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ABSTRACT

Privacy-Preserving Machine Learning (PPML) provides protocols for learning and statistical analysis of data that may be distributed amongst multiple data owners (e.g., hospitals that own proprietary healthcare data), while preserving data privacy. The PPML literature includes protocols for various learning methods, including ridge regression. Ridge regression controls the L_2 norm of the model, but does not aim to strictly reduce the number of non-zero coefficients, namely the L₀ norm of the model. Reducing the number of non-zero coefficients (a form of *feature selection*) is important for avoiding overfitting, and for reducing the cost of using learnt models in practice. In this work, we develop a first privacy-preserving protocol for sparse linear regression under L₀ constraints. The protocol addresses data contributed by several data owners (e.g., hospitals). Our protocol outsources the bulk of the computation to two non-colluding servers, using homomorphic encryption as a central tool. We provide a rigorous security proof for our protocol, where security is against semi-honest adversaries controlling any number of data owners and at most one server. We implemented our protocol, and evaluated performance with nearly a million samples and up to 40 features.

KEYWORDS

Privacy preserving machine learning, sparse linear regression, feature selection, secure multiparty computation, homomorphic encryption

1 INTRODUCTION

The Machine Learning (ML) revolution critically relies on large volumes of data to attain high confidence predictions. However, the massive amounts of data collected on individuals and organizations incur serious threats to security and privacy. From a legal perspective, privacy regulations such as the European General Data Protection Regulation (GDPR) and the California Customer Privacy Act (CCPA) aim at controlling these threats. From a technological perspective, Privacy Preserving Machine Learning (PPML) [45] attains ML utility without exposing the raw data,¹ e.g., by leveraging tools for secure computation [28, 33, 69]. Many PPML solutions focus on the inference phase, e.g., [11, 31, 34]. A growing body of literature also addresses training, covering a range of learning tasks and techniques, including training decision tree models, e.g., [45], as well as linear regression, logistic regression and neural networks models, e.g., [49]. Recently, attention has been drawn also to the task of privacy preserving feature selection [44], which -in the context of linear regression- is the focus of our work.

Feature selection [36] is the process of selecting a subset of informative features to be used for model training, while removing non-informative or redundant ones. Feature selection is important for avoiding overfitting, that is, for producing models that support high quality prediction on new data rather than models that essentially "memorize" the training data set while failing to generalize. Moreover, feature selection supports producing *sparse models* whose use for prediction in practice requires measuring only the few selected features. Sparsity is often a desired property, leading to significant cost savings when the model is repeatedly used for prediction, especially when feature extraction is expensive. For example, sparse models are highly desired in medical applications where feature extraction might involve medical interventions with associated financial and morbidity costs (see Section 3.1).

The focus of this work is on feature selection under L_0 constraints,² specifically for *wrapper methods*. In contrast, previous work on privacy preserving feature selection considered *only filter* [16, 44, 53] *and embedded methods* [1, 3, 4, 20, 27, 29, 40, 45, 46, 50, 62–64, 66, 68, 71, 71], but not *wrapper methods*. We next elaborate on the differences between these methods.

Selecting the subset of features of highest predictive power is computationally intractable [15]; nonetheless heuristic methods - which can be categorized into *filter*, *embedded* and *wrapper* methods - are widely employed in practice with great success. Filter methods assign a score to each feature in isolation, outputting the highest scoring features; they are typically very fast, but often fail to select the best features because they ignore relationships and dependencies between features. Embedded methods intrinsically incorporate feature selection into the model training process, e.g., in decision tree regression, as well as in ridge and Lasso regression; The latter two techniques penalize models according to their (L_2 and L_1 respectively) norms, favoring models with fewer high-weight features. However, they do not necessarily return a sparse model: the model often includes a tail of low-weight features (particularly in ridge regression). Wrapper methods select features in an iterative process, with a target ML algorithm in mind (e.g., linear regression). In each iteration: (1) a model is trained on the current subset of features, then (2) features are ranked according to an evaluation metric measuring their usefulness for that model, and (3) this ranking is used to specify the subset of features for the next iteration. Wrapper methods are considerably slower than filter and embedded methods, due to the multiple rounds of model training, but often lead to superior outcomes for the target ML algorithm.

In summary, none of the aforementioned methods strictly dominates the others (see, e.g., a comparative study in [39]).

¹Other PPML concerns include limiting the amount of information revealed by the output, e.g., using differential privacy in [57]; see a survey in [43].

 $^{^2}$ Concretely, an L_0 constraint determines the intended number of features in the model (e.g., dictated by hardware considerations and/or limitations, as in [52]). We then look for the best model that satisfies this constraint.

Consequently, common practices often examine several methods in search of the best performing one (using cross-validation to avoid overfitting) or use a *hybrid* approach to combine the strengths of several methods. Examples for hybrid approaches include using a filter method to quickly remove many features, then selecting from the remaining ones using an embedded or wrapper method (see, e.g., [19, 59]); or, executing wrapper and embedded methods in parallel, each scoring the features, where the output includes the features with highest total score (see, e.g., [17, 18, 35]).

Thus, providing privacy preserving solutions to a wide variety of feature selection methods is essential to supporting versatile usecases.

1.1 Our Contribution

In this work we present the first privacy-preserving feature selection solution in a wrapper method, producing a sparse regression model under L_0 constraint (i.e., with exactly the specified number of features). Concretely:

Our protocol. We design the Secure Iterative Ridge regression (SIR) protocol: a new protocol that produces a sparse ridge regression model, over input data that is (horizontally)-partitioned among distrusting data-owners, and where the bulk of the computation is outsourced to two non-colluding servers (aka, two-server model). Horizontal partitioning means that each data owner contributes a subset of data samples. Our solution utilizes homomorphic encryption [28, 54] as a central tool. The wrapper method that we realized in a privacy preserving fashion is the commonly used Recursive Feature Elimination (RFE) algorithm, introduced in the highly influential paper [37]. RFE starts by considering all features, iteratively training a model on the current set of "surviving" features, and removing features of lowest weight (the number of removed features is a tunable parameter), until reaching the L_0 constraint. The ML model that we train at each iteration is a ridge regression model, so that at the termination of all iterations we obtain a sparse regression model. As a central new component we introduce a scaled ridge regression protocol, which may be of independent interest.

Privacy & Threat Model. Privacy holds against all semi-honest computationally-bounded adversaries controlling any number of data owners and at most one of the two servers. The security guarantee is that such adversaries cannot infer any information on the inputs of data owners that they do not control, except for what can be efficiently computed directly from the public parameters, and the inputs and outputs of corrupted parties.³ Our security proof for SIR covers the case of overdetermined linear regression (more data samples than features and full rank). To demonstrate the necessity of the security measures implemented in SIR, we devise *explicit attacks* showing that simplified variants without these measures are insecure.

Complexity. The complexity of each data owner is proportional only to her input and output size (and polynomial in the security parameter). The two servers engage in a two-party protocol with round complexity logarithmic in the number of input features *d*, and complexity that is cubic in *d* (up to poly-logarithmic factors)

and logarithmic in the number of input records *n* (and polynomial in the security parameter); the protocol includes homomorphic computations of multiplicative depth at most $O(\log d + \log \log n)$.

System and empirical evaluation. We implemented our protocol SIR and empirically evaluated its performance. Our system is generic and can be applied to any dataset with numerical features. As a concrete example, we ran experiments on a gene-expression dataset derived from TCGA [60]. The full data matrix taken from TCGA breast cancer data consists of gene expression profiles for 781 samples. Each profile, representing a human subject, consists of over 10K values. Our proof of concept data represents regressing the expression pattern of a target gene (a vector with 781 entries), based on arbitrarily selected 40 other genes. Furthermore, we artificially randomly partition the 781 instances amongst 10 data owners. We note that horizontal partition, as in our experiments, has interesting use cases in analyzing gene expression related data, e.g., in [6, 8, 30, 58]. In our experiments, each iteration removes 10% of the features, and the L_0 constraint is to produce a model consisting of 8 features.

We point out that the initial selection of 40 out of 10*K* features would typically be executed using filter methods (due to their fast runtime), which can be done using the prior art on privacy preserving filter methods [16, 44, 53]. We focus therefore on selecting the 8 out of 40 remaining features using SIR –our privacy preserving RFE– which is the contribution of our work.

Our experiments demonstrate that our system produces the desired model – i.e., the same model as produced in the clear. Running in the clear takes seconds while our privacy preserving system terminates in just under a day, using 134GB RAM.

Scalability. Our protocol scales favorably with the number of input records and data owners, as demonstrated by our empirical evaluation on up to 802,816 records and 1000 data owners, where a $512 \times$ growth in the number of records (respectively, $10 \times$ growth in the number of data owners) led to runtime increase by only 10% (resp., 1%).

1.2 Comparison to Prior Work

Prior privacy preserving feature selection solutions were in filter or embedded methods, whereas ours is the first in a wrapper method (concretely, a privacy preserving RFE). Although none of these methods dominates the others, RFE was developed in [37] for the use case of gene expression data, where it excelled. Indeed, the mean square error (MSE) of the model produced by our system significantly outperforms the regression models produced by filter, ridge and Lasso (the baseline); see Section 10.2.

In terms of runtime, our system is expected to be slow, since, even in cleartext, wrapper methods are considerably slower than filter and embedded ones. This is also evident by our experiments, where the runtime of our system (on 40 features) is roughly 1 day, compared to runtimes between slightly under a minute, and a few hours, on various dataset sizes (with 20-120 features) reported in previous works [4, 16, 27, 29, 40, 44, 50, 53, 63, 64, 71, 71].

Producing better models (i.e., with smaller MSE) –as in SIR– is typically desired, even if it incurs a slower (but reasonable) training runtime. This is because training a model occurs once, whereas the fruits of having a better MSE provide recurring benefits in

³The public parameters consist of the number of input samples and features, data precision, model regularization parameter, and model sparsity.

each use of the model. Furthermore, a runtime of 1 day (and even more) seems to be reasonable in the context of gene-expression data, where the trained model is used to guide the manufacturing of a medical testing device (DNA chip), and our training time is insignificant when compared to the manufacturing pipeline.

Furthermore, our runtime can be significantly lowered by tuning the system parameters to remove a larger fraction of the features in each iteration, thus reducing the total number of iterations. In particular, when tuning parameters so that our system returns a model satisfying the L_0 constraint in a single iteration, our system terminates in only 1 hour (when executed on 20 features and 1000 data samples). This single-iteration parameter setting may be of independent interest, because it provides a privacy preserving truncated ridge model – i.e., a ridge regression model whose low weight features are truncated as to satisfy the L_0 constraint. This should be used with caution though, as our experiments indicate that there is a tradeoff between runtime and MSE – where performing more iterations typically yields a better MSE.

In summary, SIR expands over prior work in offering the first privacy preserving feature selection in a wrapper method. This widens the PPML toolset to include the commonly used RFE, which leads to favorable learning outcomes in some use cases of interest.

1.3 Paper Organization

We give an overview of our techniques, along with a comparison to techniques used in prior work, in Section 2. Preliminary definitions appear in Section 3; the problem statement in Section 4. The SIR protocol appear in Sections 5-6; our attacks (on simplified variants of SIR, demonstrating the necessity of SIR's various components) in Section 7; and the security and complexity analysis of SIR in Sections 8-9 respectively. Our system and empirical evaluation appear in Section 10. Conclusions appear in Section 11.

2 OVERVIEW OF OUR TECHNIQUES

In this section we give an overview of our techniques. We present the high level overview of SIR in Section 2.1, elaborate on its key components in Sections 2.2-2.3, discuss our attacks in Section 2.4, and compare our techniques to prior work in Section 2.6.

2.1 IR and SIR

We first describe the (insecure) feature selection algorithm, called Iterated Ridge (IR); and then present our Secure Iterative Ridge regression (SIR) protocol.

Iterated Ridge (IR, cf. Figure 1) is an RFE algorithm for sparse ridge regression, analogous to the sparse logistic regression algorithm used in [26]. IR starts with all features, removing 10% of the features in each iteration, until reaching $2 \cdot s$ features, where *s* is the user-determined target number of features, then removes features one-by-one.⁴ (This follows the paradigm of adjusting the learning rate to a smaller value when approaching the solution.) Selecting which features to remove in each iteration is done by solving ridge regression (see Section 3.1) on the surviving features to obtain an intermediate model, and removing the features whose weights (in absolute value) are in the bottom 10%.

Secure Iterative Ridge (SIR, cf. Figure 2) is executed between m data owners DO_1, \ldots, DO_m and two non-colluding servers S_1, S_2 . The data owners' inputs are a horizontal partition of the data matrix $X \in \mathbb{R}^{n \times d}$ and the target vector $\vec{y} \in \mathbb{R}^{n}$; i.e., there is a partition I_1, \ldots, I_m of $[n] = \{1, \ldots, n\}$ so that each data owner DO_j holds the restriction of *X* and \vec{y} to rows with indices in I_j , denoted X^j and $\vec{y^j}$. Let N denote a sufficiently large integer (as determined by Equation 4). In SIR we use homomorphic computation over encrypted data, which translates into computing on the underlying cleartext values with arithmetic modulo N, i.e., in the ring \mathbb{Z}_N (unless explicitly stated otherwise). The values in X, \vec{y} are assumed to be normalized to [-1, 1] (which is common in ML), and each data owner scales her data to integral values in $[-10^{\ell}, 10^{\ell}]$ for a common precision parameter ℓ . Moreover, N is set to be sufficiently large so that, despite computing modulo N, we are able to produce the same final output as if computing over the integers.

SIR is composed of four phases as detailed next.

Phase I. Setup & Upload (cf. Figures 4-5 and Figure 6 Step 1): S_2 generates a key pair (pk, sk) for a fully homomorphic encryption scheme, and publishes pk.⁵ Each data owner DO_j encrypts (entryby-entry) $A^j = (X^j)^T \cdot X^j$ and $\vec{b^j} = (X^j)^T \cdot \vec{y^j}$ under pk, and sends the ciphertexts to S_1 who homomorphically combines them to obtain ciphertexts for:

$$A = \sum_{j} A^{j} + \lambda I \in \mathbb{R}^{d \times d} \text{ and } \vec{b} = \sum_{j} \vec{b^{j}} \in \mathbb{R}^{d}.$$

Phase II. Obliviously Permute Features (cf. Figure 6 Steps 2-3): S_1 and S_2 engage in a 1-message protocol that concludes with S_1 holding ciphertexts for

$$A_p = P^T \cdot A \cdot P$$
 and $\vec{b_p} = P^T \vec{b}$,

where *P* is a random $d \times d$ permutation matrix. Importantly, S_1 and S_2 have no information on *P* other than it being a random permutation of the features' indices $[d] = \{1, \ldots, d\}$. For this purpose *P* is sampled obliviously as follows. First, S_2 samples a uniformly random $d \times d$ permutation matrix P_2 , encrypts it, and sends the ciphertexts to S_1 . Next, S_1 samples a uniformly random $d \times d$ permutation matrix P_1 , and homomorphically computes $P = P_1 \cdot P_2$, A_p and \vec{b}_p .

Phase III. Privacy Preserving RFE (cf. Figure 2, Steps 2-3): At the onset of this phase, S_1 initializes the set F of surviving features to be all features, i.e., F = [d]. Denote by $A_{p|F}$ and $\vec{b}_{p|F}$ the restriction of A_p and \vec{b}_p to the surviving features F (i.e., include only rows of A_p and \vec{b}_p whose indices are in F, and likewise for columns of A_p). While the number of features in F exceeds the L_0 constraint, features are removed as follows:

(1) Scaled ridge (cf. Figure 3): First, S_1 and S_2 engage in a two-party protocol, at the conclusion of which S_1 holds a ciphertext encrypting the scaled ridge regression model:

$$\vec{w}_{\text{scaled}} = \det(A_{p|F}) \cdot \left[(A_{p|F})^{-1} \cdot \vec{b}_{p|F} \right]$$

⁴The fraction of features to be removed in each iteration, and the threshold determining when to transition to the one-by-one phase, are both user-definable hyper-parameters.

⁵More precisely, S_2 produces two key pairs $-(pk_N, sk_N)$ and (pk_D, sk_D) , with $d+1 \leq D \ll N$ - supporting homomorphic computation modulo N and D respectively. We primarily employ pk_N ; using pk_D only briefly during ranking (Phase III, Part 2).

This is a scaling by factor det $(A_{p|F})$ of the ridge regression model for $(A_{p|F}, \vec{b}_{p|F})$ which is $\vec{w} = (A_{p|F})^{-1} \cdot \vec{b}_{p|F}$. This scaling is central for both the correctness and the efficiency of our protocol; see a detailed discussion in Section 2.2.

In detail, the scaled ridge protocol operates as follows. First, S_1 homomorphically masks $A_{p|F}$ and $\vec{b}_{p|F}$, and sends their masked versions to S_2 , where these masked versions are: $A^{\text{masked}} = A_{p|F} \cdot R$ and $\vec{b}^{\text{masked}} = \vec{b}_{p|F} + A_{p|F} \cdot \vec{r}$ for uniformly random invertible matrix R and random vector r of the appropriate dimensions.⁶ Next, S_2 decrypts, computes det (A^{masked}) and $\vec{w}_{\text{scaled}}^{\text{masked}} = \text{adj}(A^{\text{masked}}) \cdot \vec{b}^{\text{masked}}$ in the clear, encrypts them, and sends the ciphertexts to S_1 . Finally, S_1 homomorphically unmasks to obtain ciphertexts for the scaled (un-masked) model, using the algebraic identity: $\vec{w}_{\text{scaled}} = R \cdot \vec{w}_{\text{scaled}}^{\text{masked}} + \det(A^{\text{masked}}) \cdot \vec{r}$. We refer the reader to our analysis in Section 8 for the proof of correctness.

- (2) Ranking (cf. Figure 9, Steps 1-4): Next, S₁ and S₂ engage in a two-party protocol, at the conclusion of which S₁ holds a ranking –in cleartext– of the surviving features according to their weight in w_{scaled}; see details in Section 2.3. Importantly, S₁ does not know the actual weights, only their ordering. This does not violate privacy, because the features were randomly permuted; details are provided in our privacy analysis in Section 8.
- (3) Removal (cf. Figure 9, Steps 5-6): Finally, S₁ removes the (dynamically adjusted desired number of) lowest ranking features, and updates F, A_{p|F} and b_{p|F} accordingly.

We elaborate on the scaled ridge regression and ranking subprotocols in the subsections below.

Phase IV. Obliviously un-permute and rationally reconstruct (cf. *Figure 8):* At the onset of this phase the servers hold a subset $F \subseteq [d]$ of feature indices, which satisfies the L_0 constraint, i.e., |F| = s. They now engage in a two-party protocol to produce a (cleartext) sparse ridge regression model whose non-zero weights are only on features in *F*.⁷ First, S_1 and S_2 engage in a two-party sub-protocol, at the conclusion of which S_1 holds ciphertexts for the ridge regression model $\vec{w}_p = (A_p|_F)^{-1} \cdot \vec{b}_p|_F$ for the final set of features *F*. Second, S_1 homomorphically un-permutes the features' order (where features that did not survive have weight zero), and sends this un-permuted encrypted model to \mathcal{S}_2 who decrypts it, and sends it in the clear to S_1 . That is, S_1 now has $\vec{w} = A_{|F|}^{-1} \cdot \vec{b}_{|F|}$, where the inverse and product are computed in \mathbb{Z}_N . Finally, S_1 maps \vec{w} to the solution to ridge regression over the surviving features when computed over the *rationals* (rather than in \mathbb{Z}_N) via rational reconstruction [23, 65],⁸ and outputs the resulting model.

2.2 Our Scaled Ridge Protocol

A central new component in our solution is a sub-protocol that we call *scaled ridge regression*, which may be of independent interest. Our scaled ridge builds on the following two observations.

Observation 1: Ranking is invariant to scaling. Ranking indices of a vector \vec{w} according to the magnitude of their associated values w[i] (in absolute value) is invariant to scaling the vector by a positive factor. Therefore, instead of ranking features according to their magnitude in the ridge regression model, we can rank them according to any (non-zero) scaling of this model.

Observation 2: homomorphic ranking is considerably faster with our scaling. We show that homomorphic ranking is considerably faster when we scale the ridge regression model as we do. To explain why this is so, we first provide some background and point out a key complexity bottleneck in homomorphic ranking of the ridge regression model. We then explain how to eliminate this bottleneck using scaling.

Let (X, \vec{y}) be a data matrix and target vector in a ridge regression problem, and set $A = X^T \cdot X + \lambda I$ and $\vec{b} = X^T \cdot \vec{y}$. The ridge regression model is:

$$\vec{w} = A^{-1} \cdot \vec{b}$$

where the arithmetic in computing A, \vec{b} and \vec{w} is over the reals. In our privacy-preserving solution we compute an encrypted model \vec{w} via homomorphic computation over encrypted A and \vec{b} , and where the underlying plaintext computation is conducted in a finite ring \mathbb{Z}_N of integers modulo N (rather than over the reals). To ensure that the same model is obtained despite performing computations modulo N, two measures are required. First, N must be sufficiently large (cf. Equation 4) so that, e.g., $A \mod N$ and $\vec{b} \mod N$ are identical to A and \vec{b} . Second, rational reconstruction must be computed on each entry of the reduced model $A^{-1} \cdot \vec{b} \mod N$ to map it to the model \vec{w} computed over the reals. Unfortunately, *homomorphically computing rational reconstruction is a complexity bottleneck*.

Next, we show that scaling the model by the factor det(*A*) allows us to eliminate the need for rational reconstruction. Relying on the algebraic identity $A^{-1} = \frac{\operatorname{adj}(A)}{\operatorname{det}(A)}$ (where $\operatorname{adj}(A)$ is the adjugate matrix of *A*), we can see that the scaled model $\vec{w}_{\text{scaled}} = \operatorname{det}(A) \cdot A^{-1} \cdot \vec{b}$ is equal to

$$\vec{w}_{\text{scaled}} = \operatorname{adj}(A) \cdot b.$$

Since computing adj(A) involves only multiplications and additions, then –when using a sufficiently large N, as we do– no wrap-around occurs when computing \vec{w}_{scaled} modulo N. Namely, computing over \mathbb{Z}_N produces an identical scaled model as when computing over the reals. This implies that we can directly rank the entries of $\vec{w}_{scaled} \mod N$ without executing rational reconstruction. Namely, we are able to avoid performing rational reconstruction in each iteration, thus eliminating a key complexity bottleneck.

2.3 Our Ranking Protocol

We rank features in the scaled ridge model of the current iteration by their absolute value. This is done by ordering features according to their "size", measured as their distance from the nearest multiple of N. This measurement of the "size" of a feature can be thought of

⁶This masking was introduced in [29] in the context of privacy preserving ridge regression. However, unlike our work, they employ masking to produce a ridge model that is *un-scaled* and *in cleartext*; see details in Section 2.6.

⁷The ridge regression model is computed similarly to the protocol of [4], except for restricting the data to the features in *F*, and obliviously masking and un-permuting over an encrypted model; see Section 2.6.

⁸Rational reconstruction refers to the Lagrange-Gauss algorithm which allows one to recover a rational q = r/s from its representation $q' = r \cdot s^{-1} \in \mathbb{Z}_N$ for sufficiently large N (in particular, this holds for N which satisfies Equation 4).

as treating values larger than (N-1)/2 as negative, and comparing the absolute value of the features. Denote the current scaled model by $\vec{w}_{scaled} = (z_1, \dots, z_d) \in \mathbb{Z}_N^d$ s.t. it has non-zero values $z_i \neq 0$ only on indices *i* in the current surviving set of features $F \subseteq [d]$. The ranking is computed as follows. First, S_1 masks each pairwise difference $z_i^2 - z_j^2 \mod N$, with $i, j \in F$, by homomorphically adding to it a uniformly random integer $r_{i,j}$ (modulo N), and sends the masked differences to S_2 . Second, S_2 decrypts each masked difference $z_i^2 - z_i^2 + r_{i,j} \mod N$, converts it to a binary representation (in the clear), encrypts this bit-by-bit and sends the ciphertexts to S_1 . The encryption of this binary representation is under the key pair (pk_D, sk_D) , generated by S_2 during setup, whose plaintext modulus is a small integer D larger than d. Third, S_1 homomorphically compares each encrypted masked pairwise difference $z_i^2 - z_j^2 + r_{i,j}$ with his cleartext $r_{i,j}$ (where both are in binary representation, and while accounting for all possible overflows), producing an encrypted outcome bit $b_{i,j}$ which is equal to 1 if-and-only-if $z_i^2 > z_j^2$ and zero otherwise. Then, for each i, S_1 homomorphically sums up the bits $b_{i,j}$ for all j to obtain a ciphertext encrypting Ord_i , which is the number of indices j with magnitude z_i^2 smaller than z_i^2 (we assume all weights are distinct), and sends all these ciphertexts to S_2 . Fourth, S_2 decrypts all ordinals, computes the set of surviving features according to Ord₁, ..., Ord_d (i.e., the set of highest-ranking features), and sends the indicator vector of this set (in the clear) to S_1 .

Importantly, in order to support fast homomorphic summation of these encrypted results, we instructed S_2 – when encrypting the weights in binary representation – to use a small plaintext modulus of size D, where D > d is larger than the number of comparison results to be summed-up. Since D > d, then there is no overflow when computing Ord_1, \ldots, Ord_d , and so they are a permutation of $\{1, \ldots, d\}$ ranking the entries of \vec{w} by their size. The Boolean operations computed during the aforementioned homomorphic comparison are then emulated in \mathbb{Z}_D (defining, for $a, b \in \{0, 1\}$, $AND(a, b) = a \cdot b \mod D$ and $XOR(a, b) = (a - b)^2 \mod D$). This at most doubles the multiplicative depth of comparison, for the benefit of making the summation computation a linear function that requires no multiplications.

The above (simplified) description of the ranking protocol overlooked the following subtle point: in each iteration, the servers learn the ordering between the features in the current iteration's model. If *the same* permutation on features were to be used in all iterations, this knowledge from the execution of multiple iterations might reveal non-trivial information (similar to the issues which arise by performing scaled ridge on unpermuted features, see Section 7). To overcome this, we have S_1 apply a *fresh* permutation on the Ord_i's before sending them to S_2 . The permutation is inverted at the end of this step, and does not affect the rest of the computation. Privacy is preserved because each iteration uses a fresh permutation applied at the onset of the protocol). See Section 8 for details.

2.4 Security Challenges and Attacks

The iterative training of intermediate models is inherent to wrapper methods (and does not occur in filter or embedded methods), and introduces several security challenges. Indeed, we show that revealing any of the following (which are revealed in standard IR) would violate privacy (see details in Section 7):

- The order by which features are removed.
- The intermediate models.
- The scaling factor det(*A*) in a scaled ridge model.

This demonstrates the necessity of the security measures implemented in SIR. Hiding this information while maintaining efficiency is a key challenge in designing SIR.

2.5 Discussion: Model Inversion Attacks

Our protocol (SIR) guarantees that only the output model (and whatever can be efficiently inferred from it) is revealed. This is the standard security goal in secure computation; however, it leaves open the question of how much information is revealed by the output model, and how to reveal even less.

