

VerMI: Verification Tool for Masked Implementations

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Abstract. Masking is a widely used countermeasure against Side-Channel Attacks (SCA), but the implementation of these countermeasures is challenging. Experimental security evaluation requires special equipment, a considerable amount of time and extensive technical knowledge. So, to automate and to speed up this process, a formal verification can be performed to assess the security of a design. Multiple theoretical approaches and verification tools have been proposed in the literature. The majority of them are tailored for software implementations, not applicable to hardware since they do not take into account glitches. Existing hardware verification tools are limited either to combinational logic or to small designs due to the computational resources needed.

In this work we present VerMI, a verification tool in the form of a logic simulator that checks the properties defined in Threshold Implementations to address the security of a hardware implementation for meaningful orders of security. The tool is designed so that any masking scheme can be evaluated. It accepts combinational and sequential logic and is able to analyze an entire cipher in short time. With the tool we have managed to spot a flaw in the round-based KECCAK implementation by Gross *et al.*, published in DSD 2017.

Keywords: VerMI, Masking, Formal Verification, Non-completeness, Uniformity, Glitches, Logic Simulator

1 Introduction

Implementing cryptographic algorithms in hardware has become quintessential, since physical attacks on cryptographic devices are getting increasingly popular and easier to reproduce. Side-Channel Attacks (SCA) exploit the leakage from different physical properties of the device, Differential Power Analysis (DPA) [20] being one of the most common attacks. Several countermeasures have been proposed in the literature, including hiding and masking [28]. Masking has caught most attention, with multiple schemes published to date [9, 17, 19, 25, 27, 30]. They are all based on secret sharing, where each sensitive data, i.e. key dependent, x is divided into s pieces ($\mathbf{x} = (x_1, \dots, x_s)$), such that $x = x_1 \perp \dots \perp x_s$. We consider Boolean masking, where \perp is field addition denoted by \oplus , and all s shares are needed to

derive x . Threshold Implementations has been proposed in [25] by defining the following three properties to secure a hardware design:

- *Correctness*: a shared function \mathbf{f} such that $f_i(\mathbf{x}) = y_i$, where $i = 1, \dots, s$, is correctly shared if $\sum y_i = y = f(x)$.
- *Non-completeness*: a shared function \mathbf{f} is d^{th} -order non-complete if any combination of up to d component functions f_i is independent of at least one input share.
- *Uniformity*: the outputs of a shared function have to conform a uniform distribution. Note that given a uniform sharing, it is sufficient to preserve the uniformity across operations to achieve univariate security (together with non-completeness).

Checking if a cryptographic implementation is in fact secure is a very demanding exercise. One way is by using attack based evaluations, but this is highly inefficient, since it requires a considerable effort implementing different attacks, ensuring solely security against those specific attacks. Following the same principle is the non-specific test vector leakage assessment (TVLA) [12] over the power consumption or the electromagnetic radiation of the device to detect leakage. Despite a few limitations [29], this method provides a more generic conclusion on the security and has been widely used in the literature [11, 22] to assess security of several implementations. Yet, TVLA and attack based evaluations need the actual ASIC or a correctly programmed FPGA, as well as special equipment to be performed.

Formal verification is another way of evaluating the security of a cryptographic implementation. This method studies the theoretical conditions for a design to be secure [2, 3, 5, 10, 13] or models the implementation to simulate its behavior [7, 26].

Our contribution. We propose a Verification Tool to aid in the design flow towards secure hardware implementations. The tool helps to spot any mistake in the application of the aforementioned properties with bit precision and provides an initial univariate security evaluation without any special equipment. In addition, the tool is applicable to the CMS [27] and DOM [17] masking schemes, since they inherit the aforementioned TI properties. VerMI works at both algorithmic and implementation level, with an inherent capability to check designs in the presence of glitches. We build a structural model of the circuit, providing highly precise information on the behavior of every bit. When analyzing the first-order DOM KECCAK S-box, our program takes 1.34ms to check non-completeness and 1.7s to check uniformity. Thus, the total time needed for a complete analysis is less than 2s on an Intel Core i5-4590 CPU with a clock frequency of 3.3GHz and 7.6 GB of RAM running a 64-bit Linux CentOS7.

