Information-Theoretic Secure Sketch for Noisy Sources of Low Entropy

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Abstract. Secure sketch produces public information of its input \( w \) without revealing it, yet, allows the exact recovery of \( w \) given another value \( w' \) that is close to \( w \). Therefore, it can be used to reliably reproduce any error-prone secret sources (i.e., biometric) stored in secret storage. However, some sources have lower entropy compared to the error itself, formally called “more error than entropy”, a standard secure sketch cannot show its security promise perfectly to these kinds of sources. Besides, when same input is reused for multiple sketches generation, the complex error process of the input further results to security uncertainty, and offer no security guarantee. This paper focuses on secure sketch. We propose a new technique to generate re-usable secure sketch. We show security to low entropy sources and enable error correction up to Shannon bound via unique decoding. Our security defined information theoretically with Shannon entropy over some worst case random error distribution adding to the input source. In particular, given a sketch of size \( n \), our new technique is capable of providing security guarantee (minimum of single bit) for all input distributions with min-entropy at least \( \log(n+1)+1 \).

Keywords: Secure Sketch · Error Correction · Information Theory · Fuzzy Extractor

1 Introduction

Traditional cryptography systems rely on uniformly distributed and recoverable random strings for secret. For example, random passwords, tokens, and keys, all are commonly used secrets for deterministic cryptographic applications, i.e., encryption/decryption and password authentication. These secrets must present exactly on every query for a user to be authenticated and get accessed into the system. Besides, it must also consist of high enough entropy, thus making it very long and complicated, further resulted in the difficulty in memorizing it. On the other hand, there existed plentiful non-uniform strings to be utilized for secrets in practice. For instance, biometrics (i.e., human iris, fingerprint) which can be used for human recognition/identification purpose. Similarly, long passphrase (S. N. Porter, 1982 [1]), answering several questions for secure access (Niklas Frykholm et al., 2001 [2]) or personal entropy system (Ellison et al., 2000 [3]),
and list of favorite movies (Juels and Sudan, 2006 [4]), all are non-uniformly distributed random strings that can be utilized for secrets.

As a solution by utilizing non-uniform input for secrets, it raises several security and practicability concerns. Firstly, since it is not truly random and uniform, this increased the risk where an adversary may easily be guessed and compromised it, thus reveals the underlying secret. Secondly, most of the available non-uniform strings are not exactly recoverable. Therefore, they cannot be used for a typical deterministic cryptographic application. For instance, human biometric data, it is well understood that two biometric readings sourced from the same individual are rarely to be identical. Additionally, precise answer to multiple questions or entering a password through keyboard consistently, from time to time, would be a challenge for human memory although the provided answers are likely to be similar.

Nevertheless, these non-uniform measurements that always selected by human or naturally existing are believed to offer a higher entropy than human-memorable password. Especially, higher security level can be achieved by using longer/more complex human biological measurements, i.e., fingerprint, voice, retina scan, handwriting signature, and others. (N. Frykholm, 2000 [2]), (Jain et al., 2016 [5]). Most importantly, it is memory-free and somewhat difficult to steal, or loss compared to using external key storage, e.g., smart card, token, keys.

The availability of non-uniform information prompted the generation of uniform random string from non-uniform materials. Started by Bennette et al., (1988) [6], identified two major approaches to derive a uniform string from noisy non-uniform sources. The first approach is information-reconciliation, by tolerating the errors in the sources without leaking any information. The second approach refers to the privacy amplification, which converts high entropy input into a uniform random input. The information-reconciliation process can be classified into interactive (includes multi messages) and non-interactive (only includes single message) versions. For non-interactive line of work, it has been first defined by Dodis et al., (2004) [7] called the fuzzy extractor. Likewise, the fuzzy extractor used two approaches to accomplish the task, which is the secure sketch - for error tolerance, and a randomness extractor - for uniform string generation.

In this paper, we only focus on the secure sketch. Secure sketch is more demanding because it allows information-reconciliation, e.g., exact recovery of a noisy secret while offering security assurance to it. Moreover, a secure sketch can be easily extended to fuzzy extractor for uniform string generation by using a randomness extractor. There existing various secure sketch constructions in the literature. Some notable constructions involved the code-offset construction proposed by Juels and Wattenberg (1999) [8] that operates perfectly over hamming matrix space. This work generates a sketch through encoding a uniform string with error correction code, then leaving an offset via performing XOR operation with a noisy string. The uniform string can be reproduced by another noisy string by means of error tolerance, provided the error level is lower than...
a specified threshold. Besides, Juels and Sudan (2006) [4] have also proposed another construction for metric other than hamming called the fuzzy vault. An improved version of the fuzzy vault is proposed by Dodis et al., (2004) [7], and also the Pin-sketch that relies on syndrome encoding/decoding with \( t \)-error correcting BCH code \( C \), which works well for non-fixed length input over a universe \( U \).

1.1 Limitations in Stantard Secure Sketch

We here review some existing issues in the secure sketch.

**More error than entropy:** The secure sketch must contain some information about the sources to tolerate the errors. More generally, given a point (some value) \( w \), the sketch would allow the acceptance of its nearby point \( w' \) within distance \( t \). Therefore, if an adversary can predict an accepting \( w' \) with noticeable probability, the sketch must reveal \( w \) to the adversary with noticeable probability as well. The tension between the security and error tolerance capability is very strong. Precisely, the security is measured in term of the residual (min-) entropy, which is the starting entropy of \( w \) minus the entropy loss. Often, a larger tolerance distance is needed to tolerate more errors. However, exercising larger tolerance distance will offer greater advantages to the adversary in predicting \( w' \). In the end, the residual entropy becomes lower by the increment of \( t \). This consequences to an upper bound of the tolerance distance translated to a lower bound on the entropy loss of the input sources. Such event is much worsening for some non-uniform sources with low min-entropy, especially, when the sources consist of more error than entropy itself. Since the source entropy rate is lower than the error rate, simply deducting the entropy loss from the sources’ min-entropy always output a negative value, hence, show no security. One typical example of a source with more error than entropy refers to the commonly known biometric feature - IrisCode (Daugman, 2006) [9]. The IrisCode is said to provide entropy of 249 bits. Whereas, the IrisCodes generated from the same user of each 2048 bits have shown far more than 249 bits of errors. Therefore, this more error than entropy problem is indeed restricting the usage of a secure sketch from all kind of available sources.

**Distribution uncertainty:** The predictability of nearby point \( w' \) within distance \( t \) is not merely entropically connected, but it is also closely tied to the distribution of the sources. A source can be described using a family of distributions \( W = \{ W_1, \ldots, W_\gamma \} \). Given a source under a random distribution \( W \in W \) where all points are far apart, the probability for an adversary to predict any nearby point \( w' \in W' \) within distance \( t \) will be small. The entropy loss of the sketch would be bounded that is proportional to \( t \). In particular, given a source with min-entropy \( m \), a larger distance between the points implies higher min-entropy, thus, the entropy loss due to error tolerance over distance \( t \) can be compensated by the high min-entropy. This entropy loss is crude if one has set \( t > m \) for error tolerance over distance \( t \) (e.g., more error than entropy).

Fuller et al., (2013) [10] showed that under the event when the input distribution is precisely known, the crude entropy loss can be avoided by the measure-
The notion of fuzzy min-entropy, which defined as the min-entropy with maximized chances for a variable of $W$ within distance $t$ of $w'$:

$$H_{t,\infty}^{\text{fuzz}}(W) \overset{\text{def}}{=} -\log \left( \max_{w'} \Pr[W \in B_t(w')] \right)$$

where $B_t(w')$ denoted a hamming ball of radius $t$ around $w'$. Conceivably, the fuzzy min-entropy is equivalent to the residual entropy, which is at least the min-entropy minus the loss signified by the hamming ball $B_t(w')$ of radius $t$,

$$H_{\infty}^{\text{fuzz}}(W) \geq H_{\infty}(W) - \log(B_t(w')).$$

Realistically, it is imprudent to assume the source distribution is precisely known, especially for high entropy sources. The adversary may have higher computation power to model and exam the distribution compared to the designer. Such event always refer to the distribution uncertainty, where the fuzzy min-entropy notion is necessary and sufficient only when the security is defined computationally. Viewed this way, one cannot assure information theoretical security without precise knowledge over the input worst-case distribution $W$ (i.e., distance between points is minimum).

**Reusability** Reusability property is introduced by Boyen (2004) [13]. Given a user comes with a noisy input $w$ (i.e., biometric), the user may enroll $w$ for different applications. Each time the user enrolls using $w$, he/she must provide slightly different reading $w_i$ due to the error. Therefore, different sketches $ss_i$ and keys $R_i$ can be generated for different applications respectively. The security property of individual sketches and keys should hold with all existing sketches $ss_1, ss_2, \ldots, ss_{\gamma}$. In fact, this property has been well studied for current constructions of secure sketch and fuzzy extractor, but many of them do not satisfied reusability [13] [14] [15] [16].

### 1.2 Overview Results

We highlighted our main results and contributions as follow:

**Average fuzzy min-entropy:** To correct more errors, larger error tolerance distance is desired. Unfortunately, larger tolerance distance renders higher probability of success in predicting $w'$ within more considerable distance around $w$. Thus, security diminution cannot be avoided. Our new result has considered the notion of average fuzzy min-entropy, which is basically the fuzzy min-entropy with different error tolerance distances.

To be more precise, consider different variable $\Phi$ and $\Phi'$. To allow error tolerance within a larger distance $t > t'$, one must maximize the total probability mass of $\Phi$ with larger ball $B_t(\phi')^2$ around the string $\phi' \in \Phi'$. Suppose $\Phi$ is correlated with some variable $W$, if the adversary finds out $W \notin B_{t'}(w')$, then

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1. The reusability property is different to the unlinkability property [11] [12]. Unlinkability property prevents an adversary from differentiating whether two enrollments correspond to the same physical source, which is not focused in this work.
2. Sometime, we omit $\phi'$ or $w'$ to describe the ball $B_t$ or $B_{t'}$, when they are not depend upon their center $\phi'$ and $w'$ respectively
the predictability of $\Phi$ becomes $E_{w' \in W} \left[ \max_{\phi'} \Pr[\Phi \in B_t(\phi') \mid W \notin B_{t'}(w')] \right]$. On average, the average fuzzy min-entropy is:

$$\tilde{H}_{t,\infty}^{\text{fuzzy}}(\Phi \mid W \notin B_{t'}(w')) \overset{\text{def}}{=} -\log \left( E_{w' \in W} \left[ \max_{\phi'} \Pr[\Phi \in B_t(\phi') \mid W \notin B_{t'}(w')] \right] \right)$$

Intuitively, average fuzzy min-entropy refers to the fuzzy min-entropy of some variable $\Phi$ defined by a larger hamming ball $B_t$, where only the points outside an existing smaller ball $B_{t'}$ are considered. Substantial fuzzy min-entropy implies more errors can be corrected over larger tolerance distance $t > t'$, hence, higher entropy loss. In this sense, average fuzzy min-entropy $\tilde{H}_{t,\infty}^{\text{fuzzy}}(\Phi \mid W \notin B_{t'}(w'))$ reveals the entropy loss from the fuzzy min-entropy of $W$ over smaller tolerance distance $t'$. Since the quantity of entropy loss must lower bounded to the entropy of the source to show meaningful security, the average fuzzy min-entropy manifested the minimum entropy loss from a source over the worst case $t'$ (minimum $t'$). In view of this, the average-fuzzy min-entropy is useful for better monitoring the loss of the min-entropy while providing optimal resilience.

**Unique-decoding toward Shannon bound**: Our construction uses two error correction codes, one act as ‘inner’ code $C^*$ to encode a noisy input string and yield the codeword $c^* \in C^*$; another one act as ‘outer’ code to encode the noisy version of $c^*$ and yield another codeword $c \in C_\xi$. In addition to this, we adopted the principle of Locality Sensitive Hashing (LSH) to generate a resilient vector pair (trivially, a pair of longer strings with resilience property) for sketching and recovery. The resilient vector resembles additional random error adding to the codeword $c$ encoded by a the ‘outer’ code $C_\xi$. We show that in such particular setting, one is able to uniquely decode the corrupted codewords, and correcting total error rate up to Shannon bound.