Prior works [24, 25, 70] have shown that learning the model may indeed reveal non-trivial information on private inputs of honest parties. Most relevantly, [25] showed, in the context of genomic data for personalized medicine using a *(non-sparse)* linear regression model, that access to the trained model can be abused to infer private genomic attributes about individuals in the training dataset. Moreover, [25] showed that differential privacy is not effective for guaranteeing privacy because it is at odds with utility: when setting the privacy parameters sufficiently high to prevent their attack, the produced model does not retain sufficient clinical efficacy.

SIR is likewise susceptible to model inversion attacks. This is because sparsity of the model in itself does not guarantee security against inversion attacks, since even a single bit of information can compromise privacy. For example, in the context of geneexpression data, certain genetic variants are more common in some ethnicities than in others, and so revealing whether a feature corresponding to such a genetic variant is selected in the model may reveal the ethnicity of the population represented in the training dataset. Concretely, we present a model inversion attack showing that corrupt data owners who inject maliciously crafted inputs (but otherwise follow the protocol) can infer from the output model non-trivial information on the inputs of the honest data owners. The attack holds even when the output is a 1-sparse model, i.e., it consists of one selected feature. At a high-level, corrupted data owners use "balanced" inputs, in which all features have the same correlation with the response vector. Thus, inputs provided by corrupted parties do not affect the output model, and any correlations in the inputs of the honest parties will determine which features are selected in the sparse output model. The formal details are provided in Section 7.

To reduce the privacy risk associated with revealing the model, our solution SIR offers a fine grained control on how, and to whom, the model is revealed. This can be obtained by applying the following minor changes in Phase IV: "Obliviously un-permute and rationally reconstruct" step(cf. Section 2.1 and Figure 8 Step 3).

Alternative 1: Revealing the output model in cleartext to all participants of the protocol (but nothing more). This is the outcome when executing the protocol as specified in Section 2.1.

Alternative 2: Revealing the model only to one designated party, denoted *O*, who may be an external party participating only in

Phase IV, as follows. S_1 sends the (encrypted and un-permuted) model to O (instead of S_2); O homomorphically masks the model with a random additive mask (using Add from Table 1), and sends the encrypted masked model to S_2 who decrypts and returns the (cleartext) masked model to O; finally, O removes the masking and computes rational reconstruction to obtain the output model. This is motivated by scenarios where S_1, S_2 are powerful servers to which computation is outsourced (say, Amazon AWS and Google Cloud) and where O is some health organization authorized to receive the computed model (say, the World Health Organization).

Alternative 3: Outputting the model only in encrypted form. In this case S_1 simply publishes the encrypted model, instead of sending it to S_2 for decryption (i.e., remove Step 3 in Figure 8). The model in this case is specified by a vector of d ciphertexts whose plaintext values are in \mathbb{Z}_N and where at most *s* of them are non-zero (in order to hide both the indices of the selected features and their weight). Outputting an encrypted model is motivated by scenarios where the encrypted model is employed for privacy preserving inference using homomorphic computation, as follows. Given the encrypted model and a (possibly, encrypted) sample⁹ homomorphically compute the inner product of the model and sample, homomorphically mask the resulting value in \mathbb{Z}_N (using additive mask), and send the ciphertext to S_2 for decryption; then unmask the returned plaintext and apply rational reconstruction to obtain the inference result as a rational number. See Remark 8.9 for further details. We note that in order to reduce the efficacy of model inversion attacks it is advised to enforce a security policy restricting the entities authorize to make inference queries, and limiting their number of allowed queries. Analyzing such security measures is beyond the scope of this work.

2.6 Comparison to Prior Techniques

The two-server approach for privacy-preserving ridge regression dates back to the work of Nikolenko et al. [50], who were also the first to propose using additive homomorphic encryption for merging the data from all data owners. We follow them in our Setup & Upload phase. Solving the linear system (A, b)was done in [50] using garbled circuits to guarantee security. Giacomelli et al. [29] proposed instead to solve a masked linear system $(A^{\text{masked}}, \vec{b}^{\text{masked}})$, where S_1 masks the systems using homomorphic addition, S_2 decrypts, solves, and sends the solution (the model) –in cleartext– to S_1 , who unmasks and applies rational reconstruction in the clear. Importantly, in [29] the model is sent in the clear, and both the unmasking and the rational reconstruction are done in the clear. However, this is impossible in our setting: we cannot expose the intermediate models in the clear, because this compromises privacy as we show in our attacks. Moreover, we cannot simply have S_2 send the model in encrypted form and have S_1 process it homomorphically, because the rational reconstruction step requires many sequential steps, making it computationally expensive to compute homomorphically.

Blom et al. [10] proposed avoiding rational reconstruction by having S_2 send $adj(A^{masked}) \cdot \vec{b}^{masked}$ and $det(A^{masked})$ (in the clear), where S_1 unmasks to obtain $adj(A) \cdot \vec{b}$ and det(A) and

then computes the model $A^{-1}\vec{b} = \operatorname{adj}(A)\vec{b}/\operatorname{det}(A)$ with *division* over the reals. However, we cannot follow their approach, because we cannot send these values in the clear (as this would violate privacy, as we show in our attacks). Moreover, we cannot send the values in encrypted form, and have S_1 homomorphically compute the division, because computing division homomorphically (be it modulo N or over the reals) is computationally expensive and thus not a viable alternative. In fact, even in the final iteration where the model can be revealed, our attacks demonstrate that it still violates privacy to reveal the pair $(\operatorname{adj}(A)\vec{b}, \operatorname{det}(A))$ rather than only their ratio $\operatorname{adj}(A)\vec{b}/\operatorname{det}(A)$. We therefore cannot employ the approach of [10]. Nonetheless, their approach inspired us in proposing our scaled ridge regression protocol.

Our proposed scaled ridge regression offers a new formulation, which eliminates the need for both rational reconstruction and division. In our protocol, S_2 sends -in *encrypted form*-the pair $adj(A^{masked}) \cdot \vec{b}^{masked}$ and $det(A^{masked})$, which S_1 homomorphically unmasks to obtain ciphertexts for the scaled model $w_{scaled} = adj(A) \cdot \vec{b}$. Next, S_1 homomorphically ranks the features of this scaled model, without computing any division or rational reconstruction. This is novel to our work, and may be of independent interest, with potential usage in other privacy preserving solutions using ridge regression as a component in a larger computation.

The overall structure of our protocol is likewise novel to our work, including its components of obliviously permuting and unpermuting the features (Phases II and IV in SIR) as well as the iterative execution of privacy-preserving regression for the ranking and removal (Phase III in SIR). We note that this overall structure necessitates using a *fully* homomorphic encryption (FHE), e.g., BGV [14] or B/FV [12, 22], to support both homomorphic addition and multiplication with respect to our plaintext modulus N (cf. only additive homomorphism in [10, 29]). However, as observed in [4], existing FHE libraries (e.g., HElib [38] and SEAL [55]) only support plaintext modulus of size up to 64-bit, whereas our protocol requires much larger integers (1260-bit integer in our implementation). To resolve this issue we follow [4] who suggested using the Chinese Remainder Theorem to represent each integer modulo N as a tuple of integers modulo small(ish) primes as supported by these libraries.

3 PRELIMINARIES

Notation. Upper-case letters (e.g., *M*) denote matrices, and vector notation (e.g., \vec{v}) denotes vectors. We use boldface letters to denote ciphertexts (e.g., \mathbf{M}, \vec{v} for a matrix and vector, respectively). We use Greek letters to denote masked values (see, e.g., Figure 6).

For a vector \vec{w} we denote the number of its non-zero entries by nnz (\vec{w}), and call it *s*-*sparse* if nnz(\vec{w}) \leq *s*. For a vector \vec{v} (similarly, set *S*), we use $|\vec{v}|$ (|S|) to denote its length (size). For a matrix *X*, we use X_i to denote its *i*'th row, and X^T to denote its transpose. For a matrix *A*, we use adj (*A*), det (*A*) to denote the adjugate matrix and determinant of *A*, respectively. We note that for any pair *A*, *B* of matrices it holds that adj ($A \cdot B$) = adj (B)·adj (A), and det ($A \cdot B$) = det (A) · det (B). For natural $d, N \in \mathbb{N}$, we use GL (d, \mathbb{Z}_N) to denote the group of all invertible $d \times d$ matrices with entries in \mathbb{Z}_N .

For a real value x, we use abs(x) to denote its absolute value, and $\lfloor x \rfloor$ to denote its nearest integer. We extend the notation to

 $^{^9}$ The sample is a length d vector specifying the sample's value for each features. Note that we require specifying all d features, rather than only the selected s features, because in this scenario we do not reveal which features are selected to the model.

apply to vectors and matrices entry-by-entry. We say that $x \in \mathbb{R}$ has *precision* ℓ if x is given as a real number with ℓ digits after the decimal point (which could be 0). If x has precision ℓ , then by *scaling* x *to lie in* \mathbb{Z} we mean multiplying x by 10^{ℓ} .

For $N \in \mathbb{N}$, [N] denotes the set $\{1, 2, ..., N\}$, and \mathbb{Z}_N denotes the ring of integers modulo N. In our protocols, elements of \mathbb{Z}_N are represented using the integers 0, 1, ..., N - 1 (this is without loss of generality). We treat values in \mathbb{Z}_N that are greater or equal to N/2 as negative. In particular, this allows us to define the "size" – alternatively, the "absolute value" – of a group element as its distance from the nearest multiple of N. For example, 1 is considered to be smaller than $N - 2 \equiv -2 \mod N$.

For random variables R, R', R \approx R' denotes that R, R' are computationally indistinguishable. negl (κ) denotes a function which is negligible in κ , and PPT is shorthand for Probabilistic Polynomial Time. We use the standard notion of computational indistinguishability (e.g., from [32]).

3.1 Sparse Linear Regression & Applications

Linear regression is an important and widely-used statistical tool for modeling the relationship between properties of data instances $\vec{x}_i \in \mathbb{R}^d$ (features) and an outcome $y_i \in \mathbb{R}$ (response) using a linear function $\hat{y}_i = \vec{x}_i \vec{w}$ (the feature vectors are augmented with an additional first entry set to 1, as is standard). Training a regression model, takes *n* data instances $(\vec{x}_i, y_i) \in \mathbb{R}^{d+1}$ and returns a model $\vec{w} \in \mathbb{R}^{d+1}$ that minimizes a loss function, e.g., the Mean-Square-Error (MSE):

$$\vec{w} = \underset{\vec{u} \in \mathbb{R}^{d+1}}{\operatorname{argmin}} \|\vec{y} - X\vec{u}\|_2^2 \tag{1}$$

where the rows of the matrix X are the n (augmented) vectors $\vec{x_i} \in \mathbb{R}^{d+1}$.

As we will discuss below, regularizing the solution \vec{w} to Equation 1 is often beneficial, leading to LASSO regression [9, 61] and ridge regression, both are special cases of controlling the norm of \vec{w} . Ridge regression [4, 29, 41] seeks to find

$$\vec{w} = \underset{\vec{u} \in \mathbb{R}^{d+1}}{\operatorname{argmin}} \left(\|\vec{y} - X\vec{u}\|_2^2 + \lambda \|\vec{u}\|_2^2 \right)$$
(2)

where notation is as above and $\lambda \ge 0$ is the regularization (hyper)-parameter. Lasso seeks to find: $\vec{w} = \operatorname{argmin}_{\vec{u} \in \mathbb{R}^{d+1}} \left(\|\vec{y} - X\vec{u}\|_2^2 + \lambda \|\vec{u}\|_1 \right).$

In certain cases it is desired (or even required) that the output model \vec{w} be sparse. That is, we are seeking a model \vec{w} with many zero coefficients. Even stronger –due to hardware limitations, for example– we would be seeking a model with a fixed number of features. The latter is called L_0 sparsity, and leads to the following optimization task:

$$\vec{w} = \underset{\vec{u} \in \mathbb{R}^{d+1}, \text{nnz}(\vec{u}) \le s}{\operatorname{argmin}} \left(\|\vec{y} - X\vec{u}\|_2^2 + \lambda \|\vec{u}\|_2^2 \right)$$
(3)

where $nnz(\vec{u})$ denotes the number of non-zero entries in \vec{u} , and $s \in \mathbb{N}$ is the sparsity (hyper)-parameter. This task is the one addressed in this work, and is referred to as *sparse linear regression*.

In typical datasets, learning sparse linear models is useful due to two main reasons. First, simpler models are preferred during

the training stage to avoid overfitting [9, 56]. Lower complexity translates to lower degree of polynomial models and/or less features in the output model. The latter can be reduced to model sparsity. The second reason to prefer sparser models is due to practical considerations. In some cases, hardware limitations restrict the number of features which can be measured when using the prediction model in the execution phase - when used to predict values, y, for new instances. In other cases, using more features in the execution prediction model is more expensive. For example, if *y* represents tumor severity, it might be reasonable to assume that y can be expressed as a linear (or polynomial) combination of molecular genomic information, say gene expression levels, in X. However, we expect, from a biological perspective, most genes to minimally affect the prediction performance. That is, the biology will be driven by a small number of genes.¹⁰ Therefore, most components of \vec{w} can be zero so that an assay used in clinical practice, based on such a predictive model, can use less expensive hardware, quantifying the expression levels of fewer genes [7, 21, 26, 51, 67].

3.2 Feature Selection and Iterated Ridge

Feature selection is an essential component in computational modelling and in the practical application of models. It has therefore been an active and prolific field of research in various domains such as pattern recognition, machine learning, statistics and data mining [47, 48]. Clever selection of the set of features to be used for data modelling, and as part of the execution models derived from learning, has been shown to improve the performance of supervised and unsupervised learning. Reasons are discussed above, as well as in the literature [7, 21, 37, 52]

Feature selection methods can be classified into several types based on the employed techniques, as discussed in Section 1. In this work we focus on a variant of Recursive Feature Elimination [37], a wrapper approach. A detailed description of the approach, in the clear, follows. Our approach is an iterative one that starts with all features, and iteratively removes features. This is similar to [26], that developed a sparse logistic regression model using RFE. In each iteration we run ridge regression with $\lambda \ge 0$ [4, 56] to calculate the weights for all features considered. Then, we remove features with low weights (in absolute value). The algorithm operates in two phases. In the first phase, we remove a 0.1-fraction of features, whereas when the current number of features decreases below a (user-defined) threshold thr, we move to the second phase, in which we remove a single feature in each iteration (this latter phase is analogous to Backward Subset Selection). The choice of the actual value of thr and the choice of the fraction removed in the early stages can affect the computational complexity of the process. Moreover, they are hyper-parameters of the model and can be tuned by cross validation. The pseudo-code of this algorithm is given in Figure 1.

3.3 FHE

Fully-Homomorphic Encryption (FHE) is a public-key encryption scheme $\mathcal{E} = (KG, Enc, Dec, Eval)$ that allows one to compute "under

 $^{^{10}\}mathrm{The}$ human genome codes for roughly 30K genes and many more functional elements.

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Input: A dataset $D \in \mathbb{R}^{n \times d}$ and a target vector $\vec{y} \in \mathbb{R}^n$ (where entries are normalized to the same scale), and parameters *s*, rej \in (0, 1), thr \in [*d*]. **Output:** A set Ω_s of the $s \leq d$ selected features, and a ridge regression model \vec{w}_s on these features. **Steps:**

(1) Initialize Ω to be the set of all features, and $\vec{w} = \vec{1}$. (2) While $\operatorname{nnz}(\vec{w}) > \operatorname{thr:}$ (a) $\vec{w} = LR(D, y, \Omega)$ (b) $\pi = \operatorname{argsort}(\operatorname{abs}(\vec{w}))$ (c) $\operatorname{prefix}(\pi) = \pi[0: \operatorname{rej} \cdot |\Omega|]$ (d) $\Omega = \Omega \setminus \operatorname{prefix}(\pi)$ (3) While $\operatorname{nnz}(\vec{w}) > s$: (a) $\vec{w} = LR(D, y, \Omega)$ (b) smallest = $\operatorname{argmin}(\operatorname{abs}(\vec{w}))$ (c) $\Omega = \Omega \setminus \{\operatorname{smallest}\}$ (4) Let $\Omega_{S} = \Omega$ and $\vec{w}_{S} = LR(D, y, \Omega_{S})$. Return $(\Omega_{S}, \vec{w}_{S})$.

Figure 1: Iterated Ridge (IR). Notations: $LR(D, y, \Omega)$ denotes the solution of the linear regression system given by (D, y)when using only features in Ω ; $nnz(\vec{w})$ denotes the number of non-zero elements in \vec{w} ; the function argsort sorts the indices of an array according to the values it contains; $abs(\vec{w})$ returns the absolute value of each entry of \vec{w} . The regularization parameter λ is implicit in this pseudo-code.

the hood" of the encryption (without the secret decryption key). We use the scheme as a black-box, and only make the assumption that during key generation, one can choose the *plaintext space* by specifying an $N \in \mathbb{N}$, so that homomorphic operations are performed modulo N. (We note that this is the case in many FHE candidates, e.g. [13].) This assumption is captured by incorporating the plaintext modulus N explicitly into the syntax of the scheme. We now formally define FHEs. The algorithms are required to satisfy the following three properties: (1) standard decryption correctness. (2) FHE correctness, in the sense that the ciphertext obtained by evaluating a circuit C (using Eval) on a set of ciphertexts decrypts to the value that would have been obtained by evaluating C directly on the underlying messages. (3) Computational indistinguishability, namely for every κ , N, and every msg $\in \mathbb{Z}_N$, the joint distribution of pk (i.e., a public key randomly generated by KG) and c \leftarrow Enc (pk, msg) is computationally indistinguishable from the joint distribution of pk and $c_0 \leftarrow Enc(pk, 0)$. This is formalized in the following definition.

Definition 3.1 (FHE). A *Fully-Homomorphic Encryption (FHE)* scheme $\mathcal{E} = (KG, Enc, Dec, Eval)$ consists of four algorithms where KG, Enc and Eval are PPT algorithms, and Dec is (deterministic) polynomial time. The algorithms have the following syntax:

- KG (1^κ, N) takes as input a security parameter κ, and an N ∈ N. It outputs a pair of public and secret keys (pk, sk). We assume without loss of generality that pk includes N in its description.
- Enc (pk, msg) takes as input a public key pk, and a message msg ∈ Z_N, and outputs a ciphertext c.
- Dec (sk, c) takes as input a secret decryption key sk, and a ciphertext c, and outputs a plaintext message msg'.

Eval (pk, C, c₁,..., c_k) takes as input a public key pk, a circuit C: Z^k_N → Z^l_N for some l, k ∈ N, and k ciphertexts c₁,..., c_k, and outputs l ciphertexts (c₁',..., c_l').

The scheme is required to satisfy the following semantic properties.

• **Correctness.** For every natural *N*, every security parameter κ , and every message msg $\in \mathbb{Z}_N$:

$$\Pr \begin{bmatrix} (pk, sk) & \leftarrow \text{KG}(1^{\kappa}, N) \\ msg = msg': & c & \leftarrow \text{Enc}(pk, msg) \\ msg' & = \text{Dec}(sk, c) \end{bmatrix}$$

is at least 1 – negl (κ), where the probability is over the randomness of KG and Enc.

• FHE Correctness. For every natural N, every security parameter κ , every $k, l \in \mathbb{N}$, every arithmetic circuit C : $\mathbb{Z}_{N}^{k} \to \mathbb{Z}_{N}^{l}$, and every $msg_{1}, \ldots, msg_{k} \in \mathbb{Z}_{N}$:

$$\Pr\begin{bmatrix} (pk, sk) & \leftarrow KG(1^{\kappa}, N) \\ msg = msg': & c_i & \leftarrow Enc(pk, msg_i), \forall i \in [k] \\ c & \leftarrow Eval(pk, C, (c_1, \dots, c_k)) \\ msg & = Dec(sk, c) \end{bmatrix}$$

is at least $1 - \text{negl}(\kappa)$, where $\text{msg}' = C(\text{msg}_1, \dots, \text{msg}_l)$, and the probability is over the randomness of KG, Enc and Eval.

- Computational security (non-uniform distinguishers). For every κ , all public parameters params, and every msg $\in Q$, the following distributions are computationally indistinguishable by non-uniform distinguishers:
 - Sample $(pk, sk) \leftarrow KG(1^{\kappa}, params)$, and $c \leftarrow Enc(pk, msg)$.¹¹ Output (pk, c).
 - Sample $(pk, sk) \leftarrow KG(1^k, params)$, and $c \leftarrow Enc(pk, 0)$. Output (pk, c).

Remark 3.2. Though we define FHE schemes as encrypting a single ring element, we also consider FHE schemes encrypting vectors or matrices of ring elements, namely Enc might take as input a vector or matrix of ring elements, and Dec might take as input a vector or matrix of ciphertexts (each encrypting a field element). See Section 10 for further details.

4 PROBLEM STATEMENT

We follow the security and threat model of [4], and parts of this section are taken almost verbatim from [4]. SIR guarantees computational security, in the passive setting, against a single server colluding with a proper subset of the data owners. More specifically, we assume all parties, even corrupted ones, are PPT and follow the protocol (though corrupted parties will try to infer additional information). We guarantee correctness of the output, and privacy of the inputs, in this setting. Specifically, the only information revealed to the corrupted parties is the *leakage profile*, namely the information that is *explicitly* revealed by the protocol. In our protocols, the leakage profile consists of the output model \vec{w} , as well as the following public parameters: the number *n* of data instances; the number *d* of features; the precision ℓ ; a sparsity parameter *s*; and a regularization parameter $\lambda \ge 0$. More formally,

¹¹See Remark 3.2 below about simultaneously encrypting multiple field elements.

we consider *k*-privacy in the passive setting, for inputs *X* such that $A = X^T X + \lambda I$ is invertible in the ring \mathbb{Z}_N (invertability is needed for IR correctness; and in our case – as in previous works [4, 29] – also for privacy). We note that the input is horizontally-partitioned between the data owners (i.e., data owners hold disjoint subsets of rows of (X, \vec{y})).

Terminology. Let Π be an (m + 2)-party protocol executed between PPT data owners DO_1, \ldots, DO_m and PPT servers S_1, S_2 . We assume that every pair of parties share a secure point-to-point channel, and that all parties share a broadcast channel. We also restrict attention to protocols in which all parties obtain the same output, and only the data owners have inputs. For inputs x_1, \ldots, x_m of DO_1, \ldots, DO_m , we use $\Pi(x_1, \ldots, x_m)$ to denote the random variable describing the output in a random execution of Π (the probability is over the randomness of all participating parties, including the servers). For $I \subset \{DO_1, \dots, DO_m, S_1, S_2\}$, the (joint) view of *I* in Π , denoted $V_I^{\Pi}(x_1, \ldots, x_m)$, is the random variable consisting of the inputs and randomness of all parties in I, as well as the messages they received from the honest parties in a random execution of Π with inputs x_1, \ldots, x_m . We say a subset $I \subseteq \{DO_1, \dots, DO_m, S_1, S_2\}$ is *k*-permissible if it contains at most *k* data owners, and at most one of the servers.

Security notion. We consider standard computational security against a passive adversary (see, e.g., [32]), adapted to the setting of non-colluding servers as in [50]. Since optimal feature selection under L_0 (Equation 3) is NP hard in general [15], we focus on providing a secure variant of the Iterated Ridge heuristic approach (see Section 3.1). Specifically, we require correctness in the sense that the secure variant has the same output as the cleartext iterated ridge algorithm, and privacy in the sense that any k-permissible set I learns nothing except the leakage profile (which consists of the public parameters and the output model) and the inputs of the parties in I (and anything efficiently computable therefrom). We also offer the option of returning an encrypted model (cf. Section 2.5), in which case the output model is excluded from the leakage profile and the adversary learns nothing beyond the public parameters and the input of the parties in I (and anything efficiently computed therefrom). Following [29] we define correctness with respect to a subset \mathcal{T} of inputs (where there is no correctness guarantee for inputs not in \mathcal{T}). Formally,

Definition 4.1 (Secure Iterated Ridge Implementation). Let $m, k \in \mathbb{N}$, let κ be a security parameter, let \mathcal{D}, \mathcal{R} be an arbitrary domain and range, let $f : \mathcal{D}^m \to \mathcal{R}$ be an iterated ridge algorithm (e.g., the algorithm of Figure 1), and let $\mathcal{T} \subseteq \mathcal{D}^m$. We say that an (m + 2)-party protocol Π is a *secure iterated ridge implementation* of f with k-privacy for inputs in \mathcal{T} with leakage profile \mathcal{L} if:

(1) **Correctness:** there exists a negligible function negl (κ) : $\mathbb{N} \to \mathbb{N}$ such that for all inputs $(x_1, \ldots, x_m) \in \mathcal{T}$,

$$\Pr[\Pi(x_1,...,x_m) = f(x_1,...,x_m)] = 1 - \operatorname{negl}(\kappa)$$

where the probability is over the randomness of the parties. (2) **Privacy:** for every k-permissible I there exists a PPT

simulator Sim such that for every $(x_1, \ldots, x_m) \in \mathcal{T}$:

$$\mathsf{V}_{I}^{\Pi}(x_{1},\ldots,x_{m})\approx\mathsf{Sim}\left(\left(x_{j}\right)_{\mathsf{DO}_{j}\in I},\mathcal{L}\right)$$

5 SIR PROTOCOL

Our privacy preserving iterated ridge protocol SIR is specified in Figures 2-3 (with further details available in the figures in Section 6). See also an overview in Section 2; remarks on input encoding, parameter choice, and useful observations in Section 5.1; and notations for simple sub-circuits we use in the homomorphic evaluation in Table 1. Our security and complexity analysis of SIR is summarized below. Complexity is stated in term of *d* and *N* where $\log N = \widetilde{O}(d \log n)$ (by Equation 4).

THEOREM 5.1 (SIR ANALYSIS). Let $m, n, d \in \mathbb{N}, X \in \mathbb{R}^{n \times d}$ and $\vec{y} \in \mathbb{R}^{n \times 1}$ s.t. X has full rank and $d \leq n$. Then, the following holds when executing SIR on (X, \vec{y}) when horizontally partitioned amongst m data-owners:

Security. SIR (Figure 2) is a secure iterated ridge implementation of IR (Figure 1) with m-privacy.

Complexity. Let $\mathcal{E} = (\text{Gen}, \text{Enc}, \text{Dec}, \text{Eval})$ be the homomorphic encryption scheme with which SIR is instantiated, and \mathbb{Z}_N be the used plaintext ring, then:

- Each data owner runtime is dominated by the time to compute d² encryptions, and her communication complexity is dominated by transmitting d² ciphertexts (in one round).
- S₁ runtime is dominated by the time to rank features, which entails homomorphically evaluating O(log d) circuits, each with O(d² log N)= Õ(d³ log n) multiplication gates and of multiplicative depth O(log log N)= O(log d + log log n).¹²
- S₂ runtime complexity is dominated by the time to solve (in the clear) O(log d) linear systems of size d × d.
- The communication of the two servers consists of $O(\log d)$ communication rounds, transmitting $O(d^2 \log N) = \widetilde{O}(d^3 \log n)$ ciphertexts in each round.¹³

PROOF. The proof is provided in Sections 8 and 9. $\hfill \Box$

5.1 Input, Parameters and Observations

The notations and operations used in SIR are described in Table 1. Remarks clarifying some implementation details follow.