The tool reads a VHDL or Verilog module, builds the structural model of the circuit and implements a logic simulator (Sect. 3). It is able to analyze non-completeness and uniformity in combinational logic (Sec. 4) and it can handle sequential circuits (Sec. 5). Subsequently, several important items are discussed (Sec. 6) and to conclude the article, different experiments are presented (Sec. 7). The tool is tested for different implementations from the literature, finding a flaw in

the round-based KECCAK implementation in [18], which fails the non-completeness property.

2 Previous work

Formal verification for masked implementations is a widely researched topic [2, 4, 13, 15, 16, 23]. These works target software implementations and neither of them take into account glitches. Therefore, they can not be applied to verify hardware implementations.

Formal verification of masked hardware implementations can be done in several stages of the design flow: at algorithmic, at implementation or at physical level. In the work of Reparaz [26] a tool for verification at algorithmic level is presented. The tool receives a software implementation of the secured function and performs a leakage assessment over simulated traces. However, glitches are not taken into account.

At implementation level Bertoni *et al.* in [7] present a tool suitable for hardware implementations in the presence of glitches. Nevertheless, their tool only analyzes combinational logic with a simple power model. Bloem *et al.* in their recent work [10] also present a formal verification method for hardware implementations in the presence of glitches. Given a hardware implementation they extract the netlist and model the logic gates using a Fourier expansion. Three different types of variables are defined, i.e. secret variables (S), masks (M) or other variable (P), and every intermediate value of the circuit is *labeled* with a set of these variables, where the labels are based on the Fourier representation of the Boolean function. A value is not secure if the associated label contains a set with only secret variables. To simulate glitches, the representation of a gate is extended to compute any Boolean function from its original inputs and to analyze higher-orders, a SAT solver is instantiated; both cases increase the analysis complexity considerably. Looking at their analysis of the first-order DOM KECCAK S-box [18], it is possible to see how much the run time increases when performing the analysis considering glitches versus not considering them, taking 20s in the first case and around 1s in the second case. Results in [10] are gathered on an Intel Xeon E-52699v4 CPU with a clock frequency of 3.6 GHz and 512 GB of RAM running a 64-bit Linux Debian 9.

3 Design choices

VerMI is designed to parse a synthesized netlist, where a logic simulator reconstructs the logic circuit using wires, pins and gates as objects connected to one another. Thus, it is possible to simulate the functionality of the circuit and perform efficient tree search to check connections.

3.1 Building the netlist

The tool receives an HDL design that can be written in VHDL or Verilog, and has to be capable of reading designs from all kind of developers, so it is important to

take into account the different coding styles. In order to unify the files to analyze, the first step is to synthesize the design and extract the netlist. To do this, we use an RTL synthesis tool with open source NanGate libraries. The tool is currently programmed to parse components from this library, therefore restricted to netlists using gates with the same name. If needed, the code is easily adaptable to any other library.

The program parses the elementary gates of this library. To get a single netlist that uses solely these elements, we specify `-ungroup_all` so that the netlist does not synthesize sub-modules and uses them to build the top module. This tool is meant to check security oriented implementations, so in order to avoid any optimization that might compromise the security, we also specify `-exact_map`. This option specifies that the elements in the netlist exactly match the specifications in the HDL description. An implementation compiled without this option or with any optimization options could be classified as non-secure by the tool, not due to a designers fault, but due to possible optimizations of important blocks for the security of the design.

3.2 Logic simulator

We create three classes that allow us to build the structural model of a given circuit. These objects are the basic logic elements:

Wire. A wire needs, basically, to hold a name and a value. This first class includes several attributes: the name of the wire, the value, and a flag to note that the wire is already evaluated conform the attributes. It includes a single method, `eval_wire`, which evaluates the value of the wire, sets the flag to evaluated and propagates the simulation to the next gate (more details given in Section 4.3).

Gate. A gate requires, primarily, a type and a functionality. This class keeps the type of gate (AND, XOR, MUX), the name given to the instantiation of the block, and the functionality, a function that evaluates the output according to the type of gate, no matter what type. Certain gates also include the so-called *controlling value* c and *inversion* i [21]. An input value is said to be controlling if it determines the value of the output regardless of the value of the other inputs. Inversion determines whether the output value is inverted. By definition, only the four basic gates AND, OR, NAND, and NOR have these values, given in Table 1:

Pin. The third class is created to connect the previous two. The presence of this union is important, since it determines the role of each wire when evaluating a gate. It stores the name of the pin, used later when computing a gate function, and the wire and the gate to which the pin is connected.

