maintaining the friendliness while exploiting no algebraic properties of the polynomial ring. Schönhage and Nussbaumer usually adjoin algebraic structures for friendliness with expenses. We then systematically analyze how to exploit the algebraic structure endowed in $\mathbb{Z}_{4591}$, showing that $\mathbb{Z}_{4591}$ actually admits FFT, vectorization, and permutation-friendly transformations. Observe that 4591 − 1 = 2 · 3³ · 5 · 17 and 4591² − 1 = 2³ · 3³ · 5 · 7 · 17 · 41, we summarize the following findings from the works [HLY24, Hwa23].

- We qualify $\mathbb{Z}_{4591}$ as an FFT-friendly prime by considering the application of Good–Thomas and Rader’s FFTs based on the factorization of 4591 − 1 and Bruun’s FFT based on the factorization of $4591^2 − 1$ [HLY24].
- We qualify $\mathbb{Z}_{4591}$ as a vectorization-friendly prime since the product $2^5 · 3^3 · 5 · 17 = 73440$ (73440 = 16(4591 − 1)(4591² − 1)) allows a wide range of FFTs resulting small-dimensional power-of-two polynomial multiplications [HLY24].
- We qualify $\mathbb{Z}_{4591}$ as a permutation-friendly prime since 3, 5, and 17 are Fermat primes, and truncating Fermat-prime-size Rader’s FFTs gives power-of-two transformations [Hwa23].

We review two AVX2-optimized implementations in this section: (i) [BBCT22]’s approach with truncated Schönhage and Nussbaumer FFTs, and (ii) [Hwa23]’s approach with truncated Rader, Good–Thomas, and Bruun FFTs.

### 7.6.1 A Generic Approach with Truncated Schönhage and Nussbaumer FFTs

Let’s recall the AVX2-optimized polynomial multiplication for ntrulpr761/sntrup761 from [BBCT22]. For multiplying polynomials in $\mathbb{Z}_{4591}[x]/\langle x^{761} − x − 1 \rangle$, [BBCT22] computed the product in $\mathbb{Z}_{4591}[x]/\langle (x^{512} − 1)(x^{1024} + 1) \rangle$ as follows. They first applied Schönhage replacing $x^{32} − y$ with $x^{64} + 1$:

$$\frac{\mathbb{Z}_{4591}[x]}{(x^{512} − 1)(x^{1024} + 1)} \overset{\eta_5}{\approx} \frac{\mathbb{Z}_{4591}[x]}{(y^{16} − 1)(y^{32} + 1)} \overset{\eta_1}{\approx} \frac{\mathbb{Z}_{4591}[x]}{(y^{16} − 1)(y^{64} + 1)}.$$

Since $x^2$ is a principal 64-th root of unity in $\mathbb{Z}_{4591}[x]/\langle x^{64} + 1 \rangle$, we have $(y^{16} − 1)(y^{32} + 1) = \prod_{i \not\equiv 2 \bmod 4} (y − x^2)$ over $\mathbb{Z}_{4591}[x]/\langle x^{64} + 1 \rangle$. We find Schönhage’s FFT vectorization-friendly since 64 = 4 · 16. After splitting the polynomial ring in $y$, the remaining problem is multiplying in $\mathbb{Z}_{4591}[x]/\langle x^{64} + 1 \rangle$. [BBCT22] interleaved the polynomials with no leftovers and applied Nussbaumer as follows:

$$\mathbb{Z}_{4591}[x] \overset{\eta_6}{\approx} \frac{\mathbb{Z}_{4591}[x]}{(x^{8} + 1)} \overset{\eta_7}{\rightarrow} \frac{\mathbb{Z}_{4591}[x]}{(x^{16} − 1)}.$$

Since $z$ is a principal 16-th root of unity in $\mathbb{Z}_{4591}[z]/\langle z^8 + 1 \rangle$, we can factor $x^{16} − 1$ into $\prod_{i}(x − z^i)$ over $\mathbb{Z}_{4591}[z]/\langle z^8 + 1 \rangle$. In summary, we are left with $\frac{1536}{8} = 192$ = 768 polynomial multiplications in $\mathbb{Z}_{4591}[z]/\langle z^8 + 1 \rangle$. For multiplying polynomials in $\mathbb{Z}_{4591}[z]/\langle z^8 + 1 \rangle$ for details.

### 7.6.2 A Specialized Approach with Truncated Rader, Good–Thomas, and Bruun FFTs

We briefly review the friendliness measures found by [HLY24, Hwa23]. The state-of-the-art AVX2 implementation [Hwa23] computed the products in $\mathbb{Z}_{4591}[x]/\langle \phi_{17}(x^{64}) \rangle$. [Hwa23]
first applied truncated Rader’s FFT to the isomorphism:

\[
\frac{\mathbb{Z}_{4591}[x]}{\langle \Phi_{17}(x^{96}) \rangle} \cong \prod_{i \neq 0} \frac{\mathbb{Z}_{4591}[x]}{\langle x^{96} - \omega_{17}^{i} \rangle}
\]

and twisted each of \(\mathbb{Z}_{4591}[x]/\langle x^{96} - \omega_{17}^{i} \rangle\) into \(\mathbb{Z}_{4591}[x]/\langle x^{96} - 1 \rangle\). They then applied Good–Thomas FFT implementing the isomorphism:

\[
\frac{\mathbb{Z}_{4591}[x]}{\langle x^{96} - 1 \rangle} \cong \prod_{j} \frac{\mathbb{Z}_{4591}[x]}{\langle x^{16} - \omega_{6}^{j} \rangle}
\]

and twisted into \(\mathbb{Z}_{4591}[x]/\langle x^{16} \pm 1 \rangle\). Since each vector registers in AVX2 contains sixteen 16-bit values, all of the above are vectorization-friendly. The remaining problems are 48 polynomial multiplications in \(\mathbb{Z}_{4591}[x]/\langle x^{16} - 1 \rangle\) and 48 in \(\mathbb{Z}_{4591}[x]/\langle x^{16} + 1 \rangle\). Since 48 is a multiple of 16, we can interleave the polynomials with no leftovers. This implies permutation-friendliness. For multiplying polynomials in \(\mathbb{Z}_{4591}[x]/\langle x^{16} \pm 1 \rangle\), see [Hwa23] for details.

8 Overview of Advances

We give overviews of the advances of polynomial multiplications used in lattice-based cryptosystem implementations with emphases on modular arithmetic, algebraic techniques, and vectorization. Table 14 gives an overview of existing works for Dilithium, Kyber, and Saber, and Table 15 gives an overview of existing works for NTRU and NTRU Prime.