Remark 5.2 (Input representation and encoding.). We assume that the datasets entries are in the range [-1, 1], given with ℓ -digit precision. The inputs are scaled to be in \mathbb{Z}_N for a sufficiently large N (for the choice of N, see Remark 5.3). All subsequent computations in the protocol are performed in \mathbb{Z}_N or in \mathbb{Z}_D for some $D \ge d$. Note that D is much smaller than N. All inputs (and intermediate values generated during the computation) are encoded as in [4]. (We refer the interested reader to [4] for a detailed description of the encoding and its efficiency benefits.)

Remark 5.3 (On the choice of *N*). The plaintext ring \mathbb{Z}_N should be sufficiently large to guarantee that all computations during the (scaled) ridge regression step emulate the corresponding computations over the reals (i.e., no overflows occur), as well as

 $^{^{12}\}mathrm{We}$ ignore addition gates, since additive homomorphism is much faster than multiplicative homomorphism in practice. We note that the masking step includes matrix multiplication, which has complexity cubic in *d*, but since it entails only additive homomorphism it is not accounted for in the complexity analysis.

¹³When using a homomorphic encryption that supports packing sl plaintext values in each ciphertext with support for single instruction multiple data (SIMD) computation, the time and communication complexity of the servers can be divided by sl.

to allow for rational reconstruction to be performed on the output model at the end of the protocol. This can be guaranteed by using the same plaintext ring $\mathbb{Z}_{N_{\text{Gia}}}$ as [29]. However, for our selection protocol (Figure 9) we will need the modulo *N* to be at least square that value, namely:

$$N = N_{\text{Gia}}^2 > \left(2d(d-1)^{\frac{d-1}{2}} 10^{4\ell d} (n^2 + \lambda)^{2d}\right)^2 \quad (4)$$

where *n*, *d*, ℓ , λ are as specified in Section 4.

Remark 5.4 (On the choice of the plaintext modulus D in SIR.). For efficiency reasons, we would like to avoid (when possible) performing computations in the ring \mathbb{Z}_N , since such computations would be heavy due to the size of N (as described above). Instead, in SIR we are able to use a smaller modulus D for some computations. We can make due with any $D \ge d$ which can be used as a plaintext modulus in the underlying FHE scheme.

Remark 5.5 (Dimension reduction and projection). Our protocol iteratively reduces the set F of current features (i.e., ones that will be part of the output model), which is done in two steps as follows. (1) reset the entries of A, \vec{b} that correspond to entries in $[d] \setminus F$, by setting to zero the rows and columns of A (the entries of b, respectively) that are indexed by $i \notin F$, resulting in a matrix A' and a vector $\vec{b'}$. (2) projecting $A', \vec{b'}$ to F by erasing the rows and columns of A' (entries of \vec{b} , respectively) indexed by $i \notin F$. We denote this operation by $pjct_F(\cdot)$ (this operation can be applied to a matrix or a vector), namely we compute $\text{pjct}_F(A')$, $\text{pjct}_F(\vec{b'})$. Step (1) is obtained by multiplying with a nullifier matrix N_F which is defined as follows: $N_F \in \mathbb{Z}_N^{d \times d}$ is obtained from the $d \times d$ identity matrix by resetting the diagonal entries in all rows indexed by $i \notin F$ (we omit d from the notation, since it is clear from the context). More specifically, we set $A' = N_F \cdot A \cdot N_F$ and $\vec{b}' = N_F \cdot \vec{b}$. Notice that for any matrix X, multiplying by N_F from the left (right, respectively) rests the rows (columns, respectively) indexed by $i \notin F$, and similarly when multiplying a vector \vec{v} by \mathcal{N}_F from the left. Another operation which will be used in our protocols is an *expansion* from dimension F to dimension [d]. Specifically, we define $expd_F(\cdot)$ such that on input an $|F| \times |F|$ matrix X (a length-|F| vector \vec{v} , respectively) returns the $d \times d$ matrix X' (length-d vector \vec{v}' , respectively) such that for every $i \notin F$ the *i*th row and column in X' (*i*th entry in \vec{v} ', respectively) is 0, and additionally $X = \operatorname{pjct}_{F}(X'), \vec{v} = \operatorname{pjct}_{F}(\vec{v}').$

Remark 5.6 (Unique Entries in Intermediate Models). Our security analysis will rely on the assumption that for every intermediate model \vec{z}_F computed in Step 3a of the SIR protocol (Figure 2), all entries are unique (i.e., if $i \neq j$ then $\vec{z}_{F,i} \neq \vec{z}_{F,j}$). This can be easily achieved as follows. First, when scaling the inputs in the setup phase (Figure 4), we incorporate log *d* additional "empty" leastsignificant bits. That is, instead of scaling an ℓ -precision real number by multiplying it by 10^{ℓ} , we multiply it by $10^{\ell+\log d}$. Then, at the end of each scaled ridge regression iteration (Figure 3) we replace the log *d* least-significant bits of $\vec{z}_{F,i}$ with the binary representation of *i* (this can be done because at this point the ciphertext is encrypted entry-by-entry). **Remark 5.7** (Emulating Boolean circuits using arithmetic circuits). Our protocols embed binary values into a larger ring \mathbb{Z}_D , and operate over these representations. Therefore, we need to emulate the Boolean circuits BinCompareL_{c'} and BinCompareR_{c'} using arithmetic circuits over \mathbb{Z}_D . This is done as follows. $a \wedge b$ is implemented by multiplying $a \cdot b$ in \mathbb{Z}_D . $a \oplus b$ is implementing by computing $(a - b)^2$ in \mathbb{Z}_D . This perfectly emulates AND and XOR whenever $a, b \in \mathbb{Z}_D \cap \{0, 1\}$. The Neg circuit on input c is emulated by computing 1 - c (where 1 is the identity of \mathbb{Z}_D). This perfectly emulates the Neg circuit when $c \in \{0, 1\}$.

6 SIR PROTOCOL: FULL DESCRIPTION

In this section we provide the full description of all sub-protocols used as part of SIR.

Public parameters: \mathcal{E} , n, d, N, D as in Figure 2. **Input:** the parties have no private inputs. **Output:** encryption keys (pk_N, sk_N) and (pk_D, sk_D) for \mathcal{S}_2 , and public keys pk_N, pk_D for all other parties. The output of \mathcal{S}_1 additionally includes encryptions $\mathbf{P}_2, \mathbf{P}_2^T$ of P_2, P_2^T (respectively) for a random permutation matrix $P_2 \in \mathbb{Z}_N^{A \times d}$.

Steps: S_2 performs the following:

- (1) Generates encryption keys $(pk_N, sk_N) \leftarrow KeyGen(1^{\kappa}, N)$ and $(pk_D, sk_D) \leftarrow KeyGen(1^{\kappa}, D)$.
- (2) Picks a random permutation matrix $P_2 \in \mathbb{Z}_N^{d \times d}$, and encrypts $\mathbf{P}_2 \leftarrow \operatorname{Enc}(\operatorname{pk}_N, P_2)$, and $\mathbf{P}_2^T \leftarrow \operatorname{Enc}(\operatorname{pk}_N, P_2^T)$.
- (3) Sends \mathbf{P}_2 and \mathbf{P}_2^T to \mathcal{S}_1 , and publishes pk_N , pk_D .

Figure 4: Setup

Public parameters: \mathcal{E} , κ n, d, N, ℓ , n_1, \ldots, n_m , and m as in Figure 2. **Input from previous phase:** all parties take as input the public encryption key pk_N . **Input:** for every $j \in [m]$, the input of data owner DO_j consists of a matrix $X^j \in \mathbb{R}^{n_j \times d}$, and a vector $\vec{y}^j \in \mathbb{R}^{n_j}$, given with precision ℓ . **Output for the next phase:** the output of S_1 are encryptions \mathbf{A} , $\vec{\mathbf{b}}$ under key pk_N of a matrix $A = P_2^T P_1^T \cdot (X^T \cdot X + \lambda I) \cdot P_1 P_2 \in \mathbb{Z}_N^{d \times d}$ and a vector $\vec{b} = P_2^T P_1^T \cdot X^T \cdot \vec{y} \in \mathbb{Z}_N^d$, respectively, where P_1 is a random permutation matrix. The other parties have no output. **Steps:** for every $1 \le j \le m$, DO_j does the following:

- (1) **Data Representation:** Scales its inputs X^j , \vec{y}^j to have entries in \mathbb{Z} , and then embeds them in \mathbb{Z}_N . Then, DO_j computes $A^j = (X^j)^T \cdot X^j$, and $\vec{b}^j = (X^j)^T \cdot \vec{u}^j$.
- $A^{j} = (X^{j})^{T} \cdot X^{j}, \text{ and } \vec{b}^{j} = (X^{j})^{T} \cdot \vec{y}^{j}.$ (2) **Data Encryption:** Encrypts $A^{j} \leftarrow \text{Enc}(\text{pk}_{N}, A^{j})$ and $\vec{b}^{j} \leftarrow \text{Enc}(\text{pk}_{N}, b^{j}),$ and sends A^{j}, \vec{b}^{j} to S_{1} .
- (3) Data Merging and Permuting: S₁ executes the data merging and permuting algorithm of Figure 6, to obtain A, **b**.

Figure 5: Data Uploading

7 ON THE NECESSITY OF HIDING PARTIAL INFORMATION

In this section we explain the cryptographic design choices made in our protocols. Specifically, we explain why certain operations

Operation Type	Circuit Name	Inputs	Constants	output
Scaled matrix addition	Add_{λ}	matrices A_1, \ldots, A_m	$\lambda > 0$	$\sum_{i \in [m]} A_i + \lambda I$
Matrix multiplication	MatMult	matrices A_1, A_2	_	$A_1 \cdot A_2$
Matrix by vector multiplication	MatVecMult	matrix A_1 and vector \vec{v}	_	$A_1 \cdot \vec{v}$
Matrix right multiplication (w. plaintext <i>R</i>)	MatMultR _R	$d \times d$ -size matrix M	$d \times d$ -size matrix R	$M \cdot R$
Matrix left multiplication (w. plaintext L)	$MatMultL_L$	$d \times d$ -size matrix M	$d \times d$ -size matrix L	$L \cdot M$
Addition with plaintext matrix	$MatAdd_R$	$d \times d$ -size matrix M	$d \times d$ -size matrix R	M + R
Multiplication with plaintext vector	$VecMatMultR_{\vec{r}}$	$d \times d$ -size matrix M	length- d vector \vec{r}	$M \cdot \vec{r}$
Vector addition	Add	vectors $\vec{v}_1, \ldots, \vec{v}_m$	_	$\sum_{i \in [m]} \vec{v}_i$
Vector subtraction	Sub	vectors \vec{v}_1, \vec{v}_2	_	$\vec{v}_1 - \vec{v}_2$
Vector multiplication w. plaintext matrix	$MatVecMultL_R$	length- d vector \vec{v}	$d \times d$ matrix R	$R\cdot ec v$
Vector addition w. plaintext vector	VecAdd _r	vector \vec{v}	vector \vec{r}	$\vec{v} + \vec{r}$
Vector multiplication w. plaintext scalar	ScalerVecMult _c	vector \vec{v}	scalar c	$c\cdot ec v$
Vector multiplication w. secret scalars	ScalerVecMult 3 8 1	vector \vec{v} and scalars c_1, \ldots, c_k	—	$c_1 \cdot \ldots \cdot c_k \cdot \vec{v}$
Vector addition	VecBinAdd _r	vector $\vec{v} \in \{0, 1\}^k$	vector $\vec{r} \in \{0, 1\}^k$	$\vec{r} + \vec{v}$ (computed
(binary representation)				using 2's complement)
Vector subtraction	VecBinSub _r	vector $\vec{v} \in \{0, 1\}^k$	vector $\vec{r} \in \{0, 1\}^k$	$\vec{r} - \vec{v}$ (computed
(binary representation)				using 2's complement)
Scalar multiplication w. plaintext vector	VecScalerMult $_{\vec{v}}$	scalar c'	vector \vec{v}	$c'\cdot \vec{v}$
Scalar squaring	Square	scalar c'	_	$(c')^2$
Scalar addition	AddNums	scalars c', c''	_	c' + c''
Scalar subtraction	SubNums	scalars c', c''	_	c' - c''
Scalar multiplication	MultNums	scalars c', c''	_	$c' \cdot c''$
Scalar addition w. plaintext scalar	AddConst _c	scalar c'	scalar c	c + c'
Scalar smaller than	BinCompareR _c	$ec{c}'\in\{0,1\}^*$	scalar c	1 if $c' \leq c$, otherwise 0
Scalar greater than	$BinCompareL_c$	$ec{c}'\in\{0,1\}^*$	scalar c	1 if $c < c'$, otherwise 0
Scalar negation	Neg	scalar $c' \in \{0, 1\}$	_	c''s complement (i.e.,
				1 if $c = 0' + 0$ otherwise)

Table 1: Sub-circuits used for homomorphic computation in SIR. In the table, $k, d, m \in \mathbb{N}$; A_1, \ldots, A_m are matrices of the same dimensions over some ring $G; \vec{v}, \vec{v}_1, \ldots, \vec{v}_m$ are vectors of the same length over G; c', c'' are a pair of values from the same domain (e.g., from \mathbb{Z}_N), and \vec{c}', \vec{c}'' denote their binary representation. In the "vector multiplication with secret scalars" operation, $c_1 \cdot \ldots \cdot c_k$ multiplies each coordinate of \vec{v} . In the "vector addition/subtraction (binary representation)" operations, we allow VecBinAdd_{\vec{r}}, VecBinSub_{\vec{r}} to be executed on vectors in \mathbb{Z}_D^k for some $D \in \mathbb{N}$ (and emulating Boolean operations using operations in \mathbb{Z}_D , see Remark 5.7), but there is no guarantee on the output when the entries of \vec{v}, \vec{r} are not bits. The "scalar greater/smaller

than" operations are computed using standard Boolean circuits for comparing a pair of binary strings.

in our protocols are masked, or performed under the hood of the encryption (consequently increasing the round and/or communication complexity of the resultant protocol), by showing that performing these operations on cleartext (and unmasked) data would violate privacy. In the end of the section we also describe an attack showing that SIR is susceptible to inversion attacks.

We describe several "toy" attacks which illustrate the insecurities of performing the iterated ridge regression protocol (whose scaled version appears in Figure 3) on cleartext, unpermuted, or unmasked data. For the sake of clarity, we present *minimal, concrete* examples that capture the main ideas underlying the attacks. These toy examples help illustrate situations which arise in practice, when performing ridge regression on actual data (see discussion below).

An "attack" on the security of the scheme (i.e., violating Definition 4.1) consists of a pair of inputs for the data owners, for which the inputs and outputs of some permissible adversary (i.e., one which corrupts at most one server and a subset of the data owners) in the protocols are identical, but the adversary's views

of the protocol executions are different. In all attacks we consider the setting with 4 or 5 data records, with a single corrupt server (i.e., all data owners are honest). In this case, the adversary has no input, and its output is the (final) output model. Moreover, for simplicity of the examples, we set the regularization parameter to $\lambda = 0$, thus $A = X^T X$. Furthermore, we analyze the attack over \mathbb{R} (and not over \mathbb{Z}_N). Analyzing the attacks over \mathbb{R} suffices, because N is chosen such that the computation in \mathbb{Z}_N perfectly emulates the computation over \mathbb{R} (i.e., throughout the computation all values are scaled to be integers, and there are no overflows).

The necessity of permuting the data. Our protocols operate over permuted federated data (see Step 3 in Figure 6). As we show in Section 8, permuting the data hides the order in which features are discarded in the iterative learning process. This is necessary for privacy, since the order might reveal non-trivial information about the inputs, as we now show. Specifically, we will show a pair of **Public parameter:** an FHE scheme $\mathcal{E} = (KeyGen, Enc, Dec, Eval)$, a security parameter κ , a regularization parameter λ , dimensions $n \times d$ of the input matrix, a plaintext ring size N satisfying the requirements of Remark 5.3, the number of data owners m, positive input sizes $n_1, n_2, \ldots, n_m > 0$ such that $\sum_{j=1}^m n_j = n$, a sparsity parameter s < d, a precision parameter ℓ , a sparsity parameter rej which determines the fraction of features that are removed in each iteration, and a threshold parameter thr which determines when the protocol starts to remove a single feature in each iteration. Additionally, let $D \ge d$ (see Remark 5.4). **Inputs:** For every $j \in [m]$, the input of data owner DO_j consists of a data matrix $X^j \in \mathbb{R}^{n_j \times d}$ and a response vector $\vec{y}^j \in \mathbb{R}^{n_j}$. We denote by $(X | \vec{y})$ the combined input obtained from all X^j , \vec{u}^j . That is, [n] is partitioned into *m* subsets $I_1, \ldots, I_m \subseteq \{1, \ldots, n\}$, and X^j, \vec{y}^j is the restriction of $X,\,\vec{y}$ to the rows in $I_j.$ (Here, X and \vec{y} are scaled to lie in $\mathbb{Z},$ and then embedded in \mathbb{Z}_N for a sufficiently large N, see Remark 5.3.) The servers S_1, S_2 have no input.

Output: all parties obtain as output an *s*-sparse model $\vec{w} \in \mathbb{R}^d$. **Steps:**

- (1) Setup: The parties execute the setup protocol of Figure 4 to obtain keys (pk_N, sk_N) and (pk_D, sk_D). Then, the parties execute the data uploading, merging and permuting protocols of Figures 5-6, and S₁ obtains encryptions of the aggregated input matrix and response vector A, b.
- (2) Let F = [d] (i.e., initially *F* contains all features), and let $A_F = A$, $\vec{b}_F = \vec{b}$.
- (3) While |F| > s, do:
 - (a) **Ridge Regression Iteration:** S_1 and S_2 execute the scaled ridge protocol of Figure 3, where the input of S_1 consists of F, encryptions $\mathbf{A}_F, \mathbf{b}_F$ of A_F, \mathbf{b}_F , respectively, and the input of S_2 is F, sk_N . The output of S_1 is an entry-wise encryption \mathbf{z}_F of a vector $\mathbf{z}_F \in \mathbb{Z}_N^d$ under key pk_N .
 - (b) Selecting features:
 - Large-set case: If |F| > thr then set k' = ⌊rej · |F|⌋. (Intuitively, when |F| > thr the set of current features is still sufficiently large that we can remove a subset of features in each iteration.)
 - **Small-set case:** Otherwise (i.e., |*F*| ≤ thr), set *k*′ = 1. (In this case, the set of current features is small, so features should be removed one at a time.)
 - S_1 and S_2 execute the selection protocol of Figure 9 to find the smallest k' features. S_1 has input \vec{z}_F , S_2 has input sk_N , and both parties have input pk_N , pk_D , F, k'. The output of both servers is the set S_{del} consisting of the k' features to be removed.
 - (c) Compacting data for the next iteration: Let F* = F \ S_{del}. Then S₁ locally executes the compacting algorithm of Figure 7, with input F*, pk_N, A and b (encrypting A and b, respectively). The output of S₁ are updated (compacted) A_{F*}, b_{F*}.
 (d) set F = F*.
- (4) Output: Parties execute the computing and unpermuting output protocol of Figure 8 to obtain the s-sparse model w.

Figure 2: SIR: Secure Iterated Ridge

inputs for which the resultant model is identical, but the order in which columns are removed in the iterations is different.

The high-level idea of the attack is to begin with X, \vec{y} in which one column is not correlated with \vec{y} , the second is somewhat correlated with \vec{y} , and the third is highly correlated with \vec{y} , where we are looking for a 1-sparse solution. Thus, the first column will The protocol uses the circuits MatMultR_M, VecMatMultR_{\vec{r}}, MatVecMultL_M, Add, Sub, VecScalerMult_{\vec{r}} and ScalerVecMult_c of Section 5.1.

Public parameters: $\mathcal{E} = (\text{KeyGen, Enc, Dec, Eval}), d, N$, as in Figure 2. **Inputs from previous phases:** the public encryption key pk_N , the set $F \subseteq [d]$ of feature indices that "survived" to the current iteration, and encryptions $\mathbf{A}_F, \mathbf{b}_F$ of the matrix $A_F = \mathcal{N}_F \cdot A \cdot \mathcal{N}_F \in \mathbb{Z}_N^{d \times d}$ and vector $\vec{b}_F = \mathcal{N}_F \cdot \vec{b} \in \mathbb{Z}_N^d$ (see Remark 5.5 for the description of the nullifier matrix \mathcal{N}_F ; and recall that intuitively, A_F, \mathbf{b}_F are obtained from A, \vec{b} by resetting the rows, columns, and entries for $i \notin F$). S_2 additionally has as input the private decryption key sk_N .

Output: the output of S_1 is an encryption \vec{z} , under key pk_N , of $\vec{z} \in \mathbb{Z}_N^d$ such that $\vec{z} = \det(A'_F) \cdot \vec{w}_F$, where: (1) $A'_F = \text{pjct}_F(A_F)$ is the projection of A_F to the indices in F; (2) $A'_F \cdot \vec{w}'_F = \text{pjct}_F(\vec{b}_F)$, and additionally (3)

 $\vec{w}_F = \exp d_F \left(\vec{w}'_F \right)$. (See Remark 5.5 for a description of $\exp d_F (\cdot)$ and $\operatorname{pjct}_F (\cdot)$.) The other parties have no output.

Steps:

- (1) **Masks Generation:** S_1 picks a random invertible matrix $R' \leftarrow \operatorname{GL}(|F|, \mathbb{Z}_N)$, and a random vector $\vec{r}' \leftarrow \mathbb{Z}_N^d$. Then, S_1 computes $R = \operatorname{expd}_F(R')$, $\vec{r} = \mathcal{N}_F \cdot \vec{r}'$.
- (2) **Data masking:** S_1 masks the data by homomorphically computing $\Gamma_F = A_F \cdot R$ and $\vec{\beta}_F = \vec{b}_F + A_F \cdot \vec{r}$ as follows:
 - $\Gamma_F \leftarrow \text{Eval}(\text{pk}_N, \text{MatMultR}_R, \mathbf{A}_F).$ • $\mathbf{\vec{t}} \leftarrow \text{Eval}(\text{pk}_N, \text{VecMatMultR}_{\mathbf{\vec{r}}}, \mathbf{A}_F).$
 - $\vec{\boldsymbol{\beta}}_F \leftarrow \text{Eval}\left(\text{pk}_N, \text{Add}, \vec{\mathbf{b}}_F, \vec{\boldsymbol{t}}\right).$

Then, S_1 sends Γ_F , $\vec{\beta}_F$ to S_2 . (Notice that for every $i \notin F$, the *i*th row and column in Γ_F is $\vec{0}$, and similarly the *i*th entry of $\vec{\beta}_F$ is 0.)

(3) **Decrypting Masked Data:** S_2 decrypts $\Gamma_F = \text{Dec}(\text{sk}_N, \Gamma_F)$ and $\vec{\beta}_F = \text{Dec}(\text{sk}_N, \vec{\beta}_F)$. Then, S_1 projects $\Gamma_F, \vec{\beta}_F$ to the indices in F

by computing $\Gamma = \text{pjct}_F (\Gamma_F) \in \mathbb{Z}_N^{|F| \times |F|}$ and $\vec{\beta} = \text{pjct}_F (\vec{\beta}_F) \in \mathbb{Z}_N^{|F|}$.

- (4) **Masked learning:** S_2 computes $\operatorname{adj}(\Gamma)$ and $\Delta = \det(\Gamma)$, as well as $\vec{\zeta} = \operatorname{adj}(\Gamma) \cdot \vec{\beta}$. Then, S_2 computes $\vec{\zeta}_F = \operatorname{expd}_F(\zeta) \in \mathbb{Z}_N^d$. Finally, S_2 encrypts $\vec{\zeta}_F \leftarrow \operatorname{Enc}(\operatorname{pk}_N, \vec{\zeta}_F)$ and $\Delta \leftarrow \operatorname{Enc}(\operatorname{pk}_N, \Delta)$, and sends $\vec{\zeta}_F, \Delta$ to S_1 . (Intuitively, S_2 solves the linear system $\Gamma \cdot \vec{\omega} = \vec{\beta}$ to obtain the masked model $\vec{\omega}$. Notice that $\vec{\zeta} = \det(\Gamma) \cdot \vec{\omega}$.)
- (5) Unmasking: S₁ homomorphically computes z̄ = det (A'_F) · w̄_F, where A'_F = pjct_F (A_F). This is done by performing the following:
 - $\vec{t}^1 \leftarrow \text{Eval}\left(\text{pk}_N, \text{MatVecMultL}_R, \vec{\zeta}_F\right)$. (Notice that $\vec{t}^1 = R \cdot \vec{\zeta}_F$ so, as explained in the proof of Lemma 8.4, $\vec{t}^1 = \det(\Gamma) \cdot (\vec{w}_F + \vec{r})$.)
 - $\vec{t}^2 \leftarrow \text{Eval}\left(\text{pk}_N, \text{VecScalerMult}_{\vec{r}}, \Delta\right)$. (Notice that $\vec{t}^2 = \det(\Gamma) \cdot \vec{r}$.)
 - $\vec{t^3} \leftarrow \text{Eval}\left(\text{pk}_N, \text{Sub}, \vec{t^1}, \vec{t^2}\right)$. (Notice that $\vec{t^3} = \vec{t^1} - \vec{t^2} = \det(\Gamma) \cdot \vec{w}_F$.)
 - $\vec{z} \leftarrow \text{Eval}\left(\text{pk}_N, \text{ScalerVecMult}_{\det(R')^{-1}}, \vec{t^3}\right)$. (Notice that $\vec{z} = \det(R')^{-1} \cdot \vec{t^3}, \text{ so } \vec{z} = \det\left(A'_F\right) \cdot \vec{w}_F$, because $\Gamma = A'_F \cdot R'$ so $\det(\Gamma) = \det(R') \cdot \det\left(A'_F\right)$.)

(6) S_1 sets \vec{z} to be its output for the phase.

Figure 3: Scaled ridge regression (single iteration).