Connecting elements. For each wire, gate and pin, the tool instantiates a new pointer to the specific object. Class `wire` has two pointers to `pin`, `pin_from` and `pin_to` that define the beginning and the end of the wire. Class `gate` holds a vector of input pins `inputs` and another pin `output`.

Table 1: Controlling and inversion values for basic gates

	<i>c</i>	<i>i</i>
AND	0	0
OR	1	0
NAND	0	1
NOR	1	1

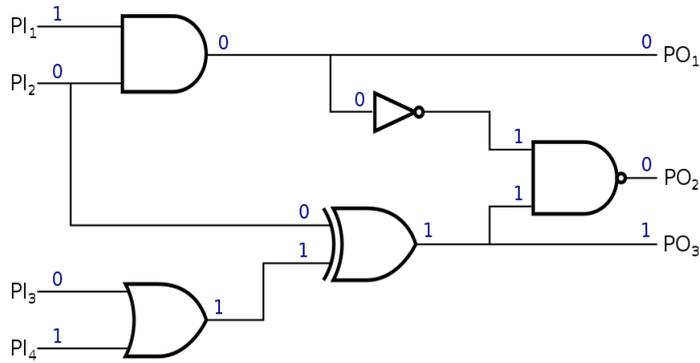


Fig. 1: Circuit structural model and logic simulator

Pins are also important to manage fan-outs. In digital logic, fan-outs occur when a logic gate output is fed into multiple subsequent gates as input. We model them by adding two more attributes to the wire class: the first one, a flag to indicate whether certain wire has a fan-out, and the second one, a vector of pins to keep the multiple endings of this wire, `fan_out_pins`. These new pins represent the fan-out wires that are driven to the different gates.

3.3 Header

The top module of the design to analyze has to include a small header in which important data for the tool is specified. The header data includes the names of the sensitive inputs, the outputs of every layer of registers, possible random numbers and the outputs to be analyzed. Thus, the tool can distinguish the sensitive data among all the inputs and for every stage in between registers, sorting the variables and their shares in a N by M matrix, where N is the number of variables and M the number of shares. The random numbers are specified as well to avoid being included in the non-completeness analysis and to see how are they taken into account when analyzing uniformity. Finally, the outputs are included in the header so that the tool knows which outputs should be considered and when.

4 VerMI

To initiate the program, we need to provide the source path for the RTL synthesizer and create few directories to store the netlist and some other files. First, the program analyzes the input file, from which the language, the header information and the name of the top module are retrieved. Then, it generates a specific *.tcl* file for this module and calls the RTL compiler to source it. Finally, the netlist is generated and wires, pins and gates are created to build the circuit model.

Once this is done the tool offers several functionalities: to calculate all input dependencies of the output variables, to check non-completeness and uniformity.

4.1 Input dependencies

This feature outputs the number and the specific input variables on which the outputs depend.

Recursive tree search. Taking advantage of the objects mentioned above, we are able to build a detailed structural model of the circuit and hence perform a highly efficient tree search to get all input dependencies. Logic circuits have a hierarchical tree structure, where the root nodes correspond to the primary outputs, i.e outputs of the module. The subtrees' parent nodes correspond to the output of a gate and the children to its inputs.

We implement a recursive algorithm that starts at a primary output and goes through the circuit backwards covering all paths containing this output. The algorithm keeps running until it arrives to a primary input, which is saved as a dependency if it is declared as sensitive in the header. Alg. 1 presents the pseudocode of this function and Fig. 2 illustrates the corresponding tree for two outputs of the circuit shown in Fig. 1:

Algorithm 1 Recursive Tree Search algorithm

```
1: procedure SEARCH_BACK(gate  $g$ , wires  $w$ )
2:   for all inputs  $i$  in  $g$  do
3:     if  $i$  is a Primary Input then
4:       if  $i$  is not yet saved and  $i$  is sensitive data then
5:          $w \leftarrow i$ 
6:       end if
7:     else
8:       SEARCH_BACK( $g_{\rightarrow i}$ ,  $w$ ) Where  $g$  is the gate driving  $i$ 
9:     end if
10:  end for
11: end procedure
```

4.2 Non-completeness

VerMI is able to check any-order non-completeness, to give a warning if it fails, and to output the specific bits on which this property is not fulfilled.