Table 14: Target architectures/extensions of existing works for Dilithium, Kyber, and Saber.

<table>
<thead>
<tr>
<th></th>
<th>Dilithium</th>
<th>Kyber</th>
<th>Saber</th>
</tr>
</thead>
<tbody>
<tr>
<td>[BKS19]</td>
<td>-</td>
<td>Armv7E-M</td>
<td>-</td>
</tr>
<tr>
<td>[KRS19]</td>
<td>-</td>
<td>-</td>
<td>Armv7E-M</td>
</tr>
<tr>
<td>[ABD+20a]</td>
<td>-</td>
<td>AVX2</td>
<td>-</td>
</tr>
<tr>
<td>[ABD+20b]</td>
<td>-</td>
<td>-</td>
<td>AVX2</td>
</tr>
<tr>
<td>[DKRV20]</td>
<td>-</td>
<td>-</td>
<td>AVX2</td>
</tr>
<tr>
<td>[ABCG20]</td>
<td>-</td>
<td>Armv7E-M</td>
<td>-</td>
</tr>
<tr>
<td>[MKV20]</td>
<td>-</td>
<td>-</td>
<td>Armv7E-M, AVX2</td>
</tr>
<tr>
<td>[JKPC20]</td>
<td>-</td>
<td>-</td>
<td>Armv7E-M</td>
</tr>
<tr>
<td>[CHK+21]</td>
<td>-</td>
<td>-</td>
<td>Armv7-M, AVX2</td>
</tr>
<tr>
<td>[GKS21]</td>
<td>Armv7-M</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>[SKS+21]</td>
<td>-</td>
<td>Armv8-A</td>
<td>-</td>
</tr>
<tr>
<td>[NG21]</td>
<td>-</td>
<td>Armv8-A</td>
<td>Armv8-A</td>
</tr>
<tr>
<td>[BHK+22b]</td>
<td>Armv8-A</td>
<td>Armv8-A</td>
<td>Armv8-A</td>
</tr>
<tr>
<td>[AHKS22]</td>
<td>Armv7-M</td>
<td>Armv7E-M</td>
<td>-</td>
</tr>
<tr>
<td>[HZZ+22]</td>
<td>-</td>
<td>Armv7E-M</td>
<td>-</td>
</tr>
<tr>
<td>[AMOT22]</td>
<td>-</td>
<td>-</td>
<td>RISC-V</td>
</tr>
<tr>
<td>[HKS23]</td>
<td>Armv7-M</td>
<td>-</td>
<td>-</td>
</tr>
</tbody>
</table>

8.1 Modular Arithmetic

We first give an overview of modular arithmetic. See Table 16 for a summary of existing works on 8-bit AVR, Armv7-M, Armv7E-M, Armv8.0-A, MVE, and AVX2.
Table 15: Target architectures/extensions of existing works for NTRU and NTRU Prime.

<table>
<thead>
<tr>
<th></th>
<th>NTRU</th>
<th>NTRU Prime</th>
</tr>
</thead>
<tbody>
<tr>
<td>[KRS19]</td>
<td>Armv7E-M</td>
<td>-</td>
</tr>
<tr>
<td>[BBC+20]</td>
<td>AVX2</td>
<td>-</td>
</tr>
<tr>
<td>[CDH+20]</td>
<td>-</td>
<td>AVX2</td>
</tr>
<tr>
<td>[ACC+21]</td>
<td>-</td>
<td>Armv7-M</td>
</tr>
<tr>
<td>[CHK+21]</td>
<td>Armv7-M, AVX2</td>
<td>-</td>
</tr>
<tr>
<td>[NG21]</td>
<td>Armv8-A</td>
<td>-</td>
</tr>
<tr>
<td>[IKPC22]</td>
<td>Armv7E-M</td>
<td>-</td>
</tr>
<tr>
<td>[AHY22]</td>
<td>Armv7-M</td>
<td>Armv7-M</td>
</tr>
<tr>
<td>[BBCT22]</td>
<td>-</td>
<td>AVX2</td>
</tr>
<tr>
<td>[CCHY23]</td>
<td>Armv8-A</td>
<td>-</td>
</tr>
<tr>
<td>[Hwa23]</td>
<td>-</td>
<td>Armv8-A, AVX2</td>
</tr>
<tr>
<td>[HLY24]</td>
<td>-</td>
<td>Armv8-A</td>
</tr>
</tbody>
</table>

Table 16: Summary of existing works of modular multiplications relevant to our target architectures and extensions.

<table>
<thead>
<tr>
<th></th>
<th>Barrett</th>
<th>Montgomery</th>
<th>Plantard</th>
</tr>
</thead>
<tbody>
<tr>
<td>Sho</td>
<td>✓</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Sei18</td>
<td>AVX2</td>
<td>AVX2</td>
<td>-</td>
</tr>
<tr>
<td>BKS19</td>
<td>Armv7E-M</td>
<td>Armv7E-M</td>
<td>-</td>
</tr>
<tr>
<td>BCG+20</td>
<td>Armv7E-M</td>
<td>Armv7E-M</td>
<td>-</td>
</tr>
<tr>
<td>ACC+21</td>
<td>Armv7E-M</td>
<td>Armv7-M</td>
<td>-</td>
</tr>
<tr>
<td>GKS21</td>
<td>-</td>
<td>Armv7-M</td>
<td>-</td>
</tr>
<tr>
<td>SKS+21</td>
<td>Armv8.0-A</td>
<td>Armv8.0-A</td>
<td>-</td>
</tr>
<tr>
<td>BHK+22b</td>
<td>Armv8.0-A</td>
<td>Armv8.0-A</td>
<td>-</td>
</tr>
<tr>
<td>AHKS22</td>
<td>Armv7E-M</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>BHK+22a</td>
<td>MVE</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>HZZ+22</td>
<td>-</td>
<td>-</td>
<td>Armv7E-M</td>
</tr>
<tr>
<td>AMOT22</td>
<td>-</td>
<td>-</td>
<td>✓</td>
</tr>
<tr>
<td>HKS23</td>
<td>Armv7-M, 8-bit AVR</td>
<td>-</td>
<td>-</td>
</tr>
</tbody>
</table>

8.1.1 Vector architecture implementations

[Sei18] was the first work proposing signed Montgomery multiplication. They applied the idea to the vectorized 16-bit NTT used in the Ring-LWE scheme NewHope. Their idea nicely captured the availability of 16-bit multiplication instructions in AVX2, and it was applied to Kyber [ABD+20] and NTRU Prime [BBC+20]. The subtractive variant was also implemented by [SKS+21] in Armv8-A. The “unsigned Barrett multiplication” was implemented in [Sho].