The algorithm is executed locally by S_1 , using the circuits Add₄, Add, MatMultL_M, MatMultR_M, MatMult and MatVecMult of Section 5.1. **Public parameters:** \mathcal{E} , κ , m, n, d, N, λ , as in Figure 2. Inputs from previous phase: the public encryption key $\mathsf{pk}_N,$ and, for every $j \in [m]$, encryptions $\mathbf{A}^j, \mathbf{b}^j$ of $A^j \in \mathbb{Z}_N^{d \times d}, \mathbf{b}^j \in \mathbb{Z}_N^d$, as well as encryptions $\mathbf{P}_2, \mathbf{P}_2^T$ of P_2, P_2^T (respectively) under key pk_N . **Output:** encryptions **A**, $\vec{\mathbf{b}}$ of $A = P_2^T P_1^T \left(\sum_{j \in [m]} A^j + \lambda I \right) P_1 P_2$ and $\vec{b} = P_2^T P_1^T \sum_{j \in [m]} \vec{b}^j$, respectively, under key pk_N, where $P_1 \in \mathbb{Z}_N^{d \times d}$ is a random permutation matrix. (Notice that A is a permuted version of $\sum_{i \in [m]} A^{i} + \lambda I$, and \vec{b} is the corresponding representation of $X^{T} \vec{y}$.) **Steps:** S_1 performs the following: (1) **Data Merging:** Homomorphically computes $T^1 = \sum_{j \in [m]} A^j + \lambda I$ $(I \in \mathbb{Z}_N^{d \times d} \text{ is the identity matrix}) \text{ and } \vec{t} = \sum_{j \in [m]} \vec{b}^j \text{ by computing } T^1 \leftarrow \text{Eval}(\text{pk}_N, \text{Add}_{\lambda}, \mathbf{A}^1, \dots, \mathbf{A}^m), \text{ and }$ $\vec{t} \leftarrow \text{Eval}\left(\text{pk}_N, \text{Add}, \vec{b}^1, \dots, \vec{b}^m\right)$. (We note that $T^1 = X^T \cdot X + \lambda I$, and $\vec{t} = X^T \cdot \vec{u}$.) (2) Permutation Generation: Picks a random permutation matrix $P_1 \in \mathbb{Z}_N^{d \times d}$, and homomorphically computes $P = P_1 \cdot P_2$ and P^T by performing $\mathbf{P} \leftarrow \text{Eval}\left(\mathsf{pk}_N, \mathsf{MatMultL}_{P_1}, \mathbf{P}_2\right)$ and

$$\mathbf{P}^{T} \leftarrow \mathsf{Eval}\left(\mathsf{pk}_{N}, \mathsf{MatMultR}_{P_{1}^{T}}, \mathbf{P}_{2}^{T}\right).$$

(3) **Data Permuting:** Homomorphically computes $A = P^T \cdot T^1 \cdot P$ and $\vec{b} = P^T \cdot \vec{t}$ as follows: $T^2 \leftarrow \text{Eval}(\text{pk}_N, \text{MatMult}, \mathbf{P}^T, T^1)$. $\mathbf{A} \leftarrow \text{Eval}(\text{pk}_N, \text{MatMult}, T^2, \mathbf{P})$. $\vec{\mathbf{b}} \leftarrow \text{Eval}(\text{pk}_N, \text{MatVecMult}, \mathbf{P}^T, \vec{t})$.

Figure 6: Data Merging and Permuting

The algorithm is executed locally by S_1 and uses the circuits MatMultR_M and MatVecMultL_M of Section 5.1.

Public parameter: Eand N as in Figure 2. **Inputs from previous phases:** a set F^* of the indices of features that survived the current iteration, the public encryption key pk_N , and encryptions $\mathbf{A}, \vec{\mathbf{b}}$ of $A \in \mathbb{Z}_N^{d \times d}$ and $\vec{b} \in \mathbb{Z}_N^d$, respectively. **Output:** encryptions $\mathbf{A}_{F^*}, \vec{\mathbf{b}}_{F^*}$ of $A_{F^*} = \text{pjct}_{F^*}$ $(A) \in \mathbb{Z}_N^{d \times d}$ and $\vec{b}_{F^*} = \text{pjct}_{F^*}$ $(\vec{b}) \in \mathbb{Z}_N^d$ (i.e., the projection of A, \vec{b} to $[F^*]$). **Steps:**

- Compacting: S₁ compacts the data by homomorphically computing A_{F*} = N_{F*} · A · N_{F*} and b
 ^{*}_{F*} = N_{F*} · b
 ^{*}_F by performing;
 - $\mathbf{T} \leftarrow \text{Eval}\left(\text{pk}_N, \text{MatMultR}_{\mathcal{N}_{F^*}}, \mathbf{A}\right)$.(Notice that \mathbf{T} encrypts $A \cdot \mathcal{N}_{F^*}$.)
 - $\mathbf{A}_{F^*} \leftarrow \operatorname{Eval}\left(\operatorname{pk}_N, \operatorname{MatMultL}_{\mathcal{N}_{F^*}}, \mathbf{T}\right)$.
 - $\vec{\mathbf{b}}_{F^*} \leftarrow \text{Eval}\left(\text{pk}_N, \text{MatVecMultL}_{N_{F^*}}, \vec{\mathbf{b}}\right)$.

(Notice that for every $i \notin F^*$, the *i*th row and column in A_{F^*} are $\vec{0}$, and all other entries are identical to the corresponding entry in A. Similarly, for every $i \notin F^*$ the *i*th entry of \vec{b}_{F^*} is 0, otherwise it equals the corresponding entry in \vec{b} .)

(2) **Output:** S_1 outputs \mathbf{A}_{F^*} , $\mathbf{\vec{b}}_{F^*}$.

Figure 7: Compacting current data.

be removed first, and the second column will be removed next. This can be used to construct a pair of inputs $X^{(0)}$, $\vec{y}^{(0)}$ and $X^{(1)}$, $\vec{y}^{(1)}$ for which the order in which columns are removed is different, by switching the locations of the first and second columns. We first

The protocol uses the circuits ScalerVecMult and MatVecMult of Section 5.1.

Public parameter: \mathcal{E} , n, d, m, s, N as in Figure 2.

Inputs from previous phases: the input of S_1 consists of the public encryption key pk_N , encryptions \mathbf{A}_F , \mathbf{b}_F of A_F , \mathbf{b}_F (respectively), the set F of the features that survived to this iteration, and an encryption \mathbf{P} of a permutation matrix P. The input of S_2 consists of F and the keys pk_N , sk_N . The data owners have no input.

Output: the output of all parties is an *s*-sparse model \vec{w} . **Steps:**

(1) Learning step:

- - The output of S₁ is an *entry-by-entry* encryption **z**_F of a vector **z**_F ∈ Z^d_N.
 - Let Δ = det (Γ) denote the determinant which S₂ computes in Step 4 of Figure 3. Then S₂ encrypts Δ⁻¹ ← Enc (pk_N, Δ⁻¹), and sends Δ⁻¹ to S₁.
- Recall that $\vec{z}_F = \exp d_F \left(\det \left(A'_F \right) \cdot \vec{w}'_F \right)$, where
- $A'_F = \text{pjct}_F(A_F) \in \mathbb{Z}_N^{|F| \times |F|}$ and $\vec{w}'_F \in \mathbb{Z}_N^{|F|}$ were defined in Figure 3. S_1 homomorphically computes $\vec{w}_F = \exp d_F(\vec{w}'_F)$ as follows:

- let
$$D = \det (A'_F)$$
, then S_1 homomorphically computes D^{-1} by

computing
$$\mathbf{D}^{-1} \leftarrow \text{Eval}\left(\text{pk}_N, \text{ScalerVecMult}_{(\det(R'))^{-1}}, \mathbf{\Delta}^{-1}\right)$$

(This step computes D^{-1} because

- $\Delta = \det (\Gamma) = \det (A'_F \cdot R') = \det (R') \cdot \det (A'_F).$
- homomorphically computes
- $\vec{\mathbf{w}}_F \leftarrow \text{Eval}(\text{pk}_N, \text{ScalerVecMult}, \vec{\mathbf{z}}_F, \mathbf{D}^{-1}).$ (Notice that $\vec{\mathbf{w}}_F = \text{expd}_F(\vec{\mathbf{w}}_F)$, where $A'_F \cdot \vec{\mathbf{w}}_F = \text{pjct}_F(\vec{b}_F).$)
- (2) Unpermuting: S₁ homomorphically unpermutes w_F to obtain w^{int} = P · w_F by computing
 w^{int} ← Eval (pk_N, MatVecMult, P, w_F), and sends w^{int} to S₂. (Notice that w_F contains the correct weights, but they are permuted according to P^T. Multiplying by P = (P^T)⁻¹ thus inverts the permutation.)
- (3) Decrypting the output: S₂ decrypts w^{int} = Dec (sk_N, w^{int}), recovers from it the model w ∈ Q^d using rational reconstruction [23, 65], and sends w to all parties.

Figure 8: Computing and unmasking the output

present the explicit example, then discuss the intuition underlying it, and possible extensions.

THE EXAMPLE. Consider the following data matrix and response vector:

$$X = \begin{pmatrix} 1 & 1 & 10 \\ -1 & 2 & 11 \\ 5 & 1 & 12 \\ 1 & 1 & 1 \end{pmatrix}, \quad \vec{y} = \begin{pmatrix} 21 \\ 23 \\ 25 \\ 3 \end{pmatrix}$$

Then the iterated ridge protocol is instantiated with inputs

$$A = X^{T}X = \begin{pmatrix} 28 & 5 & 60\\ 5 & 7 & 45\\ 60 & 45 & 366 \end{pmatrix}, \quad \vec{b} = X^{T}\vec{y} = \begin{pmatrix} 126\\ 95\\ 766 \end{pmatrix}$$

ź

The protocol uses the circuits Square, SubNums, AddConst_c, BinCompareR_c, BinCompareL_c, Neg, MultNums and AddNums of Section 5.1. All computations are in \mathbb{Z}_D .

Public parameter: $\mathcal{E} = (\text{KeyGen}, \text{Enc}, \text{Dec}, \text{Eval}) \text{ and } N, D \text{ as in Figure 2.We denote } l = \lceil \log N \rceil$.

Inputs from previous phases: both servers take as input the set $F \subseteq [d]$ of the currently used feature indices, and public encryption keys pk_N , pk_D , as well as a value k such that $1 \leq k < |F|$ which determines the size of the output set S_{del} . S_1 additionally has as input a vector \vec{z} , which is an entry-wise encryption of a vector $\vec{z} \in \mathbb{Z}_N^d$, where $z_i < \sqrt{N}$ for every $i \in [d]$ (here and below, z_i denotes the *i*'th entry of \vec{z}). S_2 additionally has as input the private decryption key sk_N .

Output: the output of S_1 , S_2 is a subset $S_{del} \subseteq [|F|]$ of size k which contains the indices of the smallest entries in \vec{z} . **Steps:**

- (1) Compute masked differences: serv₁ sends to S_2 the values $\{df_{i,j}\}_{i,j\in F, i\neq j}$ which are computed as follows:
 - For every $i \in F$, homomorphically computes the value $z'_i := z_i^2$ by computing $\mathbf{z}'_i \leftarrow \text{Eval}(\text{pk}_N, \text{Square}, \mathbf{z}_i)$.
 - For every $i, j \in F$ such that $i \neq j$, picks a random $r_{i,j} \leftarrow \mathbb{Z}_N$, and computes $\mathbf{t}_{i,j} \leftarrow \text{Eval}\left(\mathsf{pk}_N, \mathsf{SubNums}, \mathbf{z}'_i, \mathbf{z}'_i\right)$ and
 - $\mathbf{df}_{i,j} \leftarrow \mathrm{Eval}\left(\mathrm{pk}_N, \mathrm{AddConst}_{r_{i,j}}, \mathbf{t}_{i,j}\right)$. (df_{i,j} is the difference $z_i^2 z_j^2$, masked with the random $r_{i,j}$.)
- (2) Compute non-negative ranges of masked differences: S_2 performs the following for every $i, j \in F, i \neq j$:
 - Decrypts $df_{i,j} = Dec(sk_N, df_{i,j})$.
 - If $df_{i,j} < \frac{N-1}{2} + 1$ then set range $Min'_{i,j} = df_{i,j}$, range $Max'_{i,j} = df_{i,j} + \frac{N-1}{2} + 1$ (the sum is computed over the integers), and Negative_{i,j} = 0.
 - Else, set range $Min'_{i,j} = df_{i,j} \frac{N-1}{2}$ (computed over the integers), range $Max'_{i,j} = df_{i,j} + 1$, and Negative_{i,j} = 1.
 - Let $\overrightarrow{\mathsf{rangeMin}}_{i,j}$, $\overrightarrow{\mathsf{rangeMax}}_{i,j}$ denote the binary representation of $\mathsf{rangeMin}'_{i,j}$ and $\mathsf{rangeMax}'_{i,j}$ as length-*l* strings, respectively. S_2 encrypts $\overrightarrow{\mathsf{rangeMin}}_{i,j} \leftarrow \mathsf{Enc}\left(\mathsf{pk}_D, \overrightarrow{\mathsf{rangeMin}}_{i,j}\right)$, $\overrightarrow{\mathsf{rangeMin}}_{i,j} \leftarrow \mathsf{Enc}\left(\mathsf{pk}_D, \mathsf{rangeMax}_{i,j}\right)$, and $\mathbf{Negative}_{i,j} \leftarrow \mathsf{Enc}\left(\mathsf{pk}_D, \mathsf{Negative}_{i,j}\right)$.

Then, S_2 sends $\left\{\overrightarrow{\mathsf{rangeMin}}_{i,j}, \overrightarrow{\mathsf{rangeMax}}_{i,j}, \mathsf{Negative}_{i,j}\right\}_{i,j \in F, i \neq j}$ to S_1 .

- (3) **Compute ordering:** S_1 homomorphically computes the ordering of z_1, \ldots, z_d , where the order of index *i* is the number of indices $j \in F$ such that $z_i < z_j$ (as elements of \mathbb{Z}_N). Specifically, S_1 performs the following:
 - For every $i \in F$, encrypts $\operatorname{Ord}_i \leftarrow \operatorname{Enc}(\operatorname{pk}_D, 0)$. (Ord_i is the location of index *i* in the ordering; intuitively, it is initialized to 0 and will be increased for every $j \neq i$ such that $z_j \leq z_i$.)
 - For every $i, j \in F, i \neq j$, let $\vec{r}_{i,j}$ denote the length-*l* bit string representing $r_{i,j}$, then S_1 checks whether $r_{i,j} \in [rangeMin_{i,j}, rangeMax_{i,j}]$. This is done homomorphically as follows.
 - S_1 homomorphically computes two indicators: $\mathsf{lsBigger}_{i,j} \leftarrow \mathsf{Eval}\left(\mathsf{pk}_D, \mathsf{BinCompareR}_{\vec{r}_{i,j}}, \overline{\mathsf{rangeMin}_{i,j}}\right)$

IsSmaller_{*i,j*} \leftarrow Eval (pk_D, BinCompareL_{*i*_{*i,j*}, **rangeMax**_{*i,j*}) (Intuitively, IsBigger_{*i,j*} = IsSmaller_{*i,j*} = 1 if and only if rangeMin_{*i,j*} $\leq r_{i,j} < rangeMax_{i,j}$.)}

- Next, S_1 increases Ord_i by $\operatorname{ost}_{i,j} := \operatorname{lsBigger}_{i,j} \cdot \operatorname{lsSmaller}_{i,j} \cdot \operatorname{Negative}_{i,j} + \left(1 \operatorname{lsBigger}_{i,j} \cdot \operatorname{lsSmaller}_{i,j}\right) \cdot \left(1 \operatorname{Negative}_{i,j}\right)$. (Intuitively, $\operatorname{ost}_{i,j} \in \{0, 1\}$ is 1 if and only if $z_i > z_j$, which happens if either: $(1) z_i^2 z_j^2 + r_{i,j}$ is "negative", which is denoted by Negative_{i,j} = 1, and then $z_i^2 z_j^2$ is "positive" if and only if range $\operatorname{Min}_{i,j} \le r_{i,j} < \operatorname{range}\operatorname{Max}_{i,j}$, in which case the first summand is 1; or (2) $z_i^2 z_j^2 + r_{i,j}$ is "non-negative", in which case Negative_{i,j} = 0, and additionally $r_{i,j} < \operatorname{range}\operatorname{Min}_{i,j}$ or $\operatorname{range}\operatorname{Max}_{i,j} \le r_{i,j}$, i.e., the second summand is 1.) This is done by homomorphically computing the following values:
- (a) The negations notInRange_{*i*,*j*} and NotNegative_{*i*,*j*} of IsBigger_{*i*,*j*} · IsSmaller_{*i*,*j*} and Negative_{*i*,*j*} (respectively), computed as inRange_{*i*,*j*} \leftarrow Eval (pk_D, MultNums, IsBigger_{*i*,*j*}, IsSmaller_{*i*,*j*}),
- $\mathsf{notInRange}_{i,j} \leftarrow \mathsf{Eval}\left(\mathsf{pk}_D, \mathsf{Neg}, \mathsf{inRange}_{i,j}\right), \mathsf{NotNegative}_{i,j} \leftarrow \mathsf{Eval}\left(\mathsf{pk}_D, \mathsf{Neg}, \mathsf{Negative}_{i,j}\right)$
- (b) $t_{i,j}^1 \leftarrow \text{Eval}\left(\text{pk}_D, \text{MultNums}, \text{IsBigger}_{i,j}, \text{IsSmaller}_{i,j}\right)$. (Then $t_{i,j}^1 = \text{IsBigger}_{i,j} \cdot \text{IsSmaller}_{i,j}$.)
- (c) $\mathbf{t}_{i,j}^2 \leftarrow \text{Eval}\left(\text{pk}_D, \text{MultNums}, \mathbf{t}_{i,j}^1, \text{Negative}_{i,j}\right)$. (Then $t_{i,j}^2 = \text{IsBigger}_{i,j} \cdot \text{IsSmaller}_{i,j} \cdot \text{Negative}_{i,j}$.)
- (d) $\mathbf{t}_{i,j}^3 \leftarrow \text{Eval}\left(\text{pk}_D, \text{MultNums}, \text{notInRange}_{i,j}, \text{NotNegative}_{i,j}\right)$. (Then $t_{i,j}^3 = \left(1 \text{IsBigger}_{i,j} \cdot \text{IsSmaller}_{i,j}\right) \cdot \left(1 \text{Negative}_{i,j}\right)$.)
- (e) $\mathbf{t}_{i,j}^4 \leftarrow \text{Eval}\left(\text{pk}_D, \text{AddNums}, \mathbf{t}_{i,j}^2, \mathbf{t}_{i,j}^3\right)$. (Then $t_{i,j}^4 = \text{ost}_{i,j}$.)
- (f) **Ord**_{*i*} \leftarrow Eval $\left(\mathsf{pk}_D, \mathsf{AddNums}, \mathsf{Ord}_i, t_{i,j}^4 \right)$. (This increases Ord_i by $\mathsf{ost}_{i,j}$.)
- (4) **Permuting ordinals:** S_1 draws a random permutation Π on F, and computes the vector $\overrightarrow{\mathbf{Ord}}^{\Pi} \in \mathbb{Z}_D^{|F|}$ such that $\overrightarrow{\mathbf{Ord}}_i^{\Pi} = \mathbf{Ord}_{\Pi(i)}$ for every $i \in F$. Then, S_1 sends $\overrightarrow{\mathbf{Ord}}^{\Pi}$ to S_2 .
- (5) Computing k smallest features: for every $i \in F$, S_2 decrypts $\overrightarrow{Ord}_i^{\Pi} = \text{Dec}\left(\text{sk}_D, \overrightarrow{Ord}_i^{\Pi}\right)$, and generates a vector $\chi^{\Pi} \in \{0, 1\}^d$ by setting $\chi_i^{\Pi} = 1$ if $\overrightarrow{Ord}_i^{\Pi} < k$, otherwise setting $\chi_i^{\Pi} = 0$. S_2 sends $\vec{\chi}^{\Pi} := \left(\chi_1^{\Pi}, \dots, \chi_{|F|}^{\Pi}\right)$ to S_1 .
- (6) **Output:** S_1 computes $S_{del} = \{i : \vec{\chi}_{\Pi(i)}^{\Pi} = 1\}$ and sends it to S_2 . Both servers set S_{del} to be their output for the phase.

Figure 9: Selecting which features to remove in the current iteration.

The solution to the linear system $A\vec{w} = \vec{b}$ is

$$\vec{w} = \left(\begin{array}{c} 157/1281\\ 970/1281\\ 2536/1281 \end{array}\right)$$

Therefore, from the correctness of the iterated ridge step (Figure 3, see analysis in Section 8), the first column of A will be removed in the first iteration. Thus, the second iteration is initialized with inputs¹⁴

$$A' = \left(\begin{array}{cc} 7 & 45\\ 45 & 366 \end{array}\right), \quad \vec{b}' = \left(\begin{array}{c} 95\\ 766 \end{array}\right)$$

And the solution to $A'\vec{w}' = \vec{b}'$ is

$$\vec{w}' = \left(\begin{array}{c} 100/179\\ 1087/537 \end{array}\right)$$

So the second column will be removed in the second iteration (from the correctness of the iterated ridge step). Thus, for X, \vec{y} the order in which columns are removed is 1,2 (and column 3 "survives" the iterations). Consider now switching the first and second columns of X, i.e., running the protocol with inputs

$$X^{(1)} = \begin{pmatrix} 1 & 1 & 10 \\ 2 & -1 & 11 \\ 1 & 5 & 12 \\ 1 & 1 & 1 \end{pmatrix}, \quad \vec{y}^{(1)} = \begin{pmatrix} 21 \\ 23 \\ 25 \\ 3 \end{pmatrix}$$

In this case, all calculations will be symmetric to those with X, \vec{y} , except that the role of columns 1,2 is reversed. In particular, column 2 will be removed in the first iteration, and column 1 will be removed in the second iteration. Consequently, if the protocol is executed over unpermuted data, then the set of surviving features (computed in Step 3c in Figure 2) will differ when executing over X, \vec{y} , and $X^{(1)}, \vec{y}^{(1)}$, and so the adversary's view is different, even though its output (the final 1-sparse model $w = (0 \ 0 \ 766/366)^T$) is the same.

DISCUSSION: INTUITION AND EXTENSIONS. We now describe the intuition underlying the example. The starting point is a set of 4 linear equations in 3 variables, with an *exact* solution, in which each of the columns of the matrix defining the linear system has a unique "role" (i.e., there is no symmetry between the columns). Specifically, consider the following system:

$$\begin{pmatrix} 1 & 1 & 10 \\ -1 & 1 & 11 \\ 5 & 1 & 12 \\ 1 & 1 & 1 \end{pmatrix} \cdot \begin{pmatrix} w_1 \\ w_2 \\ w_3 \end{pmatrix} = \begin{pmatrix} 21 \\ 23 \\ 25 \\ 3 \end{pmatrix}$$

The solution of the system is $w_1 = 0$, $w_2 = 1$, $w_3 = 2$. Intuitively, this is because the first column is uncorrelated with the result, and the "weight" of the third column (i.e., its effect on the solution) is double that of the second column. Thus, when searching for a 1-sparse solution with these inputs, the first column will be removed in the first iteration, and the second column will be removed next. Therefore, the system given above already gives an example in which the order of removing columns reveals non-trivial information. To show that such information leakage is possible even when no exact solution exist, we add "noise" to the system,

by changing the second entry on the second row from 1 to 2, thus obtaining the X, \vec{y} described above.

We note that for simplicity, we chose to present a case in which the two inputs $X^{(0)}, X^{(1)}$ have the same columns (in a different order). However, the example generalizes to cases in which $X^{(0)}, X^{(1)}$ do not share any column, as long as the order of correlations between the columns and the response vector are different in the two inputs. We additionally note that the example can be generalized to matrices of higher dimensions, where instead of considering single columns of X, we divide the columns into 3 sets: a set that is highly correlated with \vec{y} (representing column 2 in the toy example), as that is somewhat correlated with \vec{y} (representing column 1 in the toy example).

Such types of inputs naturally arise when learning is performed over real data. Indeed, X and $X^{(1)}$ can represent records from two different sub-populations $\mathcal{P}_1, \mathcal{P}_2$ with different characteristics. Specifically, the second feature (i.e., column) might be highly correlated with the response vector in \mathcal{P}_1 but not in \mathcal{P}_2 , whereas the first feature (i.e., column) is highly correlated with the response vector in \mathcal{P}_2 (but not in \mathcal{P}_1). Thus, the information leakage described through this toy example can be used to infer from which of the sub-populations the data was taken.

The necessity of hiding the intermediate models. Our protocols hide the models computed during intermediate iterations of the ridge regressions protocol (Figure 3). We now show that this is necessary for privacy, as intermediate models might reveal nontrivial information about the inputs. Specifically, we will show a pair of inputs for which the final model, and the order in which columns are removed, are identical, but the intermediate models are not. In particular, this shows that revealing the intermediate models reveals information *beyond* what is revealed by the order in which features are removed.

The high-level idea of the attack is to consider pairs $X^{(0)}$, $\vec{y}^{(0)}$ and $X^{(1)}$, $\vec{y}^{(1)}$ of inputs for which there exist (s+1)-sparse solutions (that are not *s*-sparse) that differ only in the value of the smallest coordinate which is present in the (s + 1)-sparse solution. Since we are looking for an *s*-sparse solution, this coordinate will not appear in the final model, which will therefore be identical in both cases. More specifically, we can even take $X^{(0)}$, $X^{(1)}$ to be identical. We proceed to describe the example.

THE EXAMPLE. Consider the following data matrix and response vector:

$$X = \begin{pmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 0 \end{pmatrix}, \quad \vec{y}^{(0)} = \begin{pmatrix} 6 \\ 3 \\ 7 \\ 10 \\ 9 \end{pmatrix}$$

where we are looking for a 3-sparse solution. Then the data merging step (Figure 6) outputs a permuted version of

$$A = X^T X = \begin{pmatrix} 4 & 3 & 3 & 1 \\ 3 & 4 & 2 & 1 \\ 3 & 2 & 3 & 1 \\ 1 & 1 & 1 & 1 \end{pmatrix}$$

 $^{^{14}}$ Here, we assume that only the first feature is removed in the first iteration. This will indeed be the case for this toy example, since the cutoff point in Step 3b of Figure 2 will be computed with $|F| \leq$ thr since the number of features is small.