**New security bound for secure sketch**: Info. theoretic secure sketch is always desired. Because it does not introduce additional assumption of computational limits to the attacker, thus offers better security assurance. Most importantly, info. theoretic secure sketch eliminates the distribution uncertainty issue by showing security to all family of input distribution via min-entropy measurement. Notwithstanding its security robustness, the cost imposed by info. theoretic secure sketch to the source entropy requirement is too high, which is at least half of the input length itself [17]. It means that if the entropy is less than half of its input length, it achieves nothing where the underlying secret can be easily revealed due to exhaustive entropy loss caused by error tolerance. We constructed a pair of sketching and recover algorithm. Formal correctness and security proof have been given to show that it satisfies the properties of an info. theoretical secure sketch. Given a sketch of size $n$, our new construction is capable of showing security at least one bit for any input distribution with min-entropy $H_\infty(W) \geq \lceil \log(1/\beta) \rceil + 1$, for some probability $\beta > 0$ under the special scenario when $\lceil \log(1/\beta) \rceil = \log(n + 1)$, without distribution uncertainty.

**Reusable secure sketch**: Apart from this, the new construction offers extra security property, which is the reusability. We show that the error included
implicitly allows reusability. We defined our reusability in information theoretical sense, with a group of computational unbounded adversaries. Our results imply the flexibility of independent re-enrollment of a single source with multiple providers, yet offer security assurance to each of them, as long as the error is kept within specified range. Our reusability emphasizes the case when the providers are not communicating with each other hence it supports security to all of them individually.

1.3 Techniques

Some notation need to know: This work focus on binary hamming metric where $\mathcal{M}_1 = \{0,1\}^k$, and $\mathcal{M}_2 = \{0,1\}^n$ denoted two different sizes of metric spaces with $n > k^*$. The distance between different binary string $w$ and $w'$ is the binary hamming distance (e.g., the number of disagree elements) denoted as $\|w \oplus w'\|$ where $\|\|$ is the hamming weight that count the number of non-zero elements, and $\oplus$ is the addition modulo two operation (XOR). Besides, the error rate in between the input $w, w' \in \mathcal{M}_1$ is denoted as $\|w \oplus w'\| (k^*)^{-1}$ which is simply their normalized hamming distance. For error correction code notation, since we are more interested in tolerating the errors of a codeword $c^*$ instead of its min-distance $d$, we used $t$ instead of $d$ to explicitly represent an $[n, k, t]_2$ binary code $C_{\xi}$ with the tolerance rate denoted as $\xi = t/n$, where $\xi \in (0, 1/4)$. Besides, we also refer to another $[n^*, k^*, t^*]_2$ binary code $C^*$ with $k^* < n^* \leq k < n$. In particular, we focus on the case when both $C^*$ and $C_{\xi}$ are come with min-distance $d^* \geq 2t^* + 1$ and $d \geq 2t + 1$ respectively. At the same point, we let $t_{(+)} = \lfloor (\xi + \epsilon)k^* \rfloor$ and $t_{(-)} = \lfloor (\xi - \epsilon)k^* \rfloor$ to describe two different error tolerance distances over the smaller binary metric space $\{0,1\}^{k^*}$, with some error parameter $\epsilon > 0$.

Overview of idea: Suppose Alice wishes to conceal a noisy non-uniform string $w \in \{0,1\}^k$ while allows exact recovery of $w$ from another noisy string $w' \in \{0,1\}^k$ that is close to $w$. Then, Alice has to generate a secure sketch which able to tolerate the error in $w'$. To do so, we invoke the uses of error correction code for conventional secure sketch generation. Our scheme requires two error correction codes, an $[n^*, k^*, t^*]_2$ ‘inner’ code $C^*$ is chosen over $\{0,1\}^{k^*}$, and another $[n, k, t]_2$ ‘outer’ code $C_{\xi}$ is chosen over $\{0,1\}^n$, where $k^* < n^* \leq k < n$. Firstly, Alice encodes $w$ using the ‘inner’ code $C^*$ to output a codeword $c^*$. Then, $c^*$ is use to generate a noisy string $v^* \in \{0,1\}^n$ with $w$ and error $e$, yielding $v^* = (0^{k-n^*} \|c^*\|) \oplus (0^{k-k^*} \|w\|)$ (with zeros padding at front of $c^*$ and $w$). After that, $v^*$ is being encoded by the ‘outer’ code $C_{\xi}$ to output the final codeword $c \in C_{\xi}$. Alice then conceals $c$ by generating a sketch $ss = c \oplus \delta$ which is then made public and leaving the offset $\delta$ in the clear. The offset $\delta$ is characterized by a pair of resilient vectors $\phi, \phi' \in \{0,1\}^n$, which is generated from a pair of noisy strings $w_e', w_e \in \{0,1\}^n$, i.e., $w_e = w \oplus e$ through LSH. The resilient vectors offer resilience for the recovery of $w$ from $w'$ if $\|\delta\| \leq t$ and $\|w \oplus w'\| \leq t^*$.

Likewise the code-offset construction [8], our idea is conceptual simpler but comes with some crucial differences in term of operations. Firstly, the code-offset
construction concealing a random and uniform string (called as the witness of \( w \)) and involved only single encoding stage; our construction concealing a non-uniform input \( w \) that has gone through two different encoding stages with \( C^* \), and \( C_\xi \). Secondly, despite the code-offset construction does not limit to particular types of error correction code (i.e., not necessary to be linear), the sketch size is always bounded by the size of the input \( w \). Comparatively, in our case, Alice is free to choose any error correction code where the sizes of the concealed object and output sketch are not bounded but parametrized by the selected \([n^*,k^*,t^*]_2 \) code \( C^* \) and the \([n,k,t]_2 \) code \( C_\xi \). Thirdly, of course, our operation comes with additional random errors adding to the input \( w \) and \( w' \) during sketching and recovery.

For resilient vector generation, we only focus on a particular LSH family called hamming-hash [18]. The hamming hash is considered as one of the easiest ways to construct an LSH family by bit sampling technique. Since it will be a core element in our proposal, it is worth sketching in details on how it works.

**Hamming hash strategy.** Let \( [k^*] = \{1, \ldots, k^*\} \). For Alice with \( w \in \{0, 1\}^{k^*} \) and Bob with \( w' \in \{0, 1\}^{k^*} \). Alice and Bob agreed on this strategy as follow:

1. They are told to each other a common random integer \( N \in [k^*] \).
2. They separately output ‘0’ or ‘1’ depend upon their private string \( w \) and \( w' \), i.e., Alice output ‘1’ if the \( N \)-th bit of \( w \) is ‘1’, else output ‘0’.
3. They win if they got the same output, i.e., \( w(N) = w'(N) \).

Based on above strategy, we are interested in the probability for Alice and Bob output the same value which can be described with a similarity function \( S(w, w') = P \) with probability \( P \in [0, 1] \).

**Theorem 1.** Hamming hash strategy is a LSH with similarity function \( S(w, w') = 1 - \|w \oplus w'\|(k^*)^{-1} \)

Theorem 1 concluded that Alice and Bob always win with probability described as \( P = 1 - \|w \oplus w'\|(k^*)^{-1} \). Observe that, the similarity function for hamming hash correspond to the hamming distance between \( w \) and \( w' \).

By repeat Step 1 and Step 2 of hamming hash strategy \( n \) times, with different random integers, Alice and Bob able to output a \( n \) bits string \( \phi, \phi' \in \{0, 1\}^n \) respectively, which we have earlier named as resilient vectors.

**Theorem 2.** Suppose two resilient vectors \( \phi, \phi' \in \{0, 1\}^n \) are generated from \( w, w' \in \{0, 1\}^{k^*} \) respectively by hamming hash strategy with string \( N \in [k^*]^n \), then \( \mathbb{E}[\|\phi \oplus \phi'\|] = n \|w \oplus w'\|(k^*)^{-1} \).

**Proof.** Let \( \|\delta\| = \|\phi \oplus \phi'\| \), base on Theorem 1, we know that, for each time in comparing the hamming hash output (for \( i = 1, \ldots, n \)), the probability of disagree is describe as:

\[
\Pr[\phi(i) \neq \phi'(i)] = \|w \oplus w'\|(k^*)^{-1} = 1 - P
\]
Given some random variables \(E\), let \(\delta(i) = 1\) if \(\phi(i) \neq \phi'(i)\) and \(\delta(i) = 0\) if \(\phi(i) = \phi'(i)\). Precisely, \[|\delta| = |\phi \oplus \phi'| = \sum_{i=1}^{n} \delta(i),\] thus, \(|\delta| \sim Bin(n, 1 - P)\) follows binomial distribution of expected distance \(E[|\delta|] = n(1 - P)\) and s.d. \(\sigma = \sqrt{nP(1 - P)}\). Hence, \(E[|\delta|] = n(1 - P) = n\|w \oplus w'\|(k^*)^{-1}\) and prove the theorem.

Theorem 2 concluded that, any changes in the input hamming distance \(\|w \oplus w'\|\) can be described as an Bernoulli variable corresponds to the offset elements \(\delta(i)\). Therefore, by introducing additional error \(e \in \{0, 1\}^{k^*}\) of weight \(|e| = [k^*e]\) to the inputs, where \(e > 0\) (e.g., adding the error simply equivalent to \(\|w \oplus w' \oplus e\|\)), the probability of disagreeing for each element between the resilient vectors \(\phi, \phi'\) must increase or decrease by \(e\), which can be described as \(1 - P \pm e\).

To make the above argument more precise, we provide the following corollaries to characterize the effect on the offset \(|\delta|\) with \(e\). In our studies, we always refer to the resilient vectors generated from LSH hamming using the same random integer string \(N \in [k^*]^n\). The corollaries are given as follow.

**Corollary 1.** Given some random variables \(W, W' \in \{0, 1\}^{k^*}\), \(\Phi, \Phi' \in \{0, 1\}^n\) and an error parameter \(\epsilon > 0\). Let \(\xi = t/n\) be the tolerance rate of a \([n, k, t]\) code \(C_2\). Suppose a resilient vector \(\phi' \in \Phi'\) is generated from strings \(w' \in W'\). For two hamming ball \(B_t(\phi')\) and \(B_{t(-)}(w')\) of radius \(t(-) = [(\xi - \epsilon)k^*]\) and \(t > t(-)\), if \(W \in B_{t(-)}(w')\), then, one has the average minimum probability to find any variable \(\Phi \in B_t(\phi')\) described as \(1 - \exp(-2ne^2)\).

**Proof.** For \(W \in B_{t(-)}(w')\), it means that for all \(w \in W\), \(\|w \oplus w'\| \leq t(-)\) and so \(\|w \oplus w'\|(k^*)^{-1} \leq \xi - \epsilon\) is always true. Multiplying both sides of the inequality with \(n\), then \(n\|w \oplus w'\|(k^*)^{-1} \leq n\xi - ne\) and yield \(t \geq E[|\delta|] + ne\) (by Theorem 2). Let \(E[|\delta|] = t\), one could have a \(t_{\min}\) s.t. \(t = t + ne\). We want to look for the average probability of \(|\delta|\) to \(t_{\min}\) given \(\|w \oplus w'\|(k^*)^{-1} \leq \xi - \epsilon\). By using Hoeffding’s inequality, the average probability can be expressed as:

\[
\mathbb{E}_{w' \in W} \left[ \min_{\phi'} \Pr \left[ \Phi \in B_t(\phi') \mid W \in B_{t(-)}(w') \right] \right] = \min_{t = t_{\min}} \Pr \left[ \|\delta\| \leq t \mid \|w \oplus w'\| \leq t(-) \right] \geq 1 - \exp(-2ne^2) \tag{1}
\]

and complete the prove.

**Corollary 2.** Given some random variables \(W, W' \in \{0, 1\}^{k^*}\), \(\Phi, \Phi' \in \{0, 1\}^n\) and an error parameter \(\epsilon > 0\). Let \(\xi = t/n\) the tolerance rate of a \([n, k, t]\) code \(C_2\). Suppose a resilient vector \(\phi' \in \Phi'\) is generated from strings \(w' \in W'\). For two hamming ball \(B_t(\phi')\) and \(B_{t(+)}(w')\) of radius \(t(+) = [(\xi + \epsilon)k^*]\) and \(t > t(+)\) respectively, if \(W \not\in B_{t(+)}(w')\), then, one has the average maximum probability to find any variable \(\Phi \in B_t(\phi')\) described as \(\exp(-2ne^2)\).