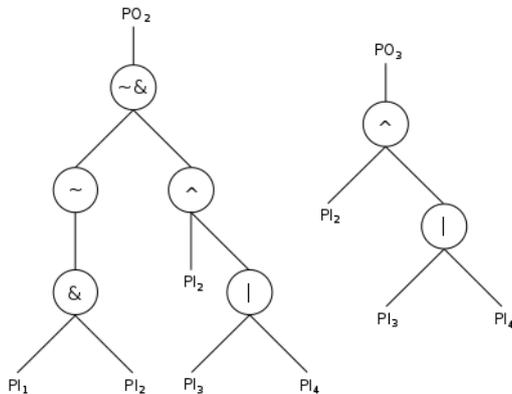


Fig. 2: Tree search in digital circuits

Decision algorithm. Once we have the dependencies of every output, we check whether all shares for the same variable are included. If this is the case, the variable fails non-completeness. The tool goes through every output performing this check. If any of them are failing, it saves this information in a text file that at the end contains the information of every output sensitive variable failing non-completeness. Finally, it announces whether this property is fulfilled or not.

To check whether all shares for the same variable are included is not a trivial task, since the tool is unable to distinguish between variables and shares. Taking advantage of the matrix data structure (See Sec. 3.3) built when parsing the netlist, the tool checks if the analyzed wire dependencies include all inputs from the same row. Hence, all shares of that variable are being used to compute certain output.

Single bit variables. Variables in a hardware module can be specified as a single bit, as collection of bits (bus) or even with more complex data structures. In case a variable is declared as a bus, the program creates a different variable for each bit in the bus. Managing the entire bus would be faster, but also less detailed. Same procedure applies with different data structures. This way the VerMI tool's results are given with bit precision.

This distinction is crucial to make the tool able to analyze masking schemes for which verification of the inputs independence is required [17, 27] as part of the non-completeness check. By performing the analysis bitwise it is possible to catch possible dependencies between bits introduced by intermediate operations.

A proof that bitwise analysis is important in the analysis of masking schemes is that VerMI tool was able to detect a flaw in the round-based KECCAK implementation in [18]. The presence of θ introduces several bit dependencies among the state which then in χ produce several failures in the non-completeness [1].

d^{th} -order non-completeness. All possible combinations of d outputs are analyzed with the same method presented above. The difference now is that the dependencies of the d outputs are combined and the tool looks among all of them. The output file includes all combination of d output variables that together fail non-completeness.

Currently VerMI supports up to third-order non-completeness verification. However, it can be easily extended to support verification of any meaningful order.

4.3 Uniformity

The third functionality is to check whether uniformity is preserved across operations. The tool calculates the output distribution of a given module by simulating all possible inputs. The frequencies of occurrence of each output vector are calculated for the different input sharings. If all frequencies are the same inside every group of input sharings, then the module is said to *preserve uniformity*. To generate uniformity-preserving shares is easy for invertible linear operations, while for non-linear operations it is not, since interaction between shares is needed. This functionality is meant to analyze these functions separately and check whether they preserve uniformity.

Simulation. All possible input vectors to the circuits are generated and simulated one by one at generation time, so there is no need to store all of them. Every primary input is evaluated with the corresponding value of the bit string. The `wire` class member function `eval_wire` is called to evaluate the wire and set it as evaluated. If a wire is already evaluated, the value does not change.

There are several levels of simulation depending on the level of modeling used to represent the simulated system. In our case we perform a *gate-level simulation*, given the structural model of the circuit built by the tool. Taking advantage of this representation, it is possible to implement an *event-driven simulation*, also known as activity-directed simulation. An event represents a change in the value of a signal, which at the same time activates the component driven by this wire [21]. The tool only evaluates active elements that may as well change their output value creating new events.

The simulation starts evaluating the primary inputs which activates the first gates and propagates the events, elements being evaluated in order of activation. A data structure `event_list` is created, where pending elements are waiting to be evaluated. An active component is evaluated only if all its inputs have already been evaluated, otherwise it is sent to the end of the queue following the already active elements. The function `eval_wire` is in charge of propagating the simulation, which continues until the event list is empty. When a wire is evaluated, all gates (including fan-outs, if exist) driven by this wire are *activated* and stored in `event_list` vector for subsequent evaluation.

We speed up the evaluation of the circuit by using the controlling values. If there is any active input driving the controlling value of the element to be updated, it is not necessary to wait until all the inputs are evaluated. The value of the output

is $c \oplus i$, c and i given in Tab. 1. In addition to set the value of the output, the rest of the inputs are fixed to *evaluated* with value $\bar{c} \oplus i$. Possible fan-outs in the inputs of the element are not evaluated with this value. By setting the rest of the inputs to *evaluated*, the possibility of extra activations is avoided.