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and

$$\vec{b}^{(0)} = X^T \vec{y}^{(0)} = \begin{pmatrix} 32\\ 29\\ 25\\ 10 \end{pmatrix}$$

where for simplicity of the description we assume the permutation is the identity (so the permuted versions are identical to A, $\vec{b}^{(0)}$). This is without loss of generality, since applying a general permutation will only permute the coordinates of the intermediate models, but will not affect their values. Therefore, the first iteration of the scaled iterated ridge regression phase (Figure 3) is run on inputs A, $\vec{b}^{(0)}$, where S_2 executes the learning algorithm over masked versions of A, $\vec{b}^{(0)}$. Again, for simplicity of the description we assume the masking is trivial (i.e., R is the identity and $\vec{r} = \vec{0}$), so that learning is performed directly on A, $\vec{b}^{(0)}$. This again is without loss of generality since from the correctness of the protocol (see Section 8), learning on masked data returns the "correct" model, which would have been computed if learning had been performed directly on unmasked data. In this case, S_2 computes the scaled model $\vec{z}^{(0)}$ as:

$$\vec{z}^{(0)} = \operatorname{adj}(A) \cdot \vec{b}^{(0)}$$

$$= \begin{pmatrix} 5 & -2 & -4 & 1 \\ -2 & 2 & 1 & -1 \\ -4 & 1 & 5 & -2 \\ 1 & -1 & -2 & 5 \end{pmatrix} \cdot \begin{pmatrix} 32 \\ 29 \\ 25 \\ 10 \end{pmatrix} = \begin{pmatrix} 12 \\ 9 \\ 6 \\ 3 \end{pmatrix} \quad (5)$$

Notice that the corresponding model is

$$\vec{w}^{(0)} = (\det(A))^{-1} \cdot \vec{z}^{(0)} = \begin{pmatrix} 4 \\ 3 \\ 2 \\ 1 \end{pmatrix}.$$

The last column of A will be removed in the first iteration,¹⁵ which will also be the last iteration since we are looking for a 3-sparse solution. The final model will be

$$\vec{w} = \begin{pmatrix} 4 \\ 3 \\ 2 \\ 0 \end{pmatrix}$$

Consider now the inputs $X, \vec{y}^{(1)}$, where

$$\vec{y}^{(1)} = \begin{pmatrix} 6 \\ 3 \\ 7 \\ 9.5 \\ 9 \end{pmatrix}$$

Again, we assume without loss of generality that the permutation and masking are trivial, and so in the first iteration of the scaled iterated ridge regression phase, S_2 computes the scaled model

$$\vec{z}^{(1)} = \operatorname{adj}(A) \cdot \vec{b}^{(1)}$$
, where

$$\vec{b}^{(1)} = X^T \vec{y}^{(1)} = \begin{pmatrix} 31.5\\ 28.5\\ 24.5\\ 9.5 \end{pmatrix}.$$

Then

$$\vec{z}^{(1)} = \begin{pmatrix} 12\\9\\6\\1.5 \end{pmatrix},$$

and notice that the corresponding unscaled model is

$$\vec{w}^{(1)} = \left(\begin{array}{c} 4 \\ 3 \\ 2 \\ 0.5 \end{array} \right).$$

Again, there will be a single iteration and the final model will be \vec{w} , but the intermediate models are different: $\vec{z}^{(0)} \neq \vec{z}^{(1)}$ and consequently also $\vec{w}^{(0)} \neq \vec{w}^{(1)}$.

The necessity of hiding det (A). Our protocols hide the determinant det (A) used to un-scale the final model (see Step 1 in Figure 8). We now show this is necessary for privacy, as det (A) might reveal non-trivial information about the inputs. Specifically, we will show a pair of inputs for which the (unscaled) final and intermediate models, and the order in which columns are removed, are identical, but det (A) is not. In particular, this shows that revealing det (A) reveals information *beyond* what is revealed by the order in which features are removed, *and* the intermediate models.

The high-level idea of the attack is conceptually simple: we consider a pair $X^{(0)}$, $\vec{y}^{(0)}$ of inputs, and a "scaled" version $X^{(1)} = 2X^{(0)}$, $\vec{y}^{(1)} = 2\vec{y}^{(0)}$. Since the data and response vector are scaled by the same scaler, the resultant models will be the same (throughout the execution of the protocol), but det (*A*) will be different. We proceed to explicitly describe the example.

THE EXAMPLE. For $X^{(0)}$, $\vec{y}^{(0)}$ we consider the same inputs as in the previous example (which showed the necessity of hiding the intermediate models). As in the previous example, we consider the case that parties are looking for a 3-sparse solution, and make the same simplifying assumptions (namely, that the permutation and masking are trivial). Consequently, all computations will be identical. In particular, the scaled model $\vec{z}^{(0)}$, the unscaled model $\vec{w}^{(0)}$, the final model \vec{w} , and det $(A^{(0)}) = \det((X^{(0)})^T \cdot X^{(0)})$ satisfy:

$$\vec{z}^{(0)} = \begin{pmatrix} 12\\ 9\\ 6\\ 3 \end{pmatrix}, \quad \vec{w}^{(0)} = \begin{pmatrix} 4\\ 3\\ 2\\ 1 \end{pmatrix},$$
$$\vec{w} = \begin{pmatrix} 4\\ 3\\ 2\\ 0 \end{pmatrix}, \quad \det\left(A^{(0)}\right) = 3.$$

¹⁵We note that though the computation is performed over the binary representation of abs $(\vec{z}^{(0)})$, it returns the same result as would have been computed directly on $\vec{z}^{(0)}$ because the computation is over \mathbb{R} and all coordinates are positive.

Now, consider the inputs $X^{(1)} = 2X^{(0)}, \vec{y}^{(1)} = 2\vec{y}^{(0)}$. Then

and

$$\vec{b}^{(1)} = \left(X^{(1)}\right)^T \vec{y}^{(1)} = \begin{pmatrix} 128\\116\\100\\40 \end{pmatrix} = 4\vec{b}^{(0)}$$

(100)

Therefore, in the first iteration of the scaled iterated ridge regression phase (Figure 3), S_2 computes the scaled model $\vec{z}^{(1)}$ as:

$$\vec{z}^{(1)} = \operatorname{adj} \left(A^{(1)} \right) \cdot \vec{b}^{(1)}$$

$$= \begin{pmatrix} 320 & -128 & -256 & 64 \\ -128 & 128 & 64 & -64 \\ -256 & 64 & 320 & -128 \\ 64 & -64 & -128 & 320 \end{pmatrix} \cdot \begin{pmatrix} 128 \\ 116 \\ 100 \\ 40 \end{pmatrix}$$

$$= 64\operatorname{adj} \left(A^{(0)} \right) \cdot 4\vec{b}^{(0)} = 256\vec{z}^{(0)} = \begin{pmatrix} 3072 \\ 2304 \\ 1536 \\ 768 \end{pmatrix} \quad (6)$$

Notice that the corresponding model is

$$\vec{w}^{(1)} = \left(\det\left(A^{(1)}\right)\right)^{-1} \cdot \vec{z}^{(1)} = \frac{1}{768} \cdot \vec{z}^{(1)} = \begin{pmatrix} 4\\ 3\\ 2\\ 1 \end{pmatrix}.$$

The last column of A will again be removed in the first iteration, which will also be the last iteration since we are looking for a 3-sparse solution. The final model will be \vec{w} as in the previous case. In summary, the (unscaled) intermediate and final models are the same, as well as the order in which columns are removed. However, det $(A^{(0)}) = 3 \neq 768 = \det (A^{(1)})$.

SIR is susceptible to inversion attacks. We conclude this section by showing that SIR is susceptible to inversion attacks. More specifically, we show that the output model may be used to infer non trivial information on the inputs of parties, even when *all parties follow the protocol* (i.e., are semi-honest). In particular, such attacks might be exploited by corrupted parties, who may choose to use different inputs (but otherwise follow the protocol) in order to learn non-trivial information about the inputs of the honest parties.

The high-level idea of the attack is for corrupted parties to use "balanced" inputs, in which all features have the same correlation with the response vector. Thus, the inputs provided by corrupted parties will not affect the output model, and any correlation in the output model will then point to correlations in the inputs of honest parties. A concrete example follows.

We consider a setting with two data owners DO_{Alice} and DO_{Bob} , each holding 3 data records with 3 features. DO_{Bob} will be corrupt, and will try to infer information about the inputs of DO_{Alice} . We note that unlike the previous attacks of the section, we cannot directly consider the final data matrix *X* (on which SIR will be executed), but rather we define the data matrices of DO_{Alice} , DO_{Bob} and use them to define X and the response vector. (The reason for this difference is that previous attacks considered only a corrupted server, so leaking information about the inputs of *any* of the data owners was problematic; whereas here we are trying to leak on the input of a *specific* data owner.)

The Example. Consider the following data matrix and response vector for DO_{Bob} :

$$X^{\text{Bob}} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad \vec{y}^{\text{Bob}} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

and two possible inputs for DO_{Alice}:

$$X^{\text{Alice},0} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad \vec{y}^{\text{Alice},0} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix},$$

and

$$X^{\text{Alice},1} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad \vec{y}^{\text{Alice},1} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

Consider executing sparse ridge regression with $\lambda = 0$, where we are looking for a 1-sparse solution. Then

$$A^{\mathsf{Bob}} \coloneqq \left(X^{\mathsf{Bob}}\right)^T \cdot X^{\mathsf{Bob}} = I$$

(here, I is the unit matrix), and

$$\vec{b}^{\text{Bob}} := \left(X^{\text{Bob}}\right)^T \cdot \vec{y}^{\text{Bob}} = \vec{y}^{\text{Bob}}.$$

In the first execution, when DO_{Alice} 's input is $X^{Alice,0}$, $\vec{y}^{Alice,0}$ we have

$$\mathbf{A}^{\mathsf{A}\mathsf{lice},0} \coloneqq \left(X^{\mathsf{A}\mathsf{lice},0}\right)^T \cdot X^{\mathsf{A}\mathsf{lice},0} = \mathbf{A}$$

and

$$\vec{b}^{\text{Alice},0} := \left(X^{\text{Alice},0}\right)^T \cdot \vec{y}^{\text{Alice},0} = y^{\text{Alice},0}$$

whereas in the second execution, when DO_{Alice} 's input is $X^{Alice,1}, \vec{y}^{Alice,1}$ we have

$$A^{\text{Alice},1} := \left(X^{\text{Alice},1}\right)^T \cdot X^{\text{Alice},1} = I$$

and

$$\vec{b}^{\text{Alice},0} \coloneqq \left(X^{\text{Alice},1} \right)^T \cdot \vec{y}^{\text{Alice},1} = y^{\text{Alice},1}$$

These are then merged into a single matrix and response vector. The merged matrices are $A^0 := A^{Alice,0} + A^{Bob} = 2I$ in the first case, and $A^1 := A^{Alice,1} + A^{Bob} = 2I$ in the second case. As for the response vectors, these are

$$\vec{b}^{0} := \vec{b}^{\text{Alice},0} + \vec{b}^{\text{Bob}} = \begin{pmatrix} 2\\1\\1 \end{pmatrix}$$

in the first case, and

$$\vec{b}^{1} := \vec{b}^{\text{Alice},1} + \vec{b}^{\text{Bob}} = \begin{pmatrix} 1\\1\\2 \end{pmatrix}$$

in the second case. The solutions \vec{w}^0, \vec{w}^1 to the linear systems $A^0 \vec{w}^0 = \vec{b}^0$ and $A^1 \vec{w}^1 = \vec{b}^1$, respectively, are

$$\vec{w}^{0} = \begin{pmatrix} 1 \\ 1/2 \\ 1/2 \end{pmatrix}, \quad \vec{w}^{1} = \begin{pmatrix} 1/2 \\ 1/2 \\ 1 \end{pmatrix}$$

Therefore, the output sparse models would be

$$\vec{w}^{0\prime} = \begin{pmatrix} 1\\ 0\\ 0 \end{pmatrix}, \quad \vec{w}^{1\prime} = \begin{pmatrix} 0\\ 0\\ 1 \end{pmatrix}$$

respectively, which reveals which feature in the input of DO_{Alice} is most correlated with the response vector.

8 SECURITY ANALYSIS

In this section we analyze the security of our protocol SIR. We first set some notation.

Notation 8.1. For natural $N, d, \lambda \ge 0$, and $\emptyset \ne F_k \subset \ldots \subset F_1 \subseteq [d]$, let $\mathcal{T}_{Inv,N,d,\lambda,F_1,\ldots,F_k}$ denote the subset of $\mathbb{R}^{n \times d} \times \mathbb{R}^{n \times 1}$ consisting of all (X, \vec{y}) such that:

- $A = X^T X + \lambda I$ is invertible in $\mathbb{Z}_N^{d \times d}$.
- For every $1 \le j \le k$, pjct_{*F_j*}(*A*) is invertible in $\mathbb{Z}_N^{|F_j| \times |F_j|}$.

Remark 8.2 (On the types of inputs for which SIR is secure). As noted in Section 1, SIR is secure when $d \leq n$ and X is invertible (the same assumption is also made in previous works [4, 29]). More specifically, we only consider security for inputs in $\mathcal{T}_{Inv,N,d,\lambda,F_1,...,F_k}$ (where λ , *d* and *N* are as defined in Section 4, and F_1, \ldots, F_k are the sets of features that survive iterations $1, \ldots, k$, respectively; notice that the sizes of these sets depend only on the public parameters of SIR). This is similar to the security guarantee of Giacomelli et al. [29], who only consider security for inputs in $\mathcal{T}_{Inv,N,d,\lambda,\lceil d \rceil}$. Our assumption that $(X,\vec{y})\in\mathcal{T}_{\mathsf{Inv},N,d,\lambda,F_1,\dots,F_k}$ is a natural extension of the assumption of [29] (that $(X, \vec{y}) \in \mathcal{T}_{Inv,N,d,\lambda,[d]}$) to our setting of iterated computation. We stress that when $d \le n$, it suffices to assume that X is inevitable (i.e., has degree d). Indeed, in this case X_F – the restriction of X to the rows and columns in $F \subseteq [d]$ – also has full degree (i.e., degree |F|), and consequently the matrices $A_F = (X_F)^T X_F$ used in the ridge regression iteration all have full degree. As noted in Section 1, for the case d > n SIR can be combined with another learning method (e.g., filter) to reduce the number of features to n.

THEOREM 8.3 (SIR SECURITY). Let $d \le n \in \mathbb{N}$. Then SIR is an iterated ridge implementation of the algorithm of Figure 1 with mprivacy for any $\lambda \ge 0$, and any $N \in \mathbb{N}$ that satisfies Equation 4, assuming the input matrix X is invertible.

PROOF OF THEOREM 8.3. Correctness Follows from Lemma 8.4 below. As for privacy, let $I \subseteq [m]$ denote the subset of corrupted data owners, and we consider three cases. First, assume that S_1 is corrupted. Then privacy follows from Lemma 8.5 below. Second, assume that S_2 is corrupt, then privacy follows from Lemma 8.6 below. Third, assume that both servers are honest. Since the servers have no input, and the output is public, simulatability follows immediately from simulatability when one of the servers is corrupted.

The next lemma states that the protocol is correct.

LEMMA 8.4 (CORRECTNESS). Protocol SIR is correct. That is, for every input X, \vec{y} , the output of SIR is identical to its non-secure version Iterative Ridge of Figure 1, except with negligible probability negl(κ).

PROOF. We will prove a stronger claim: we will prove that if the FHE scheme has *perfect* correctness, then the outputs of SIR and Iterative Ridge are *identical*. That is, we will prove that the only source of error is the correctness error of the FHE scheme (introduced by either the Eval or the Dec algorithms). This is indeed stronger than the statement of Lemma 8.4, because the correctness error of the FHE scheme is negligible. Therefore, for the remainder of the proof we assume that the FHE scheme is perfectly correct. Consequently, it suffices to prove correctness of a revised version of the protocol in which all values are given in the clear, and all computations are executed directly (not using homomorphic evaluation). This "unencrypted" version of SIR (Figure 2) differs from the non-secure Iterative Ridge algorithm (Figure 1) in the following points:¹⁶

- (1) Correctness of computing over a finite ring: Iterative Ridge performs all computations in \mathbb{R} , whereas SIR works in finite rings \mathbb{Z}_N and \mathbb{Z}_D , and then uses rational reconstruction to recover a sparse model in \mathbb{Q}^d .
- (2) Correctness of working over permuted inputs: In SIR, the data used for learning consists of *permuted* versions A, b of the merged data ∑_{j∈[m]} A^j + λI, ∑_{j∈[m]} b^j, whereas in Iterative Ridge A, b are used directly.
- (3) Correctness of the scaled ridge phase: SIR performs every ridge regression step (Figure 3) over masked data, computes the model w = A⁻¹ · b using the identity A⁻¹ = det (A) · adj (A), and outputs a model scaled by det (A). Moreover, the values Γ, β used for learning are obtained from a d × d matrix and a length-d vector, which are projected to the set F of surviving feature indices. Iterative Ridge, on the other hand, performs this learning phase in the clear (over unmasked data), computes A⁻¹ explicitly, and outputs the actual model (instead of a scaled one as in SIR). Moreover, in Iterative Ridge the values A, b used to perform the learning are the projected matrix and vector obtained from the previous iteration.
- (4) Correctness of the selection phase: The set S_{del} of smallest features that are removed in each iteration are computed from the full set [d] using *masked differences of squares* (i.e., z_i² − z_j² + r_{i,j}), whereas in Iterative Ridge it is computed directly from the set of surviving features using the absolute value (represented in ℝ). Also, in SIR these are computed over a permuted ordering, whereas in Iterative Ridge it is computed directly on the ordering.
- (5) **Correctness of the compaction phase:** The data compaction phase in SIR resets the entries of A, \vec{b} corresponding to features that did not survive the iteration,

¹⁶We note that this comparison is in terms of the *operations performed* in each of the protocols. Thus, the fact that the computation in SIR is divided between two servers, and in Iterative Ridge it is performed by a single server, is irrelevant for us, as we assume that the communication channels do not induce errors (this can be guaranteed using error-correcting codes).

whereas in Iterative Ridge these features are removed by projecting A, \vec{b} to the set of indices of surviving features.

(6) Correctness of the final output: The final learning phase in Iterative Ridge simply consists of performing another linear regression step which outputs the final sparse model. SIR uses a dedicated output phase, in which it performs masked ridge regression to obtain a scaled model, rescales it to the actual (permuted) output model, and finally unpermutes the output model.

We now argue that each of these steps preserves correctness (with probability 1) and therefore the protocol itself, which combines all steps, is also correct.

Computing over a finite ring (Item 1): the learning phase computations in SIR are performed in \mathbb{Z}_N , whereas \mathbb{Z}_D is only used to compute the ordering between the features. *N* is chosen such that no overflows will occur (see Remark 5.3), guaranteeing that all computations in \mathbb{Z}_N perfectly emulate computations in \mathbb{R} . Moreover, since $D \ge d$, and the ordering contains values between 0 and d - 1, then overflows do not occur in the computations in \mathbb{Z}_D . Moreover, correctness of the rational reconstruction algorithm was proven in [29] (and holds here because *N* is sufficiently large, see Remark 5.3).

Using permuted inputs (Item 2): permuting A, \vec{b} is equivalent to permuting the columns of the X^{j} 's and \vec{y}^{j} 's. (This holds because of the manner in which we apply the permutation, specifically by multiplying A by P^{T} from the right and by P from the left.) Put differently, the permutation simply permutes the features, as well as their weights in the output model. Other than that, the computation remains unchanged and, in particular, the computed models (in all iterations) have the "right" weights, but they are permuted according to the same permutation as the input. Following the final learning phase, we unpermute the learned model (by applying the inverse permutation $P = (P^{T})^{-1}$, see Figure 8), thus the permutation does not affect correctness.

Correctness of the scaled ridge phase: Item 3 does not affect correctness due to the following. First, computing A^{-1} as det(A) · adj(A) is based on a mathematical identity. Second, the fact that the output model is scaled by det(A) does not change the ordering (in absolute value) between the model's entries, and therefore does not affect the following stages of the iteration (in which the model is used to order the features and removes the ones with smallest weights - in absolute value). Next, we prove that the output is the correct (scaled) model det $(A'_F) \cdot \vec{w}_F$, even though computations are performed over masked A, \vec{b} , and even though the inputs to this phase were *not* projected to |F| (recall that in A_F , \vec{b}_F the rows, columns and entries corresponding to indices not in F were set to 0, but were not deleted as they are in Iterative Ridge). Referring to Figure 3, the (scaled, encrypted) model which \mathcal{S}_2 sends to \mathcal{S}_1 is $\vec{\zeta}_F = \exp d_F \left(\operatorname{adj} \left(\Gamma \right) \cdot \vec{\beta} \right)$ (see Remark 5.5 for a description of $expd_{F}(\cdot)$). S_1 then removes the masking by computing

$$(\det (R'))^{-1} \cdot \left[R \cdot \vec{\zeta}_F - \det (\Gamma) \cdot \vec{r} \right]$$

= $(\det (R'))^{-1} \cdot \left[R \cdot \exp d_F \left(\operatorname{adj} (\Gamma) \cdot \vec{\beta} \right) - \det (\Gamma) \cdot \vec{r} \right].$

We now analyze each of these components separately. We first make the following observation:

$$\forall F \subseteq [d], \forall B, C \in \mathbb{Z}_{N}^{d \times d} :$$

pjct_F ($\mathcal{N}_{F}B\mathcal{N}_{F} \cdot \mathcal{N}_{F}C\mathcal{N}_{F}$) = pjct_F (B) · pjct_F (C) (7)

and

$$\forall F \subseteq [d], \forall B \in \mathbb{Z}_N^{d \times d}, \forall \vec{v} \in \mathbb{Z}_N^{|F|} :$$

$$\text{pjct}_F \left(\mathcal{N}_F B \mathcal{N}_F \cdot \text{expd}_F (\vec{v}) \right) = \text{pjct}_F (B) \cdot \vec{v}$$
 (8)

Using Equation 7, we have:

$$\Gamma = \operatorname{pjct}_{F} (\Gamma_{F}) = \operatorname{pjct}_{F} (A_{F} \cdot R)$$
$$=^{(1)} \operatorname{pjct}_{F} (\mathcal{N}_{F}A\mathcal{N}_{F} \cdot \mathcal{N}_{F}R\mathcal{N}_{F})$$
$$=^{(2)} \operatorname{pjct}_{F} (A) \cdot \operatorname{pjct}_{F} (R) = A'_{F} \cdot R'$$

where the equality denoted by (1) follows from the definition of *A* and from the fact that $R = \exp d_F(R')$ (so $R = N_F R N_F$), the equality denoted by (2) used Equation 7, and the rightmost equality follows from the definitions of A'_F and R' (see Figure 3).

Therefore,

$$\operatorname{adj} (\Gamma) = \det (\Gamma) \cdot \Gamma^{-1}$$
$$= \det (\Gamma) \cdot (A'_F \cdot R')^{-1}$$
$$= \det (\Gamma) \cdot (R')^{-1} \cdot (A'_r)^{-1}$$

Next, we observe that:

$$\forall F \subseteq [d], \forall \vec{v}, \vec{u} \in \mathbb{Z}_N^d : \mathsf{pjct}_F(\vec{v} + \vec{u}) = \mathsf{pjct}_F(\vec{v}) + \mathsf{pjct}_F(\vec{u})$$

$$(9)$$

which implies that

$$\vec{\beta} = {}^{(1)} \operatorname{pjct}_F \left(\vec{\beta}_F \right) = {}^{(2)} \operatorname{pjct}_F \left(\vec{b}_F + A_F \cdot \vec{r} \right)$$
$$= {}^{(3)} \operatorname{pjct}_F \left(\vec{b}_F \right) + \operatorname{pjct}_F \left(A_F \cdot \vec{r} \right)$$
$$= {}^{(4)} \operatorname{pjct}_F \left(\vec{b}_F \right) + \operatorname{pjct}_F \left(A \right) \cdot \vec{r}'$$
$$= {}^{(5)} \operatorname{pjct}_F \left(\vec{b}_F \right) + A'_F \cdot \vec{r}'$$

where (1) is by the definition of $\vec{\beta}$, (2) is by the definition of $\vec{\beta}_F$, (3) follows from Equation 9, (4) follows from Equation 8 because $A_F = N_F A N_F$ and $\vec{r} = \exp d_F (\vec{r}')$, and (5) follows from the definition of A'_F .

Putting the two together, we have

$$\vec{\zeta} = \operatorname{adj} (\Gamma) \cdot \vec{\beta}$$

$$= \operatorname{det} (\Gamma) \cdot (R')^{-1} \cdot (A'_F)^{-1} \cdot \left[\operatorname{pjct}_F \left(\vec{b}_F\right) + A'_F \cdot \vec{r}'\right] \qquad (10)$$

$$= \operatorname{det} (\Gamma) \cdot (R')^{-1} \cdot \left[\vec{w}'_F + \vec{r}'\right].$$

where the right-most equality follows from the definition of \vec{w}_F' (see Figure 3).

Next, we notice that

$$\forall F \subseteq [d], \forall \vec{v}, \vec{u} \in \mathbb{Z}_N^{|F|} :$$

$$\exp d_F(\vec{v} + \vec{u}) = \exp d_F(\vec{v}) + \exp d_F(\vec{u})$$

$$(11)$$

Therefore,

$$\vec{\zeta}_F = {}^{(1)} \operatorname{expd}_F \left(\vec{\zeta} \right)$$

$$= {}^{(2)} \operatorname{expd}_F \left(\det \left(\Gamma \right) \cdot \left(R' \right)^{-1} \cdot \left[\vec{w}'_F + \vec{r}' \right] \right)$$

$$= \det \left(\Gamma \right) \cdot \operatorname{expd}_F \left(\left(R' \right)^{-1} \cdot \left[\vec{w}'_F + \vec{r}' \right] \right)$$

$$= {}^{(3)} \det \left(\Gamma \right) \cdot \operatorname{expd}_F \left(\left(R' \right)^{-1} \cdot \vec{w}'_F \right)$$

$$+ \det \left(\Gamma \right) \cdot \operatorname{expd}_F \left(\left(R' \right)^{-1} \cdot \vec{r}' \right).$$

where (1) follows from the definition of ζ , (2) follows from Equation 10, and (3) follows from Equation 11.

Next, notice that

$$\forall F \subseteq [d], \forall B \in \mathbb{Z}_{N}^{|F| \times |F|}, \forall \vec{v} \in \mathbb{Z}_{N}^{|F|} :$$

$$\exp \mathsf{d}_{F} (B \cdot \vec{v}) = \exp \mathsf{d}_{F} (B) \cdot \exp \mathsf{d}_{F} (\vec{v})$$

$$(12)$$

which implies that

$$\vec{\zeta}_{F} = {}^{(1)} \det (\Gamma) \cdot \exp d_{F} \left((R')^{-1} \cdot \vec{w}_{F}' \right) + \det (\Gamma) \cdot \exp d_{F} \left((R')^{-1} \cdot \vec{r}' \right) = {}^{(2)} \det (\Gamma) \cdot \exp d_{F} \left((R')^{-1} \right) \cdot \exp d_{F} \left(\vec{w}_{F}' \right) + \det (\Gamma) \cdot \exp d_{F} \left((R')^{-1} \right) \cdot \exp d_{F} \left(\vec{r}' \right) = {}^{(3)} \det (\Gamma) \cdot \exp d_{F} \left((R')^{-1} \right) \cdot \left[\vec{w}_{F} + \vec{r} \right]$$

where (1) was established above, (2) follows from Equation 12, and (3) follows from the definition of \vec{w}'_F and \vec{r} .