[BHK+22b] independently\(^\text{11}\) found the signed Barrett multiplication, the correspondence between Montgomery and Barrett multiplication, and their variants and implemented them with Armv8-A. [BHK+22a] later demonstrated that if one increases the precision of the arithmetic, then we have the canonical representations of the products for some special

\(^{11}\) [BHK+22b] cited the eprint version of [SKS+21]. The subtractive variant of Montgomery multiplication was shown in the published version but not the eprint one. We are informing the authors of [BHK+22b] for this miscontribution.
moduli, and implemented the idea with M-profile vector extension (MVE).

### 8.1.2 Microcontroller Implementations

[BKS19] implemented Barrett reduction and the subtractive variant of Montgomery multiplication with the SIMD instruction \texttt{smul(b, t){b, t}} in Armv7E-M. [ABC20] switched to the accumulative variant of Montgomery multiplication and absorbed the addition by replacing a \texttt{smul(b, t){b, t}} with \texttt{smla(b, t){b, t}} [ABC20, Algorithm 11]. The signed Barrett reduction was later improved by [ACC+21] with instructions \texttt{smlaw(b, t)}\textsuperscript{12}, but it was not reported (we found this while carefully examining the assembly programs). In [ACC+21], they also proposed the uses of \texttt{s{mul, mla}l} in Armv7-M for 32-bit Montgomery multiplication and \texttt{smulr} in Armv7E-M for 32-bit Barrett reduction.

The 32-bit Montgomery multiplication was independently proposed by [GKS21]. The improvement of signed Barrett reduction with Armv7E-M was later reported in [AHKS22]. [HZZ+22] and [AMOT22] independently found the signed versions of Plantard multiplication. [HZZ+22] applied the idea to 16-bit modular arithmetic with Armv7E-M instructions \texttt{s{mul, mla}w(b, t)} while [AMOT22] applied the idea to 32-bit modular arithmetic using 64 = 64 \times 64 arithmetic on K210 (64-bit) [AMOT22, Section V-B]. Shortly after, [HZZ+22] applied signed Plantard arithmetic to Armv7-M with essentially the same idea from [AMOT22]. Recently, [HKS23] proposed the uses of Barrett multiplication when long/high multiplication instructions are slow, unusable, or unavailable and implemented the ideas with Armv7-M and 8-bit AVR.

### 8.2 Algebraic Techniques

In Dilithium and Kyber, most optimizations are about modular arithmetic, memory footprint, and instructions scheduling, so we exclude them unless specified otherwise in this section.

#### 8.2.1 Vector Architecture Implementations

We first give an overview of AVX2-optimized implementations. For the big-by-small polynomial multiplication, [BBC+20] implemented 16-bit Good–Thomas FFT with permutations instantiated as logical operations for \texttt{ntrulpr761/sntrup761} and applied radix-2 FFT to the power-of-two dimension. [CHK+21] applied 16-bit size-256 negacyclic FFT to Saber and size-1024, size-1536, and size-1728 cyclic FFTs to NTRU. For the big-by-big polynomial multiplication, [MKV20, CDH+20] applied Toom–Cook and Karatsuba to NTRU and Saber. For NTRU Prime, [BBCT22] implemented truncated Schönhage’s and Nussbaumer’s FFTs (cf. Section 7.6.2), and [Hwa23] applied truncated Rader’s, Good–Thomas, and Bruun’s FFTs following [HLY24]’s Armv8-A work.

For the Armv8-A Neon implementations, [NG21] implemented 16-bit size-256 negacyclic FFT for Saber, and 3- and 4-way Toom–Cook for NTRU. Shortly after, [BHK+22b] demonstrated 32-bit negacyclic FFT is more performant for Saber\textsuperscript{13}. [CCHY23] deployed 5-way Toom–Cook to NTRU and showed that Toeplitz transformation with Toom–Cook was more favorable due to the presence of vector-by-scalar multiplication instructions on Armv8-A, and [HLY24] applied Rader’s, Good–Thomas, and Bruun’s FFTs. Finally, [Hwa23] applied truncated Rader’s FFT, Good–Thomas FFT, and Toeplitz matrix-vector products to small-dimensional cyclic/negacyclic convolutions.

\textsuperscript{12}smlaw(b, t) multiplies a 32-bit value by a certain half of a 32-bit value, accumulates the result to the accumulator, and returns the most significant 32-bit value.

\textsuperscript{13}This doesn’t say that we should do the same thing for AVX2-optimized implementation since there are no native 32-bit multiplication instructions in AVX2.
8.2.2 Microcontroller Implementations

[KRS19] applied Toom–Cook and Karatsuba to NTRU and Saber. [MKV20] later cached the homomorphisms in the case of Saber and [IKPC20] applied the Toeplitz matrix-vector product to Saber with Toom–Cook and Karatsuba as the underlying homomorphisms. [ACC+21] proposed three implementations for NTRU Prime parameter sets ntrulpr761/sntrup761: (i) a Good–Thomas FFT computing the big-by-small polynomial multiplication with 32-bit arithmetic over $\mathbb{Z}$, (ii) an FFT using radix-2, radix-3, and radix-5 butterflies with 16-bit arithmetic over $\mathbb{Z}_{4591}$, and (iii) an FFT using radix-3 and Rader’s radix-17 butterflies with 16-bit arithmetic over $\mathbb{Z}_{4591}$. The big-by-small polynomial multiplication came from [BBC+20] and was later adapted to NTRU and Saber [CHK+21]. [IKPC22] extended [IKPC20]’s work to NTRU and [AHY22] improved [ACC+21, CHK+21]’s NTRU and NTRU Prime implementations by proposing vector-radix butterflies for speed [AHY22, Section 4.1] and vectorization-friendly Good–Thomas for code size [AHY22, Section 3.3].

9 Directions for Future Works

We point out several possible future works as follows.

Non-uniform property of localization in Toom–Cook. In Section 4.1, we explain that localization does not need to be uniform among subproblems and illustrate the idea with Toom–Cook. In practice, one usually applies Toom–Cook recursively. Since the required localization for subproblems is not uniform, applying more aggressive divide-and-conquer strategies for some subproblems is possible. We want to know the practical impact of this observation of Toom–Cook and its Toeplitz version for NTRU and Saber.

Schönhage and Nussbaumer for NTRU and Saber. In lattice-based cryptosystem implementations, Schönhage and Nussbaumer FFTs were only applied to NTRU Prime where the coefficient ring is $\mathbb{Z}_q$ for an odd $q$. We want to know the practical impact of Schönhage’s FFT, Nussbaumer’s FFT, and their Toeplitz versions for NTRU and Saber where $q$ is a power of two.