In order to be able to simulate the next test vector it is necessary to reset the current values. To do so, a function is called to set the value of all wires to “empty” and set it as not evaluated.

Evaluation. We use the formulas from [9] to evaluate the uniformity. We check whether, for certain unshared input, every output has the same frequency of occurrence when all possible sharings of this input are evaluated. This is repeated for every possible unshared input together with, if added, all random bits specified. A frequencies vector is initialized to store the frequencies of the outputs happening for the evaluated unshared input. The output of the circuit evaluated modulo the size of the frequencies vector corresponds to the index of the frequency to be increased by one. This is done on the fly so that we do not need to instantiate multiple vectors.

Limitations. It is important to note that the uniformity check is limited by the total number of input bits and random bits. As explained above, the program has to generate all possible inputs for the circuit and evaluate each of them to get the output. Naturally, it is feasible to check just relatively small gadgets for uniformity, for instance SBoxes. The designer needs to provide the tool the sub-module that implements the SBox.

So far the biggest design analyzed was a six shares second-order KECCAK SBox, which meant a generation and evaluation of 2^{30} test vectors and which took almost 2 days using the same platform used in Sec. 1.

5 Sequential circuits

So far we have explained how the tool deals with combinational logic. In this section, we present how VerMI handles the presence of registers by dividing a big sequential circuit into all possible combinational sub-circuits or by simulating it altogether. This allows the program to analyze the security properties in the presence of sequential logic.

When designing for security, other than for functionality, the registers are required to prevent propagation of glitches and to synchronize refreshing. Uniformity is not affected by the presence of registers. Thus, the main goal of the registers, security wise, is to split the design in different sub-circuits in order to prevent the glitch propagation. Therefore, the tool analyzes non-completeness over the combinational logic in between registers, while uniformity is analyzed with registers included.

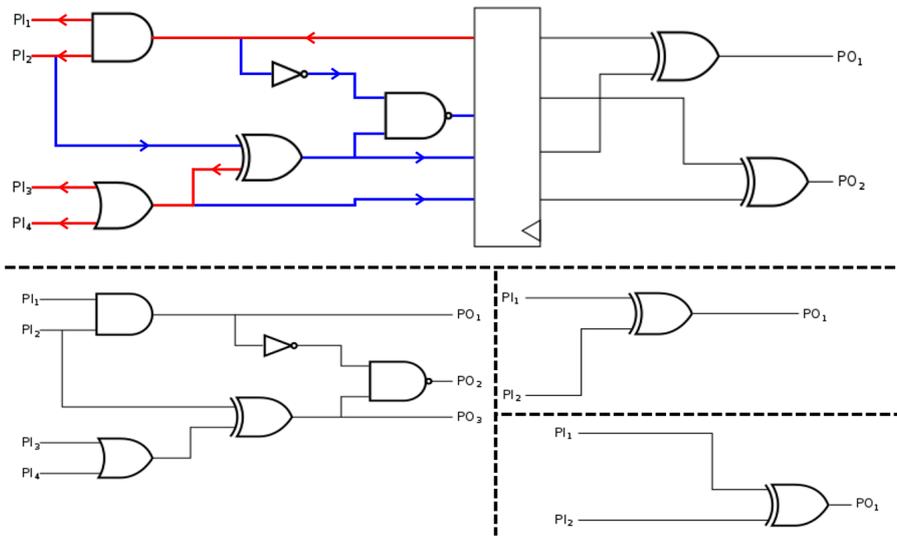


Fig. 3: Top: sequential circuit. Bottom: combinational sub-circuits for first and second stages.

5.1 Difficulties

At first sight, it is straightforward to split a sequential circuit. It is enough to get rid of the flip flops, their inputs being new primary outputs and their outputs new primary inputs. Then it is easy to decide which gates and wires belong to one or another circuit. The problem arises when a program needs to do this separation.

The tool stores a large amount of gates and wires that has to sort into the different sub-circuits. It is imperative to include the exact components that correspond to a certain sub-circuit in order to perform an accurate analysis on the security afterwards. Missing an element or including extra components, would result in a possibly non-complete output that actually should have failed the test or, on the other hand, in extra dependencies that are not in the circuit, producing a false warning.