**Proof.** This proof is instantiated from the proof of Corollary 1. For \(W \not\in B_{t(+)}(w')\), it means that for all \(w \in W\), \(\|w \oplus w'\| \geq t(+)\), \(\|w \oplus w'\|(k^*)^{-1} \geq \xi + \epsilon\) is always
true. Multiplying both sides of the inequality with \( n \), then \( n\|w \oplus w'\|(k^*)^{-1} \geq n\xi + n\epsilon \) and yield \( t \leq \mathbb{E}[\|\delta\|] - n\epsilon \) (by Theorem 2). Let \( \mathbb{E}[\|\delta\|] = t \), one could have a \( t_{\text{max}} \) s.t. \( t_{\text{max}} = t - n\epsilon \). We want to look for the average probability of \( \|\delta\| \leq t_{\text{max}} \) given \( \|w \oplus w'\|(k^*)^{-1} \geq \xi + \epsilon \). By using Hoeffding’s inequality, the average probability can be expressed as:

\[
\mathbb{E}_{w' \sim W} \left[ \max_{\phi'} \mathbb{P}[\Phi \in B_t(\phi') \mid W \not\in B_{t_{\text{max}}}(w')] \right]
= \max_{t = t_{\text{max}}} \mathbb{P}[\|\delta\| \leq t \mid \|w \oplus w'\| \geq t_{\text{max}}] \leq \exp(-2n\epsilon^2)
\]

and complete the prove.

The results obtained from Corollary 1 and Corollary 2 imply the following statement: Once the error of parameter \( \epsilon > 0 \) is introduced to the input, the probability of finding any resilient vector \( \phi \in \Phi \) close to \( \phi' \in \Phi' \) with in the ball \( B_t(\phi') \) will be bounded. These bounds are conditioned on the input \( W \), whether \( W \in B_{t_{\text{max}}}(w') \) or \( W \not\in B_{t_{\text{max}}}(w') \), that can be proven in either way by minimizing/maximizing the value of \( t = t_{\text{min}}/t_{\text{max}} \) respectively. Accordingly, we have the computed numerical bound for average fuzzy min-entropy described as

\[
\tilde{H}_{t_{\text{max}}}(\Phi \mid W \not\in B_{t_{\text{max}}}(w')) \geq -\log(\exp(-2n\epsilon^2))
\]

2 Preliminaries

In this section, we briefly highlight and recall some classical notions used in our constructions.

**Metric Spaces**: A metric space defined \( \mathcal{M} \) as finite set along with a distance function \( \text{dis} : \mathcal{M} \times \mathcal{M} \to \mathbb{R}^+ = [0, \infty) \), that takes any non-negative real values and obey symmetric e.g., \( \text{dis}(A, B) = \text{dis}(B, A) \), and triangle inequality, e.g., \( \text{dis}(A, C) \leq \text{dis}(A, B) + \text{dis}(B, C) \).

**Min-Entropy**: For security, one is always interested in the probability for an adversary to predict a random value, i.e., guessing a secret. For a random variable \( W \), \( \max_w \mathbb{P}[W = w] \) is the adversary’s best strategy to guess the most likely value, also known as the predictability of \( W \). The min-entropy thus defined as

\[
H_{\infty}(W) = -\log \left( \max_w \mathbb{P}[W = w] \right)
\]

min-entropy also viewed as worst case entropy.

**Average min-entropy**: Given pair of random variable \( W \), and \( W' \) (possible correlated), given an adversary find out the value \( w' \) of \( W' \), the predictability of \( W \) is now become \( \max_w \mathbb{P}[W = w \mid W' = w'] \). The average min-entropy of \( W \) given \( W' \) is defined as

\[
\tilde{H}_{\infty}(W \mid W') = -\log \left( \mathbb{E}_{w' \sim W'} \left[ \max_w \mathbb{P}[W = w \mid W' = w'] \right] \right)
\]
**Fuzzy min-entropy**: Given an adversary try to find $w'$ that is within distance $t$ of $w$, the fuzzy min-entropy is the total maximized probability mass of $W$ within the ball $B_t(w')$ of radius $t$ around $w$ defined as:

$$H_{t,\infty}^{\text{fuzz}}(W) = -\log \left( \max_{w'} \Pr[W \in B_t(w')] \right)$$

high fuzzy min-entropy is a necessary for strong key derivation.

**Secure sketch** [7] An $(\mathcal{M}, m, \tilde{m}, t)$-secure sketch is a pair of randomized procedures “sketch” (SS) and “Recover” (Rec), with the following properties:

- SS: takes input $w \in \mathcal{M}$ returns a secure sketch (e.g., helper string) $ss \in \{0,1\}^*$. 
- Rec: takes an element $w' \in \mathcal{M}$ and $ss$. If $\text{dis}(w, w') \leq t$, then $\text{Rec}(w', ss) = w$ with probability $1 - \beta$, where $\beta$ is some negligible quantity. If $\text{dis}(w, w') > t$, then no guarantee is provided about the output of Rec.

The security property of secure sketch guarantees that for any distribution $W$ over $\mathcal{M}$ with min-entropy $m$, the values of $W$ can be recovered by the adversary who observes $ss$ with probability no greater than $2^{-\tilde{m}}$. That is the residual entropy $H_\infty(W|W') \geq \tilde{m}$.

**Error correction code** [19]: Let $q \geq 2$ be an integer, let $[q] = \{1, \ldots, q\}$, we called an $(n, k, d)_q$-ary code $C$ consist of following properties:

- $C$ is a subset of $[q]^n$, where $n$ is an integer referring to the blocklength of $C$.
- The dimension of code $C$ can be represented as $|C| = |q|^k = V$
- The rate of code $C$ to be the normalized quantity $\frac{k}{n}$
- The min-distance between different codewords defined as $\min_{c,c' \in C} \text{dis}(c, c')$.

It is convenient to view code $C$ as a function $C : [q]^k \to [q]^n$. Under this view, the elements of $C$ can be considered as a message $v \in V$ and the process to generate its associated codeword $C(v) = c$ is called encoding. Viewed this way, encoding a message $v$ of size $k$, always adding redundancy to produce codeword $c \in [q]^n$ of longer size $n$. Nevertheless, for any codeword $c$ with at most $t = \lfloor \frac{d-1}{2} \rfloor$ symbols being modified to form $c'$, it is possible to uniquely recover $c$ from $c'$ by using certain function $f$ s.t. $f(c') = c$. The procedure to find the unique $c \in C$ that satisfied $\text{dis}(c, c') \leq t$ by using $f$ is called as decoding. A code $C$ is said to be efficient if there exists a polynomial time algorithm for encoding and decoding.

**Linear error correction code** [19]: Linear error correction code is a linear subspace of $\mathbb{F}_q^n$. A $q$-ary linear code of blocklength $n$, dimension $k$ and minimum distance $d$ is represented as $[n, k, d]_q$ code $C$. For a linear code, a string with all zeros $0^n$ is always a codeword. It can be specified into one of two equivalent ways with a generator matrix $G \in \mathbb{F}_q^{n \times k}$ or parity check matrix $H \in \mathbb{F}_q^{(n-k) \times n}$:

- a $[n, k, d]_q$ linear code $C$ can be specified as the set $\{Gv : v \in \mathbb{F}_q^k\}$ for an $n \times k$ metric which known as the generator matrix of $C$.
- a $[n, k, d]_q$ linear code $C$ can also be specified as the subspace $\{x : x \in \mathbb{F}_q^n$ and $Hx = 0^{n-k}\}$ for an $(n-k) \times n$ metric which known as the parity check matrix of $C$. 

For any linear code, the linear combination of any codewords is also considered as a codeword over \( F_q^n \). Often, the encoding of any message \( v \in F_q^k \) can be done with \( O(nk) \) operations (by multiplying it with the generator matrix, i.e., \( Gv \). The distance between two linear codewords refers to the number of disagree elements between them, also known as the hamming distance.

**Shannon Code** \[20\] Let a binary code \( C \) over \( \{0, 1\}^n \). We call that \( C \) is an \([t, \varepsilon]\)-Shannon code if there exits an encoding and decoding algorithm \( \langle \text{Encode}, \text{decode} \rangle \) such that, \( \text{Encode} \) encode any \( k \) bits message to \( n \) bits codeword \( c \in C \), and a \( \text{decode} \) decode any codeword \( c' \) for all \( t' \leq t \), and \( c \in C \), \( \Pr[\text{dis}(c, c') \leq t' \land \text{decode}(c' \neq c)] \leq \varepsilon. \)

**Locality Sensitive Hashing (LSH)** \[21\] Given that \( P_2 > P_1 \), while \( w, w' \in \mathcal{M} \), and \( H = h_i : \mathcal{M} \to U \), where \( U \) refers to the output metric space (after hashing), which comes along with a similarity function \( S \), where \( i \) is the number of hash functions \( h_i \). A locality sensitive hashing can be viewed as a probability distribution over a family \( H \) of hash functions follows \( P_{h \in H}[h(w) = h(w')] = S(w, w') \). In particular, the similarity function \( S \) described the hashed collision probability in between \( w \) and \( w' \).

\[
\begin{align*}
P_{h \in H}(h_i(w) = h_i(w')) &\leq P_1, \quad \text{if } S(w, w') < R_1 \\
P_{h \in H}(h_i(w) = h_i(w')) &\geq P_2, \quad \text{if } S(w, w') > R_2
\end{align*}
\]

LSH transforms input \( w \) and \( w' \) to its output metric space \( U \) with property that ensuring similarity inputs render higher probability of collision over \( U \), and vice versa.

### 3 Proposed Construction

We hereby provide the detail of our based design of on a pair of sketching and recover algorithm, that incorporated with LSH, by hamming hash strategy.

#### 3.1 LSH-Hamming hash

We first formulate the hamming-hash algorithm \( \Omega^{\text{ham-h}} \) which will be used in our sketching and recover algorithms description later. Generally, the hamming-hash algorithm \( \Omega^{\text{ham-h}} : \mathcal{M}_1 \times [k^*]^n \to \mathcal{M}_2 \) is an iterative process through repeating the hamming hash strategy (steps 1 and 2) up to \( n \) times. It serves to sample the input binary string of size \( k^* \) into a longer binary string a.k.a resilient vector of size \( n > k^* \).

Given input \( w \in \{0, 1\}^{k^*} \), and \( N \in [k^*]^n \), the LSH-hamming hash algorithm describes as follow:
3.2 Sketching

We denote the sketching algorithm that employs the hamming-hash algorithm, \( \Omega \), an \([n^*, k^*, t^*]\) ‘inner’ code \( C^* \) and an \([n, k, t]_2 \) ‘outer’ code \( C_\xi \) with generator matrix \( G^* \) and \( G \) respectively as \( \text{SS}_{\Omega, C^*, C_\xi} \).

For sketching, one requires to generate a resilient vector \( \phi \) by using the LSH hamming hash algorithm. The size of the resilient vector must same with the output codeword \( c \). Then, the sketch \( ss \) can be constructed by simply perform an XOR operation, i.e., \( ss = c \oplus \phi \). Besides, to add additional error to the input, we use a random error vector \( e \in \text{supp}(\chi) \) over some random distribution \( \chi \) parametrized by \( \epsilon > 0 \). Specifically, we have \( ||\chi|| = \lceil k^* \epsilon \rceil \) where the error vector \( e \) is of weight \( ||e|| = ||\chi|| = \lceil k^* \epsilon \rceil \). The sketching algorithm \( \text{SS}_{\Omega, C^*, C_\xi} \) with inputs \( w, N, G^*, G \) and \( \epsilon \) is describe as follow:

\[
\text{SS}_{\Omega, C^*, C_\xi}(w, N, G^*, G, \epsilon)
\begin{align*}
\chi &\leftarrow \{0, 1\}^{k^*} \quad \text{// sample } \chi \text{ according to the error parameter } \epsilon \\
e &\leftarrow \text{supp}(\chi) \quad \text{// sample } e \text{ from } \chi \text{ uniformly at random, where } ||e|| = ||\chi|| = \lceil k^* \epsilon \rceil \\
c^* &= G^* w; \quad \text{// encode } w \\
v^* &= (0^{k^*-n}, ||c^*||) \oplus (0^{k^*-k^*}, ||w||); \\
c &= G v^*; \quad \text{// encode } v^* \\
w_e &= w \oplus e; \\
\phi &\leftarrow \Omega_{\text{ham-h}}(w_e, N) \\
ss &= c \oplus \phi \\
\text{return } (ss, N, G^*, G)
\end{align*}
\]

All steps on \( \text{SS}_{\Omega, C^*, C_\xi}(w, N, G^*, G, \epsilon) \) can be done in \( O(n^2) \). Notably, the size of \( ss \) is now depend upon the chosen ‘outer’ code \( C_\xi \).