Moreover, notice that

$$\forall F \subseteq [d], \forall B, C \in \mathbb{Z}_{N}^{|F| \times |F|} :$$

$$expd_{F}(B \cdot C) = expd_{F}(B) \cdot expd_{F}(C)$$

$$(13)$$

in particular, this implies that

$$R \cdot \operatorname{expd}_{F}\left(\left(R'\right)^{-1}\right) = {}^{(1)} \operatorname{expd}_{F}\left(R'\right) \cdot \operatorname{expd}_{F}\left(\left(R'\right)^{-1}\right)$$
$$= {}^{(2)} \operatorname{expd}_{F}\left(R' \cdot \left(R'\right)^{-1}\right)$$
$$= \operatorname{expd}_{F}\left(I_{|F|}\right)$$
(14)

where (1) follows from the definition of *R*, (2) follows from Equation 13, and $I_{|F|}$ denotes the $|F| \times |F|$ identity matrix. Consequently, we have that

$$R \cdot \vec{\zeta}_F = {}^{(1)} R \cdot \det(\Gamma) \cdot \exp \mathsf{d}_F\left(\left(R'\right)^{-1}\right) \cdot \left[\vec{w}_F + \vec{r}\right]$$
$$= {}^{(2)} \det(\Gamma) \cdot \exp \mathsf{d}_F\left(I_{|F|} \times |F|\right) \cdot \left[\vec{w}_F + \vec{r}\right]$$
$$= {}^{(3)} \det(\Gamma) \cdot \left[\vec{w}_F + \vec{r}\right]$$

where (1) follows from substituting ζ_F with the value computed above, (2) follows from Equation 14, and (3) follows from the fact that \vec{w}_F, \vec{r} have 0 in every index $i \notin F$.

Finally, notice that

$$\det (\Gamma) = \det \left(A'_F \cdot R' \right) = \det \left(R' \right) \cdot \det \left(A'_F \right)$$
(15)

where we used the fact, noted above, that $\Gamma = A'_F \cdot R'$.

Putting it together, we have that

$$(\det (R'))^{-1} \cdot \left[R \cdot \vec{\zeta}_F - \det (\Gamma) \cdot \vec{R} \right]$$

$$= {}^{(1)} (\det (R'))^{-1} \cdot \left[\det (\Gamma) \cdot (\vec{w}_F + \vec{r}) - \det (\Gamma) \cdot \vec{r} \right]$$

$$= (\det (R'))^{-1} \cdot \det (\Gamma) \cdot \vec{w}_F$$

$$= {}^{(2)} (\det (R'))^{-1} \cdot \det (R') \cdot \det (A'_F) \cdot \vec{w}_F$$

$$= (A'_F) \cdot \vec{w}_F$$

where (1) follows by substituting $R \cdot \vec{\zeta}_F$ with the value computed above, and (2) follows from Equation 15. This concludes the correctness proof for the scaled ridge phase.

Correctness of the selection phase (Item 4): first, the fact that selection in SIR is computed from the set [d] instead of the current set F of features does not affect correctness, since S_1 only computes the ordinals of indices $i \in F$ (see Figure 9). This effectively means that the ordinals are computed over the restriction of the model \vec{z}_F to the set F of features that survived to the current iteration, exactly as in Iterative Ridge. Moreover, S_2 identifies the correct features to be removed (i.e., the ones with smallest weights) regardless of the fact that the weights are permuted, because applying a permutation between the weights does not affect the ordering between them. Once the smallest features are identified, S_1 inverts the permutation, so the resultant set S_{del} of features to be removed is identical to the set computed in Figure 1, conditioned on the ordinals being correctly computed. It therefore remains to show that the ordinals are correctly computed.

We now show that Ord_i is the number of z_i 's which are smaller than z_i . Recall that the "size" of z_i is measured as its distance from the nearest multiple of N, and so it measures the *absolute value* of z_i , when the elements of \mathbb{Z}_N are represented using the integers $\left\{-\frac{N-1}{2}, \ldots, -1, 0, 1, \ldots, \frac{N-1}{2}\right\}$. Since the elements of \mathbb{Z}_N are represented using the elements $0, 1, \ldots, N-1$, this corresponds to interpreting values $0 < x \leq (N-1)/2$ as "positive", and values (N - 1)/2 < x < N as "negative". We will show that $\operatorname{Ord}_{i} = |\{z_{j} : |z_{j}| < |z_{i}|\}|$. Notice that $|z_{j}| < |z_{i}|$ if and only if $z_j^2 < z_i^2$, because N was chosen such that $z_i, z_j < \sqrt{N}$ (i.e., $z_i^2, z_j^2 < N$), meaning no wrap around occurs when squaring. Therefore, $|z_j| < |z_i|$ if and only if $z_i^2 - z_i^2 > 0$. Thus, computing the ordinals can be done using the differences of squares, namely $Ord_i =$ $\left|\left\{j : z_i^2 - z_j^2 > 0\right\}\right|$. It remains to show that the computation using the masked differences of squares is correct. Fix a pair $i, j \in F, i \neq j$, fix an $r_{i,j} \in \mathbb{Z}_N$, and denote $\alpha_{i,j} := z_i^2 - z_j^2$ and $\alpha'_{i,j} := \alpha_{i,j} + r_{i,j}$. We consider four cases, based on whether $\alpha'_{i,i} < \frac{N-1}{2} + 1$ (i.e., it is "nonnegative" according to the aforementioned interpretation of positive and negative values in \mathbb{Z}_N) or not, and whether a wraparound occurred when computing $\alpha'_{i,j}$ from $\alpha_{i,j}$ and $r_{i,j}$. In all cases, we consider two subcases: (1) $\alpha_{i,j}$ is non-negative, i.e., it is positive (recall that we assume all weights z_i are unique, so $\alpha_{i,i} \neq 0$), in which case we show that $ost_{i,j} = 1$; and (2) $\alpha_{i,j}$ is negative, in which case we show that $ost_{i,j} = 0$. In the following, all computations are over \mathbb{Z} .

Case I: $\alpha'_{i,j} < \frac{N-1}{2} + 1$ and no wrap-around occurred. In this case, Negative_{i,j} = 0 and rangeMin'_{i,j} = $\alpha'_{i,j}$, rangeMax'_{i,j} = $\alpha'_{i,j} + \frac{N-1}{2} + \frac{N-1}{2}$ 1. Additionally, $\alpha'_{i,j} = r_{i,j} + \alpha_{i,j}$ because no wrap-around occurred. First, if $\alpha_{i,j}$ is positive then $0 < \alpha_{i,j} < \frac{N+1}{2} + 1$, which implies that

$$r_{i,j} <^{(2)} r_{i,j} + \alpha_{i,j} = \alpha_{i,j}' <^{(1)} r_{i,j} + \frac{N-1}{2} + 1.$$

Since $\alpha'_{i,j} < \frac{N-1}{2} + 1$ by the assumption of case I, inequality (1) always holds (because $r_{i,j} \ge 0$). Inequality (2) implies that $r_{i,j} < \alpha'_{i,j} = \text{rangeMin}_{i,j}$, so IsBigger_{*i*,*j*} = 0, and ost_{*i*,*j*} = 1 (because the second summand in its definition in Figure 9 is 1) as required. If, on the other hand, $\alpha_{i,j}$ is negative then $(N-1)/2 < \alpha_{i,j}$ so

$$\frac{N-1}{2} \le r_{i,j} + \frac{N-1}{2} < r_{i,j} + \alpha_{i,j} = \alpha'_{i,j}$$

(the left-most inequality holds because $r_{i,j} \ge 0$) which contradicts the case assumption that $\alpha_{i,j} \le (N-1)/2$. Therefore, if $\alpha_{i,j}$ is negative and no wrap-around occurred, then it cannot be the case that $\alpha'_{i,j} < \frac{N}{2} + 1$.

Case II: $\alpha'_{i,j} < \frac{N-1}{2} + 1$ and a wrap-around occurred. In this case, Negative_{i,j} = 0 and rangeMin'_{i,j} = $\alpha'_{i,j}$, rangeMax'_{i,j} = $\alpha'_{i,j} + \frac{N-1}{2} + 1$ as in case I, but $\alpha'_{i,j} = r_{i,j} + \alpha_{i,j} - N$ because a wrap-around occurred. (This is indeed the only other possibility since $r_{i,j}, \alpha_{i,j} < N$.) First, if $\alpha_{i,j}$ is positive, i.e., $0 < \alpha_{i,j} < \frac{N+1}{2} + 1$, then

$$r_{i,j} - N <^{(1)} r_{i,j} + \alpha_{i,j} - N = \alpha'_{i,j}$$

$$<^{(2)} r_{i,j} + \frac{N-1}{2} + 1 - N$$

$$= r_{i,j} - \frac{N-1}{2}.$$

Since $\alpha'_{i,j}$ is positive, then inequality (1) always holds over \mathbb{Z} . Inequality (2) implies that $\alpha'_{i,j} + \frac{N-1}{2} < r_{i,j}$, meaning rangeMax_{*i*,*j*} = $\alpha'_{i,j} + \frac{N-1}{2} + 1 \le r_{i,j}$, so IsSmaller_{*i*,*j*} = 0, and consequently ost_{*i*,*j*} = 1. If, on the other hand, $\alpha_{i,j}$ is negative then $(N-1)/2 < \alpha_{i,j} < N$ so

$$\begin{aligned} r_{i,j} - \frac{N-1}{2} &\leq r_{i,j} + \frac{N-1}{2} - N \\ &<^{(1)} r_{i,j} + \alpha_{i,j} - N = \alpha'_{i,j} \\ &<^{(2)} r_{i,j} + N - N = r_{i,j}. \end{aligned}$$

Then inequality (1) implies that $r_{i,j} < \alpha'_{i,j} + \frac{N-1}{2} < \text{rangeMax}_{i,j}$ so IsSmaller_{*i*,*j*} = 1, and inequality (2) implies that rangeMin_{*i*,*j*} = $\alpha'_{i,j} < r_{i,j}$ so IsBigger_{*i*,*j*} = 1. Together with the fact that Negative_{*i*,*j*} = 0, this implies that ost_{*i*,*j*} = 0.

Case III: $\alpha'_{i,j} \geq \frac{N-1}{2} + 1$ and no wrap-around occurred. In this case, Negative_{i,j} = 1 and rangeMin'_{i,j} = \alpha'_{i,j} - \frac{N-1}{2}, rangeMax'_{i,j} = $\alpha'_{i,j} + 1$. Additionally, $\alpha'_{i,j} = r_{i,j} + \alpha_{i,j}$ because no wrap-around occurred. First, if $\alpha_{i,j}$ is positive then $0 < \alpha_{i,j} < \frac{N+1}{2} + 1$, which implies as in case I that

$$r_{i,j} <^{(1)} \alpha_{i,j}' <^{(1)} r_{i,j} + \frac{N-1}{2} + 1$$

Inequality (1) implies that $r_{i,j} < \alpha'_{i,j} < \text{rangeMax}_{i,j}$ and so IsSmaller = 1. Inequality (2) guarantees that $\text{rangeMin}_{i,j} - 1 = \alpha'_{i,j} - \frac{N-1}{2} - 1 < r_{i,j}$ so $\text{rangeMin}_{i,j} \leq r_{i,j}$, meaning $\text{lsBigger}_{i,j} = 1$. Combined with the fact that $\text{Negative}_{i,j} = 1$, we get that $\text{ost}_{i,j} = 1$

(because of the first summand in its definition in Figure 9). If, on the other hand, $\alpha_{i,j}$ is negative then $(N-1)/2 < \alpha_{i,j}$ so

$$r_{i,j} + \frac{N-1}{2} < r_{i,j} + \alpha_{i,j} = \alpha_{i,j}'$$

namely rangeMin_{*i*,*j*} = $\alpha'_{i,j} - \frac{N-1}{2} > r_{i,j}$, so $\text{IsBigger}_{i,j} = 0$. Combined with the fact that $\text{Negative}_{i,j} = 1$ this implies that $\text{ost}_{i,j} = 0$.

Case IV: $\alpha'_{i,j} \ge \frac{N-1}{2} + 1$ and a wrap-around occurred. In this case, Negative_{*i*,*j*} = 1 and rangeMin'_{*i*,*j*} = $\alpha'_{i,j} - \frac{N-1}{2}$, rangeMax'_{*i*,*j*} = $\alpha'_{i,j} + 1$ as in case III, but $\alpha'_{i,j} = r_{i,j} + \alpha_{i,j} - N$ because a wrap-around occurred. We show first that in this case, $\alpha_{i,j}$ cannot be positive. Indeed, since $r_{i,j} < N$, if $\alpha_{i,j}$ were positive, i.e., $\alpha_{i,j} \le \frac{N-1}{2}$, then it would hold that

$$\alpha'_{i,j} = r_{i,j} + \alpha_{i,j} - N < N + \frac{N-1}{2} - N = \frac{N-1}{2}$$

which contradicts the case assumption that $\alpha'_{i,j} \ge \frac{N-1}{2} + 1$. It remains therefore to show that in case IV necessarily $|\text{sBigger}_{i,j} = 0$ or $|\text{sSmaller}_{i,j} = 0$ (this will imply that $\text{ost}_{i,j} = 0$ because Negative_{i,j} = 1). We show that $|\text{sSmaller}_{i,j} = 0$. Indeed, since $\alpha_{i,j} < N$ then

rangeMax_{*i*,*j*} - 1 = $\alpha'_{i,j}$ = $r_{i,j} + \alpha_{i,j} - N < r_{i,j} + N - N = r_{i,j}$

namely rangeMax_{*i*,*j*} $\leq r_{i,j}$ and so IsSmaller_{*i*,*j*} = 0.

Correctness of the compaction phase (Item 5): this phase only affects the computations using the compacted A, \vec{b} , namely the scaled ridge phase and the output phase. We show when discussing these phases, that resetting the entries corresponding to features that were removed has the same effect as projecting A, \vec{b} to the set of surviving features, so Item 5 does not affect correctness.

Correctness of the final output (item 6): we claim that the final output of SIR is correct (i.e., identical to that of Iterative Ridge). Indeed, as described in the analysis of Item 3 above, the scalde ridge phase outputs a scaled model $\vec{z}_F = \det (A'_F) \cdot \vec{w}_F$ (where \vec{w}_F is a permuted version of the actual output model). S_1 additionally obtains an encryption of

$$\Delta^{-1} = (\det (\Gamma))^{-1}$$

=⁽¹⁾ (det (A'_F) · det (R'))⁻¹
= det (A'_F)^{-1} · det (R')^{-1}

(where (1) follows from Equation 15) from which S_1 computes det $(A'_F)^{-1}$ (this is possible because S_1 knows R'). S_1 then recovers \vec{w}_F by computing det $(A_F)^{-1} \cdot \vec{z}_F$. We will show that \vec{w}_F contains the correct weights (as in the output model of Figure 1), but they are permuted according to P. This will imply the correctness of the output model \vec{w}^{int} because it is obtained by multiplying \vec{w}_F with $P^T = P^{-1}$, which inverts the permutation (and the correctness of the final output model \vec{w} then follows from the correctness of the rational reconstruction [23, 65]).

To see why \vec{w}_F contains the correct weights, but permuted according to *P*, recall that

$$\begin{split} \vec{w}_F &= \operatorname{expd}_F\left(\vec{w}_F'\right) = \operatorname{expd}_F\left(\left(A_F'\right)^{-1} \cdot \operatorname{pjct}_F\left(\vec{b}_F\right)\right) \\ &= {}^{(1)} \operatorname{expd}_F\left(\left(A_F'\right)^{-1}\right) \cdot \operatorname{expd}_F\left(\operatorname{pjct}_F\left(\vec{b}_F\right)\right) \\ &= \operatorname{expd}_F\left(\left(\operatorname{pjct}_F\left(A\right)\right)^{-1}\right) \cdot \vec{b}_F \end{split}$$

where (1) follows from Equation 12. Moreover, by the definition of A and \vec{b} we have:

$$A = P^{T} \left(X^{T} X + \lambda I \right) P = P^{T} X^{T} X P + P^{T} \cdot \lambda I \cdot F$$
$$=^{(1)} (XP)^{T} \cdot XP + \lambda I$$
) uses the fact that $P^{T} = P^{-1}$), and
$$\vec{b} = P^{T} X^{T} \vec{y} = (XP)^{T} \cdot \vec{y}.$$

(where (1

Therefore, performing the learning over A, \vec{b} (which are permuted versions of $X^TX + \lambda I$ and $X^T\vec{y}$, respectively) is equivalent to performing the learning over *unpermuted* A', \vec{b}' that were obtained from a *permuted* input X' = XP, namely in which the columns (i.e., features) of X were permuted. Therefore, the correctness of each ridge regression step guarntees that the output model \vec{w}_F – which contains the weights of these features – is permuted according to the same permutation P, as we set out to prove.

The next lemma states that SIR is secure against an adversary corrupting S_1 and an arbitrary subset of data owners. Intuitively, throughout the protocol execution the only unencrypted information which the adversary sees are the subsets S_{del} of features to be removed, which it obtains from S_2 in Step 3b of Figure 2. Thus, security follows from the fact (which we prove below) that these sets are perfectly simulatable because of the random permutation $P = P_1 \cdot P_2$ used to permute the data.

LEMMA 8.5 (PRIVACY WHEN S_1 IS CORRUPTED). Let $I \subseteq [m]$, let $\lambda, d \in \mathbb{N}$, and let $N \in \mathbb{N}$ which satisfies Equation 4. Then SIR is private against an adversary corrupting I and S_1 .

PROOF. To prove the lemma, we describe a simulator Sim, whose input consists of the public parameters of the protocol (i.e., κ , λ , N, D, n_1, \ldots, n_m , d, s, ℓ , rej, thr), the inputs $\{(X^j, \vec{y}^j)\}_{j \in I}$ of the corrupted data owners, and the output model $\vec{w} \in \mathbb{Q}^d$. We note that the number of iterations performed by SIR, and the number of features that should be removed in each iteration (i.e., the size of the set S_{del}), depend (deterministically) only on the public parameters d, s, rej and thr. Therefore, these values can be computed by Sim. Moreover, we note that if I = [m] then Sim can trivially emulate the entire execution of the protocol, because it is given the inputs X^j, \vec{y}^j of all data owners. Therefore, we assume that $I \subset [m]$.

Sim operates as follows.

- Initializes a set $F_0 := [d]$, and $f_0 = d$. (Intuitively, F_l and f_l will denote the set and number of features, respectively, which survived the *l*'th iteration.)
- During setup (Step 1 in Figure 2), Sim honestly generates encryption keys $(pk_N, sk_N), (pk_D, sk_D)$, and random encryptions $\mathbf{P}_2 \leftarrow \text{Enc}(pk_N, \mathbf{0}_d)$ and $\mathbf{P}_2^T \leftarrow \text{Enc}(pk_N, \mathbf{0}_d)$, where $\mathbf{0}_d$ denotes the $d \times d$ all-zeros matrix. Additionally,

for every honest DO_j, it generates a random encryption $\mathbf{A}^{j} \leftarrow \operatorname{Enc}(\operatorname{pk}_{N}, \operatorname{0}_{d})$, and $\vec{\mathbf{b}}^{j} \leftarrow \operatorname{Enc}(\operatorname{pk}_{N}, \operatorname{0}^{d})$ where $\operatorname{0}^{d}$ denotes the length-*d* all-zeros vector.

- In the *l*'th iteration (Step 3 in Figure 2), Sim simulates the encryptions which S₁ is given, as follows:
 - Simulates the messages received by S_1 during the execution of the ridge regression phase (Figure 3) by generating a random encryption $\zeta^l \leftarrow \text{Enc}(\text{pk}_N, 0^d)$, and $\Delta^l \leftarrow \text{Enc}(\text{pk}_N, 0)$.
 - Simulates the ciphertexts received by S_1 during the execution of the selection phase (Figure 9) by setting lsBigger_{*i*,*j*}, lsSmaller_{*i*,*j*}, Negative_{*i*,*j*} to be random encryptions of 0 under pk_D, for every *i*, *j* \in *F*₁, *i* \neq *j*.
 - Simulates the set S_{del}^{l} of features to be removed in the *l*'th iteration (computed in Step 3b of Figure 2) as follows. Let F_{l-1} denote the set of features that survived to the *l*'th iteration, and let v_l denote the number of features that should be removed in the *l*'th iteration (as noted above, Sim can compute v_l from the public parameters). Then Sim picks a random subset $S_{del}^{l} \subseteq F_{l-1}$ of size $\left|S_{del}^{l}\right| = v_l$. Then, it sets $F_l = F_{l-1} \setminus S_{del}^{l}$, and $f_l = f_{l-1} v_l$. It then samples a random permutation π on [d] and permutes the indicator vector of S_{del}^{l} according to π , to obtain a vector $\vec{\chi}^{\pi}$.
- During the output phase (Step 4 in Figure 2), Sim sets ζ to be d random encryptions of 0 under pk_N, where s is the sparsity parameter. It also generates a random encryption Δ⁻¹ ← Enc (pk_N, 0).

Sim outputs the view V_S consisting of pk_N, pk_D , the public parameters of the protocol, the inputs of the corrupted data owners, all ciphertexts sent to S_1 throughout the simulation, the permuted indicator vectors $\vec{\chi}^{\pi,l}$ of all sets S_{del}^l generated throughout the simulation, and the output model \vec{w} .

We now prove that the simulated and real views are computationally indistinguishable through a sequence of hybrids. We note that since the encryptions keys are identically distributed in the real and simulated views, it suffices to prove indistinguishability conditioned on them. The same holds for the random coins of S_1 .

- \mathcal{H}_0 : This is the real view V_R .
- \mathcal{H}_1 : In \mathcal{H}_1 , we replace all encryptions in V_R with encryptions of 0 (under the appropriate keys). We show that $\mathcal{H}_0 \approx \mathcal{H}_1$ follows from the security of the encryption scheme.

Indeed, let *t* denote the number of ciphertexts in V_R , then we define a sequence of hybrids $\mathcal{H}_0 = \mathcal{H}_0^0, \mathcal{H}_0^1, \ldots, \mathcal{H}_0^t = \mathcal{H}_1$, where in the *h*'th hybrid we replace the first *h* encrypted values from their value in V_R to 0. Then if $\mathcal{H}_0, \mathcal{H}_1$ are not computationally close, then there exists a pair of adjacent hybrids $\mathcal{H}_0^h, \mathcal{H}_0^{h+1}$ which are not computationally close. That is, there exists a distinguisher \mathcal{D} that distinguishes between them with non-negligible probability. We use \mathcal{D} to break the security of the FHE scheme against non-uniform distinguishers.

We define a (non-uniform) distinguisher \mathcal{D}' that has the inputs hard-wired into it. We will use the fact that the

intermediate matrices A, b, and the intermediate scaled models \vec{z} , are determined deterministically by these inputs. \mathcal{D}' operates as follows. Let v denote the value of the h + 1'th ciphertext. Notice that *v* is either determined by the inputs, or computable from the inputs by a random masking and permutation that can be sampled by \mathcal{D}' . \mathcal{D}' sends v, 0 to its distinguisher as the values on which it wants to be tested, and obtains from its challenger an encryption c of either v or 0, as well as pk_N or pk_D (depending on v, and whether it is encrypted using pk_N or pk_D in V_R). It honestly generates the secret and public encryption keys for the other pair (i.e., if it got pk_D then it generates (pk_N, sk_N) , and vice versa). Then, it uses c to generate the entire hybrid distribution: it computes A^j , \vec{b}^j as they are computed by the data owners, as well as A, \vec{b} and their intermediate compacted versions. It also computes the intermediate models \vec{z}^l , their masked version $\vec{\zeta}^l$ and the masked determinants Δ^{l} , the values $\{\text{IsBigger}_{i,j}^{l}, \text{IsSmaller}_{i,j}^{l}, \text{Negative}_{i,j}^{l}\}_{i,j \in F, i \neq j}$ generated during the selection phase in the l'th iteration, the inverse Δ^{-1} of the determinant in the final iteration, and all the subsets S_{del}^{l} . It honestly encrypts the values that appear encrypted in V_R using pk_N and pk_D , and then replaces the first h ciphertexts with encryptions of 0 (under

the appropriate key pk_N or pk_D). For the h + 1'th ciphertext, it uses c. Then, it runs \mathcal{D} and forwards its guess to the challenger of \mathcal{D}' . Notice that \mathcal{D}' perfectly emulates \mathcal{H}_0^h (if c encrypts v) or \mathcal{H}_0^{h+1} (if c encrypts 0) for \mathcal{D} , so \mathcal{D}' obtains the same non-negligible distinguishing advantage as \mathcal{D} .

Notice that \mathcal{H}_1 contains no information about the permutation *P* (because it contains no information about P_2).

 \mathcal{H}_2 : In \mathcal{H}_2 , we generate the sets S_{del}^l as follows. First, we compute *unpermuted* versions A', \vec{b}' of $\sum_{j=1}^m (X^j)^T \cdot X^j + \lambda I, \sum_{j=1}^m (X^j)^T \cdot \vec{y}^j$, respectively. Then, we iteratively compute the intermediate scaled models \vec{z}^l from the unpermuted A', \vec{b}' in Step 3a, and compact the unpermuted versions in Step 3c. For each iteration l, once \vec{z}^l has been computed, we compute the set S_{del}^l directly from it in Step 3b. Finally, we apply the permutation P to the S_{del}^l 's, and compute the $\vec{\chi}^{\pi,l}$ from them (using a freshly sampled permutation π as described in the simulation). In summary, a sample from \mathcal{H}_2 is generated by sampling according to \mathcal{H}_1 , then recomputing the S_{del}^l 's to be consistent with P. We claim that $\mathcal{H}_1 \equiv \mathcal{H}_2$. This holds because the permutation P does not affect the learned models \vec{z}^l except for permuting their coordinates. Indeed, assume that a ridge regression step is applied to some permuted inputs H, \vec{g} , and the output model is \vec{v} . Let H', \vec{g}' denote the unpermuted inputs, and

which is v, here H', g' achieve the unpermuted inputs, and \vec{v}' denote the output model of the ridge regression step on H', \vec{g}' . Then \vec{v} is exactly the vector obtained by applying P to \vec{v}' (here we also use the fact that the ridge regression step is deterministic, and consists of solving a linear equation).

Since the S_{del}^l 's are deterministically determined by the \vec{z}^l 's, this implies that $\mathcal{H}_1 \equiv \mathcal{H}_2$.

 \mathcal{H}_3 : \mathcal{H}_3 is identical to \mathcal{H}_2 , except for the way in which the S_{del}^l 's are permuted. In \mathcal{H}_3 , we set $P_0 = P$. Additionally, for every iteration l, we choose a permutation P_l which is uniformly random and independent subject to the constraint that P_l agrees with P_{l-1} on $\cup_{t=1}^{l-1} S_{del}^t$. Each S_{del}^l is permuted according to P_l before it is revealed to S_1 through the permuted indicator vector $\vec{\chi}^{\pi,l}$. (Intuitively, in each iteration we re-sample the images of the coordinates that were not yet revealed to S_1 .)

We claim that $\mathcal{H}_3 \equiv \mathcal{H}_2$. Indeed, notice that in \mathcal{H}_2 the permutation *P* could have been sampled "lazily", where in each iteration *l* we only sample the images of the coordinates in S_{del}^l . (This is because the ciphertexts in \mathcal{H}_2 no longer carry any information on *P*, so the only information revealed on *P* is from the sets S_{del}^l . However, the images of the other coordinates are not used in the *l*'th iteration, therefore their sampling can be deferred to the next iterations). An alternative (and identical) method is to sample an entire permutation in the first iteration, and then consistently resample the images of the coordinates that were not previously used (where by "consistently resample" we mean that the images that were already revealed in previous iterations remain unchanged). This resampling is exactly how the permutations are sampled in \mathcal{H}_3 .