Barrett multiplication for finite fields. The finite field versions of Montgomery multiplication [KA98] and Barrett reduction [Dhe03] were known in the literature. Appendix A extends the correspondence between Montgomery multiplication and Barrett multiplication [BHK+22] to principal ideal domains. For a finite field $\mathbb{F}_p$, since $\mathbb{F}_p[x]$ is a principal ideal domain, the correspondence implies the finite field version of Barrett multiplication. The Barrett reduction found by [Dhe03] is then a special case in this regard. We want to know the practical impact of the deployment of Barrett multiplication for finite fields.

Toeplitz matrix-vector product for NTRU Prime. Section 5.5.2 explains that polynomial multiplication modulo $x^n – ax – \beta$ can be turned into a Toeplitz matrix-vector product. Explore the Toeplitz approach for NTRU Prime.

A Modular Arithmetic for Principal Ideal Domains

Let $R$ be a principal ideal domain, $e_0, e_1 \in R$ be elements with $\gcd(e_0, e_1) = 1$. We assume implicitly that $R/\langle e_0 \rangle, R/\langle e_1 \rangle \subset R$ by first fixing the representatives for each equivalence classes.
Montgomery multiplication. We define Montgomery multiplication as:

\[ \frac{ab + \left(ab \left(-e_0^{-1} \mod \langle e_1 \rangle\right) \mod \langle e_1 \rangle\right)e_0}{e_1} \equiv abc_1^{-1} \mod \langle e_0 \rangle. \]

If \( b \) is a constant, we compute the following instead:

\[ \frac{a \left(be_1 \mod \langle e_0 \rangle\right) + \left(a \left(be_1 \mod \langle e_0 \rangle\right) \left(-e_0^{-1} \mod \langle e_1 \rangle\right) \mod \langle e_1 \rangle\right)e_0}{e_1} \equiv ab \mod \langle e_0 \rangle. \]

We prove the equivalence as follows.

Proof. Let \( \text{term} = ab + \left(ab \left(-e_0^{-1} \mod \langle e_1 \rangle\right) \mod \langle e_1 \rangle\right)e_0 \) be an abbreviation. By definition, we have

\[ \text{term} \mod \langle e_1 \rangle = (ab + \left(ab \left(-e_0^{-1} \mod \langle e_1 \rangle\right) \mod \langle e_1 \rangle\right)e_0) \mod \langle e_1 \rangle = 0. \]

Therefore, \( \text{term} \) is a multiple of \( e_1 \) and \( \text{term} \mod \langle e_1 \rangle \in R \). It remains to show that \( \text{term} \mod \langle e_1 \rangle \equiv abc_1^{-1} \mod \langle e_0 \rangle \). This boils down to the fact that \( \text{term} \equiv ab \mod \langle e_0 \rangle \) and \( e_0 \perp e_1 \).

Barrett multiplication. Suppose we are given an ideal \( \langle e \rangle \) and a quotient ring \( R/\langle e \rangle \) with a choice function implementing the inclusion \( R/\langle e \rangle \subset R \). For an \( a \in R \), we define \( \left[ \frac{a}{e} \right] \) as the element in \( R \) satisfying:

\[ e \left[ \frac{a}{e} \right] = a - a \mod \langle e \rangle. \]

For elements \( a, b \in R \), Barrett multiplication computes the following

\[ ab - \left[ a \left[ \frac{be_1}{e_0} \right] \right] e_0. \]

Correspondence between Montgomery and Barrett multiplication. We claim the following equation:

\[ ab - \left[ a \left[ \frac{be_1}{e_0} \right] \right] e_0 = \frac{a \left(be_1 \mod \langle e_0 \rangle\right) + \left(a \left(be_1 \mod \langle e_0 \rangle\right) \left(-e_0^{-1} \mod \langle e_1 \rangle\right) \mod \langle e_1 \rangle\right)e_0}{e_1.} \]

Proof. We first find the following:

\[ \left[ \frac{be_1}{e_0} \right] \mod \langle e_1 \rangle = (be_1 \mod \langle e_0 \rangle) \left(-e_0^{-1} \mod \langle e_1 \rangle\right). \]

Then, we have:

\[ ab - \left[ a \left[ \frac{be_1}{e_0} \right] \right] e_0 = abc_1 - a \left[ \frac{be_1}{e_0} \right] e_0 + \left(a \left[ \frac{be_1}{e_0} \mod \langle e_1 \rangle\right] \right)e_0 \]

\[ = abc_1 - a \left[ \frac{be_1}{e_0} \right] e_0 + \left(a \left(be_1 \mod \langle e_0 \rangle\right) \left(-e_0^{-1} \mod \langle e_1 \rangle\right) \mod \langle e_1 \rangle\right)e_0 \]

\[ = abc_1 - a \left(be_1 - (be_1 \mod \langle e_0 \rangle)\right) + \left(a \left(be_1 \mod \langle e_0 \rangle\right) \left(-e_0^{-1} \mod \langle e_1 \rangle\right) \mod \langle e_1 \rangle\right)e_0 \]

\[ = a \left(be_1 \mod \langle e_0 \rangle\right) + \left(a \left(be_1 \mod \langle e_0 \rangle\right) \left(-e_0^{-1} \mod \langle e_1 \rangle\right) \mod \langle e_1 \rangle\right)e_0. \]
For a non-commutative ring

Theorem 3.

For a ring we distinguish between two cases: (i)

This section presents an algebraic view of the Good–Thomas FFT \[Goo58, Goo71\]. Let

Therefore,

\[\Phi_n(\omega_n) = 0 \implies \left( \forall j = 1, \ldots, n - 1, \sum_{0 \leq i < n} \omega_n^{ij} = 0 \right).\]

Lemma 1. For a positive integer \(n\) and a proper divisor \(j\) of \(n\), \(\Phi_n(x)\) is a divisor of \(\sum_{0 \leq i < \frac{n}{j}} x^{ij}\).

Proof.

\[\sum_{0 \leq i < \frac{n}{j}} x^{ij} = \frac{x^n - 1}{x^j - 1} = \prod_{d|n} \Phi_d(x) = \Phi_n(x) \cdot \prod_{d|n,d \neq j,d<n} \Phi_d(x).\]

Therefore, \(\Phi_n(x)\) is a divisor of \(\sum_{0 \leq i < \frac{n}{j}} x^{ij}\).

Lemma 2. For a ring \(R\), an element \(\zeta \in R\), a positive integer \(n\), and a proper divisor \(j\) of \(n\), \(\Phi_n(\zeta)\) is a divisor of \(\sum_{0 \leq i < \frac{n}{j}-1} \zeta^{ij}\).