5.2 *Back-and-forth* algorithm

To do this “physical” separation in the simulated circuit, we design the *Back-and-forth* algorithm and a new class `subcircuit` that includes all inputs, outputs, wires and gates of a sub-circuit. The algorithm works as follows:

1. All primary outputs and the input of every flip-flop (which are now new primary outputs) are stored in a new vector. The same is done with all primary inputs, including flip-flop outputs.

2. Create a new **subcircuit**, pick one of the outputs of this new vector, remove this wire from the new outputs vector, and perform a *backwards* tree search (depicted in red in Fig. 3) to find all the inputs. The algorithm will keep every gate found in its passage through the circuit.
3. When a primary input is reached, it is stored (if it was not already) and then the algorithm calls a function to perform another tree search *forward* (blue) to find all the outputs that might depend on this input. When an output is reached, it is stored (if it was not already) and erased from the new outputs vector. If there is no fan-outs, no new output would be stored.
4. When the recursion is finished, the new sub-circuit is complete and it goes back to step two until the new outputs vector is empty.

Note that this algorithm may create independent sub-circuits from the same stage of a pipeline, even though visually they could be considered to belong to the same sub-circuit. This happens when there is not a fan-out that connects them together. In Fig. 3 the right sub-circuit would be divided in two by the tool, as it should be, since there is no connection whatsoever between the two of them. When analyzing higher-order non-completeness, independent sub-circuits from the same stage will be analyzed together.

Alg. 2 presents the pseudo-code for the above-presented algorithm. We use the notation $w \rightarrow g \rightarrow v$ to refer to a gate g whose output is v and has an input w . Similarly, we use $w \rightarrow g \rightarrow v$ to refer to the output v and $w \rightarrow g \rightarrow v$ for the input w .

5.3 Simulation

The simulation of registers is only needed for uniformity analysis, which is not affected by the fact that registers are memory or synchronization elements. Thus, the simulator ignores the concept of time and registers are treated as plain buffers.

6 Discussions

6.1 Fan-outs

It is important to take fan-outs into account and dedicate them special attention since their presence increases greatly the complexity of a digital circuit. The circuit is no longer a perfect tree: the nodes may have more than one parent. This results in multiple trees connected to each other. Thus, we design our *Back-and-Forth* algorithm to fully cover all these connected trees.

6.2 Map data structure

When reading the netlist, the program first identifies inputs, outputs, and wires instantiating and initializing an object for each of them. Then the same is done to create all gates and pins. The problem comes when reading the file declaration, where the program gets a string and then it has to look for the correct object **wire** to connect it to the gate. Instead of going through all the wires searching for the

Algorithm 2 Recursive *Back-and-forth* algorithm

```
1: procedure SUBCIRCUIT_SEARCH_BACK(wire  $w$ , subcircuit  $subcirc$ , wires  
    $remaining\_outs$ )  
2:   if  $w$  is a Primary Input or  $w$  is a Flip-Flop output then  
3:     if  $w$  is not yet saved then  
4:        $subcirc.inputs \leftarrow w$   
5:       SUBCIRCUIT_SEARCH_FORTH( $w$ ,  $subcirc$ ,  $remaining\_outs$ )  
6:     else  
7:       for all inputs  $i$  in  $g$  do  
8:         SUBCIRCUIT_SEARCH_BACK( $i$ ,  $subcirc$ ,  $remaining\_outs$ )  
9:       end for  
10:  end procedure  
  
11: procedure SUBCIRCUIT_SEARCH_FORTH(wire  $w$ , subcircuit  $subcirc$ , wires  
    $remaining\_outs$ )  
12:  if  $w$  is a Primary Output or  $w$  is a Flip-Flop input then  
13:    if  $w$  is not yet saved then  
14:       $subcirc.outputs \leftarrow w$   
15:      Erase  $w$  from  $remaining\_outs$   
16:      SUBCIRCUIT_SEARCH_BACK( $w$ ,  $subcirc$ ,  $remaining\_outs$ )  
17:    end if  
18:    if  $gt \rightarrow w$  is not yet saved then  $subcirc.gates \leftarrow gt \rightarrow w$   
19:    if  $w$  belongs to a fan-out then  
20:      for all wires  $fo$  emerging from  $w$  do  
21:        SUBCIRCUIT_SEARCH_FORTH( $fo$ ,  $subcirc$ ,  $remaining\_outs$ )  
22:      end for  
23:    end if  
24:  else  
25:    if  $w \rightarrow g$  is not yet saved then  
26:       $subcirc.gates \leftarrow w \rightarrow g$   
27:    end if  
28:    SUBCIRCUIT_SEARCH_FORTH( $w \rightarrow g \rightarrow v$ ,  $subcirc$ ,  $remaining\_outs$ )  
29:    if  $w$  belongs to a fan-out then  
30:      for all wires  $fo$  emerging from  $w$  do  
31:        SUBCIRCUIT_SEARCH_FORTH( $fo$ ,  $subcirc$ ,  $remaining\_outs$ )  
32:      end for  
33:    end if  
34:  end if  
35: end procedure
```