3.3 Recovery

For recovery, suppose one wishes to recover \( w \) from another string \( w' \in \{0, 1\}^{k^*} \). He/she needs to provide another resilient vector \( \phi' \). This resilient vector can be

\[\text{Remark that } G^* \text{ or } G \text{ can use to generate their corresponding parity check matrices } H^* \text{ or } H \text{ respectively}\]
generated by using the same hamming hash algorithm \( \Omega \) with error added inputs \( w' = w' \oplus e \). We want the recovery algorithm to output \( w \) for any error rate \( \| w \oplus w' \| (k^*)^{-1} \leq \xi \pm \epsilon \) or \( \| w \oplus w' \| \leq t(+) \). Therefore, the error included by an error vector \( e \in \text{supp}(\chi') \) sampled from another error distribution \( \chi' \), has shown doubled in amplitude i.e., \( \| \chi' \| = 2k^*\epsilon \) compared to \( \chi \) in the sketching phase.

We denote the recovery algorithm that employs the hamming-hash algorithm, \( \Omega \), an \( [n^*, k^*, t^*]_2 \) ‘inner’ code \( \mathcal{C}^* \) with generator matrix \( G^* \), an \( [n, k, t]_2 \) ‘outer’ code \( \mathcal{C}_s \) with generator matrix \( G \), and a decoding algorithm \( f \) as \( \text{Rec}_{\Omega, \mathcal{C}^*, \mathcal{C}_s, t} \). Let \( h_2(\epsilon) = -(\epsilon) \log (\epsilon) - (1 - \epsilon) \log (1 - \epsilon) \) be the binary entropy function of error rate \( \epsilon \), the recover algorithm \( \text{Rec}_{\Omega, \mathcal{C}^*, \mathcal{C}_s, t} \) with inputs \( ss, w', N, G^*, G \) and \( \epsilon \) to recover \( w \) is described as follow:

\[
\begin{align*}
\text{Rec}_{\Omega, \mathcal{C}^*, \mathcal{C}_s, t}(ss, w', N, G^*, G, \epsilon) \\
\chi' \leftarrow \{0,1\}^{k^*} & \text{ // sample } \chi' \text{ with error parameter } \epsilon \text{ i.e., } \| \chi' \| = 2k^*\epsilon \\
\text{if } k^* h_2(2\epsilon) \leq \log(n + 1) & \leq \left\lceil \log(1/\exp(-2n^2)) \right\rceil \text{ and } t(-) \leq t^* \\
\text{ for } i = 1, \ldots, n + 1 & \text{ // sample } e_i \text{ uniformly at random, where } \| e_i \| = \| \chi' \| = 2k^*\epsilon \\
e_i \leftarrow \text{supp}(\chi') & \text{ // sample } e_i \text{ uniformly at random, where } \| e_i \| = \| \chi' \| = 2k^*\epsilon \\
w'_{ei} = w' \oplus e_i & \\
\phi_i' = \Omega^{\text{ham}}(w'_{ei}, N) & \\
c_i' = ss \oplus \phi_i' \text{ // also } ss \oplus \phi_i' = e \oplus (\phi \oplus \phi_i') & \\
c \leftarrow f(c_i') & \text{ // first decoding} \\
v^* \leftarrow G^{-1}c & \\
\text{if } v^*[1], \ldots, v^*[k - n^*] = 0^{k - n^*} & \text{ // first } k - n^* \text{ bits of } v^* \text{ are zeros} \\
v^* = v^* \oplus (0^{k - k^*} \| w' \|) & \\
\text{set } c^* \text{ as the last } n^\star \text{ elements of } v^* & \text{ // i.e., } c^* = c^* \oplus (0^{n^* - k^*} \| w \|) \oplus (0^{n^* - k^*} \| w' \|) \\
c^* \leftarrow f(c^*) & \text{ // second decoding} \\
w \leftarrow (G^*)^{-1}c^* & \\
\text{return } w & \\
\text{break} & \\
\text{endfor} & \\
\text{endif} & \\
\text{endfor} & \\
\text{endif} & \\
\end{align*}
\]

All the while, the conditions \( k^* h_2(2\epsilon) \leq \log(n + 1) \leq \left\lceil \log(1/\exp(-2n^2)) \right\rceil \) must hold for efficient recovery process (see Section 4.1). A brief description of the recovery mechanism is given as follow. Suppose Bob has intercepted with a sketch \( ss = e \oplus \phi \). Firstly, he has to double the error parameter from \( \epsilon \) to \( 2\epsilon \) and generate a resilient vector \( \phi_i' \leftarrow \Omega^{\text{ham}}(w'_{ei}, N) \). The hamming weight of the offset can be conveniently represented as \( \| \delta_i \| = \| \phi \oplus \phi_i' \| \). By means of the similarity preservation property of LSH, the offset, \( \delta_i \), is expected to be low as well if \( w \) and \( w' \) are close to each other. Bob then performs \( ss \oplus \phi_i' \) to output the nearest codeword \( c_i' \). The errors over \( c_i' \) can be tolerated by means of error
correction with codes $C_\xi$. Same goes to the second decoding stage, where the
errors over $v^*$ can be tolerated by the code $C^*$ with a decoding function $f$. Since
$k^* < n^* < k < n$, the first $k - n^*$ bits of $v^*$ must be zeros. If the first decoding
stage returns $v^*$ with the first $k - n^*$ bits are all zeros, it means that the first
decoding stage is highly likely to be succeeded and then proceed to the second
decoding stage. Otherwise, the first decoding stage will repeat for $i = 1, \ldots, n+1$
iterations to try all possible input error patterns over $|\text{supp}(\chi')|$ and terminates.

4 Resilience

This section considers the resilience of algorithm pair $\langle SS_{\Omega,C^*,C_\xi}, \text{Rec}_{\Omega,C^*,C_\xi,t} \rangle$.
Generally, the resilience measures on how probable the offset $\|\delta\|$ can be tolerated
in facilitating the recovery of $v^*$ and so $w$ from the sketch. High resilience implies
high probability to tolerate the offset or correcting the errors.

Clearly, the resilience of $\langle SS_{\Omega,C^*,C_\xi}, \text{Rec}_{\Omega,C^*,C_\xi,t} \rangle$ is bounded by the resilience
of the selected codes pair $C^*$ and $C_\xi$. This also mean that the value of $\epsilon$ should be
bounded by the maximum achievable error tolerance rate, determined among the
chosen codes pair $C^*$ and $C_\xi$, i.e., $0 < \epsilon \leq \max \{t^*/n^*, \xi\}$. Since $t^* < t$, certainly
$0 < \epsilon \leq \xi$. Choosing a ‘good’ code with a high value of $\xi$ is non-trivial, this is because different code is subjected to different set of parameters $(n, k, t)$ and
there is no straightforward way to determine which the most efficient one is. The
design of such code under different set of parameters $(n, k, t)$ is another broad
research topic. We direct the interested user refer to the works of Macwilliams,
(1977) [22], and Peterson and Weldon, (1972) [23]. Nevertheless, by padding zeros
on the input $v^*$, the selection of different codes pair $C^*$ and $C_\xi$ are highly relieved,
since once can easily find a pair of code $C^*$ and $C_\xi$ with $k^* < n^* \leq k < n$.

In this section, we are more interested in the probability to recover the original
input $w$. We will leave the discussion of the topic regarding resilience bound to
the following Section 4.1.

Further simplification is done by describing the term overwhelming if the
value of $1 - \beta$ is close to one (e.g., negligible $\beta$). As we shall see, negligible $\beta$
means substantial average fuzzy min-entropy.

We hereby formalize the completeness of $\langle SS_{\Omega,C^*,C_\xi}, \text{Rec}_{\Omega,C^*,C_\xi,t} \rangle$ for our res-
silience claim. It captures the scenario when the players are honest, which is
define under the following definition.

**Definition 1.** For some random variables $W, W' \in \mathcal{M}_1$, and $SS \in \mathcal{M}_2$, where
$\mathcal{M}_1 = \{0, 1\}^{k^*}$ and $\mathcal{M}_2 = \{0, 1\}^n$. Given $N \in [k^*]^n$, an $[n^*, k^*, t^*]_2$ linear
code $C^*$ and an $[n, k, t]_2$ linear code $C_\xi$ with generator matrix $G^* \in \mathbb{F}_2^{n^* \times k^*}$
and $G \in \mathbb{F}_2^{n \times k}$ respectively, where $t^* < t$ and $k^* < n^* \leq k < n$. Let $t_{(\cdot)} =
[(\xi - \epsilon)k^*], \epsilon \in (0, \xi]$ and $\xi = t/n$. Suppose a sketch $ss$ generated through
$SS_{\Omega,C^*,C_\xi}(w, N, G^*, G, \epsilon) = ss$, where $ss \in SS$. For all $w \in W, w' \in W'$, then
one has $\text{Rec}_{\Omega,C^*,C_\xi,t}(ss, w', N, G^*, G, \epsilon) = w$ can be achieved with overwhelming
probability at least $1 - \beta$ if $\|w \oplus w'\| \leq t_{(\cdot)}$. We said $\langle SS_{\Omega,C^*,C_\xi}, \text{Rec}_{\Omega,C^*,C_\xi,t} \rangle$ is complete in $(\beta, \epsilon)$-fuzziness if above statement holds.
We hereby provide a proposition with proof for the completeness claim on \(\langle SS_{\Omega,C^*,c_*}, \text{Rec}_{\Omega,C^*,c_*}, t \rangle\).

**Proposition 1.** For sufficiently large \(n\), \(\langle SS_{\Omega,C^*,c_*}, \text{Rec}_{\Omega,C^*,c_*}, t \rangle\) is complete in \((\beta, \epsilon)\)-fuzziness if \(\|w \oplus w'\| \leq t_{(-)} \leq t^*\), where \(\beta = \exp(-2n\epsilon^2)\).

**Proof.** Clearly, \(\text{Rec}_{\Omega,C^*,c_*}(ss, w', N, G^*, G, \epsilon) = w\) can only be achieved if both decoding processes \(f(c^*)^4\) and \(f(c^*)\) are succeeded, where both scenarios \(\|\delta\| \leq t\) and \(\|w \oplus w'\| \leq t^*\) must hold. For the second decoding stage, it follows \(f(c^*) = f(c^* \oplus (0^{n^* - k^*} \|w\| \oplus (0^{n^* - k^*} \|w'\|)) = f(c^* \oplus (0^{n^* - k^*} \|w \oplus w'\|)).\) If \(\|w \oplus w'\| \leq t_{(-)} \leq t^*\), the second decoding stage will success with probability one then returns \(c^*\) and so \(w\). For the first decoding stage, it follows that \(f(c') = f(c \oplus \delta) = f((c \oplus \phi) \oplus \phi') = f(c \oplus (\phi \oplus \phi'))\). If \(\|\phi \oplus \phi'\| \leq \|\delta\| \leq t,\) this decoding will success and returns \(c\) and so \(w\). We here need to consider the probability for the case \(\|\delta\| \leq t\) to hold. Follow Corollary 1, when \(\|w \oplus w'\| \leq t_{(-)}\), this probability is therefore expresses as:

\[
\min_{t = t_{\text{min}}} \Pr[\|\delta\| \leq t \mid \|w \oplus w'\| \leq t_{(-)}] \geq 1 - \beta
\]

Observed that \(1 - \beta\) is overwhelming with negligible quantity \(\beta = \exp(-2n\epsilon^2)\) when \(n\) is sufficiently large. Hence, the proposition is prove.

Proposition 1 concluded that given two linear error correction codes \(C^*\) and \(C_\xi\) described follows Definition 1, for \(\epsilon \in (0, \xi]\), when \(\|w \oplus w'\| \leq t_{(-)} \leq t^*\), \(\text{Rec}_{\Omega,C^*,c_*}(ss, w', N, G^*, G, \epsilon) = w\) can be achieved with overwhelming probability at least \(1 - \beta\) with decoding function \(f\) if one has the value of \(n\) is sufficiently large.

### 4.1 Correcting More Errors in Polynomial Time

This section provided the details explanation for error correction of error rate up to \(\xi + \epsilon\).

Focusing on the second decoding stage, it only successes when \(\|w \oplus w'\| \leq t_{(-)} \leq t^*\). This result demonstrating a limited amount of error \(t_{(-)} \leq t^*\) can be corrected by the ‘inner’ code \(C^*\) with probability one. Otherwise, one can actually correct more errors with additional ‘outer’ code \(C_\xi\) imposes on top of \(C^*\). In particular, when \(\|w \oplus w'\|(k^*)^{-1} \leq \xi + \epsilon\) or \(\|w \oplus w'\| \leq t_{(+)}\). By introducing additional random error of rate \(-2\epsilon\) during recovery phase, the error rate is possible to be reduced down to \(\|w \oplus w'\|(k^*)^{-1} \leq \xi - \epsilon\), hence the remaining errors can be corrected with probability one when \(t_{(-)} \leq t^*\).