Proof of Theorem 2. For proving

\[\Phi_n(\omega_n) = 0 \implies \left( \forall j = 1, \ldots, n - 1, \sum_{0 \leq i < n} \omega_n^{ij} = 0 \right),\]

we distinguish between two cases: (i) \(j|n\) and (ii) \(j \not{|}n\).

- \(j|n\): \(\sum_{0 \leq i < n} \omega_n^{ij} = \frac{n}{j} \sum_{0 \leq i < \frac{n}{j}} \omega_n^{ij} = \frac{n}{j} \cdot \Phi_n(\omega_n) \cdot \prod_{d|n,d \neq j,d<n} \Phi_d(\omega_n) = 0\).
- \(j \not{|}n, d = \gcd(j,n)\): \(\sum_{0 \leq i < n} \omega_n^{ij} = \frac{n}{d} \sum_{0 \leq i < \frac{n}{d}} \omega_n^{ij} = \frac{n}{d} \sum_{0 \leq i < \frac{n}{d}} \omega_n^{ij} = 0\).

Theorem 3. For a non-commutative ring \(R\), Theorem 2 holds when \(\omega_n\) belongs to the center of \(R\) where the center is the subset consisting of elements commuting to all elements in \(R\).

C  Algebraic View of Good–Thomas FFT

This section presents an algebraic view of the Good–Thomas FFT \[Goo58, Goo71\]. Let \(n_0, \ldots, n_{d-1}\) be coprime integers and \(n = \prod_j n_j\). We have \(R[\mathbb{Z}_n] = \bigotimes_j R[\mathbb{Z}_{n_j}]\) as algebras, or equivalently, \(R[x]/(x^n - 1) \cong R[x_{n_0}, \ldots, x_{n_{d-1}}]/(x_0^{n_0} - 1, \ldots, x_{d-1}^{n_{d-1}} - 1)\) as polynomial rings. We leave the proof as an exercise. For a \(d\)-dimensional polynomial \(a = (a_{i_0,\ldots,i_{d-1}})_{i_0,\ldots,i_{d-1}} \in \bigotimes_j R[\mathbb{Z}_{n_j}]\), we define \(a_{i_0,\ldots,i_{d-1}}\) as the \((d-h)\)-dimensional tuple

[KAK96, KA98] demonstrated the benefit of unsigned Montgomery multiplication for multi-precision arithmetic. They computed Montgomery multiplication with \(\langle e_0 \rangle = 2^ab\mathbb{Z}\) and arithmetic modulo \(2^a\). We leave the principal-ideal-domain view of the multi-precision case \(\langle e_0 \rangle\) and its relation to Barrett multiplication as future work.
We compute and cache $V_{x_{h-1}}$ to see how general the idea was in [Tho63].

For the additive steps, we perform additions and subtractions. One observation is that

Usually, $f$ of transformation significantly. This section explains how one can save more by directly op-

The notion of homomorphism caching is the actual reason making the multi-dimensional cyclic convolution fast. Historically, Good–Thomas FFT was first presented in [Goo58] as a correspondence between a DFT defined on $R[x]/(x^n - 1)$ and a tensor product of the DFTs defined on $R[x]/(x^n - 1)$. This was cited as a motivation of Cooley–Tukey FFT in [CT65]. [GS66, Sto66] pointed out the use of Cooley–Tukey FFT for cyclic convolutions. [Goo71] explained the differences between Good–Thomas FFT and Cooley–Tukey FFT, and acknowledged the application of multi-dimensional transform to multi-dimensional cyclic convolution. Based on this, we believe that homomorphism caching was already used in [Goo71].

D Vector-Radix Transform

In Section 3.4, we know that one-dimensional size-$n$ cyclic convolution can be turned into a multi-dimensional cyclic convolution of dimensions based on a coprime factorization of $n$. If we apply isomorphism for each dimension and cache the results, then we save the cost of transformation significantly. This section explains how one can save more by directly op-

Frequently, $f_j$ is a composition of one-dimensional isomorphisms shown in Section 3. Let’s write $f_j = f_{j,0} \cdot \cdots \cdot f_{j,h-1}$. A crucial property while tensoring two compositions $f_{0,0} \circ f_{0,1}$ and $f_{1,0} \circ f_{1,1}$ is that $(f_{0,0} \circ f_{0,1}) \otimes (f_{1,0} \circ f_{1,1}) = (f_{0,0} \otimes f_{1,0}) \circ (f_{0,1} \otimes f_{1,1})$. Usually, $f_j$ can be characterized as a composition of multiplicative steps and additive steps. During the multiplicative steps, we only multiply coefficients by some constants. For the additive steps, we perform additions and subtractions. One observation is that multiplicative steps are faster if we apply their composition directly. Suppose we have two multiplicative steps represented as matrix multiplications by $I_2 \otimes \begin{pmatrix} 1 & 0 \\ 0 & \zeta_0 \end{pmatrix}$ and

$$I_2 \otimes \begin{pmatrix} 1 & 0 \\ 0 & \zeta_1 \end{pmatrix}.$$ Since $\left( I_2 \otimes \begin{pmatrix} 1 & 0 \\ 0 & \zeta_0 \end{pmatrix} \right) \left( I_2 \otimes \begin{pmatrix} 1 & 0 \\ 0 & \zeta_1 \end{pmatrix} \right) = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & \zeta_1 & 0 & 0 \\ 0 & 0 & \zeta_0 & 0 \\ 0 & 0 & 0 & \zeta_0 \zeta_1 \end{pmatrix}$, we only...

\[14\] In the literature, people commonly attribute the idea to [Goo58, Tho63]. However, we are unable to locate the work [Tho63], and only find the publication information. If someone finds a copy, we would like to see how general the idea was in [Tho63].
need three multiplications on the right-hand side. If we compute with the left-hand side, then we need four multiplications. The high-dimensional generalization and \(f_j\)'s as series of compositions are obvious. See [AHY22] for applications.