correct object, which would happen several times for each component declaration, we build a `Map` structure with `string` and `wire` types. Then using the member function `Map.find("string")` we immediately get the corresponding object.

6.3 Software

The program is written in C++, which provides great performance and valuable high-level data structures. C++11 is needed to compile several containers from the STL libraries used in the code. For synthesis we use Synopsys Design Compiler Version I-2013.12 using the NanGate 45nm Open Cell library [24].

6.4 Computational complexity

Recursive algorithms. The algorithms used to calculate the input dependencies and to split the circuit into combinational sub-circuits have a time complexity of approximately $O(\log(N))$, N being the number of gates in the circuit. Recursive algorithms might produce a stack overflow error if there are too many function calls to keep. This will mostly depend on the depth of the tree, which is directly related to the critical path of the circuit. It is highly improbable to find a circuit with such a critical path that would make the tool to consume such an amount of memory.

Non-completeness. The time complexity to evaluate this property scales proportionally with the number of output bits (N_o) and exponentially with the order of the analysis (d), following the expression $O(N_o^d)$.

Uniformity. The biggest problem to evaluate uniformity is that all possible inputs need to be evaluated to get all outputs frequencies of occurrence. Thus, the time complexity and the memory usage grow exponentially, following the expressions $O(2^{N_i N_s + N_r})$ and $O(2^{\frac{N_o(N_s-1)}{N_s}})$ respectively, where N_i is the number of input bits, N_s the number of shares and N_r the number of random bits.

6.5 Register layers

For the tool to be able to analyze the non-completeness in a sequential circuits, the user has to specify in the header which register outputs are considered sensitive data and how shares and variables are distributed.

The synthesizer often optimizes the flip-flops output by using the inverted output, creating a new signal. This is an issue, since then the variables specified in the header would never be found. To prevent this the program includes in the `.tcl` file the option `set_dont_touch` for the specified variables.

7 Evaluation

In this section we present several results to illustrate the performance of the tool analyzing the TI properties and a benchmark with several implementations analyzed with our tool.

Non-completeness. Fig. 4 presents the time that the tool needs to evaluate first-, second- and third-order non-completeness for the full round of several KECCAK implementations with different number of shares to see the effect of the different number of outputs on the execution time:

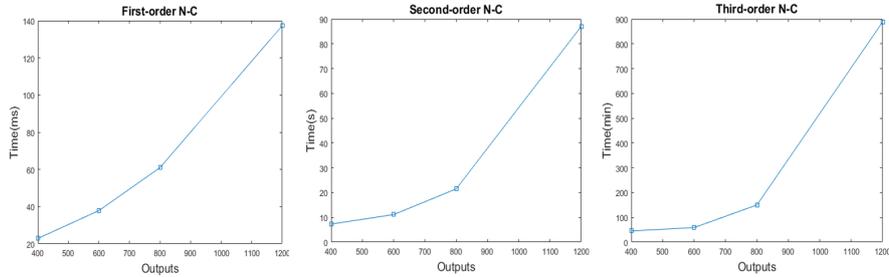


Fig. 4: From left to right: first-, second- and third-order non-completeness evaluation, time versus number of output sensitive bits

As it can be seen, the higher the order of the analysis, the faster the time grows with the number of output bits.