Based on the above argument, we hereby provide the soundness of \(\text{Rec}_{\Omega,C^*,c_*}, t\) to characterize the resilience bound of \(\text{Rec}_{\Omega,C^*,c_*}, t\) for higher error rate, e.g., at most \(\|w \oplus w'\|(k^*)^{-1} \leq \xi + \epsilon\). Formally, this soundness of \(\text{Rec}_{\Omega,C^*,c_*}, t\) covers the scenario where any adversary is capable of sampling any \(w'\) s.t. \(\|w \oplus w'\| \leq t_{(+)}\) holds.

\footnote{We here omitted the \(i\)-th notation for neater presentation}
Often, for efficient recovery, we hope that $\text{Rec}_{\Omega, C^*, C^*_f}$ can be done successfully in a few iterations, i.e., polynomial in the input sketch size $n$. The definition below defines the soundness of $\text{Rec}_{\Omega, C^*, C^*_f}$ in correcting the errors probability at least $1 - \beta$ and efficiently under the event when $\|w \oplus w'\| \leq t_{(+)}$.

**Definition 2.** For some random variables $W, W' \in \mathcal{M}_1$, and $SS \in \mathcal{M}_2$, where $\mathcal{M}_1 = \{0, 1\}^n$ and $\mathcal{M}_2 = \{0, 1\}^n$. Given $N \in [k^*]^{n}$, an $[n, k^*, t^*]_2$ linear code $C^*$ and an $[n, k, t]_2$ linear code $C_\xi$ with generator matrix $G^* \in \mathbb{F}_2^{n \times k^*}$ and $G \in \mathbb{F}_2^{n \times k}$ respectively. Let $t_{(+)} = \lceil (\xi + \epsilon)k^* \rceil$, $t_{(-)} = \lceil (\xi - \epsilon)k^* \rceil$, $\epsilon \in (0, \xi]$, and $\xi = t/n$. For all $w \in W, w' \in W'$, given a sketch $ss$ generated through $SS_{\Omega, C^*, C^*_f}(w, N, G^*, G, \epsilon) = ss \in SS$. Then, we said $\text{Rec}_{\Omega, C^*, C^*_f}$ is efficient if $\text{Rec}_{\Omega, C^*, C^*_f}(ss, w', N, G^*, G, \epsilon) = w$ can be done in time $\text{poly}(n)$ and success with probability at least $1 - \exp(-2n\epsilon^2)$.

For the ‘inner’ code $C^*$, we propose to use a type of efficient code named BCH code [23] with efficient decoding algorithm $f$ via algebraic method, i.e., syndrome decoding [24]. To claim the soundness of $(SS_{\Omega, C^*, C^*_f}, \text{Rec}_{\Omega, C^*, C^*_f})$, we have to show the existence of such ‘outer’ code $C_\xi$ for $(SS_{\Omega, C^*, C^*_f}, \text{Rec}_{\Omega, C^*, C^*_f})$ with efficient decoding algorithm $f$ as well.

We provide a theorem with proof of the existence of the ‘outer’ code $C_\xi$, and the efficiency of $\text{Rec}_{\Omega, C^*, C^*_f}$ itself.

**Theorem 3.** Let $C^*$ be an $[n^*, k^*, t^*]$ BCH code, and $\epsilon \in [(2k^*)^{-1}, \xi]$. For $[\log(1/\exp(-2n\epsilon^2))] \geq \log(n + 1)$, there exists another $[n, k, t]_2$ BCH code $C_\xi$ with syndrome decoding algorithm $f$, for $(SS_{\Omega, C^*, C^*_f}, \text{Rec}_{\Omega, C^*, C^*_f})$, where $k^* < n^* \leq k^* < n$ to correct the error rate of $\xi + \epsilon$ with probability at least $1 - \exp(-2n\epsilon^2)$ in time $\text{poly}(n)$ when $[k^* h_2(2\epsilon)] \leq \log(n + 1) \leq [\log(1/\exp(-2n\epsilon^2))]$, $[2k^* \epsilon] \leq \|w \oplus w'\| \leq t_{(+)}$, and $t^* \geq t_{(-)}$.

**Proof.** We first provide the existence proof for code $C_\xi$. Follows Eq. 2, by symmetry, we obtain $\min_{t = t_{\min}} \text{Pr}_t[\|d\| \geq t \|w \oplus w'\| \leq t_{(+)}] \leq \exp(-2n\epsilon^2)$. This implies there will have at least $2[\log(1/\exp(-2n\epsilon^2))]$ number of codewords which are consider as ‘good’ codewords s.t. $c_i \in C_\xi$, whereby the failure rate of first decoding stage can be made arbitrary small down to $\exp(-2n\epsilon^2)$. Besides, for some positive integer $m^* \geq 3$ and $t^* < 2m'^{-1}$, there exits an $[n^*, k^*, t^*]$ BCH code $C^*$ with parameters $n^* = 2m^* - 1$, $n^* - k^* \leq m^* t$ and minimum distance $d^* \geq 2t^* - 1$. For $[\log(1/\exp(-2n\epsilon^2))] \geq \log(n + 1) > \log(n^* + 1)$, we have $2[\log(1/\exp(-2n\epsilon^2))] \geq 2m^* > 2m'^*$, where the ‘outer’ $[n, k, t]_2$ BCH code $C_\xi$ exits with parameter $n = 2m^* - 1$, $n - k \leq m't$, with $t < 2m'^{-1}$, minimum distance $d \geq 2t - 1$, where $k^* < n^* \leq k < n$ holds.

We now revert to our main goal of correcting the error rate $\xi + \epsilon$ or number of errors up to $t_{(+)}$. We have to show the probability of the errors to decrease from $\|w \oplus w'\| \leq t_{(+)}$ to $\|w \oplus w'\| \leq t_{(-)}$. Given an error vector $\|e_i\| = [2k^* \epsilon]$, we have $|\text{supp}(\chi')| = \binom{k^*}{[2k^* \epsilon]}$ possible ways to describe all different combinations of the error vector $e_i \in \text{supp}(\chi')$. It follows $\text{Rec}_{\Omega, C^*, C^*_f}$ run maximally in $\binom{k^*}{[2k^* \epsilon]}$.
In the previous section, we have demonstrated the resilience of algorithm pair 4.2 Error Correction up to Shannon Bound bound in the next subsection.

It is natural to let \( \epsilon = 0 \), which will easily lead to the perfect correctness model, so, the errors can be corrected with probability one. This means there will be at least 1 - \( \beta \) and complete the prove.

In summary, for \( \epsilon \in [2k^*]^{-1}, \xi \), given \( 2k^* \epsilon \leq \| w \oplus w' \| \leq t(+) \) and \( t^* \geq t(-) \), one needs \( [k^*h_2(2\epsilon)] \leq \log(n+1) \leq [\log(1/\exp(-2n\epsilon^2))] \) to ensure efficient decoding with \( f \) in \( \text{Rec}_{\Omega, c^*, c^t, f} \) to correct the error rate of \( \xi + \epsilon \).

We would provide more details discussion regarding the error correction bound in the next subsection.

### 4.2 Error Correction up to Shannon Bound

In the previous section, we have demonstrated the resilience of algorithm pair \( \langle SS_{\Omega, C^*, C^t}, \text{Rec}_{\Omega, C^*, C^t, f} \rangle \), in term of the probability in correcting the errors at most \( t(+) \). This section will provide the discussion on the maximum errors can be corrected by using \( \langle SS_{\Omega, C^*, C^t}, \text{Rec}_{\Omega, C^*, C^t, f} \rangle \). Formally, we call this as the resilience bound of \( \langle SS_{\Omega, C^*, C^t}, \text{Rec}_{\Omega, C^*, C^t, f} \rangle \).

Generally, to study the resilience bound, the error model of the system must be conceived. It is mean to say that, without any knowledge on the error process of the input, it is difficult to precisely model and determine the resilience bound of a given error correcting construction. It is also heedless for one to believe that people have a complete understanding of the complex error pattern, or the distribution that is overtaking by the noisy non-uniform sources, i.e., biometric.

To study the resilience bound without the knowledge of the input error process, one can always use the perfect correctness model. Recall that, high resilience means the errors can be corrected with overwhelming probability 1 - \( \beta \). Ideally, it is natural to let \( \beta = 0 \), which will easily lead to the perfect correctness model, so, the errors can be corrected with probability one. This means there will be

\[
\Pr[||\delta|| \leq t \mid ||w \oplus w'|| \leq t(+)] = \frac{\left(\frac{||w \oplus w'||}{\epsilon k^*}\right)}{\left\lfloor \frac{w \oplus w'}{\epsilon k^*} \right\rfloor}
\]

For efficiency claim, we need \( \left(\frac{k^*}{2k^* \epsilon}\right) / \left(\frac{||w \oplus w'||}{\epsilon k^*}\right) \leq 2^m = n + 1 \) to ensure \( \text{Rec}_{\Omega, c^*, c^t, f} \) maximally run in \( n + 1 \) iterations. By Stirling’s approximation, \( \left(\frac{k^*}{2k^* \epsilon}\right) \leq 2^{k^* h_2(2\epsilon)} \) holds when \( \epsilon \in [2k^*]^{-1}, 1/4 \], hence \( \left(\frac{||w \oplus w'||}{\epsilon k^*}\right) \geq 2^{-[k^*h_2(2\epsilon)]} \).

Recall \( \epsilon \in (0, \xi] \) (see Proposition 1), thus \( \epsilon \in [2k^*]^{-1}, \xi \) follows. Then, for \( [k^*h_2(2\epsilon)] \leq \log(n+1) \leq [\log(1/\exp(-2n\epsilon^2))] \), the solution follows (where \( \beta = \exp(-2n\epsilon^2) \)):

\[
\Pr[||\delta|| \leq t \mid ||w \oplus w'|| \leq t(+) \] \geq 2^{-[k^*h_2(2\epsilon)]} \geq 2^{-\log(n+1)} = \frac{1}{2^{O(\log(n+1))}} = \frac{1}{\text{poly}(n)}.
\]

After \( \text{poly}(n) \) iterations, \( \text{Rec}_{\Omega, c^*, c^t, f} \) would success and output \( w \) with probability at least 1 - \( \beta \) and complete the prove.
only one unique solution for every \( w' \) within distance \( t \). Hence, the decoding process always returns the original value \( w \) precisely via unique decoding. In this model, the fuzzy min-entropy notion may not necessary, since one can easily show infinite fuzzy min-entropy without any dissension for security. Therefore, this model is useful and suitable for who try to avoid certain assumption about the exact properties of the stochastic error process, or the computational power of an adversary to carry out decoding successfully.

However, inevitably, under the perfect correctness model, one always tied to a very strong bound in term of the resilience. Typically, one can only uniquely decode the codeword by using an error correction code with min-distance \( d \geq 2t + 1 \). Saying so, the Plotkin bound (see [25]) has revealed the limited maximum number of codewords in a code of blocklength \( n \) and minimum distance \( d \). More formally, there can be only at most \( 2n \) codewords with \( d > n/2 \), which means given the residual entropy larger or equal to \( \log(n) \), there has no error correction code can correct \( n/4 \) errors with probability one and so for a secure sketch.

Despite of this, our results have shown that for sufficiently large \( n \), the code \( C_\xi \) would contain large number of ‘good’ codewords, which are enough for the first decoding stage to success with overwhelming probability. In such a case, one has a slightly relaxed notion of correctness called probabilistic correctness model. Such relaxed notion of correctness is essential for \( \langle SS_{\Omega,C^*,C_\xi}, \text{Rec}_{\Omega,C^*,C_\xi,t} \rangle \) to free from the Plotkin bound and allow it to correct more errors, e.g., at most \( t(+) \), by increment of the error parameter \( \epsilon \) and the blocklength of the outer code \( n \). For efficient recovery process, it is better to use the lower bound of \( 2^{k^*} h_2(2\epsilon) \leq n + 1 \leq \lceil \log(1/\exp(-2n\epsilon^2)) \rceil \) to describe the input’s error pattern over \( \{0, 1\}^{k^*} \) rather than the error pattern in the resilient over \( \{0, 1\}^n \). Doing so enables \( \text{Rec}_{\Omega,C^*,C_\xi,t} \) maximally run in \( n + 1 \) iteration in time \( \text{poly}(n) \).