E Generalization of Rader’s FFT

If \(n\) is an odd prime power, we define \(\mathcal{I}^* := \{z \in \mathbb{Z}_n | z \perp n\}\) and find a \(g\) satisfying \(\{g^k | k \in \mathbb{Z}_\lambda(n)\} = \mathcal{I}^*\) where \(\lambda\) is Carmichael’s lambda function.\(^{15}\) We can now split the DFT map \((a_j) \in \mathbb{Z}^n \mapsto (\hat{a}_i) \in \mathbb{Z}^n\) into \(i \in \mathcal{I}^*\) and \(i \in \mathcal{I} - \mathcal{I}^*\). For \(i \in \mathcal{I}^*\), we move \(\sum_{j \in \mathcal{I} - \mathcal{I}^*} a_j \omega_n^{ij}\) to the left-hand side and find

\[
\hat{a}_{g \log_e i} = \sum_{j \in \mathcal{I} - \mathcal{I}^*} a_j \omega_n^{ij} = \sum_{j \in \mathcal{I}^*} a_j \omega_n^{ij} = \sum_{j \in \mathcal{I}^*} a_j \omega_n^{ij} \log_e i + \log_e j.
\]

Obviously, collecting the right-hand side forms a system of equations implementing a size-\(\lambda(n)\) cyclic convolution [Win78, Section IV]. See [Ber23, Sections 4.12.3 and 4.12.4] for further generalization exploiting multiplicative subgroups in \(\mathcal{I}^*\) for arbitrary \(n\).

F A Formal Treatment of Localization

We refer to [Jac12b, Sections 7.2 and 7.3] for the localization of rings and modules. Let \(\mathcal{A}\) be an \(\mathcal{R}\)-algebra, \(z \in \mathbb{Z} - \{0\}\), and \(\mathcal{Z}^{-1} \mathcal{R}\) be the localization of \(\mathcal{R}\) at the multiplicative set \(\mathcal{Z} = \{1, z, z^2, \ldots\}\). Naturally, we have \(\mathcal{Z}^{-1} \mathcal{A}\) as a \(\mathcal{Z}^{-1} \mathcal{R}\)-module. We turn it into a \(\mathcal{Z}^{-1} \mathcal{R}\)-algebra by defining:

\[
\forall z^{-k_0} a, z^{-k_1} b \in \mathcal{Z}^{-1} \mathcal{A}, z^{-k_0} a z^{-k_1} b := z^{-k_0 - k_1} ab \in \mathcal{Z}^{-1} \mathcal{A}.
\]

Let \(\mathcal{A}, \mathcal{B}\) be \(\mathcal{R}\)-algebras, and \(\eta : \mathcal{A} \to \mathcal{B}\) be an algebra monomorphism. For an integer \(z \in \mathbb{Z} - \{0\}\), suppose we find a map \(\psi_z : \eta(\mathcal{A}) \to \mathcal{A}\) such that

\[
\forall a \in \mathcal{A}, (\psi_z \circ \eta)(a) = za.
\]

We define an algebra homomorphism \(\xi : \mathcal{Z}^{-1} \eta(\mathcal{A}) \to \mathcal{Z}^{-1} \mathcal{A}\) as

\[
\forall z^{-k} \eta(a) \in \mathcal{Z}^{-1} \eta(\mathcal{A}), \xi (z^{-k} \eta(a)) := z^{-1-k} \psi_z(\eta(a)).
\]

If we restrict the image of \(\xi\) to \(\eta(\mathcal{A})\), we find \(\xi|_{\eta(\mathcal{A})} := (\eta(a) \mapsto z^{-1} \psi_z(\eta(a))) = \eta^{-1}\). In summary, to invert \(\eta\) while given \(\psi_z\) with \(z \in \mathbb{Z} - \{0\}\) non-invertible in \(\mathcal{A}\), it suffices to define \(\xi : \mathcal{Z}^{-1} \eta(\mathcal{A}) \to \mathcal{Z}^{-1} \mathcal{A}\) and apply \(\xi|_{\eta(\mathcal{A})}\).

Notice that applying \(\xi\) assumes an already existing approach for multiplying \(z^{-1}\). An alternative way is to find \(\psi_{z_0}\) and \(\psi_{z_1}\) with \(z_0 \perp z_1\) and integers \(e_0, e_1\) satisfying \(e_0 z_0 + e_1 z_1 = 1\), and define \(\eta^{-1}\) as

\[
\eta^{-1} := e_0 \psi_{z_0} + e_1 \psi_{z_1}.
\]

Since \(e_0\) and \(e_1\) are integers, \(\eta^{-1}\) can be implemented entirely with arithmetic in \(\mathcal{R}\).

G Generalizations of Schönhage and Nussbaumer

Let \(g(x^{n_1}) \in R[x]\) be a degree-\(n_0n_1\) monic polynomial. Schönhage and Nussbaumer exploit the structure of \(g(x^{n_1})\) by introducing \(x^{n_1} \sim y\) (so \(R[x]/(g(x^{n_1})) \cong R[x,y]/(x^{n_1} - y, g(y))\)). Schönhage splits the structure into small structures by adjoining the defining condition. On the other hand, Nussbaumer adjoining a structure for splitting and uses \(g(x^{n_1})\) as the defining condition. We start by replacing \(x^{n_1} - y\) with \(h(x)\) satisfying \(\deg(h) \geq 2n_1 - 1\).

\(^{15}\)There is always such a \(g\) since \(n\) is an odd prime.
Schönhage. Schönhage identifies an \( n \) satisfying \( g(y)(y^n - 1) \) and \( h(x)\Phi_n(x) \), and treats \( R[x]/\langle h(x) \rangle \) as the coefficient ring. We then split as follows:

\[
\frac{R[x]}{\langle g(x^n) \rangle} \cong \frac{R[x,y]}{\langle x^{n^1} - y, g(y) \rangle} \mapsto \frac{R[x,y]}{\langle h(x), g(y) \rangle} \cong \biggl( \frac{R[x]}{\langle g(y) \rangle} \biggr) \biggl[ y \biggr] \cong \prod_{i \in \mathbb{Z}} \biggl( \frac{R[x]}{\langle y - x^i \rangle} \biggr).
\]

Since \( h(x)\Phi_n(x), \Phi_n(x) = 0 \in R[x]/\langle h(x) \rangle \) and \( x \) is a principal \( n \)-th root of unity defining a size-\( n \) cyclic FFT. Furthermore, since \( g(y)(y^n - 1) \), we apply truncation and obtain an FFT with indeterminate \( y \), coefficient ring \( R[x]/\langle h(x) \rangle \), and polynomial modulus \( g(y) \).

Nussbaumer. Nussbaumer identifies an \( n \) satisfying \( g(y)\Phi_n(x) \) and \( h(x)(x^n - 1) \), and splits as follows:

\[
\frac{R[x]}{\langle g(x^n) \rangle} \cong \frac{R[x,y]}{\langle x^{n^1} - y, g(y) \rangle} \mapsto \frac{R[x,y]}{\langle h(x), g(y) \rangle} \cong \biggl( \frac{R[y]}{\langle g(y) \rangle} \biggr) \biggl[ x \biggr] \cong \prod_{i \in \mathbb{Z}} \biggl( \frac{R[y]}{\langle x - y^i \rangle} \biggr).
\]

See [MV83a, MV83b, Ber01] for more discussions generalizing the notion of principal roots of unity to automorphisms defining FFTs.