 $\begin{array}{l} \mathcal{H}_4 \text{: In } \mathcal{H}_4 \text{, after computing the intermediate models } \vec{z}^l\text{'s, we} \\ \text{define vectors } \vec{u}^l\text{ as follows: for every } 1 \leq t \leq d\text{, if } z_t^l = 0 \\ \text{then } u_t^l = 0\text{. For the remaining coordinates, let } z_{t_1}^l, \ldots, z_{t_{f_{l-1}}}^l \\ \text{denote the non-0 coordinates of } \vec{z}^l\text{, ordered from the smallest} \\ \text{to the largest (i.e., } z_{t_1}^l < \ldots < z_{t_{f_{l-1}}}^l\text{). Here, we also use the} \\ \text{assumption that all entries of } \vec{z}^l\text{ are unique; see Remark 5.6.} \\ \text{Then for every } 1 \leq g \leq f_{l-1} \text{ we set } u_{t_g}^l = g\text{. The } S_{\text{del}}^l\text{'s} \\ \text{are then computed from the } \vec{u}^l\text{'s instead of the } \vec{z}^l\text{'s (and permuted as in } \mathcal{H}_3). \\ \end{array}$

Then $\mathcal{H}_3 \equiv \mathcal{H}_4$ because S_{del}^l depends only on *the ordering* between the entries of \vec{z}^l , and not on their actual values.

 $\begin{array}{l} \mathcal{H}_5 \text{: This is simulated view which the simulator outputs.} \\ \text{We claim that } \mathcal{H}_4 \equiv \mathcal{H}_5. \text{ The only difference between the hybrids is in how the } S_{\text{del}}^l$'s are chosen: in \mathcal{H}_4 they are computed according to the actual order of the coordinates in the intermediate model \vec{z}^l , whereas in \mathcal{H}_5 they are chosen as a random subset of the "surviving" coordinates. However, since each S_{del}^l in \mathcal{H}_4 is permuted using the permutation P_l , which is uniformly random and independent conditioned on being identical to P_{l-1} on $\cup_{t=1}^{l-1} S_{\text{del}}^l$, S_{del}^l is also uniformly random in \mathcal{H}_4 .

The next lemma states that SIR is secure against an adversary corrupting S_2 and an arbitrary subset of data owners. Its proof will use observations from the proof of Lemma 8.5 (regarding how to simulate the sets S_{del}^l), and an observation of [29], that the masking perfectly hides the data matrix and response vectors (see Lemma 8.7 below). We note that Giacomelli et al. [29] proved this for a single

execution of ridge regression, and we show that it extends to the multiple iterations of SIR as well, due to the per-iteration masking.

LEMMA 8.6 (PRIVACY WHEN S_2 IS CORRUPTED). Let $I \subseteq [m]$, let $\lambda, d \in \mathbb{N}$, and let $N \in \mathbb{N}$ which satisfies Equation 4. Then SIR is private against an adversary corrupting I and S_2 , for input matrices X which are invertible.

The proof of Lemma 8.6 will use the following Lemma from [29, Lemma 1].

LEMMA 8.7 (LEMMA 1 FROM [29]). Let $N, d \in \mathbb{N}$, and let $A \in GL(d, \mathbb{Z}_N)$ and $\vec{b} \in \mathbb{Z}_N^d$. Then the random variable defined by picking a random $R \leftarrow GL(d, \mathbb{Z}_N)$ and a random $\vec{r} \leftarrow \mathbb{Z}_N^d$ and outputting $(A \cdot R, \vec{b} + A \cdot \vec{r})$ is uniformly distributed over $GL(d, \mathbb{Z}_N) \times \mathbb{Z}_N^d$.

Roughly (and somewhat inaccurately), we will use Lemma 8.7 to claim that the masked matrices Γ_F , and masked vectors $\vec{\beta}_F$, which S_2 obtains in each ridge regression step, are distributed uniformly over $GL(|F|, \mathbb{Z}_N) \times \mathbb{Z}_N^{|F|}$. This, however, does not follow directly from Lemma 8.7, because in SIR the masked $\Gamma_F, \vec{\beta}_F$ are extended versions of such a matrix and vector. In the following lemma, we use Lemma 8.7 to show that $\Gamma_F, \vec{\beta}_F$ in SIR are distributed as extensions of uniformly random values in $GL(|F|, \mathbb{Z}_N)$ and $\mathbb{Z}_N^{|F|}$, respectively.

LEMMA 8.8. Let $N, d \in \mathbb{N}$, let $F \subseteq [d]$ of size f = |F|, and let $A' \in GL(f, \mathbb{Z}_N)$ and $\vec{b} \in \mathbb{Z}_N^f$. Then the random variable defined by picking a random $R' \leftarrow GL(f, \mathbb{Z}_N)$ and a random $\vec{r}' \leftarrow \mathbb{Z}_N^f$ and outputting

$$\left(\operatorname{expd}_{F}\left(A'\right)\cdot\operatorname{expd}_{F}\left(R'\right),\operatorname{expd}_{F}\left(\vec{b}\right)+\operatorname{expd}_{F}\left(A'\right)\cdot\operatorname{expd}_{F}\left(\vec{r}'\right)\right)$$

is uniformly distributed over $\operatorname{expd}_F(\operatorname{GL}(f,\mathbb{Z}_N)) \times \operatorname{expd}_F(\mathbb{Z}_N^f)$.

PROOF. Let $M := \exp d_F(A') \cdot \exp d_F(R')$, and $\vec{v} = \exp d_F(\vec{b}) + \exp d_F(A') \cdot \exp d_F(\vec{r}')$. We need to prove that $M = \exp d_F(M')$, $\vec{v} = \exp d_F(\vec{v}')$ for $M' \in \mathbb{Z}_N^{f \times f}, \vec{v}' \in \mathbb{Z}_N^f$ where (M', \vec{v}') is uniformly distributed in $GL(f, \mathbb{Z}_N) \times \mathbb{Z}_N^f$. Notice first that by Equation 12, we have:

$$\vec{v} = \exp d_F \left(\vec{b} \right) + \exp d_F \left(A' \right) \cdot \exp d_F \left(\vec{r}' \right)$$
$$= \exp d_F \left(\vec{b} \right) + \exp d_F \left(A' \cdot \vec{r}' \right)$$

which by Equation 11 implies that $\vec{v} = \exp d_F (\vec{b} + A' \cdot \vec{r}')$. Second, notice that by Equation 13, it holds that $M = \exp d_F (A') \cdot \exp d_F (R') = \exp d_F (A' \cdot R')$. Therefore, it remains to prove that $(A' \cdot R', \vec{b} + A' \cdot \vec{r}')$ is uniformly distributed over $GL(f, \mathbb{Z}_N) \times \mathbb{Z}_N^f$. This follows directly from Lemma 8.7 by setting d := f.

PROOF OF LEMMA 8.6. To prove the lemma, we describe a simulator Sim. As in the proof of Lemma 8.5, the input of Sim consists of the public parameters of the protocol (i.e., κ , λ , N, D, n_1 , ..., n_m , d, s, ℓ , rej, thr), the inputs $\{(X^j, \vec{y}^j)\}_{j \in I}$ of the corrupted data owners, and the output model $\vec{w} \in \mathbb{Q}^d$. We assume without loss of generality that $I \subset [m]$. Also, similar to the proof of Lemma 8.5, Sim can compute the number of iterations performed

by SIR, and the number of features that should be removed in each iteration (i.e., the size of the set S_{del}), since these depend (deterministically) only on the public parameters.

Sim operates as follows.

- (1) Initializes a set $F_0 := [d]$, and $f_0 = d$. (Intuitively, F_l and f_l will denote the set and number of features, respectively, which survived the *l*'th iteration.)
- (2) During setup (Step 1 in Figure 2), Sim uses the randomness of S_2 to determine the encryption keys (pk_N, sk_N) , (pk_D, sk_D) .
- (3) In the *l*'th iteration (Step 3 in Figure 2), Sim simulates the encryptions which S_2 receives, as follows:
 - (a) Messages during ridge regression phase (Figure 3): generates a random invertible matrix $\Gamma^{l\prime} \leftarrow \operatorname{GL}(f_{l-1}, \mathbb{Z}_N)$ and a random vector $\vec{\beta}^{l\prime} \leftarrow \mathbb{Z}_N^{f_{l-1}}$, sets $\Gamma^l = \exp d_{F_{l-1}} \left(\Gamma^{l\prime} \right), \vec{\beta}^l = \exp d_{F_{l-1}} \left(\vec{\beta}^{l\prime} \right)$, and randomly encrypts them as $\Gamma^l \leftarrow \operatorname{Enc} \left(\operatorname{pk}_N, \Gamma^l \right)$, and $\vec{\beta}^l \leftarrow \operatorname{Enc} \left(\operatorname{pk}_N, \vec{\beta}^l \right)$.
- (b) Messages during the feature selection phase (Figure 9): for every *i*, *j* ∈ *F*_{*l*-1}, *i* ≠ *j*, generates a random df^{*l*}_{*i*,*j*} ← Z_N, and encrypts df^{*l*}_{*i*,*j*} ← Enc (pk_N, df^{*l*}_{*i*,*j*}). Additionally, picks a random permutation Π_{*l*} on {0, 1, ..., *f*_{*l*-1} − 1} (recall that *f*_{*l*-1} is the number of features that survived to the beginning of the *l*'th iteration), computes the vector Ord^{*l*} obtained by applying Π_{*l*} on (0, 1, ..., *f*_{*l*-1} − 1)^{*T*}, and randomly encrypts Ord^{*l*} ← Enc (pk_D, Ord^{*l*}).
- (c) Simulates the set S_{del}^l of features that were removed in the l'th iteration (computed as part of the selection phase in Step 3b in Figure 2) as follows. Let v_l denote the number of features that should be removed in the l'th iteration (as noted above, Sim can compute v_l from the public parameters), and recall that F_{l-1} is the set of features that survived to the beginning of the l'th iteration. Then Sim picks a random subset $S_{del}^l \subseteq F_{l-1}$ of size $\left|S_{del}^l\right| = v_l$. Then, it sets $F_l = F_{l-1} \setminus S_{l-1}^l$, and $f_l = f_{l-1} v_l$.
- it sets F_l = F_{l-1} \ S^l_{del}, and f_l = f_{l-1} v_l.
 (4) During the output phase (Step 4 in Figure 2), Sim generates encryptions of masked matrix and vector Γ^l, β^l as described in Step 3a above. Additionally, it uses the model w ∈ Q^d which it obtained as input, to determine the model w' ∈ Z^d_N which corresponds to w (through the rational reconstruction),¹⁷ and randomly encrypts w' ← Enc (pk_N, w').

Sim outputs the view V_S consisting of the randomness of S_2 (which determines pk_N, pk_D), the public parameters of the protocol, the inputs of the corrupted data owners, all ciphertexts sent to S_2 throughout the simulation, all the sets S_{del}^l generated throughout the simulation, and the output model \vec{w} .

We now prove that the simulated and real views are identically distributed through a sequence of hybrids.

¹⁷More specifically, Sim does the following for every coordinate $1 \le t \le d$: let $\vec{w}_t = p/q$, then $\vec{w}_t := pq^{-1} \mod N$.

 \mathcal{H}_0 : This is the real view V_R .

 \mathcal{H}_1 : In \mathcal{H}_1 , we replace the values $df_{i,j}^l$ for $i, j \in F_{l-1}, i \neq j$ generated in all iterations (in the selection phase of Figure 9) with uniformly random values in \mathbb{Z}_N .

We claim that $\mathcal{H}_0 \equiv \mathcal{H}_1$. Indeed, this follows from the perfect security of the One-Time Pad (OTP). Notice that the masking $r_{i,j}$ used to create $df_{i,j}$ in Figure 9 effectively OTP-encrypts these values – i.e., $(z_i^l)^2 - (z_j^l)^2$ – with fresh keys, since the computations (i.e., adding the masks) are performed in \mathbb{Z}_N . More specifically, let *t* denote the number of such values $df_{i,j}^l$ in V_R , then we define a sequence of hybrids $\mathcal{H}_0 = \mathcal{H}_0^0, \mathcal{H}_0^1, \dots, \mathcal{H}_0^t = \mathcal{H}_1$, where in the *h*'th hybrid we replace the first *h* values from their value in V_R to random values as described above. Then each pair of adjacent hybrids are identically distributed from the security of OTP (in particular, even non-uniform distinguishers cannot distinguish between the hybrids, which is what we need in this case to deduce indistinguishability of the hybrids $\mathcal{H}_0, \mathcal{H}_1$ from the indistinguishability of a single OTP ciphertext), and consequently $\mathcal{H}_0 \equiv \mathcal{H}_1$.

 \mathcal{H}_2 : In \mathcal{H}_2 , for every iteration l we replace the pair $\left(\Gamma^l, \beta^l\right)$ generated in the ridge regression phase of Figure 3 with extensions of a uniformly random matrix in GL (f_{l-1}, \mathbb{Z}_N) and a uniformly random vector in $\mathbb{Z}_N^{f_{l-1}}$ (respectively). That is, in each iteration we choose $\vec{v} \leftarrow \mathbb{Z}_N^{f_{l-1}}$ and $M \leftarrow$ $GL(f_{l-1}, \mathbb{Z}_N)$ (these values are chosen independently of each other, and of all other values), and set $\vec{b}^l := \exp d_F(\vec{v})$ and $\Gamma^l = \exp d_F(M)$.

Then $\mathcal{H}_1 \equiv \mathcal{H}_2$ by Lemma 8.8. Indeed, Lemma 8.8 guarantees that (Γ^l, β^l) are uniformly distributed in $\exp d_F (\operatorname{GL} (f_{l-1}, \mathbb{Z}_N)) \times \exp d_F (\mathbb{Z}_N^{f_{l-1}})$. (Here, we use the fact that all intermediate matrices A_F are invertible, which holds because X is invertible and so $(X, \vec{y}) \in \mathcal{T}_{\operatorname{Inv}, N, d, \lambda, F_1, \dots, F_k}$, see Remark 8.2.) In particular, this indistinguishability holds for non-uniform distinguishers so similar to the previous set of hybrids, we can define a sequence of hybrids starting from \mathcal{H}_1 and ending with \mathcal{H}_2 in which we replace the pairs (Γ^l, β^l) one at a time. Then each pair of consecutive hybrids are indistinguishable by Lemma 8.8 and consequently $\mathcal{H}_1 \equiv \mathcal{H}_2$.

 \mathcal{H}_3 : \mathcal{H}_3 is identical to \mathcal{H}_2 , except for the way in which the permuted ordinal vectors $\vec{Ord}^{\Pi_l,l}$ are computed. In \mathcal{H}_3 , for every iteration l we pick a random permutation $\hat{\Pi}_l$ and set $\vec{Ord}^{\Pi_l,k}$ to be the vector obtained by applying $\hat{\Pi}_l$ to $(0, 1, \dots, f_{l-1} - 1)^T$.

We claim that $\mathcal{H}_3 \equiv \mathcal{H}_2$. Indeed, the intermediate model \vec{z}^l computed in the *l*'th iteration has f_{l-1} unique coordinates (see Remark 5.6). Therefore, the unpermuted ordinal vector \vec{Ord}^l computed in the *l*'th iteration is a length- f_{l-1} vector that contain each value in $\{0, 1, \ldots, f_{l-1} - 1\}$ exactly once. Put differently, it is a permutated version of the vector $(0, 1, \ldots, f_{l-1} - 1)^T$, obtained by applying some permutation Π'_l . Applying the permutation Π_l to \vec{Ord}^l is therefore

equivalent to applying the permutation $\Pi'_l \circ \Pi_l$ on the vector $(0, 1, \ldots, f_{l-1} - 1)^T$. Since the set of permutations over $\{0, 1, \ldots, f_l - 1\}$ is a group, and Π_l is uniformly random, then $\Pi'_l \circ \Pi_l$ is a uniformly random permutation, namely it is distributed identically to the permutation $\hat{\Pi}_l$ used in \mathcal{H}_3 . In summary, both \mathcal{H}_2 and \mathcal{H}_3 generate the ordinal vector $\vec{Ord}^{\Pi_l,l}$ by applying a random permutation to the vector $(0, 1, \ldots, f_{l-1} - 1)^T$. Moreover, in all other respects the hybrids are identical. Therefore $\mathcal{H}_3 \equiv \mathcal{H}_2$.

Notice that \mathcal{H}_3 contains no information about the permutation P (because it contains no information about P_1 , since we have already replaced all values - such as A, \vec{b} - that depend on it). Moreover, it contains no information about the intermediate A_F, \vec{b}_F (except for what can be deduced from the inputs of the corrupted parties).

The remaining hybrids are defined similarly to \mathcal{H}_3 , \mathcal{H}_4 and \mathcal{H}_5 in the proof of Lemma 8.6, and the proof of indistinguishability is also similar:

 \mathcal{H}_4 : \mathcal{H}_4 is identical to \mathcal{H}_3 , except for the way in which the S_{del}^l 's are computed. Specifically, in \mathcal{H}_4 , we change the way in which the S_{del}^l 's are computed. We set $P_0 = P$; and for every iteration l, we choose a permutation P_l which is uniformly random and independent subject to the constraint that P_l agrees with P_{l-1} on $\cup_{t=1}^{l-1} S_{del}^t$. Each S_{del}^l is permuted according to P_l before it is used to compute F_l in \mathcal{H}_4 . (Intuitively, in each iteration we re-sample the images of the coordinates that were not yet used to compute S_{del}^l 's which were revealed to S_2 .)

We claim that $\mathcal{H}_4 \equiv \mathcal{H}_3$. Indeed, neither of the hybrids contain any information about *P*. Moreover, as in the proof of Lemma 8.5, the permutation *P* could have been sampled "lazily" in \mathcal{H}_3 , and is therefore sampled identically to \mathcal{H}_4 .

- \mathcal{H}_5 : \mathcal{H}_5 is identical to \mathcal{H}_4 in the proof of Lemma 8.5, and the proof of indistinguishable from the previous hybrid is identical to the proof in Lemma 8.5. (Here, we also rely on the fact that the hybrids contain no information about A_F , \vec{b}_F .) \mathcal{H}_6 : This is simulated view output by the simulator.
- We claim that $\mathcal{H}_6 \equiv \mathcal{H}_5$. There are two differences between the hybrids: (1) how the encrypted model \vec{w} is computed; and (2) how S_{del}^l is are sampled. Regarding (2), these two methods of sampling S_{del}^l induce identical distributions, as proven in Lemma 8.5 (in the proof that $\mathcal{H}_4 \equiv \mathcal{H}_5$). As for (1), in \mathcal{H}_5 , \vec{w} is computed from the previously-calculated intermediate models, whereas in \mathcal{H}_6 it is reconstructed from the output model in \mathbb{Q}^d . However, since the output model in \mathbb{Q}^d is obtained from \vec{w} through rational reconstruction, the correctness of the rational reconstruction algorithm guarantees that the same model is obtained in both hybrids.

Remark 8.9. In SIR, the output model is revealed to all parties. As discussed in Section 2.5, this involves some privacy risks, which may be alleviated by revealing the output model only to some of the parties. We now explain why SIR remains secure in this setting. Consider first the variant in which S_2 does not reveal the output model to any party. This variant is still secure against

an adversary corrupting S_1 and a strict subset of data owners. Indeed, the simulator in the proof of Lemma 8.5 does not use the output model in the simulation, so the same proof works also when S_1 does not learn the output model. Next, consider the variant in which only an external output party O learns the output model. The difference from the previous variant is that now S_2 also doesn't learn the model. We claim that SIR is still secure against an adversary corrupting S_2 and a strict subset of data owners. Indeed, in the proof of Lemma 8.6, the simulator uses the output model only to generate the final message sent from S_1 to S_2 in Step 2 of Figure 8. The proof can be adjusted to the variant in which S_2 does not learn the output model as follows. First, the simulator does not receive the output model as output, and is not required to simulate the final message from S_1 to S_2 (this message does not exist in this variant). Second, hybrid \mathcal{H}_6 is not needed in the proof, since \mathcal{H}_5 is already exactly the simulated view. Finally, the view of the external party O can be simulated exactly as the integral model \vec{w}^{int} is generated from the rationally-reconstructed output model in the proof of Lemma 8.6.

9 COMPLEXITY ANALYSIS

In this section we analyze the performance of SIR, and in particular the number of iterations and communication rounds, its runtime and communication complexity.

Communication is counted in the number of ciphertexts exchanged, and S_1 performs all operations over ciphertexts. The CRT is implemented using $O(\log N)$ primes. Ciphertext size is polynomial in the security parameter. We denote $\tau = 1 - \text{rej}$. The analysis is for rej, $\tau = O(1)$, as is the case in our experiments.

The following corollary summarizing the main complexity measures of SIR.

COROLLARY 9.1. Let d, thr, ℓ , m, $n \in \mathbb{N}$ and $\lambda \ge 0$ be as in Figure 2. Then SIR has the following complexity properties:

• To execute Step 1 of SIR (the data merging and permuting step, Figure 6), S₁ evaluates a circuit (consisting solely of addition gates) of size

$$O(md^2 \lceil \frac{d^2}{\mathsf{sl}} \rceil (\ell + \log(n^2 + \lambda) + \log d))$$

• To execute Steps 3-4 of SIR, S_1 evaluates a circuit of size

$$O\left(d(d + \operatorname{thr}^2) \left\lceil \frac{d}{\mathrm{sl}} \right\rceil (\ell + \log(n^2 + \lambda) + \log d)\right)$$

and multiplicative depth

$$O\left(\log d + \log(\ell + \log(n^2 + \lambda))\right).$$

• The communication complexity between S₁ and S₂ throughout the execution is

$$O\left(d\cdot (d+\mathsf{thr}^2)\cdot \lceil \frac{d}{\mathsf{sl}}\rceil\cdot \left(\ell+\log(n^2+\lambda)+\log d\right)\right)$$

ciphertexts.

• There are $O(\log d + \text{thr})$ rounds of communication.

To prove the corollary, we analyze the number of iterations, and the complexity of the different steps in SIR. We first bound the number of iterations when executing SIR. LEMMA 9.2 (NUMBER OF ITERATIONS). Let d > thr > s > 0 be parameters as in Figure 2. Then SIR performs $O(\log d + \text{thr})$ iterations, and the number of features at the onest of each of these iterations is: $d, d \cdot \tau, d \cdot \tau^2, \dots, d \cdot \tau^r, d \cdot \tau^r - 1, \dots s$, where $\tau = 1 - \text{rej}$ and $r = \lceil \log_{\tau} \frac{\text{thr}}{d} \rceil$.

The proof is straight forward:

PROOF. Let d_i be the number of features at the onset of the *i*-th iteration, where $d = d_1$ is the number of features in the input to SIR. Then the *i*-th iteration removes $d_i \cdot \text{rej}$ features if $d_i > \text{thr}$ and it removes a single feature otherwise. Since $\tau = 1 - \text{rej}$, the number of features at the onset of each iteration is $d, d \cdot \tau, d \cdot \tau^2, \dots, d\tau^r, d \cdot \tau^r - 1, \dots s + 1$, where $r = \lceil \log_{\tau} \frac{\text{thr}}{d} \rceil$.

We next turn to analyze the data owner complexity.

LEMMA 9.3 (DATA OWNER COMPLEXITY). Let $n_j, d, N \in \mathbb{N}$ be parameters as in Figure 2, let $sl \in \mathbb{N}$ be the number of slots in a ciphertext, and let $X^j \in \mathbb{R}^{n_j \times d}$, and $\vec{y}^j \in \mathbb{R}^{n_j}$ be the input of data owner DO_j . Then the running time of DO_j in SIR is $O(d^2 \cdot n_j)$, and shes sends $O(d[\frac{d^2}{cl}] \log N)$ ciphertexts.

PROOF. We note that DO_j , $j \in [m]$ participates only in the data uploading and merging phase (Figure 6) where she computes $A^j = (X^j)^T \cdot X^j$ and $\vec{b}^j = (X^j)^T \cdot \vec{y}^j$. The dominant part is computing and uploading A^j . Computing A^j is done in plaintext and takes $O(d^2 \cdot n_j)$ time. Since we use the encoding and the packing of [4], A is encoded using d rotated copies. These d rotated copies of Aconsist of $O\left(d \cdot \lceil \frac{d^2}{sl} \rceil\right)$ elements in total. Since each element is CRTencoded using $O(\log N)$ ciphertexts, the total communication is $O(d\lceil \frac{d^2}{sl} \rceil \log N)$ ciphertexts.

We note that using a different encoding (e.g. as described in [2, 42]) can reduce the time and communication requirement from the data owner on the expense of increasing the complexity for S_1 .

LEMMA 9.4 (DATA PREPARATION). Let $d, N, m \in \mathbb{N}$ be parameters as in Figure 2. Then during the data merging and permuting step (Figure 6), S_1 performs $O(md \lceil \frac{d^2}{sl} \rceil \log N)$ operations over ciphertexts.

PROOF. The dominant part is merging the A^j 's into A, and permuting A. Computing $A = \sum_{j=1}^{m} A^j$ requires $O(md\lceil \frac{d^2}{sl}\rceil)$ operations on elements of A. Permuting A is done by O(1) matrix multiplications where each matrix multiplication takes $O(d\lceil \frac{d^2}{sl}\rceil)$ operations on elements of A. (This is because A has $\lceil \frac{d^2}{sl}\rceil$ elements, and is represented using d rotated copies, since we use the encoding of [4].)

Each element of *A* is CRT-encoded with $O(\log N)$ different plaintext moduli. This yields a total running time of $O(d\lceil \frac{d^2}{sl} \rceil \log N)$.

LEMMA 9.5. (Single SIR iteration) Let d_i be the number of features at the onset of the *i*-th iteration, N be as in Figure 2, and sl be the number of slots in a ciphertext. Then in the *i*-th iteration:

• S_1 evalutes a circuit of size $O(d_i \lceil \frac{d_i}{s!} \rceil \log N + d_i^2 (\log \log N + \lceil \frac{\log N}{s!} \rceil))$ and depth $O(\log \log N)$.

- \bullet The communication complexity between \mathcal{S}_1 and \mathcal{S}_2 is $O(d_i^2 \lceil \frac{\log N}{sl} \rceil + d_i \lceil \frac{d_i}{sl} \rceil \cdot \log N).$ • There are O(1) rounds of communication.

PROOF. A single SIR iteration is composed of a scaled ridge regression step, in which a vector w that satisfies Aw = b (for the given A, \vec{b} is computed, and of a ranking step where the elements of *w* are ranked.

By [4, Thm. 5], the ridge step can be implemented using a circuit of size $O(d_i \lceil \frac{d_i^2}{s!} \rceil \cdot \log N)$ with no multiplications (i.e., the multiplicative depth is 0), and with a single communication round, communicating $O(\lceil \frac{d_i}{sl} \rceil \log N)$ ciphertexts.

To rank the (squared) elements of w (Figure 9), SIR first computes the masked differences $\Delta_{i,j} = w_i^2 - w_j^2 + r_{i,j}$ for all i > j, where $r_{i,j}$ is chosen uniformly at random. Next, S_1 and S_2 communicate to compute ranges in binary representation. S_1 then compares these ranges to $r_{i,j}$ to determine whether $w_i^2 > w_j^2$ for all *i*, *j*, and then computes the ranks. We now analyze: (i) computing $\Delta_{i,i}$, for i > j, (ii) computing the ranges and (iii) ranking the elements of w.