For our resilience bound studies, we refer to the random error model which was famously considered by Shannon [20]. For any discrete memoryless channel, the error tolerance rate is characterized by the maximum mutual information between the input and outputs. Precisely, in a binary symmetric channel, like our case, there exists a code encoding \( k \) bits into \( n \) bits which able to tolerate the error of probability \( p \) for every single bit, if and only if:

\[
k < \lfloor (1 - h_2(p))n \rfloor
\]

Since \( h_2(p) \) is maximally one when \( p = 1/2 \), conversely, this theorem indicates the existence of a secure sketch even for high error rate as long as \( p \) is smaller than \( 1/2 \).

With above reasoning, our efficiency claim for maximum error correction using \( \text{Rec}_{\Omega,C^*,C_\xi,t} \) is as follow:

**Proposition 2.** If both \( C^* \) and \( C_\xi \) are BCH codes with syndrome decoding algorithm \( f \), where \( \xi = t/n \in (0, 1/4) \). For \( \epsilon \in [(2k^*)^{-1}, \xi] \), \( \text{Rec}_{\Omega,C^*,C_\xi,t} \) is efficient when \( [k^* h_2(2\epsilon)] \leq \log(n + 1) \leq \lceil \log(1/\exp(-2n\epsilon^2)) \rceil \), \( [k^* \epsilon] \leq \|w \oplus w'\| \leq t(+) \), and \( t^* \geq t(-) \) where the maximum correctable error rate is \( 2\epsilon \leq 2\xi < 1/2 \).

**Proof.** By Theorem 3, \( \text{Rec}_{\Omega,C^*,C_\xi,t} \) can correct the error rate of \( \|w \oplus w'\| (k^*)^{-1} \leq \xi + \epsilon \) efficiently when \( [k^* h_2(2\epsilon)] \leq \log(n + 1) \leq \lceil \log(1/\exp(-2n\epsilon^2)) \rceil \), \( [2k^* \epsilon] \leq \}
The correctable error rate is \( \|w \oplus w'\| \leq t_+(\epsilon) \), and \( t^* \geq t_-(\epsilon) \). Clearly, with maximum \( \epsilon = \xi \), the maximum correctable error rate is \( \|w \oplus w'\| (k^*)^{-1} \leq \xi + \epsilon \leq 2\epsilon \leq 2\xi < 1/2 \).

Finally, we give a corollary whom proof is instantiated by the proof of Theorem 3 and Proposition 2, to formalize \( \langle \SS\Omega, C^*, C_\xi, \RecC_\Omega, C^*, C_\xi, t \rangle \) as an \([t_+(\epsilon), \beta] \) Shannon code.

**Corollary 3.** For \( \epsilon \in [(2k^*)^{-1}, \xi] \), given any pair of BCH codes \( C^* \) and \( C_\xi \) with efficient decoding algorithm \( f \) used in \( \langle \SS\Omega, C^*, C_\xi, \RecC_\Omega, C^*, C_\xi, t \rangle \) where \( k^* < n^* \leq k < n \), \( \langle \SS\Omega, C^*, C_\xi, \RecC_\Omega, C^*, C_\xi, t \rangle \) is an efficient \([t_+(\epsilon), \beta] \) Shannon code where \( \beta = \exp(-2n\epsilon^2) \), when \( |k^*h_2(2\epsilon)| \leq \log(n+1) \leq \lceil \log(1/\beta) \rceil \), and \( t^* \geq t_-(\epsilon) \).

It is useful to have an example to show how \( \RecC_\Omega, C^*, C_\xi, t \) works according to our claim follows Corollary 3 with two BCH codes.

**Example 1.** For simplicity, we let \( \lceil \log(1/\exp(-2n\epsilon^2)) \rceil = \log(n+1) \). Suppose one wishes to correct some errors over an input \( w \in \{0, 1\}^{k^*} \) of length \( k^* = 11 \). Given an \([511, 67, 87]_2 \) BCH code is chosen for ‘outer’ code \( C_\xi \). By efficiency argument, he/she needs \( |k^*h_2(2\epsilon)| \leq \log(n+1) \), thus, \( h_2(2\epsilon) \leq 0.1343 \), so \( \epsilon \leq 0.12 \). In such a case, one has the correctable error rate is bounded at most \( \xi + \epsilon = 0.2001 \) (i.e., \( t_+ = \lceil (0.2803)k^* \rceil \), and he/she needs an ‘inner’ code \( C^* \) that could correct at least \( t_- = \lceil (0.0503)k^* \rceil = 1 \) error, i.e., \([n^*, k^*, t^*] \) code \( C^* \) with \( n^* = 31, k^* = 11, t^* = 5 \). On the other hand, let say the input is of length \( k^* = 4 \). For an \([511, 10, 127]_2 \) ‘outer’ code \( C_\xi \) where \( \xi = 0.2485 \). One can easily compute \( h_3(2\epsilon) \leq 0.9 \). Then, he/she is capable of choosing maximum \( \epsilon = \xi = 0.2485 \) for maximum error correction capacity, which is at most of rate \( \xi + \epsilon = 0.4971 \). The errors can be corrected with overwhelming probability at least \( 1 - 3 \times 84 \times 10^{-28} \). Meanwhile, he/she would need to choose an ‘inner code’ \( C^* \) with \( n^* = 7, k^* = 4 \) and \( t^* = 1 \). since \( t_-(\epsilon) = 0 \leq t^* \), the second decoding stage would success with probability one by syndrome decoding algorithm \( f \).

Apart from this, computationally efficient code achieve Shannon bound is also found by Forney in 1965, named as concatenated code [27]. Our construction relies on similar approach as the concatenated code for \( \langle \SS\Omega, C^*, C_\xi, \RecC_\Omega, C^*, C_\xi, t \rangle \) with an ‘outer’ code \( C_\xi \) build on top of an ‘inner code’ \( C^* \), where both are linear codes as well. However, obviously, our construction operating differently by taking into consideration over the input error’s distributions parametrized by \( \epsilon \), and the resilient vector.

## 5 Security

Recall that for all \( w \in W \) in some random distribution \( W \) over \( M_1 \), the soundness of \( \RecC_\Omega, C^*, C_\xi, t \) captured the scenario where any adversary \( A \) is capable of sampling any \( w' \in W' \) satisfy \( \|w \oplus w'\| (k^*)^{-1} \leq \xi + \epsilon \) or \( \|w \oplus w'\| \leq t_+(\epsilon) \).

The security of our proposal depends upon the hardness in searching a variable \( W \) satisfy \( W \in B_{t_+(\epsilon)}(w') \). Since error correction implies entropy loss, this loss should proportional to the number of codewords in \( C_\xi \) which are consider
as ‘good’ (e.g., \( c'_i \in C_k \)) for the first decoding stage to success. Therefore, any ‘good’ codewords would contribute to additional information for an attacker to differentiate whether \( W \in B_{t+1}(w') \). In the absence of these additional information, \( W \) is hidden in information theoretically fashion with security proportional to the entropy contained in the distribution \( W \) over \( \mathcal{M}_1 \).

We now formalize the security of the sketching algorithm \( SS_{\Omega,C^*,C_k} \). We assume an original input \( w \) is randomly sampled from some random distribution \( W \) (not mandatory uniform) over a metric space \( \mathcal{M}_1 = \{0,1\}^k \). Besides, we restrain another sample \( w' \in W' \) that show at least error rate of \( \|w \oplus w'\| (k^*)^{-1} \geq \xi + \epsilon \) (holds for \( \|w \oplus w'\| \geq t_{(+)\text{}} \)) with the original sample \( w \). Recall the number of correctable error is bounded proportional to the introduced error of parameter \( \epsilon \) (i.e., \( 2\epsilon \)).

We take to characterize the security of \( SS_{\Omega,C^*,C_k} \) by using an adversary \( \mathcal{A} \) comes with \textit{unlimited} computation power and probable of sampling any \( w' \) satisfies \( \|w \oplus w'\| \geq t_{(+)\text{}} \). Meanwhile, \( \mathcal{A} \) possesses full power in choosing any other error parameter \( \epsilon' \leq \epsilon \) in recovering \( w \). Noting that when \( \epsilon' = \epsilon \), it means optimal error correction. The security is formalize by using an attack running together with \( \mathcal{A} \). Formally, \( \mathcal{A} : \mathcal{M}_1 \times \mathcal{M}_2 \times F_2^{n \times k^*} \times F_2^{n \times k} \times [k^*]^n \rightarrow \mathcal{M}_1 \) is just an algorithm that is computationally unbounded, aim to recover \( w \) from a sketch \( ss \in M_2 \), with the generator matrices \( G^* \in F_2^{n \times k^*} \) and \( G \in F_2^{n \times k} \), a random integer string \( N \in [k^*]^n \) and \( w' \in \mathcal{M}_1 \) and error parameter \( \epsilon' \leq \epsilon \). The attack is denote as \( \text{Attack}(SS_{\Omega,C^*,C_k}, N, G^*, G, \epsilon, \mathcal{A}) \) with sketching algorithm \( SS_{\Omega,C^*,C_k} \), and inputs \( N, G^*, G, \epsilon, \) and \( \mathcal{A} \) as follow:

\[
\begin{align*}
\text{Attack}(SS_{\Omega,C^*,C_k}, N, G^*, G, \epsilon, \mathcal{A}) \\
1: \quad & w \leftarrow W \parallel \text{sample according to some distribution } W \in \mathcal{M}_1 \\
2: \quad & w' \leftarrow W' \\
3: \quad & \text{if } \|w \oplus w'\| \leq t_{(+)\text{}} \text{, repeat step 2 until } \|w \oplus w'\| \geq t_{(+)\text{}} \\
4: \quad & \text{if } \mathcal{A}(SS_{\Omega,C^*,C_k}(w, N, G^*, G, \epsilon), w', N, G^*, G, \epsilon') = w \\
5: \quad & \text{Output } \text{true} \\
6: \quad & \text{else} \\
7: \quad & \text{Output } \text{false} \\
8: \quad & \text{endif} \\
9: \quad & \text{endif}
\end{align*}
\]

We then have the following definition for our security.

**Definition 3.** Let \( \mu > 0 \) and \( \epsilon \in [(2k^*)^{-1}, \xi] \). Given some random variables \( W, W' \in \mathcal{M}_1 \), and \( SS \in \mathcal{M}_2 \), where \( \mathcal{M}_1 = \{0,1\}^k \) and \( \mathcal{M}_2 = \{0,1\}^n \). Given \( N \in [k^*]^n \), an \([n^*, k^*, t^*]\) linear code \( C^* \) and an \([n, k, t]\) linear code \( C_k \) with generator matrices \( G^* \in F_2^{n \times k^*} \) and \( G \in F_2^{n \times k} \) respectively, where \( \xi = t/n \) and \( k^* < n^* \leq k < n \). For all \( w \in W \), \( w' \in W' \), and \( SS_{\Omega,C^*,C_k}(w, N, G^*, G, \epsilon) = ss \in SS \), then algorithm \( SS_{\Omega,C^*,C_k} \) is \((\mu, \xi + \epsilon)\)-information theoretically secure if \( \Pr[\text{Attack}(SS_{\Omega,C^*,C_k}, N, G^*, G, \epsilon, \mathcal{A}) = \text{true}] \leq \mu \) for any computationally bounded adversary \( \mathcal{A} \).
According to Definition 3, we give a theorem with proof to generally characterize the security of \(SS_{\Omega,C^*,C_t}\).

**Theorem 4.** Let \(\log(n+1) = \lfloor \log(1/\exp(-2n\epsilon^2)) \rfloor\). For a positive integer \(m \geq 1\) and \(\|w + w'\| \geq t_{(+)}\), if both \(C^*\) and \(C_t\) are BCH codes with syndrome decoding algorithm \(f\), then, \(SS_{\Omega,C^*,C_t}\) is \((\mu, \xi + \epsilon)\)-information theoretically secure with \(\mu = (\frac{1}{2} - \frac{\log(1/\beta)}{m})\) when \([k^*h_2(2\epsilon)] > \log(n + 1)\).