H Applications of Truncation

H.1 \( R[x]/\langle x^r + 1 \rangle \) from \( R[x]/\langle x^{2r} - 1 \rangle \) for \( r \perp 2 \)

Our second application is to systematically generalize the isomorphism \( R[x]/\langle x^r + 1 \rangle \cong R[x,y]/\langle x + y, y^r - 1 \rangle \) for an odd \( r \). Let \( \psi : \mathbb{Z}_{2r} \cong \mathbb{Z}_2 \times \mathbb{Z}_r \) be the additive group isomorphism \( 1 \mapsto (1,1) \). Recall that \( \psi \) induces an algebra isomorphism \( \psi' : R[x]/\langle x^{2r} - 1 \rangle \cong R[z]/\langle z^2 - 1 \rangle \otimes R[y]/\langle y^r - 1 \rangle \) (cf. Section C). From \( R[z]/\langle z^2 - 1 \rangle \cong \prod R[z]/\langle z \pm 1 \rangle \), we have

\[
\frac{R[x]}{\langle x^r + 1 \rangle} \cong \psi'^{-1} \biggl( \frac{R[z]}{\langle z + 1 \rangle} \otimes \frac{R[y]}{\langle y^r - 1 \rangle} \biggr) \cong \frac{R[x,y]}{\langle x + y, y^r - 1 \rangle}.
\]

Similarly, whenever we are working on a polynomial ring with modulus a factor of \( x^{q_1q_2} - 1 \) for \( q_0 \perp q_1 \), we can always look for transformations for \( R[z]/\langle z^{q_1} - 1 \rangle \otimes R[y]/\langle y^{q_2} - 1 \rangle \) and pull them back to the desired domain (in our example, we exploit \( R[z]/\langle z^2 - 1 \rangle \cong \prod R[z]/\langle z \pm 1 \rangle \)) Examples in the literature are the CRT negacyclic/tricyclic transform in [HVDH22, Sections 3.5 and 3.6].

One should notice that we could derive optimizations by exploiting some properties of a factor of \( x^{q_1q_2} - 1 \) and bring the resulting computation back to the isomorphism \( R[x]/\langle x^{q_1q_2} - 1 \rangle \cong R[z]/\langle z^{q_1} - 1 \rangle \otimes R[y]/\langle y^{q_2} - 1 \rangle \). The optimization comes from splitting \( \Phi_{2q_2} = (x^{2^k} - \omega_6) (x^{2^k} - \omega_5^3) \) exploiting the identity \( \omega_6 + \omega_5^3 = 1 \) [LS19] and \( \Phi_3 = (x - \omega_3)(x - \omega_5^3) \) exploiting the identity \( \omega_3 + \omega_5^3 = -1 \) [DV78a, HY22, AHY22]. We leave them as exercises for the readers.

H.2 Nussbaumer from Schönhage

As we know, for arbitrary \( g \) a factor of \( x^{2^k} - 1 \), we can derive the corresponding Schönhage’s FFT via truncating the Schönhage’s FFT for \( R[x]/\langle x^{2^k} \rangle \). We now show how to exploit the same idea for Nussbaumer’s FFT systematically. An example is to derive the Nussbaumer for \( R[x]/\langle x^{1536} + 1 \rangle \) from the Schönhage for \( R[x]/\langle x^{1024} \rangle \).
Given polynomials $g(z)|(z^n - 1)$ and $h(z)|\Phi_n(z)$ with $\deg(g) = 2n_0$ and $\deg(h) = 2n_1$, we have a size-$2n_0n_1$ transformation via Schönhage as follows

$$R[x] \langle g(x^{n_1}) \rangle \cong \frac{R[x,y]}{\langle x^{n_1} - y, g(y) \rangle} \leftrightarrow \frac{R[x,y]}{\langle h(x), g(y) \rangle} \cong \frac{R[x,y]}{\langle h(x)^2, g(y)^2 \rangle} \cong \frac{R[x]}{\langle h(x), g(y) \rangle} \cong \frac{[y]}{\langle g(y) \rangle}.$$ 

We exchange $x$ and $y$ in $(R[x]/\langle h(x) \rangle)[y]/\langle g(y) \rangle$, and invert the derivation of Nussbaumer. This gives us the following transformation for Nussbaumer

$$R[x] \langle h(x^{n_0}) \rangle \cong \frac{R[x,y]}{\langle x^{n_0} - y, h(y) \rangle} \leftrightarrow \frac{R[x,y]}{\langle g(x), h(y) \rangle} \cong \frac{R[y]}{\langle h(y) \rangle} \cong \frac{[x]}{\langle g(x) \rangle}.$$ 

I Interpreting Multiplications in $R[x]/\langle x^n - \alpha x - \beta \rangle$ as TMVPs

We outline [Yan23]'s ideas interpreting multiplications in $R[x]/\langle x^n - \alpha x - \beta \rangle$ as Toeplitz matrix-vector products for generic $\beta$ as follows. For reducing modulo $x^n - \alpha x$, if we additionally add the element $\sum_{j=0}^{n-2} a_{b_{n-1-j}} a_j$ to $c_0$, then the resulting computation is compatible with a Toeplitz matrix-vector product. This gives us the following transformation matrix mapping $a$ to $ab \in R[x]/\langle x^n - \alpha x - \beta \rangle$:

$$M_0 + M_1 + M_2' = \begin{pmatrix} 0 & \cdots & 0 & \alpha b_{n-1} & \cdots & \alpha b_1 & 0 \\ 0 & \cdots & 0 & 0 & \cdots & 0 & 0 \\ \vdots & \ddots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & \cdots & 0 & 0 & \cdots & 0 & 0 \end{pmatrix}$$

where $M_0$ and $M_1$ are the same as previous paragraph and

$$M_2' = \text{Toeplitz}_n(0, \ldots, 0, ab_{n-1}, \ldots, ab_1, 0).$$

Since $M_0 + M_1 + M_2'$ is the Toeplitz matrix

$$\text{Toeplitz}_n(b_{n-1}, \ldots, b_1, b_0 + \alpha b_{n-1}, \beta b_{n-1} + \alpha b_{n-2}, \ldots, \beta b_2 + \alpha b_1, \beta b_1),$$

$ab \in R[x]/\langle x^n - \alpha x - \beta \rangle$ can be written as a Toeplitz matrix-vector product with post-processing as follows:

$$ab \mod (x^n - \alpha x - \beta) = (M_0 + M_1 + M_2') a - \begin{pmatrix} \alpha b_{n-1} & \cdots & \alpha b_1 & 0 \\ 0 & \cdots & 0 & 0 \\ \vdots & \ddots & \vdots & \vdots \\ 0 & \cdots & 0 & 0 \end{pmatrix} a.$$

J A Formal Treatment of Bilinear Systems

Let $A, B, C$ be modules over the ring $R$. We call a map $\eta : A \times B \to C$ a bilinear map if

- $\forall a \in A, \eta(a, -) : B \to C$ is a module homomorphism.
- $\forall b \in B, \eta(-, b) : A \to C$ is a module homomorphism.