Computing $\Delta_{i,j}$. The elements of *w* are packed in the slots of a ciphertext *C* (if $d_i > \text{sl}$ this is simulated using $\lceil \frac{d_i}{sl} \rceil$ ciphertexts). Subtracting a rotation of *C* by *j* slots (C - Rotate(C, j)) yields $\Delta_{i,i+j}$, for $i = 1, 2, \dots, d_i - j$. Repeating this for $j = 1, 2, \dots, d_i - 1$ gives $\Delta_{i,j}$ for all i > j. This step is performed by S_1 using a circuit of size $O(d_i \lceil \frac{d_i}{s!} \rceil \log N)$ and multiplicative depth 0. (There are d_i vectors Rotate(*C*, *j*), each represented using $\lceil \frac{d_i}{sl} \rceil \log N$ ciphertexts.)

Computing ranges. To compute the ranges for a pair i, j, S_1 sends $\Delta_{i,j}$ to S_2 . S_2 then decrypts $\Delta_{i,j}$ (which are masked differences), computes the ranges - in binary representation - and sends the encryptions of the ranges to S_1 . Each value in these ranges can be represented with $\lceil \log_2 N \rceil$ bits (padded with 0s if needed). The bits are encoded in the slots of a single ciphertext (where if $\log N > \text{sl}$ then this is simulated using $\lceil \frac{\log N}{|\mathsf{s}|} \rceil$ ciphertexts). Therefore, computing the ranges can be done with a single communication round in which $O(d_i \lceil \frac{d_i}{s_i} \rceil \log N +$ $d_i^2 \lceil \frac{\log N}{|\mathsf{sl}|} \rceil$ ciphertexts are communicated. (The first term is due to communicating the $(\Delta_{i,j})_{i < j}$ from S_1 to S_2 , where the second is due to communicating the ranges.)

Computing ranks. To compute the ranks, S_1 computes an indicator $\chi_{i,j}$ of whether $w_i^2 < w_j^2$, namely $\chi_{i,j} = 1$ if $w_i^2 < w_j^2$, otherwise $\chi_{i,j} = 0$. $\chi_{i,j}$ is computed by comparing the appropriate ranges to $r_{i,j}$. This comparison is done using a circuit of size $O(\log \log N + \lceil \frac{\log N}{s} \rceil)$ and depth $O(\log \log N)$. Computing the ranks of all d_i features is done by computing all indicators $\chi_{i,j}$ and summing rank_i = $\sum_{j \neq i} \chi_{i,j}$. Therefore, the entire circuit has size $O(d_i^2(\log \log N + \lceil \frac{\log N}{s} \rceil))$ and depth $O(\log \log N)$.

Putting everything together gives the bounds specified in the theorem statement. П

We note that an alternative method for computing the ranks is to use a sorting network (e.g., bitonic or Batcher sort). In this case, the ranking protocol (which would replace parts of the protocol of Figure 9) can be done using a circuit of size $O(d^2 \log^2 d \log \log N)$ and depth $O(\log^2 d \log \log N)$.

THEOREM 9.6 (SIR ANALYSIS). Let d, s, N, rej, thr be as in Figure 2. Then SIR has the following complexity properties:

• To execute Step 1 of SIR (the data merging and permuting step, Figure 6), S_1 evaluates a circuit (consisting solely of addition gates) of size

$$O(md\lceil \frac{d^2}{\mathsf{sl}}\rceil\log N)$$

• To execute Steps 3-4 of SIR, S_1 evaluates a circuit of size

$$O((d + \text{thr}^2) \lceil \frac{d}{\text{sl}} \rceil \log N + O\left((d^2 + \text{thr}^3)(\log \log N + \lceil \frac{\log N}{\text{sl}} \rceil)\right)$$

and multiplicative depth $O(\log \log N)$.

• The communication complexity between S_1 and S_2 throughout the execution is

$$O\left((d + \mathsf{thr}^2) \lceil \frac{d}{\mathsf{sl}} \rceil \log N + (d^2 + \mathsf{thr}^3) \lceil \frac{\log N}{\mathsf{sl}} \rceil\right)$$

ciphertexts.

• There are $O(\log d + \text{thr})$ rounds of communication.

PROOF. The complexity of the circuit which S_1 evaluates in Step 1 of SIR is described in Lemma 9.4. Let $I = O(\log d)$ denote the number of iterations in the first phase of SIR (i.e., when each iteration removes a rej-fraction of features). By Lemma 9.2, the number of features at the onset of the iterations of SIR are: d, d. $\tau, d \cdot \tau^2, \dots, d \cdot \tau^r, d \cdot \tau^r - 1, \dots s$, where $\tau = 1 - rej$, and $d\tau^r = 1$ O(thr). Substituting these numbers in the formula describing the complexity of a single iteration in Lemma 9.5, we have that the size of the entire circuit (evaluating all iterations) is

$$\begin{split} O\left(\sum_{i=1}^{I} (d\tau^{i} \lceil \frac{d\tau^{i}}{\mathsf{sl}} \rceil \log N + d^{2}\tau^{2i} (\log \log N + \lceil \frac{\log N}{\mathsf{sl}} \rceil))\right) \\ &+ \sum_{\delta=\mathsf{s}}^{\mathsf{thr}} (\delta \lceil \frac{\delta}{\mathsf{sl}} \rceil \log N + \delta^{2} (\log \log N + \lceil \frac{\log N}{\mathsf{sl}} \rceil)) \end{split}$$

rearranging, we get

$$\begin{split} O\!\left(d\log N \cdot \sum_{i=1}^{I} \tau^{i} \lceil \frac{d\tau^{i}}{\mathrm{sl}} \rceil + d^{2}(\log\log N + \lceil \frac{\log N}{\mathrm{sl}} \rceil) \cdot \sum_{i=1}^{I} \tau^{2i} \\ &+ \log N \sum_{\delta=s}^{\mathrm{thr}} \delta \lceil \frac{\delta}{\mathrm{sl}} \rceil + (\log\log N + \lceil \frac{\log N}{\mathrm{sl}} \rceil) \sum_{\delta=s}^{\mathrm{thr}} \delta^{2} \right) \\ &\leq O\left(d\log N \cdot \sum_{i=1}^{\infty} \tau^{i} \lceil \frac{d\tau^{i}}{\mathrm{sl}} \rceil\right) \\ &+ O\left(d^{2}(\log\log N + \lceil \frac{\log N}{\mathrm{sl}} \rceil) \cdot \sum_{i=1}^{\infty} \tau^{2i}\right) \\ &+ \log N \sum_{\delta=s}^{\mathrm{thr}} \mathrm{thr} \lceil \frac{\mathrm{thr}}{\mathrm{sl}} \rceil + (\log\log N + \lceil \frac{\log N}{\mathrm{sl}} \rceil) \sum_{\delta=s}^{\mathrm{thr}} \mathrm{thr}^{2} \end{split}$$

using the formula for an infinite geometric sum, we get

$$O(d \log N \cdot \lceil \frac{d}{\mathsf{sl}} \rceil + d^2 (\log \log N + \lceil \frac{\log N}{\mathsf{sl}} \rceil)) + \log N \cdot \mathsf{thr}^2 \lceil \frac{\mathsf{thr}}{\mathsf{sl}} \rceil + (\log \log N + \lceil \frac{\log N}{\mathsf{sl}} \rceil) \cdot \mathsf{thr}^3 \leq O((d + \mathsf{thr}^2) \lceil \frac{d}{\mathsf{sl}} \rceil \log N + O\left((d^2 + \mathsf{thr}^3) \left(\log \log N + \lceil \frac{\log N}{\mathsf{sl}} \rceil\right)\right)$$

where in the last inequality we use the fact that d > thr.

Since every iteration starts with fresh ciphertexts (because in each iteration S_2 generates fresh ciphertexts) then circuit depth is $O(\log \log N)$. The analysis of the communication complexity is similar to the analysis for the circuit size, and yields

$$O((d + \operatorname{thr}^2) \lceil \frac{d}{\operatorname{sl}} \rceil \log N + (d^2 + \operatorname{thr}^3) \lceil \frac{\log N}{\operatorname{sl}} \rceil).$$

Corollary 9.1 now follows by plugging-in the value of *N* from Equation 4:

PROOF OF COROLLARY 9.1. By Equation 4 we have that $\log N = O\left(d(\ell + \log(n^2 + \lambda) + \log d)\right)$. Plugging this into Theorem 9.6, immediately gives the stated size of the circuit computed by S_1 in Step 1 of SIR. Using the fact that d >thr, $x \ge \log x$ for every x > 0, and $\left\lceil \frac{d(\ell + \log(n^2 + \lambda) + \log d)}{sl} \right\rceil < \left\lceil \frac{d}{sl} \right\rceil (\ell + \log(n^2 + \lambda) + \log d)$, we get that S_1 evaluates a circuit of size

$$O\left(d \cdot (d + \mathsf{thr}^2) \cdot \lceil \frac{d}{\mathsf{sl}} \rceil \cdot \left(\ell + \log(n^2 + \lambda) + \log d\right)\right)$$

and depth

 $O\left(\log d + \log(\ell + \log(n^2 + \lambda))\right)$

and the communication between S_1 and S_2 consists of

$$O\left(d \cdot (d + \mathsf{thr}^2) \cdot \lceil \frac{d}{\mathsf{sl}} \rceil \cdot \left(\ell + \log(n^2 + \lambda) + \log d\right)\right)$$

ciphertexts.

10 SYSTEM AND EMPIRICAL EVALUATION

We implemented the SIR protocol into a system and ran experiments on real data to evaluate its concrete complexity and correctness (i.e., that output models match cleartext results). Furthermore, we compare the iterated ridge approach (as securely realized in SIR) to the filter and truncation approaches for feature selection, showing it significantly outperforms the latter .

10.1 Data

The Cancer Genome Atlas (TCGA), a landmark cancer genomics program, molecularly characterized over 20,000 primary cancer and matched normal human tissue samples spanning 33 cancer types. The program integrates contributions from many researchers coming from diverse disciplines and from multiple institutions. The data spans genomic, epigenomic, transcriptomic, and proteomic data measured on the aforementioned samples. We used a small portion of this data for our experiments. Concretely we used randomly selected portions of one of the breast cancer transcriptomics data matrices. We start with a matrix with features normalized to lie in [-1, 1] with 3-digit precision. The matrix has 781 rows (samples/instances) and > 10K columns (features, representing genes profiled). Each (i, j) entry of the matrix represents the expression level of gene j in sample i. We use \mathcal{D} to denote this full TCGA breast cancer expression profiling matrix. The TCGA data also includes 781 TIL levels for this cohort, as part of additional data to support biological and clinical interpretation. TIL levels quantify tumor infiltrating immune cells in the (tumor) samples.

To run an experiment with *d* features, that is adequate for our current running time complexity, we chose to work with 4, 10, 40 and 100 features. To generate a dataset for a given *d*, we randomly (uniformly) selected *d* features (columns of \mathcal{D}) to be the columns of the data matrix *X*. We then set the target vector \vec{y} to be the vector of TIL levels. To support *bias*, we add an extra column of 1's to *X*. When relevant, we evenly distributed the 781 samples between the data owners. As described in the protocol, each data owner computed $A = \lfloor 10^{\ell} X^T X \rceil$ and $\vec{b} = \lfloor 10^{\ell} X^T \vec{y} \rceil$, which also scaled and rounded the values. Note that in our experiments on *d* features, *A* and \vec{b} are therefore of dimensions $(d + 1) \times (d + 1)$ and (d + 1), respectively. Solving for \vec{y} continues in the same way as in Protocol 2 (computing adjugate and determinant of a $(d+1) \times (d+1)$ matrix), but computing the ranks of the features involves only *d* features because the bias is not treated as a selectable feature.

10.2 Comparing IR to Filter, Ridge and Lasso, on Our Example Dataset

To quantify the advantage of iterative ridge (IR) over the filter, ridge, Lasso, and truncated ridge (truncate) approaches (the baseline algorithms) we ran experiments in the clear. Data was generated as detailed in Section 10.1. We generated 1000 data sets, each consisting of d = 100 features selected uniformly at random. The 781 samples are 80/20 split into training and test. For each of the 1000 datasets we ran IR, filter, ridge, Lasso and truncated ridge on the training data. IR selects 10 features as specified in Figure 1. Filter selects the top 10 features according to their Pearson correlation to the target vector (on the training data); ridge regression was executed with the regularization parameter set to its default value $\lambda = 1$ while in Lasso, we set it to get the same number of non-zero feature as in IR; truncate executes ridge regression and then removes features with low weight to maintain the 10 features with the highest weights. In each one of these cases we then obtain the actual model (coefficients) and apply it to the test data. In Figure 10 we compare the resulting MSEs for IR to the other approaches. The histogram represents the observed results for the percentage difference:

$$\Delta = \frac{\text{MSE(baseline)} - \text{MSE(IR)}}{\text{MSE(IR)}} \cdot 100$$
(16)

We clearly observe a significant performance advantage for IR in our example gene expression dataset. Concretely, IR outperforms (non-negative Δ) filter, ridge, Lasso and truncate in 100.0%, 77.4%, 93.9% and 100.0% of the experiments, respectively. The mean percentage difference is 27.23%, 16.43%, 27.06% and 17.08%, respectively. We repeated the experiment, selecting 8 out of *d* = 40 features, showing

similar results: IR outperforms filter, ridge, Lasso and truncate in 100.0%, 79.5%, 93.5% and 100.0% of the experiments, respectively.

10.3 System Implementation Details

Ring size. To obtain correctness in SIR, the ring sizes needed for our experiments exceeded the sizes currently supported by FHE libraries. For example, for inputs with 40 features, we require a ring of size 1,260 bits, while current libraries support rings of size less than 64 bits. To support such large ring sizes, we encoded the input using the Chinese Remainder Theorem (CRT) with several distinct 30-bit primes, as was used in [4].

Permuting the input. In a preliminary step S_1 and S_2 participate in a protocol to permute the input: $A = (P_1 \cdot P_2)^T \cdot T^1 \cdot (P_1 \cdot P_2)$ (for T^1 an intermediate value, see Figure 6), where P_1 and P_2 are random permutation matrices chosen by S_1 and S_2 , respectively. There are several ways to compute this step. One option is for S_1 to perform all the computations using FHE (with multiplicative depth 2). Another option – which is the one used in our implementation – is to utilize a protocol between S_1 and S_2 that uses masking and requires only additive homomorphism. This step is executed only once at the onset of the protocol, and its running time is inconsequential compared to the total protocol runtime (e.g., with 40 features, this step took 1,152 seconds out of 84,690 seconds. See Table 2).

Ranking weights. To decide which entries of \vec{w} to remove in each iteration, we compute a full ranking over the entries (see Figure 9). This involves comparing pairs of entries. Our experiments show that the majority of the running time is spent in this step. For example, the total real time of SIR when d = 40 was 84,690 seconds, while computing the ranks took 76,184 seconds (see Table 2). To Compare a single pair w_i, w_j of entries, S_1 compares $w_i^2 - w_j^2 + r_{ij}$ to ranges received from S_2 , to determine whether $w_i^2 - w_i^2 \in [0, N/2]$ (and hence $w_i \ge w_i$). In our implementation S_1 performed all $\binom{d}{2}$ comparisons. An alternative is to use an approach similar to Bitonic sort (or Batcher sort, see [5]). However, while a sorting approach performs only $\frac{d}{2} \begin{pmatrix} \lceil \log_2 d \rceil \\ 2 \end{pmatrix}$ comparisons, it is less amenable to parallelization. Specifically, the sorting approach is faster when $\lceil \frac{1}{\text{CPUs}} \binom{d}{2} \rceil > \lceil \frac{d/2}{\text{CPUs}} \rceil \cdot \binom{\lceil \log_2 d \rceil}{2}$, so for the number of features and CPUs in our experiments the naive all-pairs approach was faster. We stress that to utilize the Bitonic sort alternative (which would be faster for larger d's), one only needs to implement the comparison step using Bitonic sort, making our protocol flexible, efficiently supporting both regimes of *d*.

Cryptographic Libraries. At a high level, the steps of our protocol can be categorized into two types with different characteristics:

- *Ranking steps.* Computing the ranks of features in \vec{w} , when the entries are given in binary. These steps involve a subcircuit of large depth for sorting *d* large numbers in binary representation, e.g. 1,260-bit numbers when d = 40. This requires a key that supports large-depth circuits, and possibly also bootstrapping. We note that the plaintext modulo needed by these steps is relatively small.
- *CRT steps* consist of all other steps, and operate over numbers that are represented using CRT. The CRT steps

of the protocol require only *additive* homomorphism, but necessitate multiple (co-prime) plaintext moduli to implement the CRT. Preferably, these plaintext moduli should be as large as possible, because larger moduli mean less elements in the CRT encoding.

We used two different FHE libraries (with different schemes) to implement these two types of steps. For ranking we use BGV in HElib [38] 2.1.0, because it supports bootstrapping (unlike SEAL). For CRT steps we use B/FV in SEAL [55] 4.0, in which it is easier to configure keys for multiple plaintext moduli. Switching between the two libraries and schemes is done by S_2 , who generated the keys (pk_N , sk_N) and (pk_D , sk_D) in HElib and SEAL respectively. In detail, in HElib [38] 2.1.0 we initialize the keys while setting the plaintext modulo to 17^2 , and the cyclotomic polynomial degree to 78,881. This resulted in ciphertexts with 7,000 slots, supporting a multiplicative depth of 28, as well as bootstrapping. In SEAL we initialize the keys while setting the cyclotomic polynomial degree to 8,192, a chain length of 7, chain bits of 25 and prime bits of 30. This resulted in a ciphertext with 4,096 slots that supports additive homomorphism.

10.4 Evaluation Setup

We executed SIR (Protocol 2) on the data generated from TCGA described in Section 10.1, and measured performance of the data owners and servers. We executed two types of experiments: end-to-end and single-iteration experiments. In all experiments rej was set to 10% and the ring size N was determined by Equation 4.

End-to-end experiments measure performance when executing the entire SIR protocol, including the data encoding and all iterations, until producing a sparse model that selects *s* out of the *d* initial features from a dataset of *n* records distributed amogst *m* data owners. We ran end-to-end experiments on the following *m*, *n*, *d*, *s* parameters: (1) TCGA data with number of features (*d*, *s*) varying between (4, 2), (10, 4), (40, 8) and (*m*, *n*) = (10, 781); (2) Synthetic data with number of records *n* =1568, 6272, 12544, 50176, 100352, 200704, 401408, 802816 and (*m*, *d*, *s*) = (10, 10, 2); (3) Synthetic data with number of data owners *m* = 100, 200, . . . , 1000 and (*n*, *d*, *s*) = (802816, 10, 2).

Single-iteration experiments measure performance when executing a single iteration (Protocol 2, Step 3, i.e., computing scaled ridge, ranking the features, and removing the features with the smallest weight) on different values of *d*. Concretely, we take $5 \le d \le 40$ features, in increments of 5.

Hardware. In all experiments, we used a single virtual machine to simulate the data owners, S_1 and S_2 . The virtual machine had 100 Xeon 2.7GHz CPUs and 900 GigaBytes of RAM. These are off-the-shelf standard CPUs. Nonetheless, each data owner was executed on a *single CPU*, to capture the prevalent usecase in which data owners are computationally significantly weaker than the servers.

What we measured. We report the total runtime, as well as the runtime of each sub-task in SIR: *encrypt* (Figure 5, Step 2); *permute* (Figure 6, Step 3); *mask* (Figure 3, Step 2); *unmask* (Figure 3, Step 5);



Figure 10: IR outperforms filter, ridge, Lasso and truncate in terms of the resulting MSE on the test data, for our example datasets (1000 random test sets generated from the breast cancer gene expression data matrix from TCGA [60]). The histograms depict the number of experiments (y-axis) for which we observe a given value for the percentage difference Δ of Eq 16 (x-axis).

(d, s, N)	RAM	encrypt	permute	mask	unmask	decrypt	solve	pair diffs	ranges	ranks	total
$(4, 2, 2^{180})$	21	1 (×2)	11 (×84)	1 (×100)	5 (×78)	1 (×100)	7 (×70)	1 (×10)	7 (×4)	1510 (×5)	2142 (×4)
$(10, 4, 2^{360})$	43	80 (×2)	105 (×80)	3 (×100)	41 (×60)	11 (×87)	56 (×70)	2 (×24)	23 (×17)	4540 (×24)	5718 (×21)
$(40, 8, 2^{1260})$	134	80 (×2)	1152 (×52)	76 (×58)	1408 (×35)	152 (×92)	1584 (×40)	66 (×77)	336 (×65)	76184 (×79)	84690 (×74)
m 11 a D		1 \			(0.2) 1		/			1 1	

Table 2: Runtime (seconds), memory consumption (GB), and parallelization ratio (in parenthesis) in end-to-end SIR executions.

(d, N)	mask	unmask	decrypt	solve	pair diffs	ranges	ranks
$(5, 2^{210})$	2 (×29)	3 (×42)	1 (×7)	3 (×61)	1 (×3)	5 (×4)	806 (×10)
$(10, 2^{360})$	1 (×100)	20 (×53)	4 (×80)	24 (×64)	1 (×10)	11 (×25)	939 (×43)
$(15, 2^{510})$	3 (×57)	44 (×44)	1 (×130)	42 (×40)	1 (×23)	39 (×47)	2319 (×63)
$(20, 2^{660})$	5 (×46)	77 (×34)	4 (×100)	72 (×29)	1 (×51)	45 (×58)	4147 (×87)
$(25, 2^{810})$	5 (×56)	139 (×32)	4 (×86)	158 (×38)	1 (×97)	38 (×67)	7104 (×90)
$(30, 2^{960})$	6 (×64)	274 (×36)	26 (×91)	323 (×44)	2 (×65)	55 (×63)	13093 (×87)
$(35, 2^{1110})$	7 (×57)	371 (×29)	9 (×90)	394 (×32)	3 (×72)	57 (×63)	11728 (×95)
$(40, 2^{1260})$	9 (×58)	473 (×30)	24 (×91)	519 (×34)	5 (×72)	54 (×70)	19354 (×91)

$(10, 2^{360})$	1568	97	7407
$(10, 2^{420})$	6272	112	7391
$(10, 2^{450})$	12544	113	7373
$(10, 2^{480})$	50176	114	7367
$(10, 2^{510})$	100352	112	7312
$(10, 2^{540})$	200704	126	8166
$(10, 2^{540})$	401408	133	8209
$(10, 2^{570})$	802816	139	8048

п

solve

ranks

Table 3: Runtime (seconds) in a single SIR iteration, and parallelization ratio (in parenthesis).

Table 4: Runtime (seconds) of SIR on a growing number of records (n).

decrypt (Figure 3, Step 3);¹⁸ solve (Figure 3, Step 4);¹⁹ pair diff (Figure 9, Step 1); ranges (Figure 9, Step 2); ranks (Figure 9, Step 3). Furthermore, we report the *parallelization ratio*, which is the ratio between runtime when executing the computation on a single CPU (as measured by the operating system) vs. the runtime on our 100cores system. Intuitively, this indicates the average number of CPUs that were busy performing the task, where a higher ratio means the task is more amenable to parallelization as it utilize more CPUs (the maximum being 100).

10.5 SIR Performance

Tables 2-3 summarize the performance exhibited in the end-toend experiments and the single-iteration experiments, respectively. Table 4 presents SIR runtime on various database sizes.

runtime in our end-to-end (single-iteration) experiment on d = 40. Increasing the number of records by 512× (from 1568 to 802,816 records) led to runtime increase by less than 10% (from 7,504 to 8,187 seconds). Increasing the number of data owners by 10× (from 100 to 1000 data owners) affects only the time to homomorphically merge the data (Step 1 in Figure 8), that indeed increased by ten-fold (from 10 to 102 seconds); however this has only a minor influence on the overall runtime (which is dominated by the 8048 seconds to rank features), and so a ten-fold increase in the number of data owners led to an increase in the total runtime by roughly 1%.

Runtime. The total runtime is dominated by the time it takes to

rank the weights. For example, ranking took 91% (94%) of the total

(d, N)

RAM. The RAM usage of our system was significantly lower than the allocated RAM, ranging from 21GB to 134GB. Furthermore, our experiments indicate that the RAM requirement grows sub linearly in the measured values for *d* (e.g. from 43GB when d = 10 to 134GB when d = 40). This is because our ciphertexts had more slots than

¹⁸Recall that we encoded the numbers using CRT; the time reported here includes the CRT decoding time.

¹⁹Here the computations are over \mathbb{Z}_N , where N is large (e.g., 1, 260-bits for 40 features).

needed for our encodings (for small *d*'s), so the total number of ciphertexts grew only mildly in *d*.

Parallelization. As *d* grows, most tasks become more parallelizeable. In particular, the ranking task –which dominates the bulk of the runtime– is "embarrassingly" parallelizable since we make all $\binom{d}{2}$ comparisons, which can be executed in parallel. We note that if we had an *unlimited number of CPUs*, the ranking runtime would essentially be the time of a single comparison. For example, when $(d, N) = (40, 2^{1260})$ (cf. Table 3 bottom row), our ranking utilized an average of 91 CPUs (the system had 100 CPUs), whereas having access to $\binom{d}{2}$ CPUs is expected to improve the ranking runtime by a factor of $\binom{40}{2}/91 \approx 8.6$, thus improving the total runtime by 6×.

We remark that an alternative way to compute the ranking would be to homomorphically evaluate an oblivious sorting algorithm (e.g., bitonic sort). Bitonic sort would require less comparisons – $O(d \log^2 d)$; but this type of sorting admits a circuit structure having $O(\log^2 d)$ layers, which is less amenable to parallelization. For 40 features and 100 CPUs, this alternative would have higher runtime.

11 CONCLUSIONS

We develop and analyze a privacy-preserving multi-party protocol for running sparse linear regression in a federated learning setup, based on an iterated ridge framework. Our protocol enjoys rigorous security, and scales favorably with the number of records and data owners. Moreover, our protocol naturally gives a privacypreserving ridge truncation protocol, which is less accurate (as we have shown), but simpler and faster, and therefore may be preferred in some cases.

The design of our protocol is based, amongst other consideration, on certain potential attacks that can be developed when partial or intermediate information is leaked. In particular, we show in Section 7 that revealing the order in which features are removed can be used to infer non-trivial information about the input data. We also extend this attack to other leakages such as revealing intermediate models or the determinant of the intermediate *A* matrices. As explained in Sections 2.5 and 7, SIR is susceptible to inversion attacks. Determining the exact extent to which such attacks are harmful, and devising measures to protect against them, are left for future work.

We mostly focus on the case $d \le n$. In particular, our security proof addresses this case and furthermore requires the matrix A to be invertible. Our protocol can be adjusted for settings with d > nby combining SIR with a faster learning method (e.g., filter) to first partially reduce the number of features. One can similarly perform a preparatory step to handle the case in which X is not full rank.

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