**Proof.** We first analyse the amount of effort for adversary \(A\) in recovering \(w\) from a sketch when \(\|w + w'\| \geq t_{(+)}\). We claim that this amount of effort is large and bounded by the number of codewords which are considered as ‘good’ for the first decoding stage to success. In particular, given \(\|e'\| = [2k^*\epsilon'] \leq [2k^*\epsilon]\), let \(t'_{(+)} = [(\xi + \epsilon')k^*]\), and \(t'_{(-)} = [(\xi - \epsilon')k^*]\), (where \(\beta = \exp(-2n\epsilon^2)\):

\[
\min_{t=t_{\text{min}}} \Pr[\|\delta\| \leq t \mid \|w + w'\| \leq t'_{(-)}] = 1 - \exp(-2n(\epsilon')^2) \leq 1 - \beta
\]

\[
\max_{t=t_{\text{max}}} \Pr[\|\delta\| \leq t \mid \|w + w'\| \geq t'_{(+)}] = \exp(-2n(\epsilon')^2) \geq \beta
\]

Therefore, the number of codewords which are considered as ‘good’ is at most \(1/\exp(-2n(\epsilon')^2) \leq 1/\beta\) by Eq. 5. It follows this number can be further bounded as \(\log(1/\beta) = 2\log(1/\beta) \leq 2[\log(1/\beta)] = 2^{-\log(n + 1)}\), hence:

\[
\Pr[A(SS_{\Omega,C^*,C_t}(w, N, G^*, G, \epsilon), w', N, G^*, G, \epsilon') = w] \leq 2^{-\lfloor \log(1/\beta) \rfloor} = 2^{-\log(n + 1)}
\]

(6)

We now revert to our main problem where \(w\) is not sampled randomly instead of selected by the algorithm itself according to some distribution \(W\) (could be non-uniformly) over \(M_1\). We will show that in this case, the probability to sample any \(W \in B_{t_{(+)}}(w')\) is at most \((\frac{2^{m-1}}{2^m})\)

It should be described as follow:

\[
\Pr[\text{Attack}(SS_{\Omega,C^*,C_t}, N, G^*, G, \epsilon, A) = \text{true}] = \Pr[\|w + w'\| \leq t_{(+)} \mid \|\delta\| \leq t]
\]

To continue, we denote two events \(\{\text{Event}_a, \text{Event}_b\}\) where \(a, b \in \{0, 1\}\) as follow:

\[
\text{Event}_a = \begin{cases} 
\|\delta\| \leq t, & a = 0 \\
\|\delta\| > t, & a = 1
\end{cases}
\]

\[
\text{Event}_b = \begin{cases} 
\|w + w'\| \leq t_{(+)}, & b = 0 \\
\|w + w'\| \geq t_{(+)}, & b = 1
\end{cases}
\]
By using Bayes’ law:

\[
\Pr[\|w + w'\| \leq t_+ | \|\delta\| \leq t] = \frac{\Pr[\|\delta\| \leq t | \|w + w'\| \leq t_+] \Pr[\|w + w'\| \leq t_+]}{\Pr[\|\delta\| \leq t]}
\]

\[
= \frac{\Pr[\text{Event}_{a=0} | \text{Event}_{b=0} \cap \text{Event}_{b=0}] \Pr[\text{Event}_{b=0}]}{\Pr[\text{Event}_{a=0} | \text{Event}_{b=0} \cap \text{Event}_{b=0}] \Pr[\text{Event}_{b=0}]}
\]

\[
= \frac{\Pr[\text{Event}_{a=0} | \text{Event}_{b=0} \cap \text{Event}_{b=0}] \Pr[\text{Event}_{b=0}] + \Pr[\text{Event}_{a=0} | \text{Event}_{b=1} \cap \text{Event}_{b=1}] \Pr[\text{Event}_{b=1}]}{\Pr[\text{Event}_{a=0} | \text{Event}_{b=0} \cap \text{Event}_{b=0}] \Pr[\text{Event}_{b=0}]}
\]

\[
= \frac{1}{1 + \frac{\Pr[\text{Event}_{a=0} | \text{Event}_{b=1} \cap \text{Event}_{b=1}] (1 - \Pr[\text{Event}_{b=0}])}{\Pr[\text{Event}_{a=0} | \text{Event}_{b=0} \cap \text{Event}_{b=0}] \Pr[\text{Event}_{b=0}]}} = \frac{\Pr[\text{Event}_{a=0} | \text{Event}_{b=0} \cap \text{Event}_{b=0}] \Pr[\text{Event}_{b=0}]}{\Pr[\text{Event}_{a=0} | \text{Event}_{b=1} \cap \text{Event}_{b=1}] (1 - \Pr[\text{Event}_{b=0}])}
\]

\[
= \left( \frac{\Pr[\text{Event}_{a=0} | \text{Event}_{b=0} \cap \text{Event}_{b=0}]}{\Pr[\text{Event}_{a=0} | \text{Event}_{b=1} \cap \text{Event}_{b=1}] \Pr[\text{Event}_{b=0}]} \right) \left( \frac{\Pr[\text{Event}_{b=0}]}{1 - \Pr[\text{Event}_{b=0}]} \right)
\]

(7)

By Eq. 5 and 6, we have \(\Pr[\text{Event}_{a=0} | \text{Event}_{b=1}] \leq 2^{-\lceil \log(1/\beta) \rceil} = 2^{-\log(n+1)}\).

By the result from Theorem 3 (Eq. 4), we have (for \(\epsilon \in [(2k^*)^{-1}, \xi]\), \(2k^* \epsilon \leq \|w \oplus w'\| \leq t_+)\):

\[
\Pr[\text{Event}_{a=0} | \text{Event}_{b=0}] = \Pr[\|\delta\| \leq t | \|w \oplus w'\| \leq t_+] \geq 2^{-k^* \epsilon_2(2\epsilon)} \geq 2^{-[k^* h_2(2\epsilon)]}
\]

To look for the solution of \(\Pr[\text{Event}_{b=0}]\), we need to use the fuzzy min-entropy notion, s.t. \(\max_{w'} \Pr[W \in B_{t_+}(w')] = 2^{-\hat{H}_{t_+}(W)}\). Therefore:

\[
\Pr[\text{Event}_{b=0}] = \Pr[\|w \oplus w'\| \leq t_+]
\]

\[
\leq \max_{w'} \Pr[W \in B_{t_+}(w')] = 2^{-\hat{H}_{t_+}}(W)
\]

Taking into consideration over all possible distributions for \(W\) of fuzzy min-entropy at least one bit, \(\hat{H}_{t_+}^{\text{fuzz}}(W) \geq 1\), it follows \(\hat{H}_{t_+}^{\text{fuzz}}(W) \geq H_{\infty}(W) = m \geq 1\). Doing so implies the worst case distribution \(W\) comes with min-entropy \(H_{\infty}(W) = m\) at least one bit. Thus, Eq. (7) can be interpreted as:

\[
\left( \frac{\Pr[\text{Event}_{a=0} | \text{Event}_{b=0}]}{\Pr[\text{Event}_{a=0} | \text{Event}_{b=1}]} \right) \left( \frac{\Pr[\text{Event}_{b=0}]}{1 - \Pr[\text{Event}_{b=0}]} \right) = \left( \frac{2^{-[k^* h_2(2\epsilon)]}}{2^{-\log(n+1)}} \right) \left( \frac{2^{-m}}{1 - 2^{-m}} \right)
\]
For \([k^*h_2(2\epsilon)] > \log(n+1), [k^*h_2(2\epsilon)] − \log(n+1) ≥ 1\) must hold by minimum. The maximum achievable probability is thus:

\[
\Pr[\text{Attack}(SS_{Ω, C^∗, C_t}, N, G^∗, G, \epsilon, A) = \text{true}] \leq \left( \frac{2^{-[k^*h_2(2\epsilon)]}}{2^{−\log(n+1)}} \right) \left( \frac{2^{-m}}{1-2^{-m}} \right)
\]

hence complete the prove.

Eventually, we give the below proposition to formalize \(SS_{Ω, C^∗, C_t}, Rec_{Ω, C^∗, C_t, t}\) as an information theoretically secure sketch. Recall \(\beta = \exp(−2n\epsilon^2)\):

**Proposition 3.** Given \(\log(n+1) = \lceil \log(1/β) \rceil\), \(SS_{Ω, C^∗, C_t}, Rec_{Ω, C^∗, C_t, t}\) is an efficient \(\langle M_2, m, m−\log(n+1), t(+)\rangle\)-secure sketch.

**Proof.** We start from the proof of correctness. Obviously, the correctness simply follows the proof of Theorem 3. When \([2k^*] ≤ \|w \oplus w'\| ≤ t(+), [k^*h_2(2\epsilon)] ≤ \log(n+1) ≤ \lceil \log(1/β) \rceil\), the errors can be corrected with overwhelming probability (at least \(1 − \exp(−2n\epsilon^2)\)) efficiently after \(Rec_{Ω, C^∗, C_t, t}\) has run in \(\text{poly}(n)\) iterations for sufficiently larger \(n\).

For security proof, by Theorem 4 (first line of Eq. 8). For \(\epsilon \in [(2k^*)^{-1}, \xi]\) and \(\|w \oplus w'\| > t(+), \) given a sketch \(ss \in SS\) over \(M_2\), two generator matrices \(G^∗ \in \mathbb{F}_2^n \times k^∗\) and \(G \in \mathbb{F}_2^n \times k\), a random integer string \(N \in [k^∗]^n\) and \(w' \in W'\) over \(M_1\), the residual entropy required for a computationally unbounded attacker to find any variable \(W \in B_t(+)(w')\) can be expressed as:

\[
\tilde{H}_∞(W|SS, G^∗, G, N, W', \epsilon) = −\log\left(\Pr[\text{Attack}(SS_{Ω, C^∗, C_t}, N, G^∗, G, \epsilon, A) = \text{true}]\right)
\]

\[
> −\log\left(\frac{2^{-[m+[k^*h_2(2\epsilon)]−\log(n+1)]}}{1−2^{−m}}\right) = m + [k^*h_2(2\epsilon)]−\log(n+1) + \log(1−2^{−m})
\]

For \(m ≥ 1\), the term \(0 ≥ \log(1−2^{−m}) ≥ −1\). Also, by efficiency claim, the term \([k^*h_2(2\epsilon)] ≤ \log(n+1)\) must hold. Therefore, by minimum, the average minimum entropy is describe as:

\[
\tilde{H}_∞(W|SS, G^∗, G, N, W', \epsilon) > m + [k^*h_2(2\epsilon)]−\log(n+1) + \log(1−2^{−m}) ≥ m−\log(n+1)
\]

and complete the prove.

### 5.1 Security Bound on Secure Sketch

In this section, we consider the security bound on the secure sketch. Formally, this security bound also refer to the best possible security can offer by a secure sketch construction. Particularly, we are interested in the best possible security by using the new sketching and recover algorithm pair \(SS_{Ω, C^∗, C_t}, Rec_{Ω, C^∗, C_t, t}\).
If a secure sketch allows recovery of the input from some errors with high probability, it must consist of enough information to describe the error pattern. According to Dodis et al. [7], in a random error model, under the relaxed correctness notion, describing the outcome of \( n \) independent coin flips with probability of error, \( p \) requires \( nh_2(p) \) bits of entropy. Therefore, the sketch must loss \( nh_2(p) \) bits of entropy. They used the Shannon entropy to describe the security bound in this model and assumed the input is random and uniformly distributed. Since \( nh_2(p) \) bits of entropy is loss from the sketch, the upper bound residual entropy is thus reduced to \( n(1 - h_2(p) - o(1)) \). Larger value of \( p \in (0, 1/2) \) results to lower residual entropy.

In our model, the entropy loss can be described by \( \log(n + 1) \) (see Eq. 9). Observably, \( \log(n + 1) \) could lower than \( nh_2(p) \) with higher value of \( p \). This result suggested a better achievable lower bound to describe the error pattern in the resilient vectors of size \( n \) by using \( \log(n + 1) \) rather than \( nh_2(p) \), especially for high error rate \( p \).

More formally, our residual entropy is shown to be larger than \( m + [k^*h_2(2\epsilon)] - \log(n + 1) - \log(1 - 2^{-m}) \). Given \( [k^*h_2(2\epsilon)] \leq \log(n + 1) \), entropy loss cannot be avoided, therefore, high min-entropy became a necessary condition to show security for any sources under a family of distributions \( \{W_1, \ldots \} \in W \) over \( M_1 \). In viewed of this, meaningful security (e.g., at least one bit) can only be showed over any distribution \( W \in W \) with entropy larger than the total entropy loss.

On the other hand, if \( [k^*h_2(2\epsilon)] > \log(n + 1) \), our results (see Theorem 4) replied that the residual entropy could be equal to \( m \). Therefore one can always show meaningful security for any random distributions \( W \in M_1 \), including the worst case distribution with min-entropy \( H_\infty(W) = m \geq 1 \). However, there will have no efficiency guaranty for the recovery algorithm \( \text{Rec}_{\Omega, C^*, c_t, t} \) to success and terminate in time \( \text{poly}(n) \).

In a nutshell, we could have \( \langle SS_{\Omega, C^*, c_t, t}, \text{Rec}_{\Omega, C^*, c_t, t} \rangle \) to accept any sources with any distribution of min-entropy at least \( \log(n + 1) + 1 \) (super-logarithm) to claim correctness and security of at least one bit.