Uniformity. Fig. 5 shows the uniformity results for three different first-order KECCAK SBox implementations from [6, 8, 14]:

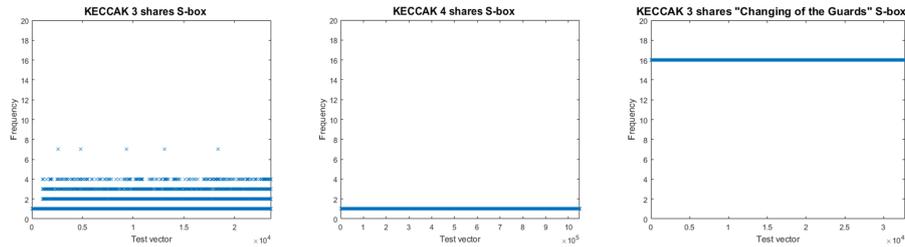


Fig. 5: Uniformity analysis on [6, 8, 14]

The conclusion from the analysis matches the theory from the aforementioned works. The first one is not uniform, as more than a single frequency can be appreciated. The second one achieves uniformity without any additional randomness with the frequency equal to 1, since the non-shared function is a permutation and so is the shared version. The last one, with the same number of shares as the first one, uses four bits of randomness uniformly distributing the output with frequency equal to 16.

Benchmarking. Table 2 gathers the results for several implementations analyzed with the tool: protected AND gates from the literature, various sharing schemes of the KECCAK SBox and AES SBox, few whole round-based KECCAK implementations.

Table 2: Verification Tool benchmark

Design	Cells		Variables			1st N-C		2nd N-C		3rd N-C		Uniformity	
	Comb.	Regs.	Ins	Rand	Outs	Time	Result	Time	Result	Time	Result	Time	Result
Shared AND gates													
Trich [30]	7	0	4	1	2	2.2 ms	✗	2.5 ms	✗	2.5 ms	✗	442 μ s	✓
ISW [19]	7	0	4	1	2	2.2 ms	✗	2.6 ms	✗	2.4 ms	✗	365 μ s	✓
TI [25]	12	0	6	0	3	2 ms	✓	2.7 ms	✗	2.6 ms	✗	739 μ s	✗
DOM [17]	8	4	4	1	2	1.7 ms	✓	2.2 ms	✗	2.5 ms	✗	189 μ s	✓
Shared KECCAK SBoxes													
DOM [18]	45	20	10	5	10	1.3 ms	✓	2.6 ms	✗	10.1 ms	✗	1.7 s	✓
TI3sh. [6]	99	0	15	0	15	1.9 ms	✓	2.8 ms	✗	11 ms	✗	2 s	✗
CG3sh. [14]	104	0	15	4	15	2 ms	✓	4.5 ms	✗	9.8 ms	✗	35 s	✓
TI4sh. [8]	82	0	20	0	20	1.2 ms	✓	4.4 ms	✗	16.3 ms	✗	85 s	✓
Shared $d + 1$ AES SBoxes													
2sh. [11]	862	144	16	64	16	4.8 ms	✓	55.7 ms	✗	417 ms	✗	-	-
3sh. [11]	1.95k	270	24	162	24	6.5 ms	✓	106 ms	✓	4.03 s	✗	-	-
Shared round-based KECCAK Implementations													
DOM	2.7k	800	400	200	800	22.86 ms	✗	7.28 s	✗	45.2 m	✗	-	-
TI3sh.	4.2k	0	600	0	600	37.82 ms	✓	11.12 s	✗	58.8 m	✗	-	-
TI4sh.	6.3k	0	800	0	800	60.98 ms	✓	21.47 s	✗	150 m	✗	-	-
TI6sh.	17k	0	1200	0	1200	137.28 ms	✓	87 s	✓	14.8 h	✗	-	-
Related work [10]													
DOM AND	8	2	-	-	-	-	-	-	-	-	-	≤ 2 s	✓
DOM KECCAK SB	50	10	-	-	-	-	-	-	-	-	-	≤ 20 s	✓
DOM AES SB	536	208	-	-	-	-	-	-	-	-	-	≤ 5 -10 h	✓

Contrary to [10], VerMI is limited to univariate analysis. However, this results in considerably improved performance, which allows the verification of complex designs and complete ciphers, while [10] is limited by the inner complexity. The possibility to check non-completeness on a whole cipher led us to find a flaw in the round-based KECCAK implementation from [18].

8 Conclusions

We have presented VerMI, a formal verification tool to help in automating the security evaluation of cryptographic hardware implementations. Our tool is able to address univariate security of any logic circuit, even in the presence of glitches, by checking non-completeness. Furthermore, the tool is able to check whether uniformity is preserved in smaller blocks. Thus, a complete security assessment is given for any hardware masking scheme published to date. To evaluate the functionality of the tool, multiple schemes from the literature were studied, successfully finding a flaw in one of them: the round-based KECCAK implementation from Gross *et al.* [18].

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