Suppose we have maps $\psi : A^* \to A', \kappa : B \to B', \iota : C' \to C^*$, and a bilinear map $\xi : C' \times B' \to A'$ satisfying

$$\forall b \in B, \xi(-, \kappa(b)) = \psi \circ \eta(-, b)^* \circ \iota.$$
If \( \eta(-, b) = f_b \circ g_b \) for some \( f_b \) and \( g_b \), we have the corresponding factorization for \( \xi (-, \kappa (b)) \):

\[
\forall b \in \mathcal{B}, \xi (-, \kappa (b)) = \psi \circ g_b^* \circ f_b^* \circ \iota.
\]

In Section 5.5, we present the ideas with bilinear systems. We now rephrase the core idea of [Win80] as follows: Let’s assume \( \mathcal{A}' = \mathcal{A}, \mathcal{B}' = \mathcal{B}, \mathcal{C}' = \mathcal{C}, \psi = a^* \mapsto a, \kappa = \text{id}_\mathcal{B}, \) and \( \iota = c \mapsto c^* \). For finite index sets \( I, J, K \) and \( \{(i, j, k) \mid (i, j, k) \in I \times J \times K\} \), define \( \alpha = (a_i)_{i \in I} \in \mathcal{A}, \beta = (b_j)_{j \in J} \in \mathcal{B}, \gamma = (c_k)_{k \in K} \in \mathcal{C} \). Then, we write

\[
\begin{align*}
\left( \sum_{i \in I} \sum_{j \in J} r(i, j, k) a_i b_j \right)_{k \in K} &= \eta(-, b)(\alpha) \\
\left( \sum_{j \in J} \sum_{k \in K} r(i, j, k) c_k b_j \right)_{i \in I} &= \xi (-, b)(\gamma)
\end{align*}
\]

and find \( \xi (-, b) = (\psi \circ \eta(-, b)^* \circ \iota) \).

**K Implementing Transposition Matrices**

We give a conceptual review of transposing a matrix with vector instructions. The idea was introduced by [Flo72] under the context of permuting with pages and more recently transposing arbitrary matrices. There are two steps: (i) transpose as if we are transposing a 2\( \times \)2 matrix, and (ii) transpose each of the 2\( \times \)2 matrices. We implement step (i) by permuting the pairs \((v_0, v_2)\) and \((v_1, v_3)\), and for step (ii), we permute the pairs \((v_0, v_1)\) and \((v_2, v_3)\). See Figure 2 for an illustration. Obviously, the idea generalizes to transposing arbitrary 2\( k \)\( \times \)2\( k \) matrices – we transpose as if we are transposing a 2\( \times \)2 matrix.
with entries $2^k - 1 \times 2^k - 1$ matrices, and transpose the $2^k - 1 \times 2^k - 1$ matrices recursively. Since we start from the root level of the recursion tree, we call the approach top-down transposition. Notice that we can swap the order of (i) and (ii). We call the resulting approach bottom-up transposition (cf. Figure 3).

Figure 3: Bottom-up transposition of the $4 \times 4$ matrix with rows $(a_0, \ldots, a_3)$, $(a_4, \ldots, a_7)$, $(a_8, \ldots, a_{11})$, and $(a_{12}, \ldots, a_{15})$.

L Constructing the Column Representation of a Toeplitz Matrix

Algorithm 10 constructs the columns with only memory loads, and Algorithm 11 replaces some memory instructions with permutation instructions.

**Algorithm 10** Constructing the columns of a Toeplitz matrix from its array form with memory loads [CCHY23].

**Inputs:** Array $M[8] = \{0, a_3', a_2', a_1', a_0, a_1, a_2, a_3\}$.

**Outputs:** Vector registers

\[
\begin{align*}
& t_0 = a_3 \parallel a_2 \parallel a_1 \parallel a_0, \\
& t_1 = a_2 \parallel a_1 \parallel a_0 \parallel a_1', \\
& t_2 = a_1 \parallel a_0 \parallel a_1' \parallel a_2', \\
& t_3 = a_0 \parallel a_1' \parallel a_2' \parallel a_3'.
\end{align*}
\]

1: $t_0 = M[4-7]$
2: $t_1 = M[3-6]$
3: $t_2 = M[2-5]$
4: $t_3 = M[1-4]$
5: $\triangleright$ Memory load.
**Algorithm 11** Constructing the columns of a Toeplitz matrix from its array form with memory loads and permutations [Hwa23].

**Inputs:** Array $\mathbf{M}[8] = \{0, a'_3, a'_2, a'_1, a_0, a_1, a_2, a_3\}$.

**Outputs:** Vector registers

- $t_0 = a_3 \| a_2 \| a_1 \| a_0$,
- $t_1 = a_2 \| a_1 \| a_0 \| a'_1$,
- $t_2 = a_1 \| a_0 \| a'_1 \| a'_2$,
- $t_3 = a_0 \| a'_1 \| a'_2 \| a'_3$.

1. $t_0 = \mathbf{M}[4-7]$
2. $t_3 = \mathbf{M}[0-3]$
3. $t_1 = \text{ext}(t_3, t_0, 3)$
4. $t_2 = \text{ext}(t_3, t_0, 2)$
5. $t_3 = \text{ext}(t_3, t_0, 1)$

\[ \begin{align*}
\text{ext}(\mathbf{a}, \mathbf{b}, \mathbf{c}) & = \{ \mathbf{a} \| \mathbf{b} \| \mathbf{c} \} \\
\text{Memory load} & \quad & \text{Memory load.}
\end{align*} \]

**References**


[Ber01] Daniel J. Bernstein. Multidigit multiplication for mathematicians. 2001. [https://cr.yp.to/papers.html#m3](https://cr.yp.to/papers.html#m3). 7, 19, 20, 25, 47


SoK: Polynomial Multiplications for Lattice-Based Cryptosystems


[Yan22] Bo-Yin Yang, 2022. Personal communication. 33

[Yan23] Bo-Yin Yang, 2023. Personal communication. 48