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<thead>
<tr>
<th>Security Bound for ( \beta )-Correct Secure Sketch</th>
<th>Computational</th>
<th>Best possible security</th>
<th>( H_\infty(W) - \log(1 - \beta) )</th>
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<td>Computational</td>
<td>FRS sketch(universal hash functions) [28]</td>
<td>( H_{\text{fuzz}}^f(W) - \log(1/\beta) - \log \log(\text{supp}(W)) - 1 )</td>
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<tr>
<td>Computational</td>
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<tr>
<td>Info. theoretic</td>
<td>Proposed</td>
<td>( H_\infty(W) - \log(n + 1) )</td>
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Table 1: Summary of security bound of \( \beta \)-correct secure sketch in term of fuzzy-min entropy.

Table 1 tabulated the security bound for various \( \beta \)-correct probabilistic secure sketch in correcting the error in probability \( 1 - \beta \). We hereby stress that we have \( \lfloor \log(1/\beta) \rfloor = \lfloor \log(1/\exp(-2\epsilon^2)) \rfloor = \log(n + 1) \), a special case in our proposal.
6 Reusability

We focus on the reusability of \((SS_\Omega, c^*, c_\xi, \text{Rec}_\Omega, c^*, c_\xi, f)\) in this section. First stated by Boyen, 2004 [13], any information theoretical secure sketch or fuzzy extractor must leak certain amount of fresh information about the input for each time it reuses/re-enrolls. The reusability property allows the reuse/re-enrollment of the noisy data with multiple providers. Trivially, if \((SS_\Omega, c^*, c_\xi, \text{Rec}_\Omega, c^*, c_\xi, f)\) can show reusability property, it also suggested a reusable fuzzy extractor for uniform random strings generation.

In the context of showing reusability, \((SS_\Omega, c^*, c_\xi)\) may run in multiple times for enrollment of correlating samples \(w_1, w_2, \ldots, w_\gamma\). Each enrollment should return a sketch \(ss\) which possesses individual security that holds even under the existence of other sketches for \(i \in \{1, \ldots, \gamma\}\). Boyen's work on assuming a single adversary should be able to perform some perturbation on the original input \(w^*\) to yield a list of correlating samples \(w_1, w_2, \ldots, w_\gamma\), further gains advantages in recovering \(w_i\) from its corresponding sketch \(ss_i\). The works of Boyen on reusability has focused on a particular class of perturbation which is the transitive and isometric permutation applied to \(w^*\). This constraint applied to the perturbation is unlikely in a real and practical scenario. However, his work has encouraged the needs of showing reusability for a secure sketch to offer stronger security guarantee.

Apart from Boyen works, Fuller et al., (2016) [28] provided a modified definition of reusability that covered a more realistic scenario. In their works, they split the adversary into a group of adversaries \(\{A_1, \ldots, A_\gamma\}\). This group of adversaries implicitly defined different distributions over the published sketch \(\{ss_1, \ldots, ss_\gamma\}\). Each sketch is subjected to a particular adversary in the group to show security individually. The act of showing security for a group of adversaries manifested the reusability for independent re-enrollment of the original input with multiple providers that may not trust each other. They utilized set of functions \(f_1, \ldots, f_\gamma\) to sample \(w', \ldots, w_\gamma\) s.t. \(w_i = f_i(w^*, ss_1, \ldots, ss_i)\). These set of functions come with the main property, is to offer fresh min-entropy to the new sample \(w_i\) over a particular distribution \(W_i\). The security is defined computationally with fuzzy min-entropy and holds for a large class of family of distributions \(\{W_1, \ldots, W_\gamma\}\) over \(\mathcal{M}\).

Our intuition of showing reusability for a group of adversary follows the works proposed by Fuller et al., [28]. The goal is to show security to the original sample \(w^*\) for different independent re-enrollments come with certain degree of perturbations. It considered a stronger notion of reusability compare to the previous case studied by Boyen and Fuller et al.. It means to show security for any perturbation applied to the input as long as the perturbation is kept within some limited strength, i.e., the maximum number of altered bits is bounded. This notion is more applicable to real case scenario since it does not introduce any assumption on the type of perturbation applied to the input but only provides a bound on it. To do so, we have introduced additional random error \(\{e_1, \ldots, e_\gamma\}\), s.t. \(|e_i| = [k^*e_i] \leq [k^*\epsilon]\), i.e., \(e_i \leq \epsilon\) acting as perturbation to the input \(w^*\) to sample a list of correlating reading \(\{w_1, \ldots, w_\gamma\}\). The usage of random
error is better fit to real case scenario, since any perturbation occurs during re-enrollment must cause certain amount of bits flip to the original sample \( w^* \).

To formalize the reusability of \( \langle SS_{\Omega,C,t}, Rec_{\Omega,C,t} \rangle \) with perturbation parameter \( \epsilon_i \leq \epsilon \), we assume an original input \( w^* \) is randomly sampled from a metric space \( M_1 = \{0,1\}^{k^*} \), then we apply perturbation on \( w^* \) to generate a list of correlated samples \( \{w_1, \ldots, w_\gamma\} \) over some random distribution \( \{W_1, \ldots, W_\gamma\} \in M_1 \) (parametrized by \( \epsilon_i \leq \epsilon \)) respectively. Such realization of perturbation in fact can be done straightforwardly with \( SS_{\Omega,C,t}(w^*, N, G^*, G, \epsilon_i) \rightarrow SS_i \) to output a random sketch \( SS_i \) over \( M_2 = \{0,1\}^n \). In such a case, we could have another sample \( w' \in W' \) over \( M_1 \) that show at least error rate of \( \|w_i \oplus w'\| (k^*)^{-1} \geq \xi + \epsilon \geq \xi + \epsilon_i \), where \( \|w_i \oplus w'\| \geq t_{(+)} \) is always true by \( \epsilon_i \leq \epsilon \) (for \( i = 1, \ldots, \gamma \)). We aim to characterize the reusability of \( \langle SS_{\Omega,C,t}, Rec_{\Omega,C,t} \rangle \) by using a group of adversaries \( \{A_1, \ldots, A_\gamma\} \) comes with unlimited computation power. Formally, each adversary \( A_i : M_1 \times M_2 \times \mathbb{F}_2^{n \times k^*} \times \mathbb{F}_2^{n \times k^*} \times \mathbb{F}_2^{n \times k^*} \rightarrow M_1 \) is simply an algorithm that is computationally unbounded to output \( w_i \in M_1 \) from a public sketch \( SS_i \in M_2 \), with input \( w' \in M_1 \), generator matrices \( G^* \in \mathbb{F}_2^{n \times k^*} \) and \( G \in \mathbb{F}_2^{n \times k^*} \) and a random integer string \( N \in [k^*]^n \). Our formalization uses a second attack running with \( \{A_1, \ldots, A_\gamma\} \). Likewise the formulation of Attack, each adversary \( A_i \) is giving full power of choosing any other error parameter \( \epsilon_i' \leq \epsilon_i \) in recovering \( w_i \) for maximum error tolerance.

The second attack is depict on Attack2(\( SS_{\Omega,C,t}, N, G^*, G, \epsilon, \{A_1, \ldots, A_\gamma\} \)) with sketching algorithm \( SS_{\Omega,C,t} \), and inputs \( N, G^*, G, \epsilon \) and \( A_i \), which is consider as succeeded if at least one adversary \( A_i \in \{A_1, \ldots, A_\gamma\} \) has successfully recover \( w_i \) from the sketch \( SS_i \).

The reusability of \( \langle SS_{\Omega,C,t}, Rec_{\Omega,C,t} \rangle \) can be generally characterized by the definition below.
\textbf{Definition 4.} Let \( \mu' > 0, \epsilon \in [(2k^*)^{-1}, \xi] \) and \( \epsilon_i \leq \epsilon \) and \( i = 1, \ldots, \gamma \). Let \( W_i, W', W* \in \mathcal{M}_1 \) and \( SS \in \mathcal{M}_2 \) be some random variable over \( \mathcal{M}_1 = \{0,1\}^{k^*} \) and \( \mathcal{M}_2 = \{0,1\}^n \) respectively. Given \( N \in [k^*]^{n}, \) an \( [n^*, k^*, t^*]_2 \) linear code \( \mathcal{C}^* \) and an \( [n, k, t]_2 \) linear code \( \mathcal{C}_\xi \) with generator matrices \( G^* \in \mathbb{F}_2^{n^* \times k^*} \) and \( G \in \mathbb{F}_2^{n \times k} \) respectively, where \( \xi = t/n \) and \( k^* < n^* \leq k < n \). For all \( w' \in W', \) \( w_i \in W_i, \) \( w^* \in W \) and \( SS_{\mathcal{C}_\xi, \mathcal{C}_\xi}^{SS}(w^*, N, G^*, G, \epsilon_i) = s_{s_i} \in SS_i, \) we said algorithm pair \( (SS_{\mathcal{C}_\xi, \mathcal{C}_\xi}, \text{Rec}_{\mathcal{C}_\xi, \mathcal{C}_\xi}) \) is \( (\epsilon, \mu', \gamma) \)-reusable if one has the probability \( \Pr[\text{Attack}_2(SS_{\mathcal{C}_\xi, \mathcal{C}_\xi}, N, G^*, G, \epsilon, \{A_1, \ldots, A_\gamma\}) = \text{true}] \leq \mu'. \)

\textbf{Theorem 5.} Let a positive integer \( m \geq 1 \) and \( \log(n+1) = \lceil \log(1/\exp(-2n\epsilon^2)) \rceil \).

For \( \|w_i \oplus w'\| \geq t_\epsilon \), given both \( \mathcal{C}^* \) and \( \mathcal{C}_\xi \) are BCH codes with syndrome decoding algorithm \( f \), then, \( (SS_{\mathcal{C}_\xi, \mathcal{C}_\xi}, \text{Rec}_{\mathcal{C}_\xi, \mathcal{C}_\xi}) \) is \( (\epsilon, \mu', \infty) \)-reusable when \( [k^*h_2(2\epsilon)] \leq \log(n+1) \) where \( \mu' = \left( \frac{2^{-m+\log(n+1)}}{1-2^{-m}} \right) \).

\textbf{Proof.} Clearly, \text{Attack}_2 \ will output a true result if at least one of the adversary \( A_i \) has successfully recover \( w_i \) from the sketch \( s_{s_i} \). Since, \( \epsilon_i' \leq \epsilon_i \leq \epsilon \), one obtains the same bound by Eq. 5 and Eq. 6:

\[
\Pr [A_i(SS_{\mathcal{C}_\xi, \mathcal{C}_\xi}^{SS}(w^*, N, G^*, G, \epsilon_i), w', N, G^*, G, \epsilon_i') = w_i] \leq 2^{-\lceil \log(1/\beta) \rceil} = 2^{-\log(n+1)}
\]

Therefore, the reusability attack \text{Attack}_2 \ is at least as hard as \text{Attack} \ over single adversary setting with maximum error parameter \( \epsilon \). It follows:

\[
\begin{align*}
\Pr [\text{Attack}_2(SS_{\mathcal{C}_\xi, \mathcal{C}_\xi}^{SS}(N, G^*, G, \epsilon, \{A_1, \ldots, A_\gamma\}) = \text{true}] & \leq \Pr [A_i(SS_{\mathcal{C}_\xi, \mathcal{C}_\xi}^{SS}(N, G^*, G, \epsilon, \{A_1, \ldots, A_\gamma\}) = \text{true}] \\
& < \left( \frac{2^{-[k^*h_2(2\epsilon)]}}{2^{-\log(n+1)}} \right) \left( \frac{2^{-m}}{1-2^{-m}} \right) \leq \left( \frac{2^{-m+\log(n+1)}}{1-2^{-m}} \right)
\end{align*}
\]

The last line follows by \( [k^*h_2(2\epsilon)] \leq \log(n+1) \), hence complete the prove.

Theorem 5 concluded that the original input \( w^* \in W \) can be reused for \( \gamma \) times to generate \( \gamma \) number sketches \( SS_{\mathcal{C}_\xi, \mathcal{C}_\xi}^{SS}(w^*, N, G^*, G, \epsilon_i) = s_{s_i} \in SS_i \) with perturbation parameter \( \epsilon_i \leq \epsilon \). Viewed this way, adding error of parameter \( \epsilon \) larger than the input perturbation \( \epsilon_i \leq \epsilon \) while sketching implicitly allows reusability (under the case where all providers are not communicating to each other).

\textbf{References}


